

In-Triangle Test



```
bool InTriangle( P, Q, R, S )  
    return ToLeft( P, Q, S ) == ToLeft( Q, R, S )  
        && ToLeft( Q, R, S ) == ToLeft( R, P, S );
```

To-Left Test



```
bool ToLeft( P, Q, S )
```

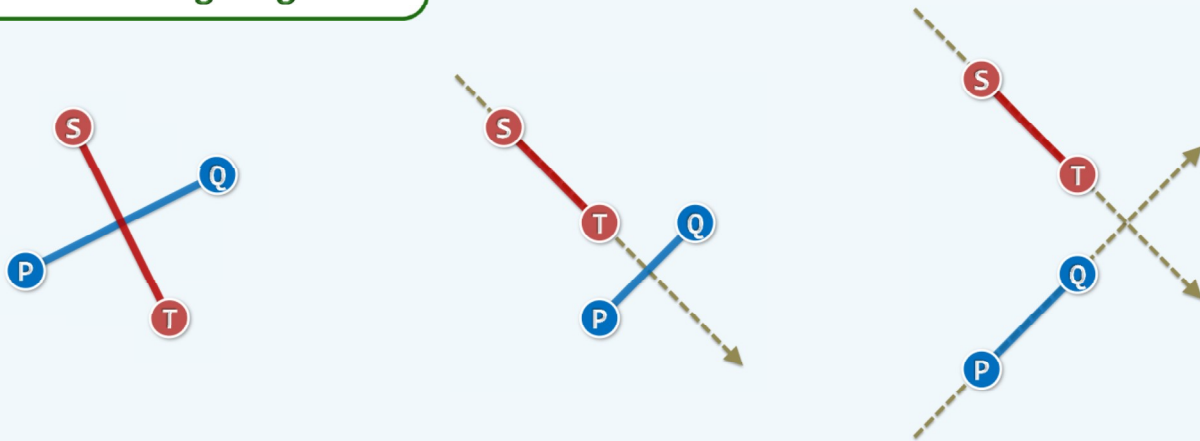
```
    return  0 < P.x * Q.y - P.y * Q.x  
           + Q.x * S.y - Q.y * S.x  
           + S.x * P.y - S.y * P.x;
```

$$2 \cdot S_{\Delta PQS} = \begin{vmatrix} P_x & P_y & 1 \\ Q_x & Q_y & 1 \\ S_x & S_y & 1 \end{vmatrix}$$

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Intersecting Segments



```
bool intersect( P, Q, S, T )
```

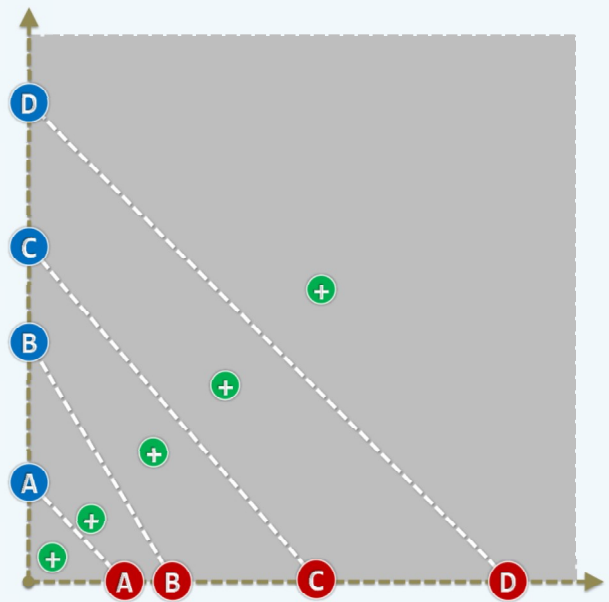
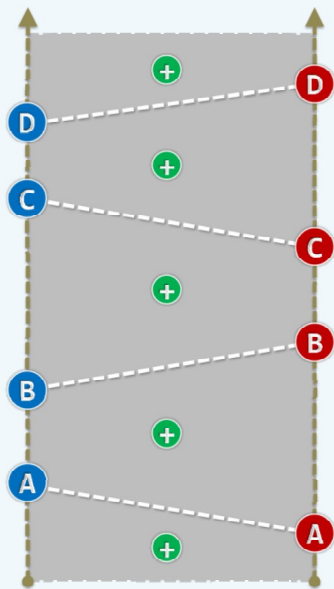
```
    return ToLeft( S, T, P ) ^ ToLeft( S, T, Q)
```

```
    && ToLeft( P, Q, S ) ^ ToLeft( P, Q, T);
```

