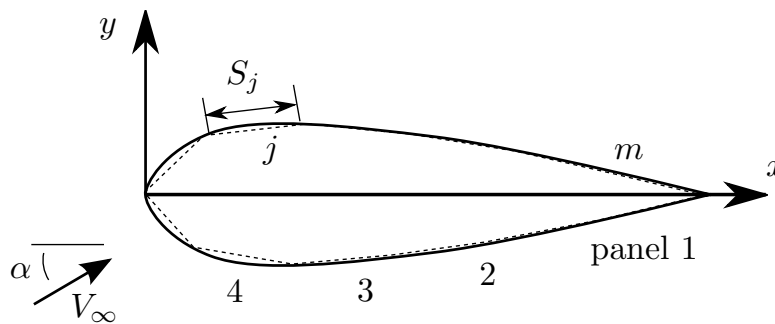


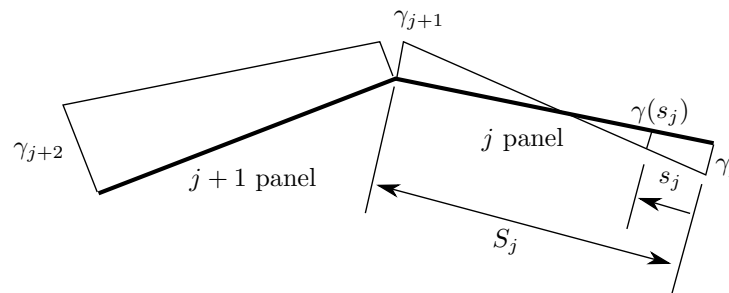
## THE VORTEX PANEL METHOD



- Approximate the contour of the airfoil by an inscribed polygon with  $m$  sides, called “**panels**”. Number the panels clockwise with panel #1 starting on the lower (pressure) side, at the trailing edge and panel # $m$  ending on the trailing edge from the upper (suction) side.
- Assume that each panel represents a planar vortex sheet with linearly varying strength and such that the end strength of each panel is the same as the starting strength of the next panel:

$$\gamma(s_j) = \gamma_j + \frac{s_j}{S_j}(\gamma_{j+1} - \gamma_j)$$

Exception:  $\gamma_1 \neq \gamma_{m+1}$



Instead of the dimensional strength  $\gamma$  (in velocity units), it is more convenient to use the **dimensionless** strength  $\gamma'$ , defined as

$$\gamma' = \frac{\gamma}{2\pi V_\infty}$$

Then,

$$\gamma'(s_j) = \gamma'_j + \frac{s_j}{S_j}(\gamma'_{j+1} - \gamma'_j)$$

- c) The only unknowns of this problem are the **end strengths**  $\gamma'_j$ ,  $j = 1, 2, \dots, m+1$ . They can be found by solving  $m+1$  equations consisting of
- i)  $m$ -equations, expressing the **no penetration** condition at the  $m$  mid-points of the panels (called “control points”)
  - ii) one equation, expressing the **Kutta condition**.

Once  $\gamma_j$  are found, the velocity can be found by superposition and the pressure can be computed from Bernoulli’s equation.

- d) Apply the **Kutta condition** at the trailing edge. Note that strict application of K-c would require that

$$(V_u)_{t.e.} = (V_l)_{t.e.} = 0$$

Instead, apply the weaker condition

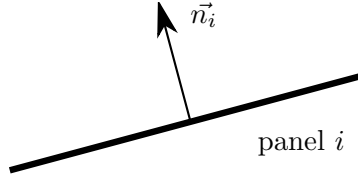
$$(V_u - V_l)_{t.e.} = 0$$

which implies that

$$\gamma'_1 + \gamma'_{m+1} = 0 \tag{A}$$

- e) Apply the **no penetration** condition at the  $m$  **control points** (mid-panels). Notice that all panels are assumed to be parts of the same streamline. The equipotential lines are normal to streamlines and, therefore, to panels. Let  $\phi$  be the velocity potential. Then,

$$\nabla\phi = \vec{V}, \text{ which implies that } V_{ni} = \frac{\partial\phi}{\partial n_i}$$



