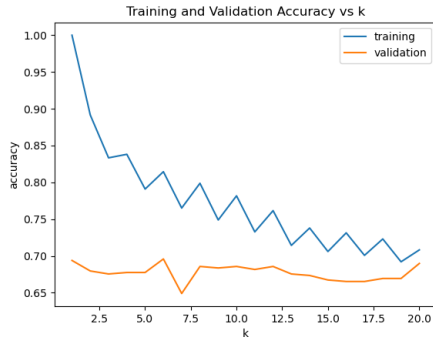


Q1:

(a) In `hwl_q_code.py`

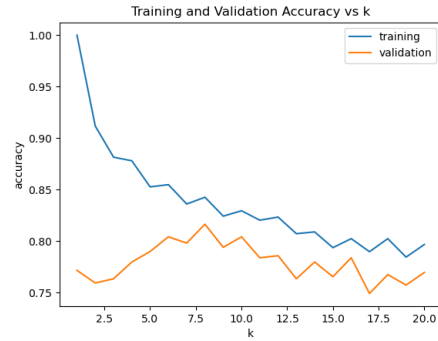
(b) I generate two plots. one with metric = 'cosine'. one not

Plot without metric = 'cosine'



Best validation accuracy: 0.6959183673469388
Best accuracy on the test data: 0.6428571428571429

Plot with metric = 'cosine'



Best validation accuracy: 0.8163265306122449
Best accuracy on the test data: 0.7591836734693878

(c)

metric = 'cosine' calculates the distance using the following formula

$$\vec{x} \cdot \vec{y} = |\vec{x}| \cdot |\vec{y}| \cos \angle \vec{x}, \vec{y} \Rightarrow \cos \angle \vec{x}, \vec{y} = \frac{\vec{x} \cdot \vec{y}}{|\vec{x}| |\vec{y}|}$$

Since the value of $\cos \angle \vec{x}, \vec{y}$ can let us know the angle between those two vectors, it is easier to know whether those two data sets are related with metric = 'cosine' than the Euclidean metric

Qs:

as Similar to what we learned from class

$$w_j \leftarrow w_j - \frac{\partial J^P}{\partial w_j}$$

$$\begin{aligned} \text{Now calculate } \frac{\partial J^P}{\partial w_j} &= \frac{\partial (J + R)}{\partial w_j} = \frac{\partial J}{\partial w_j} + \frac{\partial}{\partial w_j} \left(\frac{1}{2} \sum_{j=1}^D \beta_j w_j^2 \right) \\ &= \underbrace{\frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)})}_{\text{from lecture}} + \beta_j w_j \end{aligned}$$

$$\text{So } w_j \leftarrow w_j - \alpha \left(\frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) + \beta_j w_j \right) \quad (1)$$

$$\text{Since } y = \sum_{j=1}^D w_j x_j^{(i)} + b \Rightarrow b = y - \sum_{j=1}^D w_j x_j^{(i)} \quad (2)$$

plug (1) into (2), we get

$$b \leftarrow y - \sum_{j=1}^D \left(w_j - \alpha \left(\frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) + \beta_j w_j \right) \right) x_j^{(i)}$$

Substitute y with $b + \sum_{j=1}^D w_j x_j^{(i)}$

We got

$$b \leftarrow b + \sum_{j=1}^D w_j x_j^{(i)} - \sum_{j=1}^D \left(w_j - \alpha \left(\frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) + \beta_j w_j \right) \right) x_j^{(i)}$$

$$\text{So we have } b \leftarrow b + \sum_{j=1}^D \alpha \left(\frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) \right) x_j^{(i)} + \beta_j w_j x_j^{(i)}$$

$$b \leftarrow b + \frac{\alpha}{N} \sum_{j=1}^D \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) x_j^{(i)} + \alpha \cdot \sum_{j=1}^D \beta_j w_j x_j^{(i)}$$

(b): By part (a)

$$\text{We know } \frac{\partial J^P}{\partial w_j} = \frac{1}{N} \sum_{i=1}^N x_j^{(i)} (y^{(i)} - t^{(i)}) + \beta_j w_j$$

Substitute with $y = \sum_{j=1}^D w_j x_j^{(i)}$

$$\begin{aligned}
\text{So } \frac{\partial J_{reg}}{\partial w_j} &= \frac{1}{N} \sum_{i=1}^N x_j^{(i)} \left(\sum_{j'=1}^D w_{j'} x_j^{(i)} - t^{(i)} \right) + \beta_j w_j \\
&= \frac{1}{N} \sum_{i=1}^N x_j^{(i)} \sum_{j'=1}^D w_{j'} x_j^{(i)} + \beta_j w_j - \frac{1}{N} \sum_{i=1}^N x_j^{(i)} t^{(i)} \\
&= \frac{1}{N} \sum_{i=1}^N \left(x_j^{(i)} \sum_{j'=1}^D w_{j'} x_j^{(i)} + N \cdot \beta_j w_j \right) - \frac{1}{N} \sum_{i=1}^N x_j^{(i)} t^{(i)} = A_{jj'} w_{j'} - C_j.
\end{aligned}$$