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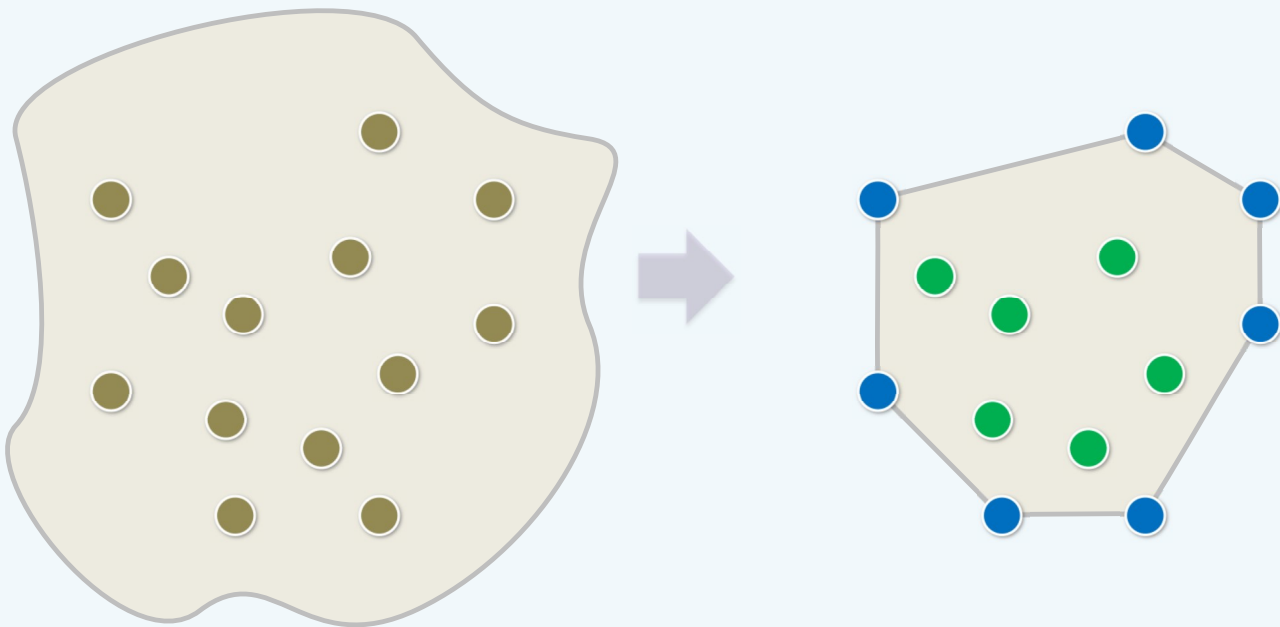
Point Location in A Ladder



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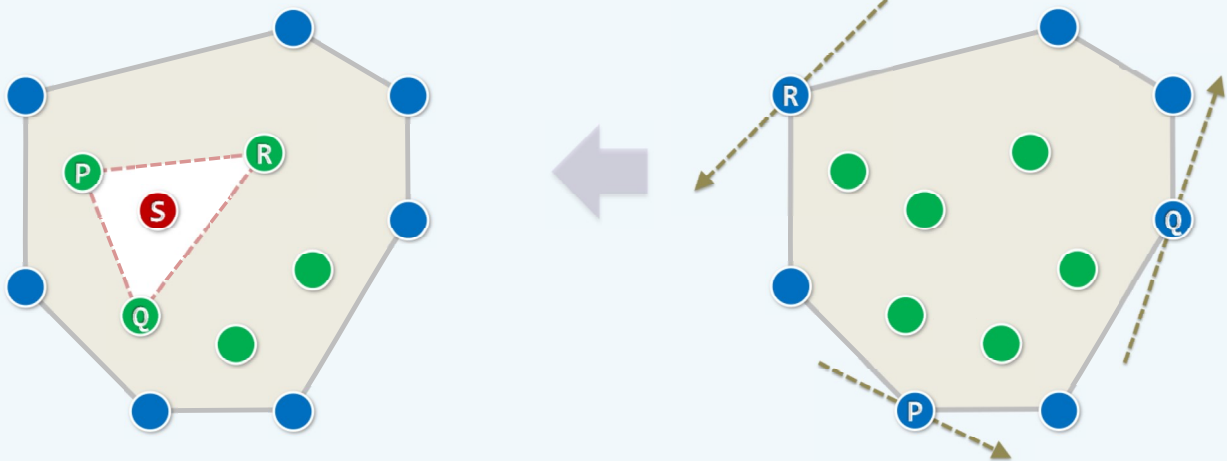
CH: Convex Hull



