[ExternalLocation=./]Consolas.ttf

Contents

1 Basic

1.1 vimrc

```
set number
syntax on
set showmode
set tabstop=2
set shiftwidth=2
set expandtab
set cursorline
set autoindent
set breakindent
filetype indent on
set smartcase
inoremap {<CR> {<CR>}<Esc>ko
```

1.2 Default code

```cpp
#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef pair<int, int> pii;
typedef pair<ll, ll> pll;
#define X first
#define Y second
#define SZ(a) ((int)a.size())
#define pb push_back
signed main() {
  ios::sync_with_stdio(0);
  cin.tie(0);
  return 0;
}
```

1.3 readchar

```cpp
inline char readchar() {
  static const size_t bufsize = 65536;
  static char buf[bufsize];
  static char *p = buf, *end = buf;
  if (p == end)
    end = buf + fread_unlocked(buf, 1, bufsize, stdin),
        p = buf;
  return *p++;
}
```

1.4 useful$_{s}truct$

```cpp
// copy from https://blog.csdn.net/hcmdghv587/article/
    details/108615937
const double EPS = 1e-8;
const double PI = acos(-1.0);
int sgn(double x) {
  if (fabs(x) < EPS)
    return 0;
  if (x < 0)
    return -1;
  return 1;
}
// 点向量/
struct Point {
  double x, y;
  Point() : x(0), y(0) {}
  Point(double _x, double _y) : x(_x), y(_y) {}
  bool operator==(const Point &other) const {
    return sgn(x - other.x) == 0 && sgn(y - other.y) ==
        0;
  }
  bool operator<(const Point &other) const {
    return sgn(x - other.x) == 0 ? sgn(y - other.y) < 0
        : x < other.x;
  }
  Point operator-(const Point &other) const {
    return {x - other.x, y - other.y};
  }
  Point operator+(const Point &other) const {
    return {x + other.x, y + other.y};
  }
  // cross
  double operator^(const Point &other) const {
    return x * other.y - y * other.x;
  }
```

```
  // dot
  double operator*(const Point &other) const {
    return x * other.x + y * other.y;
  }
  double len() const { return hypot(x, y); }
};
typedef Point Vector;
// 直线线段/
struct Line {
  Point src, dest;
  Line() {}
  Line(const Point &_src, const Point &_dest) : src(
      _src), dest(_dest) {}
  // 通过 ax + by + c = 0 构建直线
  Line(double a, double b, double c) {
    if (sgn(a) == 0) {
      src = {0, -c / b};
      dest = {1, -c / b};
    } else if (sgn(b) == 0) {
      src = {-c / a, 0};
      src = {-c / a, 1};
    } else {
      src = {0, -c / b};
      dest = {1, (-c - a) / b};
    }
  }
  double len() const { return (dest - src).len(); }
  // 求两直线交点需保证两直线不平行、不重合()
  Point crossPoint(const Line &other) const {
    double a1 = (other.dest - other.src) ^ (src - other
        .src);
    double a2 = (other.dest - other.src) ^ (dest -
        other.src);
    return {
        (src.x * a2 - dest.x * a1) / (a2 - a1),
        (src.y * a2 - dest.y * a1) / (a2 - a1),
    };
  }
};
```

1.5 Black Magic

```
#include <ext/pb_ds/assoc_container.hpp> //rb_tree
#include <ext/pb_ds/priority_queue.hpp>
#include <bits/stdc++.h>
using namespace __gnu_pbds;
using namespace std;
#define ll long long
typedef __gnu_pbds::priority_queue<int> heap;
int main() {
  heap h1, h2;
  h1.push(1), h1.push(3);
  h2.push(2), h2.push(4);
  h1.join(h2);
  cout << h1.size() << h2.size() << h1.top() << endl;
      // 404
  tree<ll, null_type, less<ll>, rb_tree_tag,
      tree_order_statistics_node_update>
      st;
  tree<ll, ll, less<ll>, rb_tree_tag,
      tree_order_statistics_node_update> mp;
  for (int x : {0, 2, 3, 4})
    st.insert(x);
  cout << *st.find_by_order(2) << st.order_of_key(1) <<
       endl; // 31
}
//__int128_t,__float128_t
```

2 Graph

2.1 BCC Vertex*

```
vector<int> G[N]; // 1-base
vector<int> nG[N], bcc[N];
int low[N], dfn[N], Time;
int bcc_id[N], bcc_cnt; // 1-base
bool is_cut[N];         // whether is av
bool cir[N];
int st[N], top;

void dfs(int u, int pa = -1) {
  int child = 0;
  low[u] = dfn[u] = ++Time;
  st[top++] = u;
  for (int v : G[u])
    if (!dfn[v]) {
      dfs(v, u), ++child;
      low[u] = min(low[u], low[v]);
      if (dfn[u] <= low[v]) {
        is_cut[u] = 1;
        bcc[++bcc_cnt].clear();
        int t;
        do {
          bcc_id[t = st[--top]] = bcc_cnt;
          bcc[bcc_cnt].push_back(t);
        } while (t != v);
        bcc_id[u] = bcc_cnt;
        bcc[bcc_cnt].pb(u);
      }
    } else if (dfn[v] < dfn[u] && v != pa)
      low[u] = min(low[u], dfn[v]);
  if (pa == -1 && child < 2)
    is_cut[u] = 0;
}

void bcc_init(int n) {
  Time = bcc_cnt = top = 0;
  for (int i = 1; i <= n; ++i)
    G[i].clear(), dfn[i] = bcc_id[i] = is_cut[i] = 0;
}

void bcc_solve(int n) {
  for (int i = 1; i <= n; ++i)
    if (!dfn[i])
      dfs(i);
  // circle-square tree
  for (int i = 1; i <= n; ++i)
    if (is_cut[i])
      bcc_id[i] = ++bcc_cnt, cir[bcc_cnt] = 1;
  for (int i = 1; i <= bcc_cnt && !cir[i]; ++i)
    for (int j : bcc[i])
      if (is_cut[j])
        nG[i].pb(bcc_id[j]), nG[bcc_id[j]].pb(i);
}
```

2.2 Bridge*

```
int low[N], dfn[N], Time; // 1-base
vector<pii> G[N], edge;
vector<bool> is_bridge;

void init(int n) {
  Time = 0;
  for (int i = 1; i <= n; ++i)
    G[i].clear(), low[i] = dfn[i] = 0;
}

void add_edge(int a, int b) {
  G[a].pb(pii(b, SZ(edge))), G[b].pb(pii(a, SZ(edge)));
  edge.pb(pii(a, b));
}

void dfs(int u, int f) {
  dfn[u] = low[u] = ++Time;
  for (auto i : G[u])
    if (!dfn[i.X])
      dfs(i.X, i.Y), low[u] = min(low[u], low[i.X]);
    else if (i.Y != f)
      low[u] = min(low[u], dfn[i.X]);
  if (low[u] == dfn[u] && f != -1)
    is_bridge[f] = 1;
}

void solve(int n) {
  is_bridge.resize(SZ(edge));
  for (int i = 1; i <= n; ++i)
    if (!dfn[i])
      dfs(i, -1);
}
```

2.3 Bipartite Matching*

```
// x nodes are numbered 1 to n, y nodes are numbered n
    +1 to n+m
```

```
// g[X].push_back[Y] / g[u].push_back(nx + v)
vector<int> g[200007];
int nx, ny, ma[200007], d[200007];
bool bfs() {
  int i, u, v, len;
  queue<int> Q;
  for (i = 1; i <= nx; i++) {
    if (ma[i] == 0) {
      d[i] = 0;
      Q.push(i);
    } else
      d[i] = INF;
  }
  d[0] = INF;
  while (!Q.empty()) {
    u = Q.front();
    Q.pop();
    if (u != 0) {
      len = g[u].size();
      for (i = 0; i < len; i++) {
        v = g[u][i];
        if (d[ma[v]] == INF) {
          d[ma[v]] = d[u] + 1;
          Q.push(ma[v]);
        }
      }
    }
  }
  return (d[0] != INF);
}
bool dfs(int u) {
  int i, v, len;
  if (u != 0) {
    len = g[u].size();
    for (i = 0; i < len; i++) {
      v = g[u][i];
      if (d[ma[v]] == d[u] + 1) {
        if (dfs(ma[v])) {
          ma[v] = u;
          ma[u] = v;
          return true;
        }
      }
    }
    d[u] = INF;
    return false;
  }
  return true;
}
int hopcroft_karp() {
  int res = 0, i;
  while (bfs())
    for (i = 1; i <= nx; i++)
      if (ma[i] == 0 && dfs(i))
        res++;
  return res;
}
```

2.4 2SAT (SCC)*

```
struct SAT { // 0-base
  int low[N], dfn[N], bln[N], n, Time, nScc;
  bool instack[N], istrue[N];
  stack<int> st;
  vector<int> G[N], SCC[N];
  void init(int _n) {
    n = _n; // assert(n * 2 <= N);
    for (int i = 0; i < n + n; ++i)
      G[i].clear();
  }
  void add_edge(int a, int b) { G[a].pb(b); }
  int rv(int a) {
    if (a > n)
      return a - n;
    return a + n;
  }
  void add_clause(int a, int b) { add_edge(rv(a), b),
      add_edge(rv(b), a); }
  void dfs(int u) {
    dfn[u] = low[u] = ++Time;
    instack[u] = 1, st.push(u);
    for (int i : G[u])
      if (!dfn[i])
        dfs(i), low[u] = min(low[i], low[u]);
      else if (instack[i] && dfn[i] < dfn[u])
        low[u] = min(low[u], dfn[i]);
    if (low[u] == dfn[u]) {
      int tmp;
      do {
        tmp = st.top(), st.pop();
        instack[tmp] = 0, bln[tmp] = nScc;
      } while (tmp != u);
      ++nScc;
    }
  }
  bool solve() {
    Time = nScc = 0;
    for (int i = 0; i < n + n; ++i)
      SCC[i].clear(), low[i] = dfn[i] = bln[i] = 0;
    for (int i = 0; i < n + n; ++i)
      if (!dfn[i])
        dfs(i);
    for (int i = 0; i < n + n; ++i)
      SCC[bln[i]].pb(i);
    for (int i = 0; i < n; ++i) {
      if (bln[i] == bln[i + n])
        return false;
      istrue[i] = bln[i] < bln[i + n];
      istrue[i + n] = !istrue[i];
    }
    return true;
  }
};
```