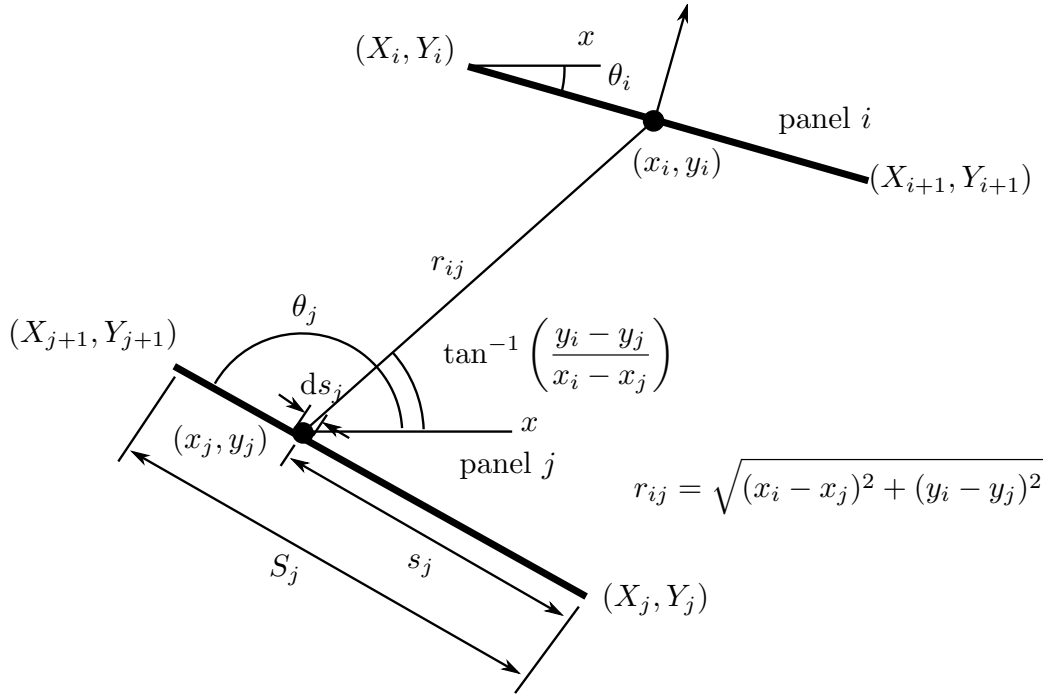
where  $V_{ni}$  is the velocity component normal to the panel  $i$ , and  $\partial\phi/\partial n_i$  is the derivative of  $\phi$  in the direction of the normal vector,  $\vec{n}_i$ . Therefore, the  $n$ -equation of no penetration becomes

$$\frac{\partial\phi(x_i, y_i)}{\partial n_i} = 0, \quad i = 1, 2, \dots, m \quad (\text{B})$$

- f) The velocity potential  $\phi(x_i, y_i)$  at a control point can be found by superposition of the potential due to the uniform stream and the potentials due to the  $m$  vortex panels, as

$$\phi(x_i, y_i) = V_\infty(x_i \cos \alpha + y_i \sin \alpha) + \sum_{j=1}^m \int_{\text{panel } j} \frac{-\gamma(s_j)}{2\pi} \tan \frac{y_i - y_j}{x_i - x_j} ds_j \quad (\text{C})$$

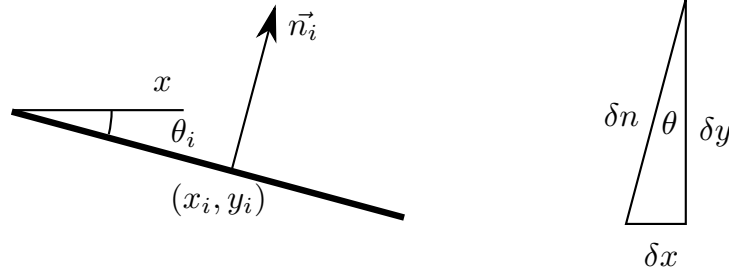
The remaining work is only algebraic and trigonometric manipulations.



g) Notice that

$$\frac{\partial x_i}{\partial n_i} \approx \frac{\delta x_i}{\delta n_i} = \sin \theta_i$$

$$\frac{\partial y_i}{\partial n_i} \approx \frac{\delta y_i}{\delta n_i} = \cos \theta_i$$



Then, by chain rule,

$$\frac{\partial \phi}{\partial n_i} = \frac{\partial \phi}{\partial x_i} \frac{\partial x_i}{\partial n_i} + \frac{\partial \phi}{\partial y_i} \frac{\partial y_i}{\partial n_i} = \frac{\partial \phi}{\partial x_i} \sin \theta_i + \frac{\partial \phi}{\partial y_i} \cos \theta_i$$

In expression (C), everything has already been expressed in terms of  $x_i$ ,  $y_i$ , so it is straightforward to apply the chain rule to the various derivatives.