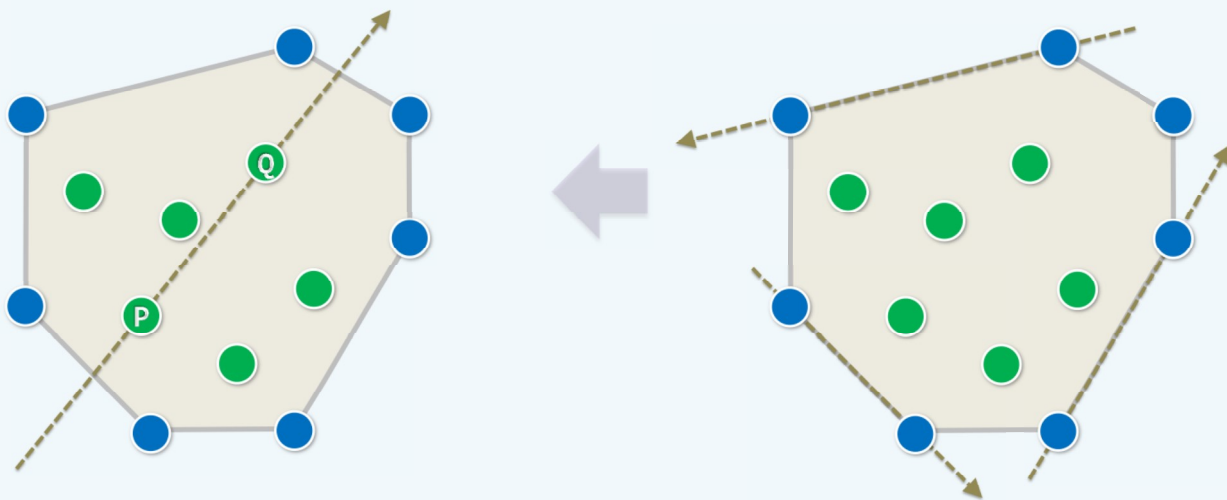
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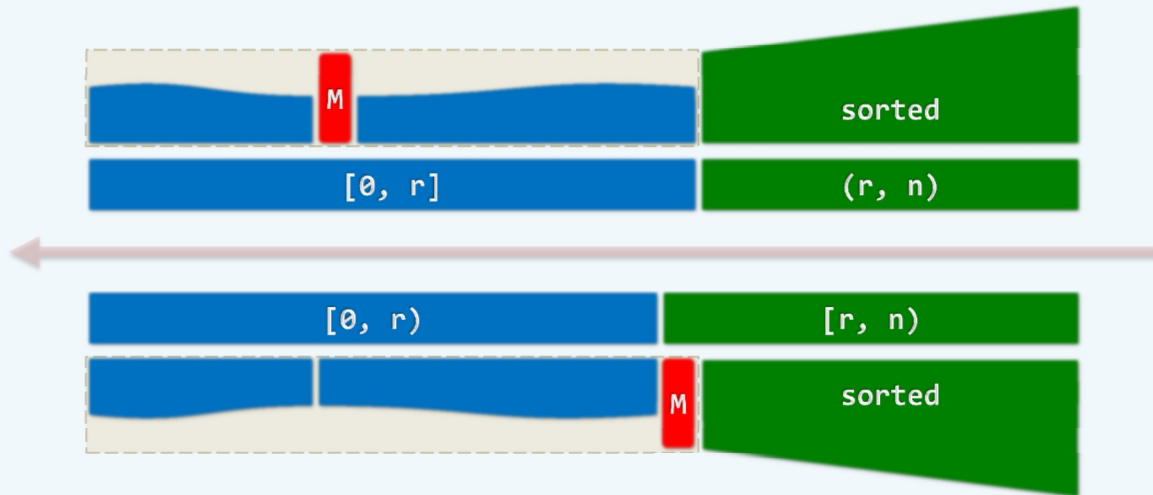
CH: Extreme Points



