```
import Tkinter
import ttk
import subprocess


window = Tkinter.Tk()
window.title("DroneKit Launcher")
try:
    window.iconbitmap('C:\\Users\\Usuario\\Documents\\GitHub\\quadcopters-tfg-lvaro\\Dronekit\\favicon.ico')
except:
    pass
window.resizable(0,0)

mainFrame=Tkinter.LabelFrame(window,relief=Tkinter.RIDGE)
mainFrame.grid(sticky=Tkinter.NS)

#### PLATFORM ####


platform=Tkinter.LabelFrame(mainFrame,text="Platform")
platform.grid(row=0,rowspan=2,column=0,padx=5,pady=5,ipadx=5,ipady=5,sticky=Tkinter.NS)


def changeSelection(*args):
    if str(platformValue.get())=="SITL":
        platformSITLlaunch.configure(state=Tkinter.NORMAL)
        mvpyPortText.configure(text="Port")
        mvpyAddress.set("tcp:127.0.0.1")
        mvpyPort.set("5760")
    elif str(platformValue.get())=="UAV":
        platformSITLlaunch.configure(state=Tkinter.DISABLED)
        mvpyPortText.configure(text="Baud rate")
        if str(platformUAVselect.get())=="USB":
            mvpyAddress.set("com6")
            mvpyPort.set("115200")
        elif str(platformUAVselect.get())=="Telemetry":
            mvpyAddress.set("com4")
            mvpyPort.set("57600")
        else:
            mvpyAddress.set("")
            mvpyPort.set("")

def launchSitl():
    openCMD='START CMD /K '
    sitlRoute='"C:\\Users\\Usuario\\Google Drive\\TFG Alvaro Melgosa Pascual\\WinPython-64bit-2.7.10.3\\python-2.7.10.amd64\\Scripts\\dronekit-sitl.exe" '
    sitlArgs='copter-v3.2.1 --model x --home=40.333266, -3.765728,620,0'
    subprocess.call(openCMD + sitlRoute + sitlArgs, shell=True)


platformValue=Tkinter.StringVar()

platformSITL=Tkinter.Radiobutton(platform,text="SITL",variable=platformValue,value="SITL",command=changeSelection)
platformSITL.grid(row=0,column=0,padx=5,pady=5)

platformSITLlaunch=Tkinter.Button(platform,text="Launch",command=launchSitl,width=8)
platformSITLlaunch.grid(row=0,column=1,padx=5,pady=5)

platformUAV=Tkinter.Radiobutton(platform,text="UAV",variable=platformValue,value="U
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AV",command=changeSelection)
platformUAV.grid(row=1,column=0,padx=5,pady=5)

platformUAVconnect=Tkinter.StringVar()
platformUAVselect=ttk.Combobox(platform,width=7,textvariable=platformUAVconnect)
platformUAVselect['values']=("USB","Telemetry")
platformUAVselect.bind("<<ComboboxSelected>>",changeSelection)
platformUAVselect.grid(row=1,column=1,padx=5,pady=5)


#### MAVPROXY ####

mvpy=Tkinter.LabelFrame(mainFrame,text="MAVProxy",relief=Tkinter.GROOVE)
mvpy.grid(row=0,rowspan=2,column=1,padx=5,pady=5,ipadx=5,ipady=5,sticky=Tkinter.NS)


def launchMavproxy(address,port):
    openCMD='START CMD /K '
    mavproxyRoute='"C:\\Users\\Usuario\\Google Drive\\TFG Alvaro Melgosa Pascual\\MAVProxy\\mavproxy.exe" '
    if address[0:3]=="com":
        mavproxyArgs=' --master=' + address + ' --baud=' + port + ' --out=127.0.0.1:14550 --out=127.0.0.1:14551'
    else:
        mavproxyArgs=' --master=' + address + ':' + port + ' --out=127.0.0.1:14550 --out=127.0.0.1:14551'
    subprocess.call(openCMD + mavproxyRoute + mavproxyArgs, shell=True)

mvpyAddressText=Tkinter.Label(mvpy,text="Address")
mvpyAddressText.grid(row=0,column=0,padx=5,pady=5,sticky=Tkinter.E)

mvpyAddress=Tkinter.StringVar()
mvpyAddressValue=Tkinter.Entry(mvpy,textvariable=mvpyAddress,width=12)
mvpyAddressValue.grid(row=0,column=1,padx=5,pady=5)

mvpyPortText=Tkinter.Label(mvpy,text="Baud rate")
mvpyPortText.grid(row=1,column=0,padx=5,pady=5,sticky=Tkinter.E)

mvpyPort=Tkinter.StringVar()
mvpyPortValue=Tkinter.Entry(mvpy,textvariable=mvpyPort,width=12)
mvpyPortValue.grid(row=1,column=1,padx=5,pady=5)

mvpyConnect=Tkinter.Button(mvpy,text="Connect",command=lambda:launchMavproxy(str(mvpyAddress.get()),str(mvpyPort.get())))
mvpyConnect.grid(row=2,column=1,padx=5,pady=5,sticky=Tkinter.E)


#### SCRIPT ####

script=Tkinter.LabelFrame(mainFrame,text="Script",relief=Tkinter.GROOVE)
script.grid(row=0,column=2,padx=5,pady=5,ipadx=5,ipady=5)

def runScript(route):
    openCMD='START CMD /K '
    scriptRoute='"C:\\Users\\Usuario\\Documents\\GitHub\\quadcopters-tfg-lvaro\\Dronekit\\' + route + '\\main.py"'
    subprocess.call(openCMD + scriptRoute, shell=True)

scriptLabel=Tkinter.Label(script,text="File location")
scriptLabel.grid(row=0,column=0,padx=5,pady=5)

scriptFileLocation=Tkinter.StringVar()
scriptFile=Tkinter.Entry(script,textvariable=scriptFileLocation,width=15)
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116 scriptFile.grid(row=1,column=0,padx=5)
117
118 scriptRun=Tkinter.Button(script,text="Run script",command=lambda:runScript(str(scri
    ptFileLocation.get())))
119 scriptRun.grid(row=1,column=1,padx=5,pady=5)
120
121
122 #### MISSION PLANNER ####
123
124 def launchPlanner():
125     openCMD='START CMD /K '
126     plannerRoute='"C:\\Program Files (x86)\\Mission Planner\\MissionPlanner.exe"'
127     subprocess.call(openCMD + plannerRoute, shell=True)
128
129 planner=Tkinter.Button(mainFrame,text="Launch Mission Planner",command=launchPlanne
    r)
130 planner.grid(column=2,row=1,padx=5,pady=5)
131
132
133
134
135 window.mainloop()
136
137
```