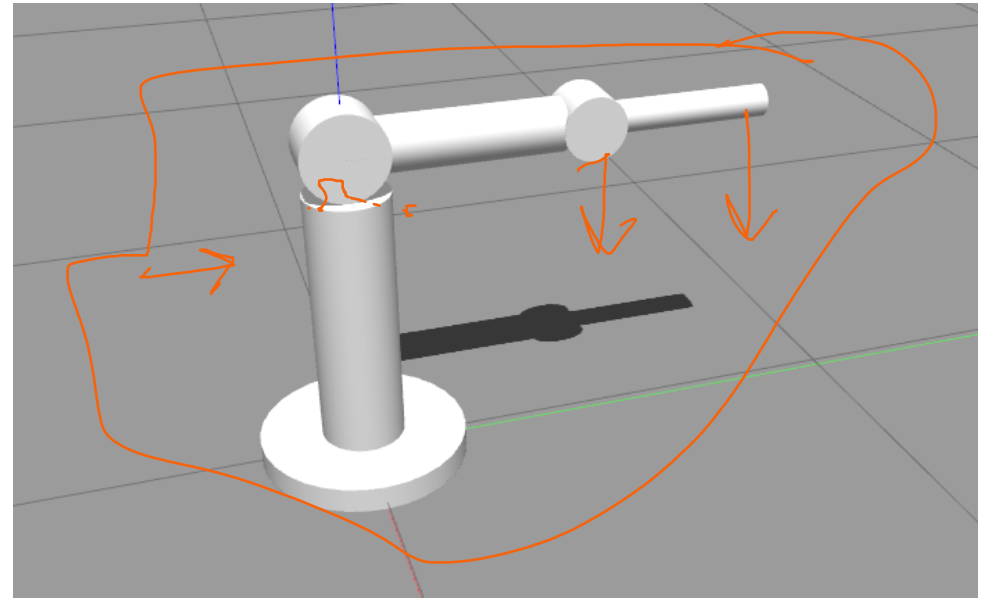


Gazebo and Physical Properties

Tuesday, 21 September 2021 10:48 AM

- Gazebo <-> ROS
- Spawning a model process
- Forces action on Robot



Inertia Properties