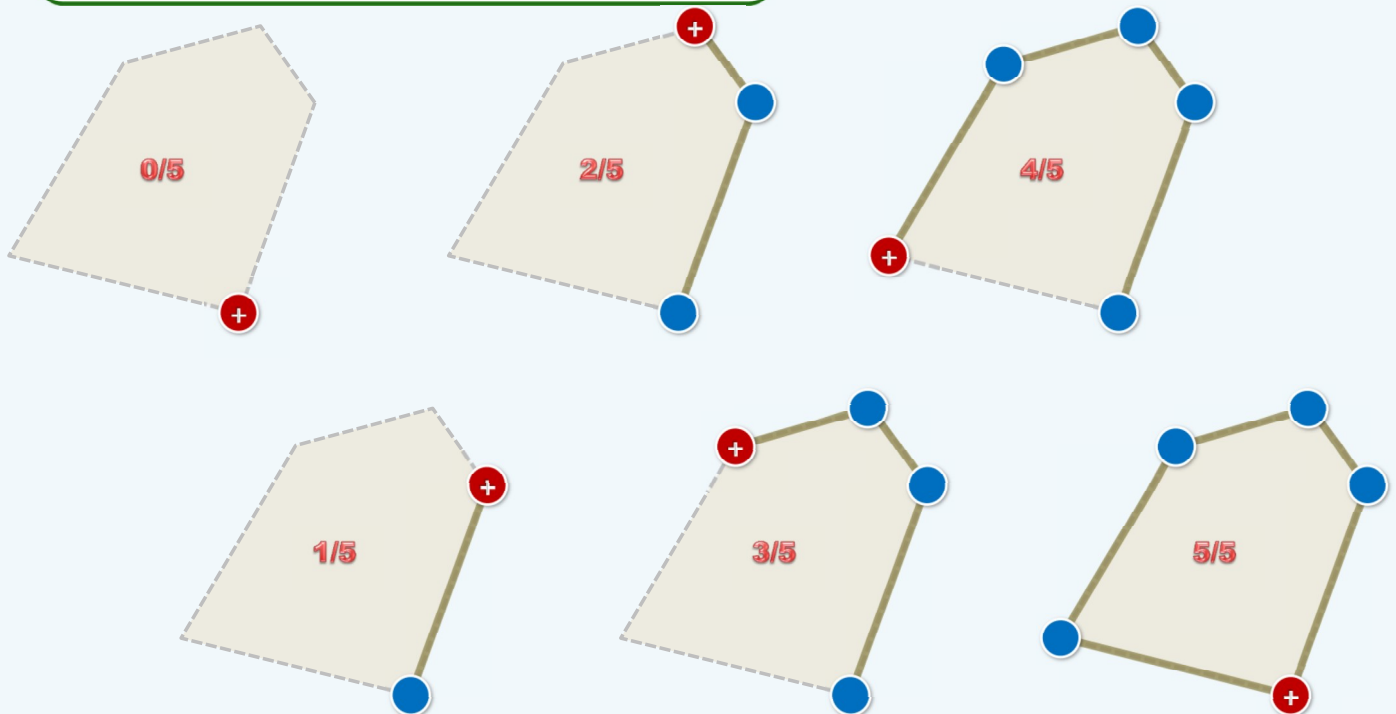
CH: Extreme Edges



CH: Jarvis March: Selectionsort



CH: Jarvis March = Gift Wrapping



CH: Jarvis March: Algorithm

Find O an extreme point