Reminder

$$\frac{\partial}{\partial t} \tan^{-1}[f(t)] = \frac{1}{1 + f^2(t)} \frac{df}{dt}$$

Then

$$\frac{\partial}{\partial x_i} \left[ \tan^{-1} \frac{y_i - y_j}{x_i - x_j} \right] = \frac{-1}{1 + \left( \frac{y_i - y_j}{x_i - x_j} \right)^2} \frac{y_i - y_j}{(x_i - x_j)^2}$$

$$\frac{\partial}{\partial y_i} \left[ \tan^{-1} \frac{y_i - y_j}{x_i - x_j} \right] = \frac{1}{1 + \left( \frac{y_i - y_j}{x_i - x_j} \right)^2} \frac{1}{x_i - x_j}$$

h) The integral in eq. (C) is w.r.t. the  $j$  panel, therefore  $x_i$ ,  $y_i$  are constant during integration. Because  $x_j$ ,  $y_j$ ,  $s_j$  vary, it is necessary to express all of them in terms of one variable, e.g.  $s_j$ .

$$x_j = X_j - s_j \cos \theta_j$$

$$y_j = Y_j + s_j \sin \theta_j$$

Also  $\gamma(s_j)$  has been expressed in terms of  $s_j$ . Then the integral for panel  $j$  becomes

$$\gamma'_j \int_0^{S_j} f_{1j}(s_j) ds_j + \gamma'_{j+1} \int_0^{S_j} f_{2j}(s_j) ds_j$$

which can be computed numerically.

- i) Following various manipulations (see textbook for some details) one gets the system of  $m + 1$  linear, algebraic equations

$$\sum A_{nij} \gamma'_j = \sin(\theta_i - \alpha), \quad i = 1, 2, \dots, m$$

$$\gamma'_1 + \gamma'_{m+1} = 0$$

where the constants  $A_{nij}$  depend only on the coordinates of the end points of panels  $i$  and  $j$  and can be computed immediately once the panels have been selected. Notice that the effect of panel  $i$  on itself has also been taken into account. The system of the above equations is solved numerically to provide the end strengths.

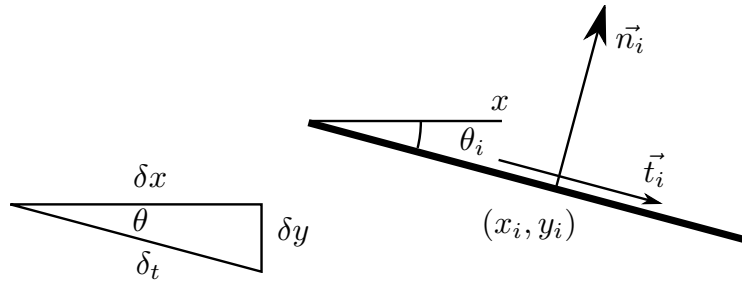
$$\gamma'_j, \quad j = 1, 2, \dots, m + 1$$

- j) The **velocity at the control points is tangential** to the panel and can be found as

$$V_i = V_{t_i} = \frac{\partial \phi}{\partial t_i} = \frac{\partial \phi}{\partial x_i} \frac{\partial x_i}{\partial t_i} + \frac{\partial \phi}{\partial y_i} \frac{\partial y_i}{\partial t_i}$$

or

$$V_i = \frac{\partial \phi}{\partial x_i} \cos \theta_i + \frac{\partial \phi}{\partial y_i} \sin \theta_i$$



Instead of the dimensional velocity  $V_i$ , the program computes a **dimensionless** velocity as

$$\forall_i = \frac{V_i}{V_\infty} = \frac{1}{V_\infty} \frac{\partial \phi}{\partial t_i}$$

Following various manipulations, this is found as

$$\forall_i = \sum_{j=1}^{m+1} A_{t_{ij}} \gamma'_j + \cos(\theta_i - \alpha), \quad i = 1, 2, \dots, m$$

where the coefficients  $A_{t_{ij}}$  depend on the end coordinates of panels  $i$  and  $j$  alone.

k) The pressure **at the control points** can be found from Bernoulli's eq. as

$$C_{P_i} = \frac{P_i - P_\infty}{\frac{1}{2} \rho V_\infty^2} = 1 - \forall_i^2$$

l) The lift can be found in two ways:

- i) By integrating all vortex strengths and using the **Kutta-Joukowski** theorem.
- ii) By integrating the surface pressure.