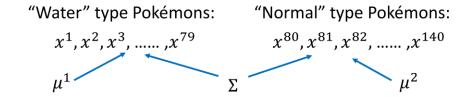
# Modifying Model

Ref: Bishop, chapter 4.2.2

#### Maximum likelihood

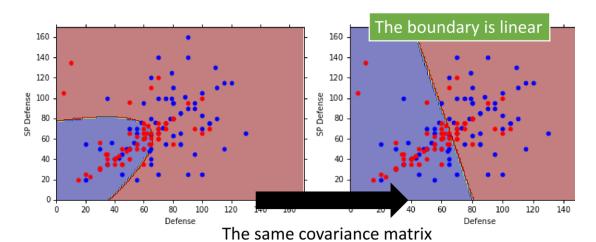


Find  $\mu^1$ ,  $\mu^2$ ,  $\Sigma$  maximizing the likelihood  $L(\mu^1,\mu^2,\Sigma)$ 

$$L(\mu^{1},\mu^{2},\Sigma) = f_{\mu^{1},\Sigma}(x^{1})f_{\mu^{1},\Sigma}(x^{2})\cdots f_{\mu^{1},\Sigma}(x^{79}) \times f_{\mu^{2},\Sigma}(x^{80})f_{\mu^{2},\Sigma}(x^{81})\cdots f_{\mu^{2},\Sigma}(x^{140})$$

 $\mu^1$  and  $\mu^2$  is the same  $\Sigma = \frac{79}{140} \Sigma^1 + \frac{61}{140} \Sigma^2$ 

# Modifying Model

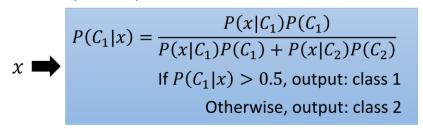


All: total, hp, att, sp att, de, sp de, speed

54% accuracy 73% accuracy

#### Three Steps

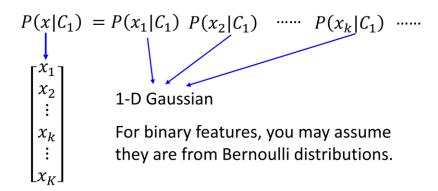
• Function Set (Model):



- Goodness of a function:
  - The mean  $\mu$  and covariance  $\Sigma$  that maximizing the likelihood (the probability of generating data)
- Find the best function: easy

### **Probability Distribution**

• You can always use the distribution you like ©



If you assume all the dimensions are independent, then you are using *Naive Bayes Classifier*.