define an indicator function $I_j = \begin{cases} 1, j=j' \\ 0, \text{otherwise} \end{cases}$

$$\text{So } \frac{\partial J_{reg}}{\partial w_j} = \frac{1}{N} \sum_{i=1}^N \left(x_j^{(i)} \sum_{j'=1}^D x_j^{(i)} w_{j'} + N \cdot \sum_{j'=1}^D \beta_{j'} I_j w_{j'} \right) - \frac{1}{N} \sum_{i=1}^N x_j^{(i)} t^{(i)}$$

$$\text{Hence, } A_{jj'} = \frac{1}{N} \sum_{i=1}^N \left(x_j^{(i)} \cdot x_{j'}^{(i)} + N \cdot \beta_{j'} I_j \right)$$

$$C_j = \frac{1}{N} \sum_{i=1}^N x_j^{(i)} t^{(i)}$$

(C):

$$\text{let } \beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_D \end{pmatrix}, \quad \beta_i \text{ are vectors, } \beta_i = \beta_{j'} \text{ if } i=j'$$

$$A = (X^T X + N \beta \cdot \beta^T) \cdot \frac{1}{N}$$

$$C = (X^T E) \cdot \frac{1}{N}$$

$$A \cdot w - C = 0 \Rightarrow w = A^{-1} \cdot C = (X^T X + N \beta \beta^T)^{-1} \cdot X^T \cdot E$$

$$Q_3: J = \frac{1}{N} \sum_{i=1}^N f(y^{(i)}, t^{(i)}) = \frac{1}{N} \sum_{i=1}^N (1 - \cos(y^{(i)} - t^{(i)}))$$

$$\text{So } y = w^T x + b = \sum_{j=1}^D w_j x_j^{(i)} + b$$

$$\frac{\partial J}{\partial y} = \frac{1}{N} \sum_{i=1}^N \sin(y^{(i)} - t^{(i)})$$

$$\frac{\partial J}{\partial w_j} = \frac{\partial J}{\partial y} \cdot \frac{\partial y}{\partial w_j} = \left(\frac{1}{N} \sum_{i=1}^N \sin(y^{(i)} - t^{(i)}) \right) \cdot x_j^{(i)}$$

$$\text{So } \frac{\partial J}{\partial w} = \begin{pmatrix} \frac{\partial J}{\partial w_1} \\ \vdots \\ \frac{\partial J}{\partial w_D} \end{pmatrix} = \begin{pmatrix} \frac{1}{N} \sum_{i=1}^N (\sin(y^{(i)} - t^{(i)}) x_j^{(i)}) \\ \vdots \\ \frac{1}{N} \sum_{i=1}^N (\sin(y^{(i)} - t^{(i)}) x_D^{(i)}) \end{pmatrix}$$

$$\frac{\partial J}{\partial b} = \frac{\partial J}{\partial y} \cdot \frac{\partial y}{\partial b} = \frac{1}{N} \sum_{i=1}^N \sin(y^{(i)} - t^{(i)}) \cdot 1 = \frac{1}{N} \sum_{i=1}^N \sin(y^{(i)} - t^{(i)})$$

Q4: (a) code both shown in `hw1-g4-code.py`

(b): code shown in `hw1-g4-code.py`

The order should be `shuffle-data`

↓
`split-data` → `train-model` → `predict` → `loss` → `cross-validation`.