2.5 MinimumMeanCycle*

```
ll road[N][N]; // input here
struct MinimumMeanCycle {
  ll dp[N + 5][N], n;
  pll solve() {
    ll a = -1, b = -1, L = n + 1;
    for (int i = 2; i <= L; ++i)
      for (int k = 0; k < n; ++k)
        for (int j = 0; j < n; ++j)
          dp[i][j] = min(dp[i - 1][k] + road[k][j], dp[
              i][j]);
    for (int i = 0; i < n; ++i) {
      if (dp[L][i] >= INF)
        continue;
      ll ta = 0, tb = 1;
      for (int j = 1; j < n; ++j)
        if (dp[j][i] < INF && ta * (L - j) < (dp[L][i]
            - dp[j][i]) * tb)
          ta = dp[L][i] - dp[j][i], tb = L - j;
      if (ta == 0)
        continue;
      if (a == -1 || a * tb > ta * b)
        a = ta, b = tb;
    }
    if (a != -1) {
      ll g = __gcd(a, b);
      return pll(a / g, b / g);
    }
    return pll(-1LL, -1LL);
  }
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i)
      for (int j = 0; j < n; ++j)
        dp[i + 2][j] = INF;
  }
};
```

2.6 Maximum Clique Dyn*

```
const int N = 150;
struct MaxClique { // Maximum Clique
  bitset<N> a[N], cs[N];
  int ans, sol[N], q, cur[N], d[N], n;
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; i++)
      a[i].reset();
  }
```

```
  void addEdge(int u, int v) { a[u][v] = a[v][u] = 1; }
  void csort(vector<int> &r, vector<int> &c) {
    int mx = 1, km = max(ans - q + 1, 1), t = 0, m = r.
        size();
    cs[1].reset(), cs[2].reset();
    for (int i = 0; i < m; i++) {
      int p = r[i], k = 1;
      while ((cs[k] & a[p]).count())
        k++;
      if (k > mx)
        mx++, cs[mx + 1].reset();
      cs[k][p] = 1;
      if (k < km)
        r[t++] = p;
    }
    c.resize(m);
    if (t)
      c[t - 1] = 0;
    for (int k = km; k <= mx; k++)
      for (int p = cs[k]._Find_first(); p < N; p = cs[k
          ]._Find_next(p))
        r[t] = p, c[t] = k, t++;
  }
  void dfs(vector<int> &r, vector<int> &c, int l,
      bitset<N> mask) {
    while (!r.empty()) {
      int p = r.back();
      r.pop_back(), mask[p] = 0;
      if (q + c.back() <= ans)
        return;
      cur[q++] = p;
      vector<int> nr, nc;
      bitset<N> nmask = mask & a[p];
      for (int i : r)
        if (a[p][i])
          nr.push_back(i);
      if (!nr.empty()) {
        if (l < 4) {
          for (int i : nr)
            d[i] = (a[i] & nmask).count();
          sort(nr.begin(), nr.end(), [&](int x, int y)
              { return d[x] > d[y]; });
        }
        csort(nr, nc), dfs(nr, nc, l + 1, nmask);
      } else if (q > ans)
        ans = q, copy_n(cur, q, sol);
      c.pop_back(), q--;
    }
  }
  int solve(bitset<N> mask = bitset<N>(string(N, '1')))
      { // vertex mask
    vector<int> r, c;
    ans = q = 0;
    for (int i = 0; i < n; i++)
      if (mask[i])
        r.push_back(i);
    for (int i = 0; i < n; i++)
      d[i] = (a[i] & mask).count();
    sort(r.begin(), r.end(), [&](int i, int j) { return
        d[i] > d[j]; });
    csort(r, c), dfs(r, c, 1, mask);
    return ans; // sol[0 ~ ans-1]
  }
} graph;
```

2.7 Maximum Clique*

```
struct Maximum_Clique {
  typedef bitset<MAXN> bst;
  bst N[MAXN], empty;
  int p[MAXN], n, ans;
  void BronKerbosch2(bst R, bst P, bst X) {
    if (P == empty && X == empty)
      return ans = max(ans, (int)R.count()), void();
    bst tmp = P | X;
    int u;
    if ((R | P | X).count() <= ans)
      return;
    for (int uu = 0; uu < n; ++uu) {
      u = p[uu];
      if (tmp[u] == 1)
        break;
      }
      // if (double(clock())/CLOCKS_PER_SEC > .999)
      // return;
      bst now2 = P & ~N[u];
      for (int vv = 0; vv < n; ++vv) {
        int v = p[vv];
        if (now2[v] == 1) {
          R[v] = 1;
          BronKerbosch2(R, P & N[v], X & N[v]);
          R[v] = 0, P[v] = 0, X[v] = 1;
        }
      }
    }
    void init(int _n) {
      n = _n;
      for (int i = 0; i < n; ++i)
        N[i].reset();
    }
    void add_edge(int u, int v) { N[u][v] = N[v][u] = 1;
        }
    int solve() { // remember srand
      bst R, P, X;
      ans = 0, P.flip();
      for (int i = 0; i < n; ++i)
        p[i] = i;
      random_shuffle(p, p + n), BronKerbosch2(R, P, X);
      return ans;
    }
};
```

2.8 Minimum Steiner Tree*

```
// Minimum Steiner Tree
// O(V 3^T + V^2 2^T)
struct SteinerTree { // 0-base
  static const int T = 10, N = 105, INF = 1e9;
  int n, dst[N][N], dp[1 << T][N], tdst[N];
  int vcost[N]; // the cost of vertexs
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i) {
      for (int j = 0; j < n; ++j)
        dst[i][j] = INF;
      dst[i][i] = vcost[i] = 0;
    }
  }
  void add_edge(int ui, int vi, int wi) { dst[ui][vi] =
      min(dst[ui][vi], wi); }
  void shortest_path() {
    for (int k = 0; k < n; ++k)
      for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j)
          dst[i][j] = min(dst[i][j], dst[i][k] + dst[k
              ][j]);
  }
  int solve(const vector<int> &ter) {
    shortest_path();
    int t = SZ(ter);
    for (int i = 0; i < (1 << t); ++i)
      for (int j = 0; j < n; ++j)
        dp[i][j] = INF;
    for (int i = 0; i < n; ++i)
      dp[0][i] = vcost[i];
    for (int msk = 1; msk < (1 << t); ++msk) {
      if (!(msk & (msk - 1))) {
        int who = __lg(msk);
        for (int i = 0; i < n; ++i)
          dp[msk][i] = vcost[ter[who]] + dst[ter[who]][
              i];
      }
      for (int i = 0; i < n; ++i)
        for (int submsk = (msk - 1) & msk; submsk;
            submsk = (submsk - 1) & msk)
          dp[msk][i] =
              min(dp[msk][i], dp[submsk][i] + dp[msk ^
                  submsk][i] - vcost[i]);
      for (int i = 0; i < n; ++i) {
        tdst[i] = INF;
        for (int j = 0; j < n; ++j)
          tdst[i] = min(tdst[i], dp[msk][j] + dst[j][i
              ]);
      }
```

```
      for (int i = 0; i < n; ++i)
        dp[msk][i] = tdst[i];
    }
    int ans = INF;
    for (int i = 0; i < n; ++i)
      ans = min(ans, dp[(1 << t) - 1][i]);
    return ans;
  }
};
```

2.9 Minimum Arborescence*

```
struct zhu_liu { // O(VE)
  struct edge {
    int u, v;
    ll w;
  };
  vector<edge> E; // 0-base
  int pe[N], id[N], vis[N];
  ll in[N];
  void init() { E.clear(); }
  void add_edge(int u, int v, ll w) {
    if (u != v)
      E.pb(edge{u, v, w});
  }
  ll build(int root, int n) {
    ll ans = 0;
    for (;;) {
      fill_n(in, n, INF);
      for (int i = 0; i < SZ(E); ++i)
        if (E[i].u != E[i].v && E[i].w < in[E[i].v])
          pe[E[i].v] = i, in[E[i].v] = E[i].w;
      for (int u = 0; u < n; ++u) // no solution
        if (u != root && in[u] == INF)
          return -INF;
      int cntnode = 0;
      fill_n(id, n, -1), fill_n(vis, n, -1);
      for (int u = 0; u < n; ++u) {
        if (u != root)
          ans += in[u];
        int v = u;
        while (vis[v] != u && !~id[v] && v != root)
          vis[v] = u, v = E[pe[v]].u;
        if (v != root && !~id[v]) {
          for (int x = E[pe[v]].u; x != v; x = E[pe[x
              ]].u)
            id[x] = cntnode;
          id[v] = cntnode++;
        }
      }
      if (!cntnode)
        break; // no cycle
      for (int u = 0; u < n; ++u)
        if (!~id[u])
          id[u] = cntnode++;
      for (int i = 0; i < SZ(E); ++i) {
        int v = E[i].v;
        E[i].u = id[E[i].u], E[i].v = id[E[i].v];
        if (E[i].u != E[i].v)
          E[i].w -= in[v];
      }
      n = cntnode, root = id[root];
    }
    return ans;
  }
};
```