Find OK the first extreme edge

Repeat

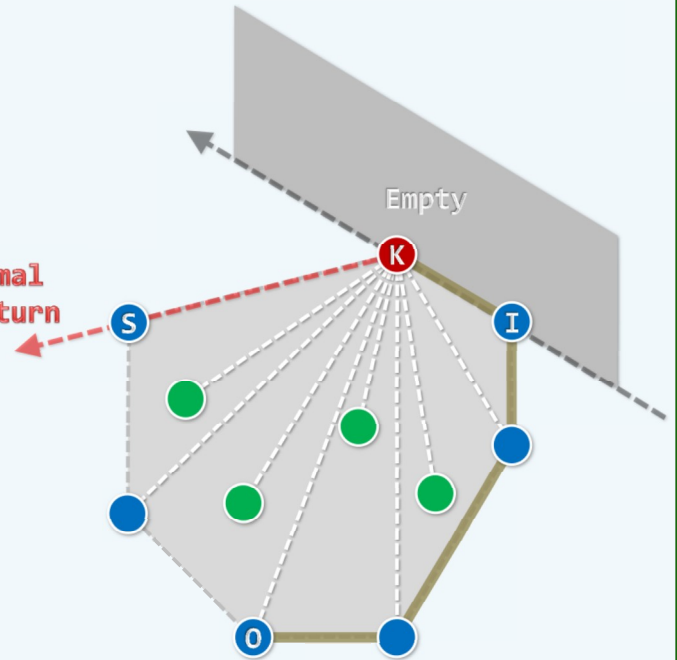
Find the next extreme edge KS

$K = S$

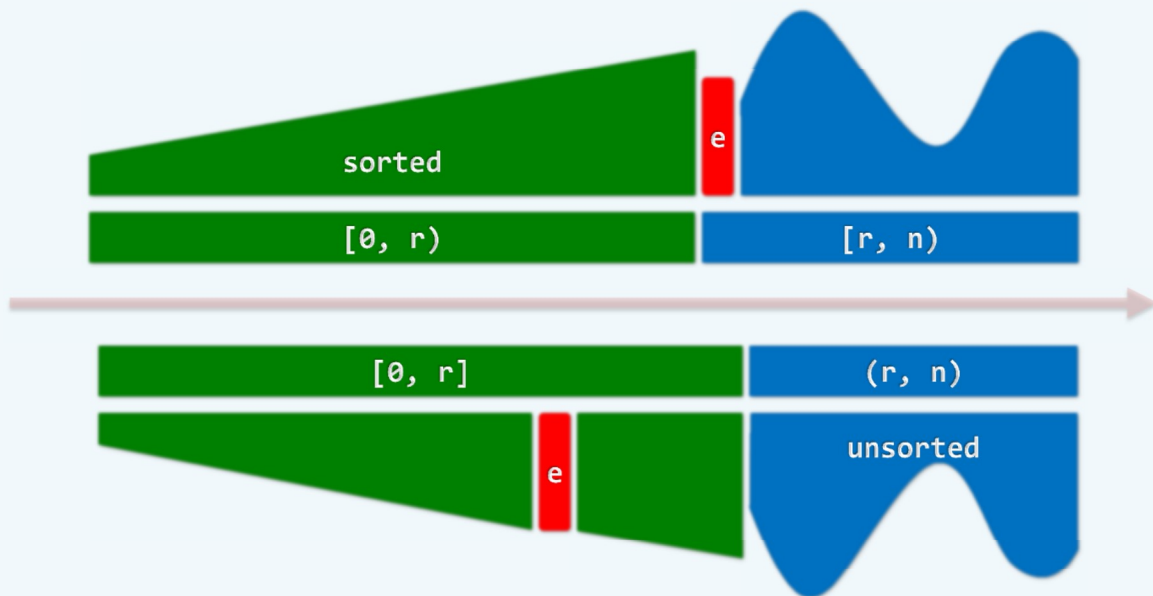
until $K == O$

//What if S is **NOT** unique?

