```python
import dronekit

def Connect(mode="udp",address=["127.0.0.1",14550]):
    """ Connects to the vehicle defined in the arguments and returns its class
        Admissible modes: udp (default), serial or tcp """

    if mode=="serial":
        connection_string=address[0]
        baudrate=str(address[1])
    elif mode=="udp":
        connection_string=str(address[0])+":"+str(address[1])
    elif mode=="tcp":
        connection_string="tcp:"+str(address[0])+":"+str(address[1])
    else:
        raise Exception('Connection mode has to be "serial", "udp" or "tcp"')


    print "Connecting on: %s" % connection_string
    if mode=="serial":
        vehicle=dronekit.connect(ip=connection_string,wait_ready=True,rate=50,baud=baudrate)
    else:
        vehicle=dronekit.connect(ip=connection_string,wait_ready=True,rate=50)

    print "Vehicle connected"
    return vehicle
```