2.10 Vizing's theorem

```
namespace vizing { // returns edge coloring in adjacent
                   // matrix G. 1 - based
int C[kN][kN], G[kN][kN];
void clear(int N) {
  for (int i = 0; i <= N; i++) {
    for (int j = 0; j <= N; j++)
      C[i][j] = G[i][j] = 0;
  }
}
void solve(vector<pair<int, int>> &E, int N, int M) {
  int X[kN] = {}, a;
  auto update = [&](int u) {
    for (X[u] = 1; C[u][X[u]]; X[u]++)
      ;
  };
  auto color = [&](int u, int v, int c) {
    int p = G[u][v];
    G[u][v] = G[v][u] = c;
    C[u][c] = v, C[v][c] = u;
    C[u][p] = C[v][p] = 0;
    if (p)
      X[u] = X[v] = p;
    else
      update(u), update(v);
    return p;
  };
  auto flip = [&](int u, int c1, int c2) {
    int p = C[u][c1];
    swap(C[u][c1], C[u][c2]);
    if (p)
      G[u][p] = G[p][u] = c2;
    if (!C[u][c1])
      X[u] = c1;
    if (!C[u][c2])
      X[u] = c2;
    return p;
  };
  for (int i = 1; i <= N; i++)
    X[i] = 1;
  for (int t = 0; t < E.size(); t++) {
    int u = E[t].first, v0 = E[t].second, v = v0, c0 =
        X[u], c = c0, d;
    vector<pair<int, int>> L;
    int vst[kN] = {};
    while (!G[u][v0]) {
      L.emplace_back(v, d = X[v]);
      if (!C[v][c])
        for (a = (int)L.size() - 1; a >= 0; a--)
          c = color(u, L[a].first, c);
      else if (!C[u][d])
        for (a = (int)L.size() - 1; a >= 0; a--)
          color(u, L[a].first, L[a].second);
      else if (vst[d])
        break;
      else
        vst[d] = 1, v = C[u][d];
    }
    if (!G[u][v0]) {
      for (; v; v = flip(v, c, d), swap(c, d))
        ;
      if (C[u][c0]) {
        for (a = (int)L.size() - 2; a >= 0 && L[a].
            second != c; a--)
          ;
        for (; a >= 0; a--)
          color(u, L[a].first, L[a].second);
      } else
        t--;
    }
  }
}
} // namespace vizing
```

2.11 Minimum Clique Cover*

```
struct Clique_Cover { // 0-base, O(n2^n)
  int co[1 << N], n, E[N];
  int dp[1 << N];
  void init(int _n) {
    n = _n, fill_n(dp, 1 << n, 0);
    fill_n(E, n, 0), fill_n(co, 1 << n, 0);
  }
  void add_edge(int u, int v) { E[u] |= 1 << v, E[v] |=
      1 << u; }
  int solve() {
    for (int i = 0; i < n; ++i)
      co[1 << i] = E[i] | (1 << i);
    co[0] = (1 << n) - 1;
    dp[0] = (n & 1) * 2 - 1;
    for (int i = 1; i < (1 << n); ++i) {
      int t = i & -i;
      dp[i] = -dp[i ^ t];
      co[i] = co[i ^ t] & co[t];
    }
    for (int i = 0; i < (1 << n); ++i)
```

```
      co[i] = (co[i] & i) == i;
    fwt(co, 1 << n);
    for (int ans = 1; ans < n; ++ans) {
      int sum = 0;
      for (int i = 0; i < (1 << n); ++i)
        sum += (dp[i] *= co[i]);
      if (sum)
        return ans;
    }
    return n;
  }
};
```

2.12 NumberofMaximalClique*

```
struct BronKerbosch { // 1-base
  int n, a[N], g[N][N];
  int S, all[N][N], some[N][N], none[N][N];
  void init(int _n) {
    n = _n;
    for (int i = 1; i <= n; ++i)
      for (int j = 1; j <= n; ++j)
        g[i][j] = 0;
  }
  void add_edge(int u, int v) { g[u][v] = g[v][u] = 1;
      }
  void dfs(int d, int an, int sn, int nn) {
    if (S > 1000)
      return; // pruning
    if (sn == 0 && nn == 0)
      ++S;
    int u = some[d][0];
    for (int i = 0; i < sn; ++i) {
      int v = some[d][i];
      if (g[u][v])
        continue;
      int tsn = 0, tnn = 0;
      copy_n(all[d], an, all[d + 1]);
      all[d + 1][an] = v;
      for (int j = 0; j < sn; ++j)
        if (g[v][some[d][j]])
          some[d + 1][tsn++] = some[d][j];
      for (int j = 0; j < nn; ++j)
        if (g[v][none[d][j]])
          none[d + 1][tnn++] = none[d][j];
      dfs(d + 1, an + 1, tsn, tnn);
      some[d][i] = 0, none[d][nn++] = v;
    }
  }
  int solve() {
    iota(some[0], some[0] + n, 1);
    S = 0, dfs(0, 0, n, 0);
    return S;
  }
};
```

2.13 Dijkstra*

```
// luogu4779
vector<pii> edge[100020];
int dis[100020];
int vis[100020];
void dijkstra(int s) {
  memset(dis, 0x3f, sizeof(dis));
  dis[s] = 0;
  priority_queue<pii, vector<pii>, greater<pii>> pq;
  pq.emplace(0, s);
  while (pq.size()) {
    int now = pq.top().Y;
    pq.pop();
    if (vis[now])
      continue;
    vis[now] = 1;
    for (pii e : edge[now]) {
      if (!vis[e.X] && dis[e.X] > dis[now] + e.Y) {
        dis[e.X] = dis[now] + e.Y;
        pq.emplace(dis[e.X], e.X);
      }
    }
  }
}
```

2.14 Kosaraju*

```
// find Strong Connected Component
vector<pii> edge[100020], redge[100020];
int vis[100020], scc[100020];
void dfs1(int x, vector<int> &stk) {
  vis[x] = 1;
  for (pii i : edge[x])
    if (!vis[i.X])
      dfs1(i.X, stk);
  stk.emplace_back(x);
}
void dfs2(int x, int id) {
  scc[x] = id;
  for (pii i : redge[x])
    if (!scc[i.X])
      dfs2(i.X, id);
}
void kosaraju() {
  int nscc = 0;
  vector<int> stk;
  for (int i = 1; i <= n; i++)
    if (!vis[i])
      dfs1(i, stk);
  while (stk.size()) {
    if (!scc[stk.back()])
      dfs2(stk.back(), ++nscc);
    stk.pop_back();
  }
}
```

2.15 Simple Graph Matching*

```
#include <bits/stdc++.h>
using namespace std;
#define FOR(i, a, b) for (int i = a; i <= b; i++)
#define REP(u) for (int i = h[u], v; v = e[i].t, i; i =
    e[i].n)
const int N = 520, M = 2e5 + 1;
queue<int> q;
int n, m, tot, qwq, ans;
int h[N], lk[N], tag[N], fa[N], pre[N], dfn[N];
struct edge {
  int t, n;
} e[M];
void link(int x, int y) { lk[x] = y, lk[y] = x; }
void add_edge(int x, int y) {
  if (!lk[x] && !lk[y])
    link(x, y), ans++;
  e[++tot] = (edge){y, h[x]}, h[x] = tot;
  e[++tot] = (edge){x, h[y]}, h[y] = tot;
}
void rev(int x) {
  if (x)
    rev(x[pre][lk]), link(x, pre[x]);
}
int find(int x) { return fa[x] == x ? x : fa[x] = find(
    fa[x]); }
int lca(int x, int y) {
  for (qwq++;; x = x[lk][pre], swap(x, y))
    if (dfn[x = find(x)] == qwq)
      return x;
    else if (x)
      dfn[x] = qwq;
}
int shrink(int x, int y, int p) {
  for (; find(x) != p; x = pre[y]) {
    pre[x] = y, y = lk[x], fa[x] = fa[y] = p;
    if (tag[y] == 2)
      tag[y] = 1, q.push(y);
  }
}
int blossom(int u) {
  FOR(i, 1, n) tag[i] = pre[i] = 0, fa[i] = i;
  tag[u] = 1, q = queue<int>(), q.push(u);
  for (int p; !q.empty(); q.pop())
    REP(u = q.front())
  if (tag[v] == 1)
    p = lca(u, v), shrink(u, v, p), shrink(v, u, p);
  else if (!tag[v]) {
    pre[v] = u, tag[v] = 2;
    if (!lk[v])
```

```
      return rev(v), 1;
    else
      tag[lk[v]] = 1, q.push(lk[v]);
  }
  return 0;
}
int main() {
  scanf("%d%d", &n, &m);
  for (int x, y; m--; add_edge(x, y))
    scanf("%d%d", &x, &y);
  FOR(i, 1, n) ans += !lk[i] && blossom(i);
  cout << ans << '\n';
  for (int i = 1; i <= n; i++)
    cout << i << ' ' << lk[i] << '\n' return 0;
}
```

2.16 Theory

$|\text{Maximum independent edge set}| = |V| - |\text{Minimum edge cover}|$
$|\text{Maximum independent set}| = |V| - |\text{Minimum vertex cover}|$

3 Data Structure

3.1 Leftist Tree

```
struct node {
  ll v, data, sz, sum;
  node *l, *r;
  node(ll k) : v(0), data(k), sz(1), l(0), r(0), sum(k)
       {}
};
ll sz(node *p) { return p ? p->sz : 0; }
ll V(node *p) { return p ? p->v : -1; }
ll sum(node *p) { return p ? p->sum : 0; }
node *merge(node *a, node *b) {
  if (!a || !b)
    return a ? a : b;
  if (a->data < b->data)
    swap(a, b);
  a->r = merge(a->r, b);
  if (V(a->r) > V(a->l))
    swap(a->r, a->l);
  a->v = V(a->r) + 1, a->sz = sz(a->l) + sz(a->r) + 1;
  a->sum = sum(a->l) + sum(a->r) + a->data;
  return a;
}
void pop(node *&o) {
  node *tmp = o;
  o = merge(o->l, o->r);
  delete tmp;
}
```