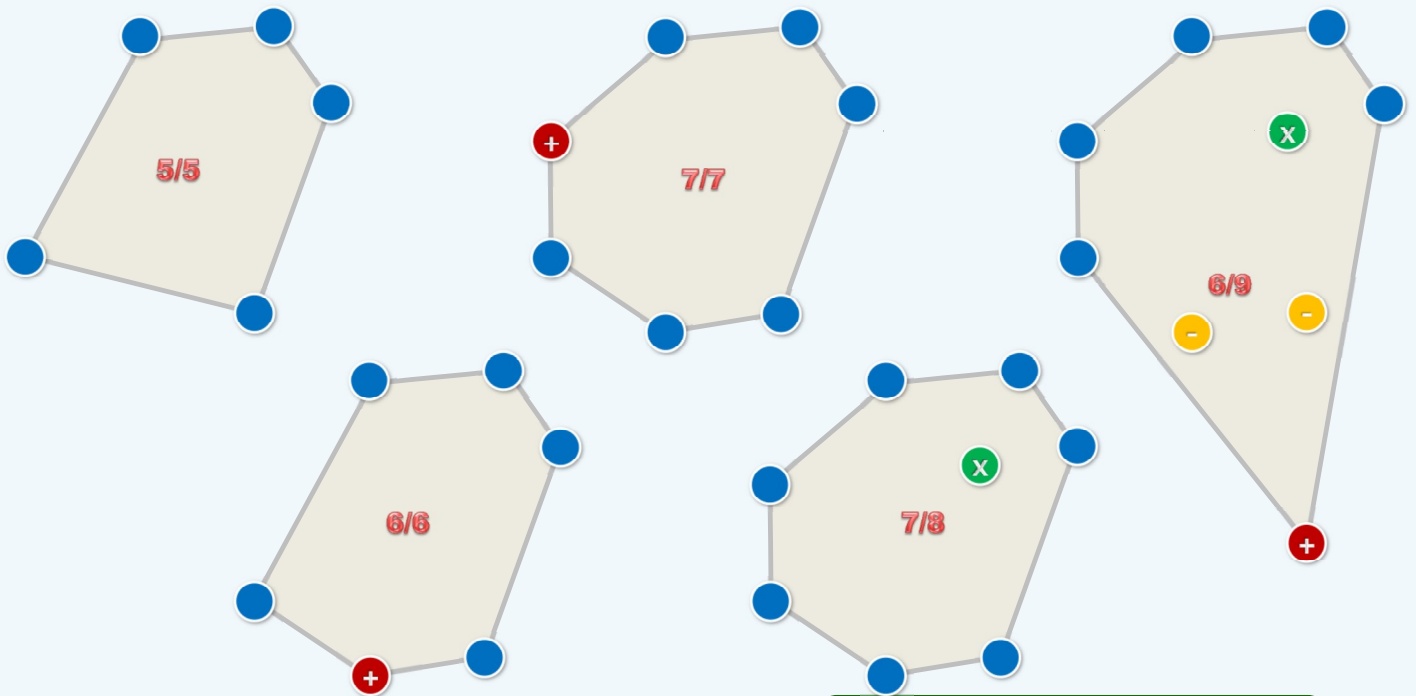
minimal
left turn



CH: Incremental Construction: Insertionsort



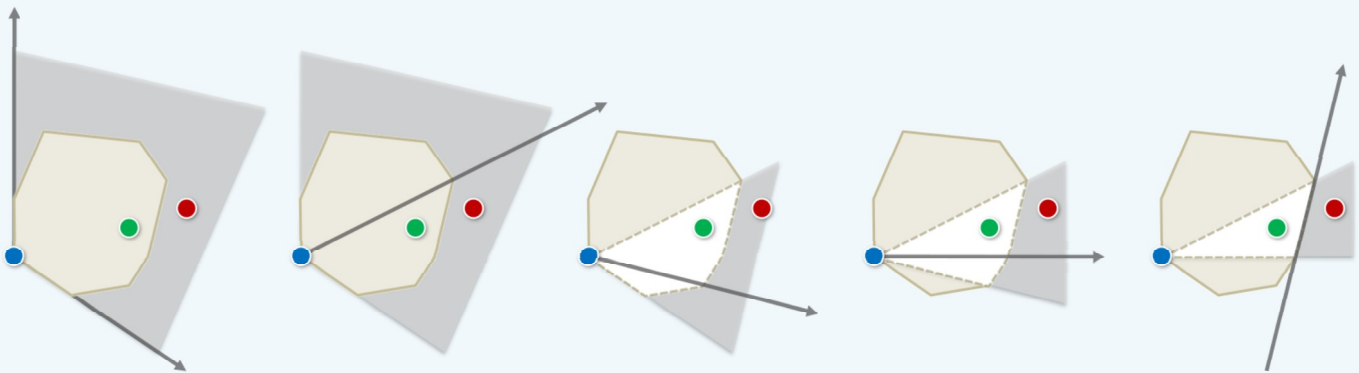
CH: Incremental Construction: Strategy



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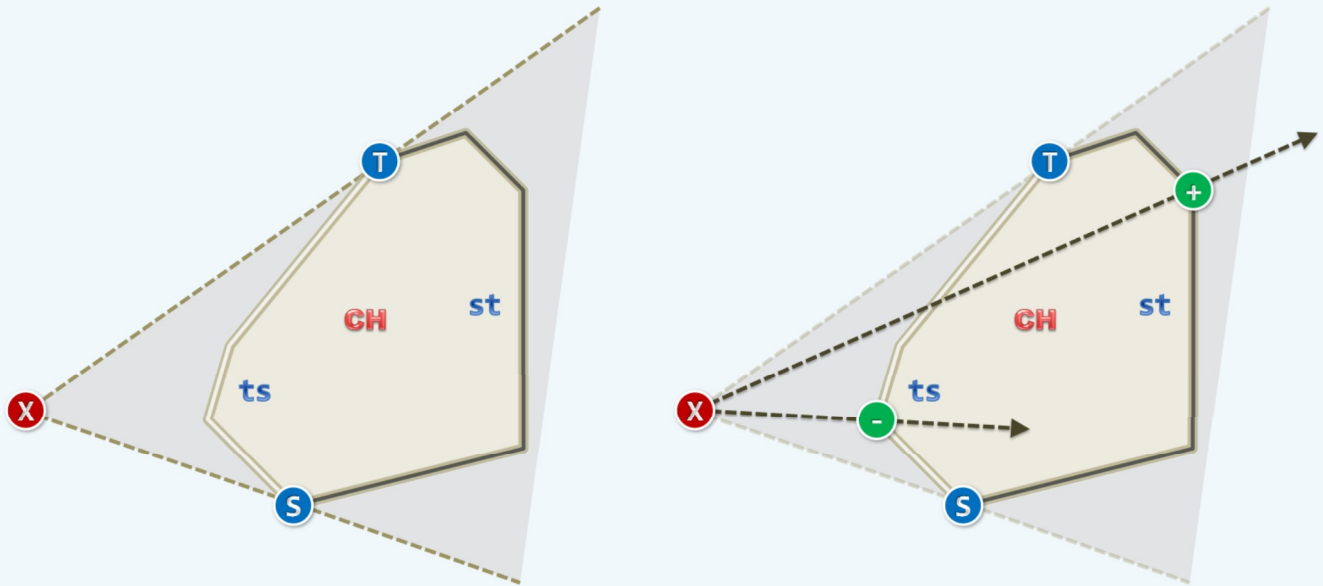
CH: Incremental Construction: In-Convex-Polygon Test



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CH: Incremental Construction: Support Lines + Turn Pattern



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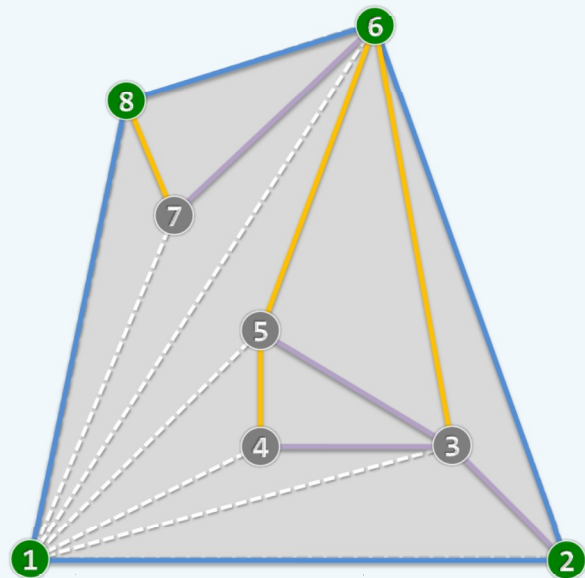
CH: Graham Scan: Complexity

