main.py Page 1

```
22 #### Step 2: Observe state until "take control" condition is met ####
23
24 ch70bs=0bserve(vehicle.channels["7"], 2001)
25
   print "Waiting for condition to be met"
26
27 ch70bs.update(vehicle.channels["7"])
while not ch70bs.geq(ch70bs.value-200): # 200 PWM tolerance
29
        timeLoop = time.clock()
30
        while (time.clock()-timeLoop) < 0.2:</pre>
31
            pass # Do not continue until there is new data to update
        ch7Obs.update(vehicle.channels["7"])
32
        print "CH7 current value: %i CH7 target: %i" % (ch70bs.variable, ch70bs.value
33
    )
34
35 print "Condition met"
36 sound.beep(440, 200)
```