3.2 Heavy light Decomposition

```
struct Heavy_light_Decomposition { // 1-base
  int n, ulink[10005], deep[10005], mxson[10005], w
      [10005], pa[10005];
  int t, pl[10005], data[10005], dt[10005], bln[10005],
       edge[10005], et;
  vector<pii> G[10005];
  void init(int _n) {
    n = _n, t = 0, et = 1;
    for (int i = 1; i <= n; ++i)
      G[i].clear(), mxson[i] = 0;
  }
  void add_edge(int a, int b, int w) {
    G[a].pb(pii(b, et)), G[b].pb(pii(a, et)), edge[et
        ++] = w;
  }
  void dfs(int u, int f, int d) {
    w[u] = 1, pa[u] = f, deep[u] = d++;
    for (auto &i : G[u])
      if (i.X != f) {
        dfs(i.X, u, d), w[u] += w[i.X];
        if (w[mxson[u]] < w[i.X])
          mxson[u] = i.X;
      } else
        bln[i.Y] = u, dt[u] = edge[i.Y];
  }
  void cut(int u, int link) {
    data[pl[u] = t++] = dt[u], ulink[u] = link;
    if (!mxson[u])
      return;
    cut(mxson[u], link);
    for (auto i : G[u])
      if (i.X != pa[u] && i.X != mxson[u])
        cut(i.X, i.X);
  }
  void build() { dfs(1, 1, 1), cut(1, 1), /*build*/; }
  int query(int a, int b) {
    int ta = ulink[a], tb = ulink[b], re = 0;
    while (ta != tb)
      if (deep[ta] < deep[tb])
        /*query*/, tb = ulink[b = pa[tb]];
      else /*query*/
        , ta = ulink[a = pa[ta]];
    if (a == b)
      return re;
    if (pl[a] > pl[b])
      swap(a, b);
    /*query*/
    return re;
  }
};
```

3.3 Centroid Decomposition*

```
struct Cent_Dec { // 1-base
  vector<pll> G[N];
  pll info[N];   // store info. of itself
  pll upinfo[N]; // store info. of climbing up
  int n, pa[N], layer[N], sz[N], done[N];
  ll dis[__lg(N) + 1][N];
  void init(int _n) {
    n = _n, layer[0] = -1;
    fill_n(pa + 1, n, 0), fill_n(done + 1, n, 0);
    for (int i = 1; i <= n; ++i)
      G[i].clear();
  }
  void add_edge(int a, int b, int w) { G[a].pb(pll(b, w
      )), G[b].pb(pll(a, w)); }
  void get_cent(int u, int f, int &mx, int &c, int num)
       {
    int mxsz = 0;
    sz[u] = 1;
    for (pll e : G[u])
      if (!done[e.X] && e.X != f) {
        get_cent(e.X, u, mx, c, num);
        sz[u] += sz[e.X], mxsz = max(mxsz, sz[e.X]);
      }
    if (mx > max(mxsz, num - sz[u]))
      mx = max(mxsz, num - sz[u]), c = u;
  }
  void dfs(int u, int f, ll d, int org) {
    // if required, add self info or climbing info
    dis[layer[org]][u] = d;
    for (pll e : G[u])
      if (!done[e.X] && e.X != f)
        dfs(e.X, u, d + e.Y, org);
  }
  int cut(int u, int f, int num) {
    int mx = 1e9, c = 0, lc;
    get_cent(u, f, mx, c, num);
    done[c] = 1, pa[c] = f, layer[c] = layer[f] + 1;
    for (pll e : G[c])
      if (!done[e.X]) {
        if (sz[e.X] > sz[c])
          lc = cut(e.X, c, num - sz[c]);
        else
          lc = cut(e.X, c, sz[e.X]);
        upinfo[lc] = pll(), dfs(e.X, c, e.Y, c);
      }
    return done[c] = 0, c;
  }
  void build() { cut(1, 0, n); }
  void modify(int u) {
    for (int a = u, ly = layer[a]; a; a = pa[a], --ly)
        {
      info[a].X += dis[ly][u], ++info[a].Y;
      if (pa[a])
        upinfo[a].X += dis[ly - 1][u], ++upinfo[a].Y;
    }
  }
  ll query(int u) {
    ll rt = 0;
```

```
    for (int a = u, ly = layer[a]; a; a = pa[a], --ly)
        {
      rt += info[a].X + info[a].Y * dis[ly][u];
      if (pa[a])
        rt -= upinfo[a].X + upinfo[a].Y * dis[ly - 1][u
            ];
    }
    return rt;
  }
};
```

3.4 Smart Pointer*

```
#ifndef REFERENCE_POINTER
#define REFERENCE_POINTER
template <typename T> struct _RefCounter {
  T data;
  int ref;
  _RefCounter(const T &d = 0) : data(d), ref(0) {}
};
template <typename T> struct reference_pointer {
  _RefCounter<T> *p;
  T *operator->() { return &p->data; }
  T &operator*() { return p->data; }
  operator _RefCounter<T> *() { return p; }
  reference_pointer &operator=(const reference_pointer
      &t) {
    if (p && !--p->ref)
      delete p;
    p = t.p;
    p && ++p->ref;
    return *this;
  }
  reference_pointer(_RefCounter<T> *t = 0) : p(t) { p
      && ++p->ref; }
  reference_pointer(const reference_pointer &t) : p(t.p
      ) { p && ++p->ref; }
  ~reference_pointer() {
    if (p && !--p->ref)
      delete p;
  }
};
template <typename T> inline reference_pointer<T>
    new_reference(const T &nd) {
  return reference_pointer<T>(new _RefCounter<T>(nd));
}
#endif
// note:
reference_pointer<int> a;
a = new_reference(5);
a = new_reference<int>(5);
a = new_reference((int)5);
reference_pointer<int> b = a;

struct P {
  int a, b;
  P(int _a, int _b) : a(_a), b(_b) {}
} p(2, 3);
reference_pointer<P> a;
c = new_reference(P(1, 2));
c = new_reference<P>(P(1, 2));
c = new_reference(p);
```

3.5 LiChaoST*

```
struct LiChao_min {
  struct line {
    LL m, c;
    line(LL _m = 0, LL _c = 0) {
      m = _m;
      c = _c;
    }
    LL eval(LL x) { return m * x + c; }
  };
  struct node {
    node *l, *r;
    line f;
    node(line v) {
      f = v;
      l = r = NULL;
    }
  };
  typedef node *pnode;
  pnode root;
  int sz;
#define mid ((l + r) >> 1)
  void insert(line &v, int l, int r, pnode &nd) {
    if (!nd) {
      nd = new node(v);
      return;
    }
    LL trl = nd->f.eval(l), trr = nd->f.eval(r);
    LL vl = v.eval(l), vr = v.eval(r);
    if (trl <= vl && trr <= vr)
      return;
    if (trl > vl && trr > vr) {
      nd->f = v;
      return;
    }
    if (trl > vl)
      swap(nd->f, v);
    if (nd->f.eval(mid) < v.eval(mid))
      insert(v, mid + 1, r, nd->r);
    else
      swap(nd->f, v), insert(v, l, mid, nd->l);
  }
  LL query(int x, int l, int r, pnode &nd) {
    if (!nd)
      return LLONG_MAX;
    if (l == r)
      return nd->f.eval(x);
    if (mid >= x)
      return min(nd->f.eval(x), query(x, l, mid, nd->l)
          );
    return min(nd->f.eval(x), query(x, mid + 1, r, nd->
        r));
  }
  /* -sz <= query_x <= sz */
  void init(int _sz) {
    sz = _sz + 1;
    root = NULL;
  }
  void add_line(LL m, LL c) {
    line v(m, c);
    insert(v, -sz, sz, root);
  }
  LL query(LL x) { return query(x, -sz, sz, root); }
};
```

3.6 Link cut tree*

```
struct Splay { // xor-sum
  static Splay nil;
  Splay *ch[2], *f;
  int val, sum, rev, size;
  Splay(int _val = 0) : val(_val), sum(_val), rev(0),
      size(1) {
    f = ch[0] = ch[1] = &nil;
  }
  bool isr() { return f->ch[0] != this && f->ch[1] !=
      this; }
  int dir() { return f->ch[0] == this ? 0 : 1; }
  void setCh(Splay *c, int d) {
    ch[d] = c;
    if (c != &nil)
      c->f = this;
    pull();
  }
  void push() {
    if (!rev)
      return;
    swap(ch[0], ch[1]);
    if (ch[0] != &nil)
      ch[0]->rev ^= 1;
    if (ch[1] != &nil)
      ch[1]->rev ^= 1;
    rev = 0;
  }
  void pull() {
    // take care of the nil!
    size = ch[0]->size + ch[1]->size + 1;
    sum = ch[0]->sum ^ ch[1]->sum ^ val;
    if (ch[0] != &nil)
      ch[0]->f = this;
```

```
    if (ch[1] != &nil)
      ch[1]->f = this;
  }
} Splay::nil;
Splay *nil = &Splay::nil;
void rotate(Splay *x) {
  Splay *p = x->f;
  int d = x->dir();
  if (!p->isr())
    p->f->setCh(x, p->dir());
  else
    x->f = p->f;
  p->setCh(x->ch[!d], d);
  x->setCh(p, !d);
  p->pull(), x->pull();
}
void splay(Splay *x) {
  vector<Splay *> splayVec;
  for (Splay *q = x;; q = q->f) {
    splayVec.pb(q);
    if (q->isr())
      break;
  }
  reverse(ALL(splayVec));
  for (auto it : splayVec)
    it->push();
  while (!x->isr()) {
    if (x->f->isr())
      rotate(x);
    else if (x->dir() == x->f->dir())
      rotate(x->f), rotate(x);
    else
      rotate(x), rotate(x);
  }
}
Splay *access(Splay *x) {
  Splay *q = nil;
  for (; x != nil; x = x->f)
    splay(x), x->setCh(q, 1), q = x;
  return q;
}
void root_path(Splay *x) { access(x), splay(x); }
void chroot(Splay *x) {
  root_path(x), x->rev ^= 1;
  x->push(), x->pull();
}
void split(Splay *x, Splay *y) { chroot(x), root_path(y
    ); }
void link(Splay *x, Splay *y) {
  root_path(x), chroot(y);
  x->setCh(y, 1);
}
void cut(Splay *x, Splay *y) {
  split(x, y);
  if (y->size != 5)
    return;
  y->push();
  y->ch[0] = y->ch[0]->f = nil;
}
Splay *get_root(Splay *x) {
  for (root_path(x); x->ch[0] != nil; x = x->ch[0])
    x->push();
  splay(x);
  return x;
}
bool conn(Splay *x, Splay *y) { return get_root(x) ==
    get_root(y); }
Splay *lca(Splay *x, Splay *y) {
  access(x), root_path(y);
  if (y->f == nil)
    return y;
  return y->f;
}
void change(Splay *x, int val) { splay(x), x->val = val
    , x->pull(); }
int query(Splay *x, Splay *y) {
  split(x, y);
  return y->sum;
}
```