Planar graph

$$v - e + f - c = 1$$

$$e = \mathcal{O}(n)$$

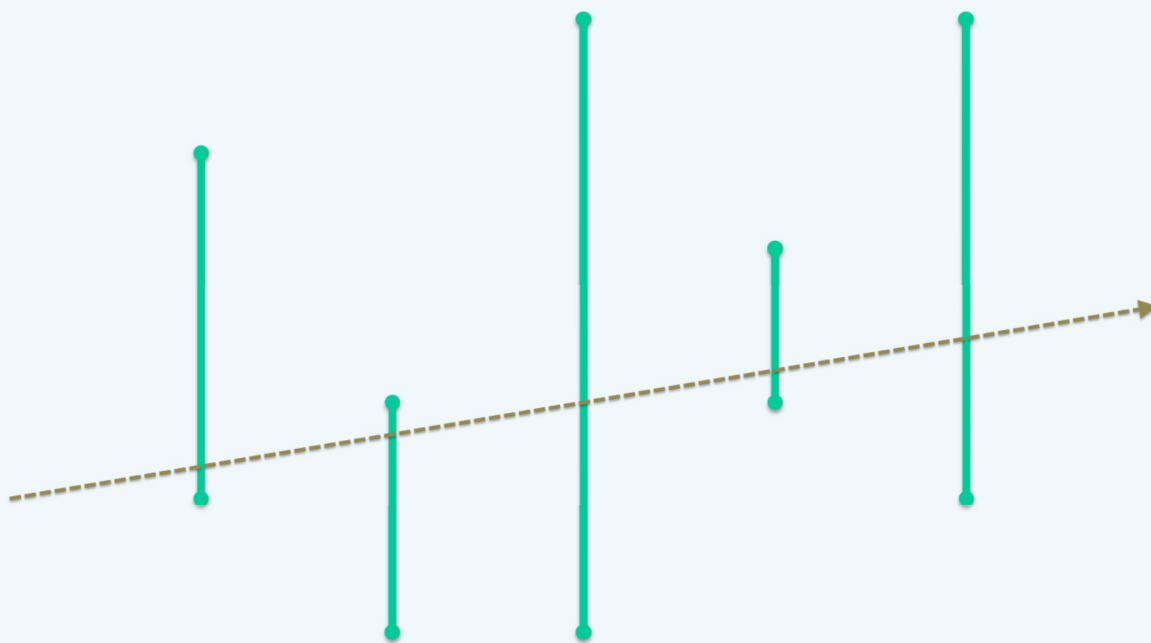
$$f = \mathcal{O}(n)$$



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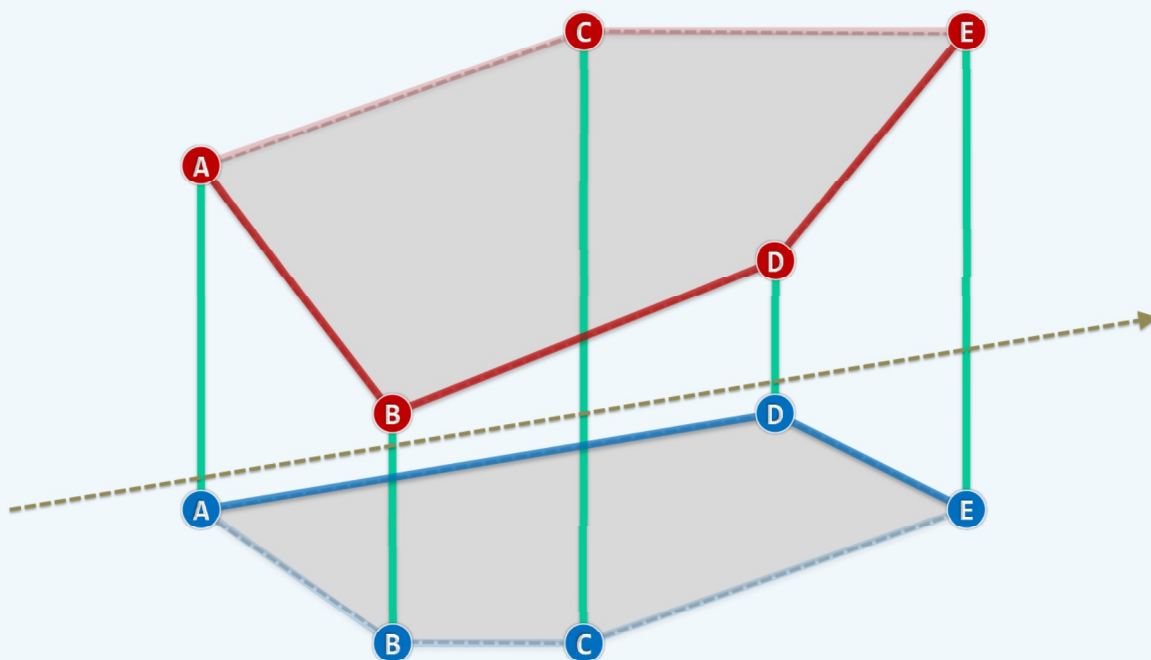
CH: Fruit Ninja



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CH: Fruit Ninja: Intersecting Convex Hulls



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