



FPGA Challenge

Working across several multi-disciplinary domains, at PreTalen we are often required to leverage FPGAs in order to solve complex, real-world challenges and develop the next generation of technologies for signal domain analysis, generation and en/decoding.

Prior to your next interview, please complete the challenge problem outlined below and be prepared to provide a short presentation of your design process and accompanying VHDL/Verilog code.

For the presentation we suggest bringing your own laptop. You will have access to a TV, speakers, and an internet connection if needed. If you are unable to bring a laptop, please let us know in advance.

FPGA Challenge Problem:

You have been given a mystery machine which uses an FPGA to control its functions. You will be required to design and develop the Verilog/VHDL code for control of these functions.

The machine uses an input clock operating at 100MHz, 50% duty cycle. The user must press a button to start the mystery box operations. When the start button is pressed, a light is illuminated (assume it is digitally controlled by an io pin on the FPGA, don't worry about the circuit involved). In addition, once the start button is pressed, the machine will begin analyzing the input wire to detect a preamble coming in over the wire. Upon detecting the preamble, the machine must rotate a servo with a flag attached from its starting position clockwise 90 degrees to a vertical position. This flag remains up for 10 seconds after which the whole system must reset, awaiting the start button press.

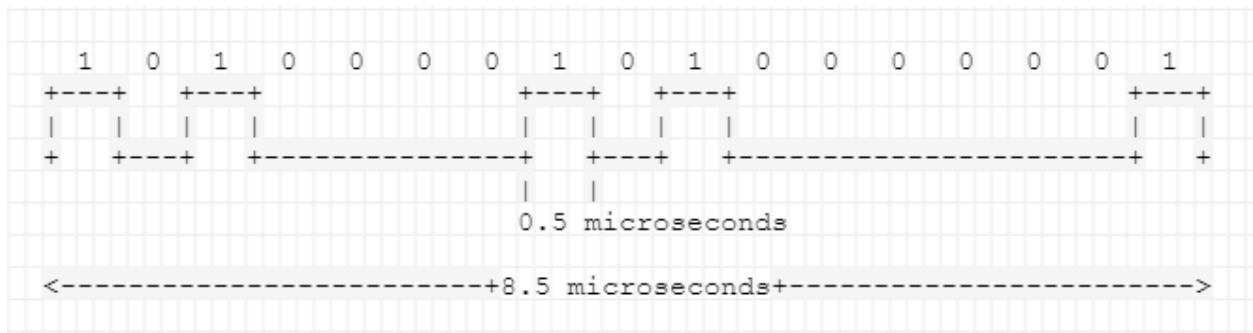
Please draw a state machine of the system and write out the implementation in VHDL or Verilog. Do not worry about a pin connection file.

Assume the inputs to the system are the following:

- *clk_in*: the previously mentioned clock
- *button*: the start button, (on or off)
- *data_line*: constant data where the preamble must be detected (wire)
- *led*: toggles an LED (on or off)
- *servo*: controls the PWM for the servo holding the flag

Please note that the servo operates with a period of 20ms, the starting position requires a duty cycle of 1.0 ms and the up position requires a duty cycle of 1.5 ms

The following figure describes the preamble:



The preamble will be transmitted on the *data_line* with the attached format, but any other data could be on the wire, so be careful not to detect just anything!

Presentation Criteria:

- Explanation of your approach
- State machine of the system
- VHDL/Verilog code
- Knowledge learned