3.7 KDTree

```
namespace kdt {
int root, lc[maxn], rc[maxn], xl[maxn], xr[maxn], yl[
    maxn], yr[maxn];
point p[maxn];
int build(int l, int r, int dep = 0) {
  if (l == r)
    return -1;
  function<bool(const point &, const point &)> f =
    [dep](const point &a, const point &b) {
      if (dep & 1)
        return a.x < b.x;
      else
        return a.y < b.y;
    };
  int m = (l + r) >> 1;
  nth_element(p + l, p + m, p + r, f);
  xl[m] = xr[m] = p[m].x;
  yl[m] = yr[m] = p[m].y;
  lc[m] = build(l, m, dep + 1);
  if (~lc[m]) {
    xl[m] = min(xl[m], xl[lc[m]]);
    xr[m] = max(xr[m], xr[lc[m]]);
    yl[m] = min(yl[m], yl[lc[m]]);
    yr[m] = max(yr[m], yr[lc[m]]);
  }
  rc[m] = build(m + 1, r, dep + 1);
  if (~rc[m]) {
    xl[m] = min(xl[m], xl[rc[m]]);
    xr[m] = max(xr[m], xr[rc[m]]);
    yl[m] = min(yl[m], yl[rc[m]]);
    yr[m] = max(yr[m], yr[rc[m]]);
  }
  return m;
}
bool bound(const point &q, int o, long long d) {
  double ds = sqrt(d + 1.0);
  if (q.x < xl[o] - ds || q.x > xr[o] + ds || q.y < yl[
      o] - ds ||
      q.y > yr[o] + ds)
    return false;
  return true;
}
long long dist(const point &a, const point &b) {
  return (a.x - b.x) * 1ll * (a.x - b.x) + (a.y - b.y)
      * 1ll * (a.y - b.y);
}
void dfs(const point &q, long long &d, int o, int dep =
     0) {
  if (!bound(q, o, d))
    return;
  long long cd = dist(p[o], q);
  if (cd != 0)
    d = min(d, cd);
  if ((dep & 1) && q.x < p[o].x || !(dep & 1) && q.y <
      p[o].y) {
    if (~lc[o])
      dfs(q, d, lc[o], dep + 1);
    if (~rc[o])
      dfs(q, d, rc[o], dep + 1);
  } else {
    if (~rc[o])
      dfs(q, d, rc[o], dep + 1);
    if (~lc[o])
      dfs(q, d, lc[o], dep + 1);
  }
}
void init(const vector<point> &v) {
  for (int i = 0; i < v.size(); ++i)
    p[i] = v[i];
  root = build(0, v.size());
}
long long nearest(const point &q) {
  long long res = 1e18;
  dfs(q, res, root);
  return res;
}
} // namespace kdt
```

3.8 Segment Tree with tag

```
void push(int id, int l, int r) {
  int mid = (l + r) >> 1;
```

```
  seg[id * 2] += tag[id] * (mid - l + 1);
  seg[id * 2 + 1] += tag[id] * (r - mid);
  tag[id * 2] += tag[id];
  tag[id * 2 + 1] += tag[id];
  tag[id] = 0;
}
void modify(int id, int l, int r, int ql, int qr, int
    val) {
  if (ql > r || qr < l)
    return;
  if (ql <= l && r <= qr) {
    seg[id] += val * (r - l + 1);
    tag[id] += val;
    return;
  }
  if (l == r)
    return;
  push(id, l, r);
  int mid = (l + r) >> 1;
  modify(id * 2, l, mid, ql, qr, val);
  modify(id * 2 + 1, mid + 1, r, ql, qr, val);
  seg[id] = seg[id * 2] + seg[id * 2 + 1];
}
int query(int id, int l, int r, int ql, int qr) {
  if (ql > r || qr < l)
    return 0;
  if (ql <= l && r <= qr)
    return seg[id];
  push(id, l, r);
  int mid = (l + r) >> 1;
  return query(id * 2, l, mid, ql, qr) + query(id * 2 +
      1, mid + 1, r, ql, qr);
}
```

4 Flow/Matching

4.1 Dinic

```
struct MaxFlow { // 0-base
  struct edge {
    int to, cap, flow, rev;
  };
  vector<edge> G[MAXN];
  int s, t, dis[MAXN], cur[MAXN], n;
  int dfs(int u, int cap) {
    if (u == t || !cap)
      return cap;
    for (int &i = cur[u]; i < (int)G[u].size(); ++i) {
      edge &e = G[u][i];
      if (dis[e.to] == dis[u] + 1 && e.flow != e.cap) {
        int df = dfs(e.to, min(e.cap - e.flow, cap));
        if (df) {
          e.flow += df;
          G[e.to][e.rev].flow -= df;
          return df;
        }
      }
    }
    dis[u] = -1;
    return 0;
  }
  bool bfs() {
    FILL(dis, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
      int tmp = q.front();
      q.pop();
      for (auto &u : G[tmp])
        if (!~dis[u.to] && u.flow != u.cap) {
          q.push(u.to);
          dis[u.to] = dis[tmp] + 1;
        }
    }
    return dis[t] != -1;
  }
  int maxflow(int _s, int _t) {
    s = _s, t = _t;
    int flow = 0, df;
    while (bfs()) {
      FILL(cur, 0);
      while (df = dfs(s, INF))
        flow += df;
    }
    return flow;
  }
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i)
      G[i].clear();
  }
  void reset() {
    for (int i = 0; i < n; ++i)
      for (auto &j : G[i])
        j.flow = 0;
  }
  void add_edge(int u, int v, int cap) {
    G[u].pb(edge{v, cap, 0, (int)G[v].size()});
    G[v].pb(edge{u, 0, 0, (int)G[u].size() - 1});
  }
};
```

4.2 Kuhn Munkres

```
struct KM { // 0-base
  int w[MAXN][MAXN], hl[MAXN], hr[MAXN], slk[MAXN], n;
  int fl[MAXN], fr[MAXN], pre[MAXN], qu[MAXN], ql, qr;
  bool vl[MAXN], vr[MAXN];
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n; ++i)
      for (int j = 0; j < n; ++j)
        w[i][j] = -INF;
  }
  void add_edge(int a, int b, int wei) { w[a][b] = wei;
      }
  bool Check(int x) {
    if (vl[x] = 1, ~fl[x])
      return vr[qu[qr++] = fl[x]] = 1;
    while (~x)
      swap(x, fr[fl[x] = pre[x]]);
    return 0;
  }
  void Bfs(int s) {
    fill(slk, slk + n, INF);
    fill(vl, vl + n, 0), fill(vr, vr + n, 0);
    ql = qr = 0, qu[qr++] = s, vr[s] = 1;
    while (1) {
      int d;
      while (ql < qr)
        for (int x = 0, y = qu[ql++]; x < n; ++x)
          if (!vl[x] && slk[x] >= (d = hl[x] + hr[y] -
              w[x][y]))
            if (pre[x] = y, d)
              slk[x] = d;
            else if (!Check(x))
              return;
      d = INF;
      for (int x = 0; x < n; ++x)
        if (!vl[x] && d > slk[x])
          d = slk[x];
      for (int x = 0; x < n; ++x) {
        if (vl[x])
          hl[x] += d;
        else
          slk[x] -= d;
        if (vr[x])
          hr[x] -= d;
      }
      for (int x = 0; x < n; ++x)
        if (!vl[x] && !slk[x] && !Check(x))
          return;
    }
  }
  int Solve() {
    fill(fl, fl + n, -1), fill(fr, fr + n, -1), fill(hr
        , hr + n, 0);
    for (int i = 0; i < n; ++i)
      hl[i] = *max_element(w[i], w[i] + n);
    for (int i = 0; i < n; ++i)
      Bfs(i);
    int res = 0;
    for (int i = 0; i < n; ++i)
      res += w[i][fl[i]];
```

```
    return res;
  }
};
```

4.3 MincostMaxflow

```
struct MCMF { // 0-base
  struct edge {
    ll from, to, cap, flow, cost, rev;
  } *past[MAXN];
  vector<edge> G[MAXN];
  bitset<MAXN> inq;
  ll dis[MAXN], up[MAXN], s, t, mx, n;
  bool BellmanFord(ll &flow, ll &cost) {
    fill(dis, dis + n, INF);
    queue<ll> q;
    q.push(s), inq.reset(), inq[s] = 1;
    up[s] = mx - flow, past[s] = 0, dis[s] = 0;
    while (!q.empty()) {
      ll u = q.front();
      q.pop(), inq[u] = 0;
      if (!up[u])
        continue;
      for (auto &e : G[u])
        if (e.flow != e.cap && dis[e.to] > dis[u] + e.
            cost) {
          dis[e.to] = dis[u] + e.cost, past[e.to] = &e;
          up[e.to] = min(up[u], e.cap - e.flow);
          if (!inq[e.to])
            inq[e.to] = 1, q.push(e.to);
        }
    }
    if (dis[t] == INF)
      return 0;
    flow += up[t], cost += up[t] * dis[t];
    for (ll i = t; past[i]; i = past[i]->from) {
      auto &e = *past[i];
      e.flow += up[t], G[e.to][e.rev].flow -= up[t];
    }
    return 1;
  }
  ll MinCostMaxFlow(ll _s, ll _t, ll &cost) {
    s = _s, t = _t, cost = 0;
    ll flow = 0;
    while (BellmanFord(flow, cost))
      ;
    return flow;
  }
  void init(ll _n, ll _mx) {
    n = _n, mx = _mx;
    for (int i = 0; i < n; ++i)
      G[i].clear();
  }
  void add_edge(ll a, ll b, ll cap, ll cost) {
    G[a].pb(edge{a, b, cap, 0, cost, G[b].size()});
    G[b].pb(edge{b, a, 0, 0, -cost, G[a].size() - 1});
  }
};
```

