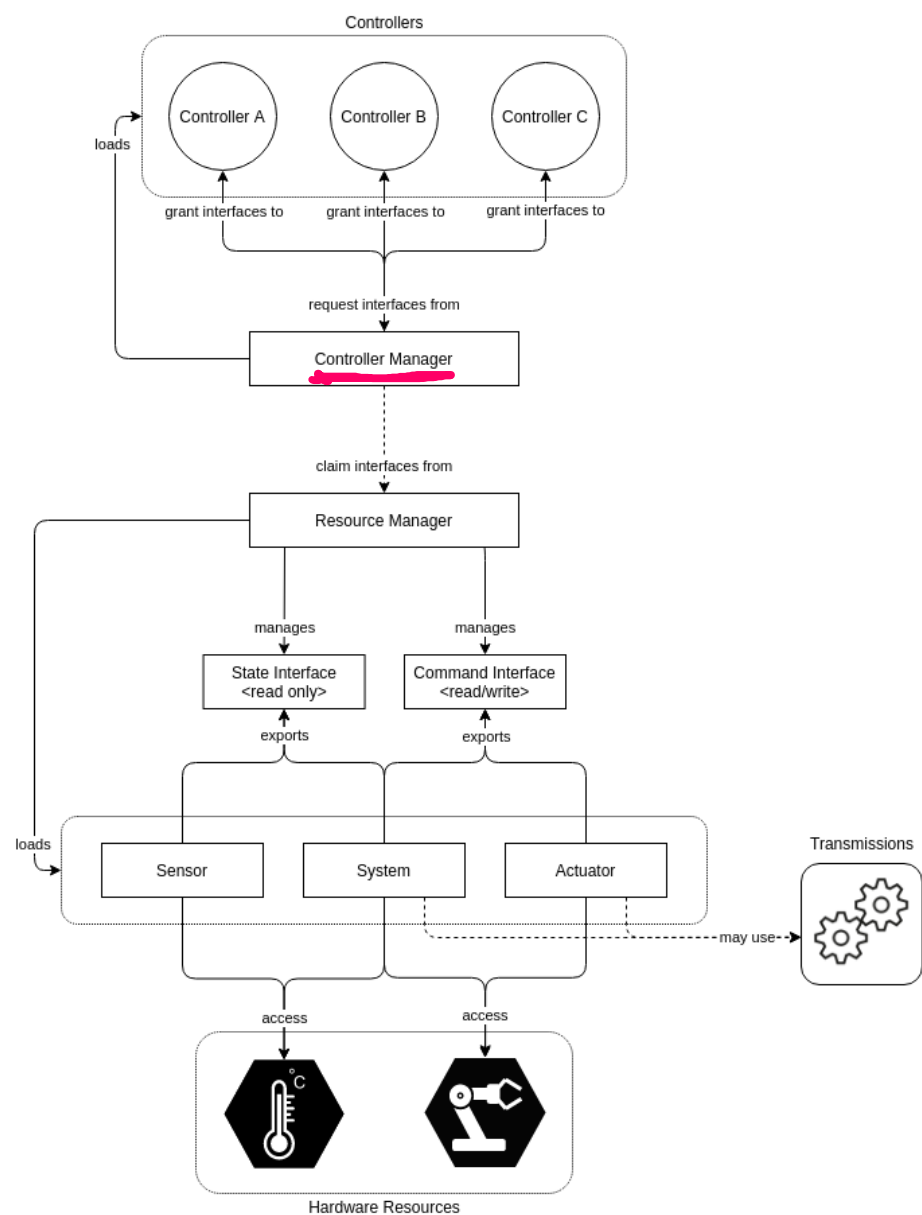


ROS-2 Control

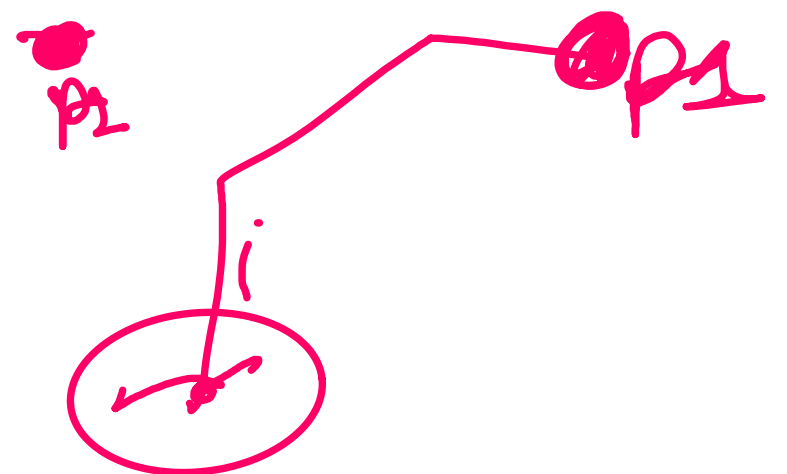
- Command Interface
- State Interface



http://control.ros.org/getting_started.html

Controllers Workflow

- Position Controller
- Acceleration Controller
- Velocity Controller
- Joint Trajectory Controller



Install a Controller

Points
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Command
State

Controller yard

< Control >

C.I

S.I

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body

Controller
Managers.

body
Controller

body