The arguments are: `data`,
 `number of folds`,
 `a sequence of lambda`

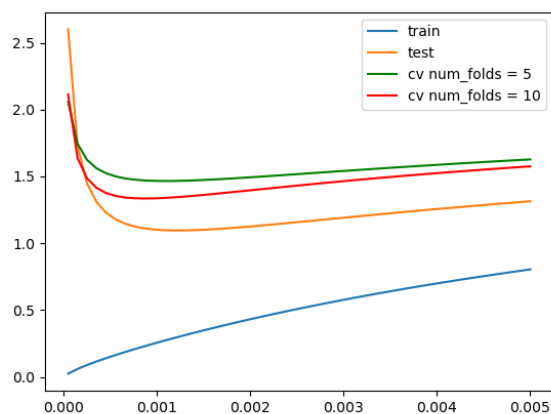
(c): The output is shown below:

```
lambda: 5e-05
  train error: 0.023827398142615853
  test error: 2.601391644823133
lambda: 0.0001510204081632653
  train error: 0.05891274573913389
  test error: 1.7287677994041546
lambda: 0.00025204081632653066
  train error: 0.08829510341160723
  test error: 1.449041107721426
lambda: 0.000353061224489796
  train error: 0.11469870650014892
  test error: 1.3106086900637661
lambda: 0.0004540816326530613
  train error: 0.13923988850774655
  test error: 1.2304985961640553
lambda: 0.0005551020408163266
  train error: 0.16248341903497207
  test error: 1.180389255472875
lambda: 0.000656122448979592
  train error: 0.18474660580356297
  test error: 1.1477791855291435
lambda: 0.0007571428571428573
  train error: 0.20622199234302155
  test error: 1.1262495170677962
lambda: 0.0008581632653061226
  train error: 0.2270338998077502
  test error: 1.1121518828937422
lambda: 0.0009591836734693879
  train error: 0.2472669246464069
  test error: 1.1032544106716156
lambda: 0.001060204081632653
  train error: 0.26698132507945677
  test error: 1.098113519790282
lambda: 0.0011612244897959184
  train error: 0.28622180470505515
  test error: 1.0957538481482645
lambda: 0.0012622448979591838
  train error: 0.3050227607306162
  test error: 1.095492899034103
lambda: 0.001363265306122449
  train error: 0.3234115438629369
  test error: 1.0968392292395663
lambda: 0.0014642857142857144
  train error: 0.34141055052213537
  test error: 1.09943045388258
lambda: 0.0015653061224489796
  train error: 0.35903860424252554
  test error: 1.1029939651442386
lambda: 0.001666326530612245
  train error: 0.3763118905865588
  test error: 1.1073211894755193
lambda: 0.0017673469387755104
  train error: 0.3932446038612771
  test error: 1.1122502216496666
lambda: 0.0018683673469387756
  train error: 0.4098494033148334
  test error: 1.1176538117834807
```

```
lambda: 0.001969387755102041
    train error: 0.4261377407022199
    test error: 1.1234308705075875
lambda: 0.0020704081632653064
    train error: 0.44212009936214197
    test error: 1.129500344237022
lambda: 0.002171428571428572
    train error: 0.4578061713896179
    test error: 1.1357967224805834
lambda: 0.002272448979591837
    train error: 0.4732049908414316
    test error: 1.1422666911374024
lambda: 0.0023734693877551023
    train error: 0.488325035281242
    test error: 1.1488666047195637
lambda: 0.002474489795918368
    train error: 0.5031743042367003
    test error: 1.155560553114307
lambda: 0.002575510204081633
    train error: 0.5177603806219526
    test error: 1.1623188662165589
lambda: 0.0026765306122448983
    train error: 0.5320904794538496
    test error: 1.1691169452851025
lambda: 0.0027775510204081635
    train error: 0.5461714869921581
    test error: 1.1759343410147318
lambda: 0.002878571428571429
    train error: 0.5600099925916275
    test error: 1.1827540199582744
lambda: 0.0029795918367346943
    train error: 0.5736123149542308
    test error: 1.1895617761946022
lambda: 0.0030806122448979595
    train error: 0.5869845240389066
    test error: 1.196345756047619
lambda: 0.003181632653061225
    train error: 0.6001324595729604
    test error: 1.2030960715562675
lambda: 0.0032826530612244903
    train error: 0.6130617468798986
    test error: 1.2098044841755544
lambda: 0.0033836734693877555
    train error: 0.6257778105688381
    test error: 1.2164641444656075
lambda: 0.003484693877551021
    train error: 0.6382858865043091
    test error: 1.2230693767226455
lambda: 0.0035857142857142863
    train error: 0.6505910323804636
    test error: 1.229615499917253
lambda: 0.0036867346938775514
    train error: 0.6626981371520451
    test error: 1.2360986781407932
lambda: 0.003787755102040817
    train error: 0.6746119295199954
    test error: 1.2425157951688124
```

```
lambda: 0.0038887755102040822
  train error: 0.6863369856278856
  test error: 1.2488643488391782
lambda: 0.003989795918367347
  train error: 0.6978777360932145
  test error: 1.2551423617905224
lambda: 0.004090816326530612
  train error: 0.7092384724728255
  test error: 1.26134830577148
lambda: 0.004191836734693878
  train error: 0.7204233532423231
  test error: 1.2674810372558627
lambda: 0.004292857142857143
  train error: 0.731436409354227
  test error: 1.2735397425155066
lambda: 0.004393877551020408
  train error: 0.7422815494277314
  test error: 1.2795238906352722
lambda: 0.004494897959183674
  train error: 0.7529625646135095
  test error: 1.2854331932216374
lambda: 0.004595918367346939
  train error: 0.7634831331695463
  test error: 1.2912675697720937
lambda: 0.004696938775510204
  train error: 0.7738468247780177
  test error: 1.297027117847228
lambda: 0.00479795918367347
  train error: 0.7840571046284165
  test error: 1.302712087329965
lambda: 0.004898979591836735
  train error: 0.7941173372883514
  test error: 1.3083228581730006
lambda: 0.005
  train error: 0.8040307903801956
  test error: 1.3138599211313071
5-fold cross validation lambda: 0.001060204081632653
10-fold cross validation lambda: 0.0008581632653061226
```

(b): The plot is shown below-



The λ proposed is :

```
5-fold cross validation lambda: 0.001060204081632653  
10-fold cross validation lambda: 0.0008581632653061226
```

Comments: As we can see from the plot.

The trend of test, cv num_folds=5 and cv num_folds=10 are close to each other, they all decrease first then increase. While for the train error line, the curve always increase.