4.4 Maximum Simple Graph Matching*

```
struct GenMatch { // 1-base
  int V, pr[N];
  bool el[N][N], inq[N], inp[N], inb[N];
  int st, ed, nb, bk[N], djs[N], ans;
  void init(int _V) {
    V = _V;
    for (int i = 0; i <= V; ++i) {
      for (int j = 0; j <= V; ++j)
        el[i][j] = 0;
      pr[i] = bk[i] = djs[i] = 0;
      inq[i] = inp[i] = inb[i] = 0;
    }
  }
  void add_edge(int u, int v) { el[u][v] = el[v][u] =
      1; }
  int lca(int u, int v) {
    fill_n(inp, V + 1, 0);
    while (1)
      if (u = djs[u], inp[u] = true, u == st)
        break;
      else
        u = bk[pr[u]];
    while (1)
      if (v = djs[v], inp[v])
        return v;
      else
        v = bk[pr[v]];
    return v;
  }
  void upd(int u) {
    for (int v; djs[u] != nb;) {
      v = pr[u], inb[djs[u]] = inb[djs[v]] = true;
      u = bk[v];
      if (djs[u] != nb)
        bk[u] = v;
    }
  }
  void blo(int u, int v, queue<int> &qe) {
    nb = lca(u, v), fill_n(inb, V + 1, 0);
    upd(u), upd(v);
    if (djs[u] != nb)
      bk[u] = v;
    if (djs[v] != nb)
      bk[v] = u;
    for (int tu = 1; tu <= V; ++tu)
      if (inb[djs[tu]])
        if (djs[tu] = nb, !inq[tu])
          qe.push(tu), inq[tu] = 1;
  }
  void flow() {
    fill_n(inq + 1, V, 0), fill_n(bk + 1, V, 0);
    iota(djs + 1, djs + V + 1, 1);
    queue<int> qe;
    qe.push(st), inq[st] = 1, ed = 0;
    while (!qe.empty()) {
      int u = qe.front();
      qe.pop();
      for (int v = 1; v <= V; ++v)
        if (el[u][v] && djs[u] != djs[v] && pr[u] != v)
            {
          if ((v == st) || (pr[v] > 0 && bk[pr[v]] > 0)
              )
            blo(u, v, qe);
          else if (!bk[v]) {
            if (bk[v] = u, pr[v] > 0) {
              if (!inq[pr[v]])
                qe.push(pr[v]);
            } else
              return ed = v, void();
          }
        }
    }
  }
  void aug() {
    for (int u = ed, v, w; u > 0;)
      v = bk[u], w = pr[v], pr[v] = u, pr[u] = v, u = w
          ;
  }
  int solve() {
    fill_n(pr, V + 1, 0), ans = 0;
    for (int u = 1; u <= V; ++u)
      if (!pr[u])
        if (st = u, flow(), ed > 0)
          aug(), ++ans;
    return ans;
  }
};
```

4.5 Minimum Weight Matching (Clique version)*

```
struct Graph { // 0-base (Perfect Match), n is even
  int n, match[N], onstk[N], stk[N], tp;
  ll edge[N][N], dis[N];
  void init(int _n) {
    n = _n, tp = 0;
    for (int i = 0; i < n; ++i)
      fill_n(edge[i], n, 0);
  }
  void add_edge(int u, int v, ll w) { edge[u][v] = edge
      [v][u] = w; }
  bool SPFA(int u) {
    stk[tp++] = u, onstk[u] = 1;
```

```
    for (int v = 0; v < n; ++v)
      if (!onstk[v] && match[u] != v) {
        int m = match[v];
        if (dis[m] > dis[u] - edge[v][m] + edge[u][v])
            {
          dis[m] = dis[u] - edge[v][m] + edge[u][v];
          onstk[v] = 1, stk[tp++] = v;
          if (onstk[m] || SPFA(m))
            return 1;
          --tp, onstk[v] = 0;
        }
      }
    onstk[u] = 0, --tp;
    return 0;
  }
  ll solve() { // find a match
    for (int i = 0; i < n; ++i)
      match[i] = i ^ 1;
    while (1) {
      int found = 0;
      fill_n(dis, n, 0);
      fill_n(onstk, n, 0);
      for (int i = 0; i < n; ++i)
        if (tp = 0, !onstk[i] && SPFA(i))
          for (found = 1; tp >= 2;) {
            int u = stk[--tp];
            int v = stk[--tp];
            match[u] = v, match[v] = u;
          }
      if (!found)
        break;
    }
    ll ret = 0;
    for (int i = 0; i < n; ++i)
      ret += edge[i][match[i]];
    return ret >> 1;
  }
};
```

4.6 SW-mincut

```
// global min cut
struct SW { // O(V^3)
  static const int MXN = 514;
  int n, vst[MXN], del[MXN];
  int edge[MXN][MXN], wei[MXN];
  void init(int _n) { n = _n, MEM(edge, 0), MEM(del, 0)
      ; }
  void addEdge(int u, int v, int w) { edge[u][v] += w,
      edge[v][u] += w; }
  void search(int &s, int &t) {
    MEM(vst, 0), MEM(wei, 0), s = t = -1;
    while (1) {
      int mx = -1, cur = 0;
      for (int i = 0; i < n; ++i)
        if (!del[i] && !vst[i] && mx < wei[i])
          cur = i, mx = wei[i];
      if (mx == -1)
        break;
      vst[cur] = 1, s = t, t = cur;
      for (int i = 0; i < n; ++i)
        if (!vst[i] && !del[i])
          wei[i] += edge[cur][i];
    }
  }
  int solve() {
    int res = INF;
    for (int i = 0, x, y; i < n - 1; ++i) {
      search(x, y), res = min(res, wei[y]), del[y] = 1;
      for (int j = 0; j < n; ++j)
        edge[x][j] = (edge[j][x] += edge[y][j]);
    }
    return res;
  }
};
```

4.7 BoundedFlow(Dinic*)

```
struct BoundedFlow { // 0-base
  struct edge {
    int to, cap, flow, rev;
  };
  vector<edge> G[N];
  int n, s, t, dis[N], cur[N], cnt[N];
  void init(int _n) {
    n = _n;
    for (int i = 0; i < n + 2; ++i)
      G[i].clear(), cnt[i] = 0;
  }
  void add_edge(int u, int v, int lcap, int rcap) {
    cnt[u] -= lcap, cnt[v] += lcap;
    G[u].pb(edge{v, rcap, lcap, SZ(G[v])});
    G[v].pb(edge{u, 0, 0, SZ(G[u]) - 1});
  }
  void add_edge(int u, int v, int cap) {
    G[u].pb(edge{v, cap, 0, SZ(G[v])});
    G[v].pb(edge{u, 0, 0, SZ(G[u]) - 1});
  }
  int dfs(int u, int cap) {
    if (u == t || !cap)
      return cap;
    for (int &i = cur[u]; i < SZ(G[u]); ++i) {
      edge &e = G[u][i];
      if (dis[e.to] == dis[u] + 1 && e.cap != e.flow) {
        int df = dfs(e.to, min(e.cap - e.flow, cap));
        if (df) {
          e.flow += df, G[e.to][e.rev].flow -= df;
          return df;
        }
      }
    }
    dis[u] = -1;
    return 0;
  }
  bool bfs() {
    fill_n(dis, n + 3, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
      int u = q.front();
      q.pop();
      for (edge &e : G[u])
        if (!~dis[e.to] && e.flow != e.cap)
          q.push(e.to), dis[e.to] = dis[u] + 1;
    }
    return dis[t] != -1;
  }
  int maxflow(int _s, int _t) {
    s = _s, t = _t;
    int flow = 0, df;
    while (bfs()) {
      fill_n(cur, n + 3, 0);
      while ((df = dfs(s, INF)))
        flow += df;
    }
    return flow;
  }
  bool solve() {
    int sum = 0;
    for (int i = 0; i < n; ++i)
      if (cnt[i] > 0)
        add_edge(n + 1, i, cnt[i]), sum += cnt[i];
      else if (cnt[i] < 0)
        add_edge(i, n + 2, -cnt[i]);
    if (sum != maxflow(n + 1, n + 2))
      sum = -1;
    for (int i = 0; i < n; ++i)
      if (cnt[i] > 0)
        G[n + 1].pop_back(), G[i].pop_back();
      else if (cnt[i] < 0)
        G[i].pop_back(), G[n + 2].pop_back();
    return sum != -1;
  }
  int solve(int _s, int _t) {
    add_edge(_t, _s, INF);
    if (!solve())
      return -1; // invalid flow
    int x = G[_t].back().flow;
    return G[_t].pop_back(), G[_s].pop_back(), x;
  }
};
```

4.8 Flow Models

•Maximum/Minimum flow with lower bound / Circulation problem

1.Construct super source S and sink T.
2.For each edge (x, y, l, u), connect $x \to y$ with capacity $u - l$.
3.For each vertex v, denote by $in(v)$ the difference between the sum of incoming lower bounds and the sum of outgoing lower bounds.
4.If $in(v) > 0$, connect $S \to v$ with capacity $in(v)$, otherwise, connect $v \to T$ with capacity $-in(v)$.

–To maximize, connect $t \to s$ with capacity ∞ (skip this in circulation problem), and let f be the maximum flow from S to T. If $f \neq \sum_{v \in V, in(v)>0} in(v)$, there's no solution. Otherwise, the maximum flow from s to t is the answer.
–To minimize, let f be the maximum flow from S to T. Connect $t \to s$ with capacity ∞ and let the flow from S to T be f'. If $f + f' \neq \sum_{v \in V, in(v)>0} in(v)$, there's no solution. Otherwise, f' is the answer.
5.The solution of each edge e is $l_e + f_e$, where f_e corresponds to the flow of edge e on the graph.

•Construct minimum vertex cover from maximum matching M on bipartite graph (X, Y)
1.Redirect every edge: $y \to x$ if $(x, y) \in M$, $x \to y$ otherwise.
2.DFS from unmatched vertices in X.
3.$x \in X$ is chosen iff x is unvisited.
4.$y \in Y$ is chosen iff y is visited.

•Minimum cost cyclic flow

1.Consruct super source S and sink T
2.For each edge (x, y, c), connect $x \to y$ with $(cost, cap) = (c, 1)$ if $c > 0$, otherwise connect $y \to x$ with $(cost, cap) = (-c, 1)$
3.For each edge with $c < 0$, sum these cost as K, then increase $d(y)$ by 1, decrease $d(x)$ by 1
4.For each vertex v with $d(v) > 0$, connect $S \to v$ with $(cost, cap) = (0, d(v))$
5.For each vertex v with $d(v) < 0$, connect $v \to T$ with $(cost, cap) = (0, -d(v))$
6.Flow from S to T, the answer is the cost of the flow $C + K$

•Maximum density induced subgraph
1.Binary search on answer, suppose we're checking answer T
2.Construct a max flow model, let K be the sum of all weights
3.Connect source $s \to v$, $v \in G$ with capacity K
4.For each edge (u, v, w) in G, connect $u \to v$ and $v \to u$ with capacity w
5.For $v \in G$, connect it with sink $v \to t$ with capacity $K + 2T - (\sum_{e \in E(v)} w(e)) - 2w(v)$
6.T is a valid answer if the maximum flow $f < K|V|$

•Minimum weight edge cover
1.For each $v \in V$ create a copy v', and connect $u' \to v'$ with weight $w(u, v)$.
2.Connect $v \to v'$ with weight $2\mu(v)$, where $\mu(v)$ is the cost of the cheapest edge incident to v.
3.Find the minimum weight perfect matching on G'.

•Project selection problem
1.If $p_v > 0$, create edge (s, v) with capacity p_v; otherwise, create edge (v, t) with capacity $-p_v$.
2.Create edge (u, v) with capacity w with w being the cost of choosing u without choosing v.
3.The mincut is equivalent to the maximum profit of a subset of projects.

•0/1 quadratic programming

$$\sum_x c_x x + \sum_y c_y \bar{y} + \sum_{xy} c_{xy} x\bar{y} + \sum_{xyx'y'} c_{xyx'y'}(x\bar{y} + x'\bar{y'})$$

can be minimized by the mincut of the following graph:

1.Create edge (x, t) with capacity c_x and create edge (s, y) with capacity c_y.
2.Create edge (x, y) with capacity c_{xy}.
3.Create edge (x, y) and edge (x', y') with capacity $c_{xyx'y'}$.

5 String

5.1 KMP

```
int F[MAXN];
vector<int> match(string A, string B) {
  vector<int> ans;
  F[0] = -1, F[1] = 0;
  for (int i = 1, j = 0; i < SZ(B); F[++i] = ++j) {
    if (B[i] == B[j])
      F[i] = F[j]; // optimize
    while (j != -1 && B[i] != B[j])
      j = F[j];
  }
  for (int i = 0, j = 0; i < SZ(A); ++i) {
    while (j != -1 && A[i] != B[j])
      j = F[j];
    if (++j == SZ(B))
      ans.pb(i + 1 - j), j = F[j];
  }
  return ans;
}
```

5.2 Z-value

```
const int MAXn = 1e5 + 5;
int z[MAXn];
void make_z(string s) {
  int l = 0, r = 0;
  for (int i = 1; i < s.size(); i++) {
    for (z[i] = max(0, min(r - i + 1, z[i - l]));
         i + z[i] < s.size() && s[i + z[i]] == s[z[i]];
              z[i]++)
      ;
    if (i + z[i] - 1 > r)
      l = i, r = i + z[i] - 1;
  }
}
```

5.3 Manacher*

```
int z[MAXN];
int Manacher(string tmp) {
  string s = "&";
  int l = 0, r = 0, x, ans;
  for (char c : tmp)
    s.pb(c), s.pb('%');
  ans = 0, x = 0;
  for (int i = 1; i < SZ(s); ++i) {
    z[i] = r > i ? min(z[2 * l - i], r - i) : 1;
    while (s[i + z[i]] == s[i - z[i]])
      ++z[i];
    if (z[i] + i > r)
      r = z[i] + i, l = i;
  }
  for (int i = 1; i < SZ(s); ++i)
    if (s[i] == '%')
      x = max(x, z[i]);
  ans = x / 2 * 2, x = 0;
  for (int i = 1; i < SZ(s); ++i)
    if (s[i] != '%')
      x = max(x, z[i]);
  return max(ans, (x - 1) / 2 * 2 + 1);
}
```

5.4 SAIS*

```
class SAIS {
public:
  int *SA, *H;
  // zero based, string content MUST > 0
  // result height H[i] is LCP(SA[i - 1], SA[i])
  // string, length, |sigma|
  void build(int *s, int n, int m = 128) {
    copy_n(s, n, _s);
    _h[0] = _s[n++] = 0;
    sais(_s, _sa, _p, _q, _t, _c, n, m);
    mkhei(n);
    SA = _sa + 1;
    H = _h + 1;
  }

private:
  bool _t[N * 2];
  int _s[N * 2], _c[N * 2], x[N], _p[N], _q[N * 2], r[N
      ], _sa[N * 2], _h[N];
  void mkhei(int n) {
    for (int i = 0; i < n; i++)
      r[_sa[i]] = i;
    for (int i = 0; i < n; i++)
      if (r[i]) {
        int ans = i > 0 ? max(_h[r[i - 1]] - 1, 0) : 0;
        while (_s[i + ans] == _s[_sa[r[i] - 1] + ans])
          ans++;
        _h[r[i]] = ans;
      }
  }
  void sais(int *s, int *sa, int *p, int *q, bool *t,
      int *c, int n, int z) {
    bool uniq = t[n - 1] = 1, neq;
    int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,
        lst = -1;

#define MAGIC(XD)

    \
```

```
  fill_n(sa, n, 0);

      \
  copy_n(c, z, x);

      \
  XD;

      \
  copy_n(c, z - 1, x + 1);

      \
  for (int i = 0; i < n; i++)

      \
    if (sa[i] && !t[sa[i] - 1])

        \
      sa[x[s[sa[i] - 1]]++] = sa[i] - 1;
                                                \
  copy_n(c, z, x);

      \
  for (int i = n - 1; i >= 0; i--)
                                                  \
    if (sa[i] && t[sa[i] - 1])

        \
      sa[--x[s[sa[i] - 1]]] = sa[i] - 1;

    fill_n(c, z, 0);
    for (int i = 0; i < n; i++)
      uniq &= ++c[s[i]] < 2;
    partial_sum(c, c + z, c);
    if (uniq) {
      for (int i = 0; i < n; i++)
        sa[--c[s[i]]] = i;
      return;
    }
    for (int i = n - 2; i >= 0; i--)
      t[i] = (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i
          + 1]);
    MAGIC(for (int i = 1; i <= n - 1; i++) if (t[i] &&
        !t[i - 1])
            sa[--x[s[i]]] = p[q[i] = nn++] = i);
    for (int i = 0; i < n; i++)
      if (sa[i] && t[sa[i]] && !t[sa[i] - 1]) {
        neq = (lst < 0) ||
              !equal(s + lst, s + lst + p[q[sa[i]] + 1]
                  - sa[i], s + sa[i]);
        ns[q[lst = sa[i]]] = nmxz += neq;
      }
    sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
        + 1);
    MAGIC(for (int i = nn - 1; i >= 0; i--) sa[--x[s[p[
        nsa[i]]]]] = p[nsa[i]]);
  }
} sa;
```

5.5 Aho-Corasick Automatan

```
const int len = 400000, sigma = 26;
struct AC_Automatan {
  int nx[len][sigma], fl[len], cnt[len], pri[len], top;
  int newnode() {
    fill(nx[top], nx[top] + sigma, -1);
    return top++;
  }
  void init() { top = 1, newnode(); }
  int input(string &s) { // return the end_node of
      string
    int X = 1;
    for (char c : s) {
      if (!~nx[X][c - 'a'])
        nx[X][c - 'a'] = newnode();
      X = nx[X][c - 'a'];
    }
    return X;
  }
  void make_fl() {
    queue<int> q;
    q.push(1), fl[1] = 0;
    for (int t = 0; !q.empty();) {
      int R = q.front();
      q.pop(), pri[t++] = R;
      for (int i = 0; i < sigma; ++i)
        if (~nx[R][i]) {
          int X = nx[R][i], Z = fl[R];
          for (; Z && !~nx[Z][i];)
            Z = fl[Z];
          fl[X] = Z ? nx[Z][i] : 1, q.push(X);
        }
    }
  }
  void get_v(string &s) {
    int X = 1;
    fill(cnt, cnt + top, 0);
    for (char c : s) {
      while (X && !~nx[X][c - 'a'])
        X = fl[X];
      X = X ? nx[X][c - 'a'] : 1, ++cnt[X];
    }
    for (int i = top - 2; i > 0; --i)
      cnt[fl[pri[i]]] += cnt[pri[i]];
  }
};
```

5.6 Smallest Rotation

```
string mcp(string s) {
  int n = SZ(s), i = 0, j = 1;
  s += s;
  while (i < n && j < n) {
    int k = 0;
    while (k < n && s[i + k] == s[j + k])
      ++k;
    if (s[i + k] <= s[j + k])
      j += k + 1;
    else
      i += k + 1;
    if (i == j)
      ++j;
  }
  int ans = i < n ? i : j;
  return s.substr(ans, n);
}
```

5.7 De Bruijn sequence*

```
constexpr int MAXC = 10, MAXN = 1e5 + 10;
struct DBSeq {
  int C, N, K, L, buf[MAXC * MAXN]; // K <= C^N
  void dfs(int *out, int t, int p, int &ptr) {
    if (ptr >= L)
      return;
    if (t > N) {
      if (N % p)
        return;
      for (int i = 1; i <= p && ptr < L; ++i)
        out[ptr++] = buf[i];
    } else {
      buf[t] = buf[t - p], dfs(out, t + 1, p, ptr);
      for (int j = buf[t - p] + 1; j < C; ++j)
        buf[t] = j, dfs(out, t + 1, t, ptr);
    }
  }
  void solve(int _c, int _n, int _k, int *out) {
    int p = 0;
    C = _c, N = _n, K = _k, L = N + K - 1;
    dfs(out, 1, 1, p);
    if (p < L)
      fill(out + p, out + L, 0);
  }
} dbs;
```

5.8 SAM

```
const int MAXM = 1000010;
struct SAM {
  int tot, root, lst, mom[MAXM], mx[MAXM];
  int acc[MAXM], nxt[MAXM][33];
  int newNode() {
    int res = ++tot;
    fill(nxt[res], nxt[res] + 33, 0);
```

```
    mom[res] = mx[res] = acc[res] = 0;
    return res;
  }
  void init() {
    tot = 0;
    root = newNode();
    mom[root] = 0, mx[root] = 0;
    lst = root;
  }
  void push(int c) {
    int p = lst;
    int np = newNode();
    mx[np] = mx[p] + 1;
    for (; p && nxt[p][c] == 0; p = mom[p])
      nxt[p][c] = np;
    if (p == 0)
      mom[np] = root;
    else {
      int q = nxt[p][c];
      if (mx[p] + 1 == mx[q])
        mom[np] = q;
      else {
        int nq = newNode();
        mx[nq] = mx[p] + 1;
        for (int i = 0; i < 33; i++)
          nxt[nq][i] = nxt[q][i];
        mom[nq] = mom[q];
        mom[q] = nq;
        mom[np] = nq;
        for (; p && nxt[p][c] == q; p = mom[p])
          nxt[p][c] = nq;
      }
    }
    lst = np;
  }
  void push(char *str) {
    for (int i = 0; str[i]; i++)
      push(str[i] - 'a' + 1);
  }
} sam;
```

5.9 PalTree

```
struct palindromic_tree { // Check by APIO 2014
                          // palindrome
  struct node {
    int next[26], fail, len;
    int cnt, num; // cnt: appear times, num: number of
                  // pal. suf.
    node(int l = 0) : fail(0), len(l), cnt(0), num(0) {
      for (int i = 0; i < 26; ++i)
        next[i] = 0;
    }
  };
  vector<node> St;
  vector<char> s;
  int last, n;
  palindromic_tree() : St(2), last(1), n(0) {
    St[0].fail = 1, St[1].len = -1, s.pb(-1);
  }
  inline void clear() {
    St.clear(), s.clear(), last = 1, n = 0;
    St.pb(0), St.pb(-1);
    St[0].fail = 1, s.pb(-1);
  }
  inline int get_fail(int x) {
    while (s[n - St[x].len - 1] != s[n])
      x = St[x].fail;
    return x;
  }
  inline void add(int c) {
    s.push_back(c -= 'a'), ++n;
    int cur = get_fail(last);
    if (!St[cur].next[c]) {
      int now = SZ(St);
      St.pb(St[cur].len + 2);
      St[now].fail = St[get_fail(St[cur].fail)].next[c
          ];
      St[cur].next[c] = now;
      St[now].num = St[St[now].fail].num + 1;
    }
    last = St[cur].next[c], ++St[last].cnt;
  }
  inline void count() { // counting cnt
    auto i = St.rbegin();
    for (; i != St.rend(); ++i) {
      St[i->fail].cnt += i->cnt;
    }
  }
  inline int size() { // The number of diff. pal.
    return SZ(St) - 2;
  }
};
```

5.10 cyclicLCS

```
#define L 0
#define LU 1
#define U 2
const int mov[3][2] = {0, -1, -1, -1, -1, 0};
int al, bl;
char a[MAXL * 2], b[MAXL * 2]; // 0-indexed
int dp[MAXL * 2][MAXL];
char pred[MAXL * 2][MAXL];
inline int lcs_length(int r) {
  int i = r + al, j = bl, l = 0;
  while (i > r) {
    char dir = pred[i][j];
    if (dir == LU)
      l++;
    i += mov[dir][0];
    j += mov[dir][1];
  }
  return l;
}
inline void reroot(int r) { // r = new base row
  int i = r, j = 1;
  while (j <= bl && pred[i][j] != LU)
    j++;
  if (j > bl)
    return;
  pred[i][j] = L;
  while (i < 2 * al && j <= bl) {
    if (pred[i + 1][j] == U) {
      i++;
      pred[i][j] = L;
    } else if (j < bl && pred[i + 1][j + 1] == LU) {
      i++;
      j++;
      pred[i][j] = L;
    } else {
      j++;
    }
  }
}
int cyclic_lcs() {
  // a, b, al, bl should be properly filled
  // note: a WILL be altered in process
  //       -- concatenated after itself
  char tmp[MAXL];
  if (al > bl) {
    swap(al, bl);
    strcpy(tmp, a);
    strcpy(a, b);
    strcpy(b, tmp);
  }
  strcpy(tmp, a);
  strcat(a, tmp);
  // basic lcs
  for (int i = 0; i <= 2 * al; i++) {
    dp[i][0] = 0;
    pred[i][0] = U;
  }
  for (int j = 0; j <= bl; j++) {
    dp[0][j] = 0;
    pred[0][j] = L;
  }
  for (int i = 1; i <= 2 * al; i++) {
    for (int j = 1; j <= bl; j++) {
      if (a[i - 1] == b[j - 1])
        dp[i][j] = dp[i - 1][j - 1] + 1;
      else
        dp[i][j] = max(dp[i - 1][j], dp[i][j - 1]);
      if (dp[i][j - 1] == dp[i][j])
```

```
        pred[i][j] = L;
      else if (a[i - 1] == b[j - 1])
        pred[i][j] = LU;
      else
        pred[i][j] = U;
    }
  }
  // do cyclic lcs
  int clcs = 0;
  for (int i = 0; i < al; i++) {
    clcs = max(clcs, lcs_length(i));
    reroot(i + 1);
  }
  // recover a
  a[al] = '\0';
  return clcs;
}
```

5.11 Suffix Array

```
#include <bits/stdc++.h>
#define FILL(x, y) memset(x, y, sizeof(x))
using namespace std;

struct suffix_array {
  int box[100007], tp[100007], m;
  bool not_equ(int a, int b, int k, int n) {
    return ra[a] != ra[b] || a + k >= n || b + k >= n
        || ra[a + k] != ra[b + k];
  }
  void radix(int *key, int *it, int *ot, int n) {
    fill_n(box, m, 0);
    for (int i = 0; i < n; ++i)
      ++box[key[i]];
    partial_sum(box, box + m, box);
    for (int i = n - 1; i >= 0; --i)
      ot[--box[key[it[i]]]] = it[i];
  }
  void make_sa(string s, int n) {
    int k = 1;
    for (int i = 0; i < n; ++i)
      ra[i] = s[i];
    do {
      iota(tp, tp + k, n - k), iota(sa + k, sa + n, 0);
      radix(ra + k, sa + k, tp + k, n - k);
      radix(ra, tp, sa, n);
      tp[sa[0]] = 0, m = 1;
      for (int i = 1; i < n; ++i) {
        m += not_equ(sa[i], sa[i - 1], k, n);
        tp[sa[i]] = m - 1;
      }
      copy_n(tp, n, ra);
      k *= 2;
    } while (k < n && m != n);
  }
  void make_he(string s, int n) {
    for (int j = 0, k = 0; j < n; ++j) {
      if (ra[j])
        for (; s[j + k] == s[sa[ra[j] - 1] + k]; ++k)
          ;
      he[ra[j]] = k, k = max(0, k - 1);
    }
  }
  int sa[100007], ra[100007], he[100007];
  void build(string s) {
    FILL(sa, 0), FILL(ra, 0), FILL(he, 0);
    FILL(box, 0), FILL(tp, 0), m = 256;
    make_sa(s, s.size());
    make_he(s, s.size());
  }
};
main() {
  string s;
  cin >> s;
  suffix_array saa;
  saa.build(s);
  for (int i = 0; i <= s.length(); i++) {
    cout << i << " " << saa.sa[i] << " " << saa.ra[i]
        << " " << saa.he[i]
         << endl;
  }
}
```

5.12 Suffix Array2

```
// array c is eventually equal to the position of the
    suffixes in the suffix
// array don't add another '$' to the string
int sa[400007], c[400007], sa_new[400007], c_new
    [400007], cnt[400007],
    pos[400007], lcp[400007];
pair<char, int> P[400007];
void calc_suffix_array(string s) {
  s += '$';
  int n = s.size();
  for (int i = 0; i < n; i++)
    P[i] = {s[i], i};
  sort(P, P + n);
  for (int i = 0; i < n; i++)
    sa[i] = P[i].second;
  c[sa[0]] = 0;
  for (int i = 1; i < n; i++)
    c[sa[i]] = c[sa[i - 1]] + (P[i].first > P[i - 1].
        first ? 1 : 0);
  int k = 1;
  while (k < n) {
    for (int i = 0; i < n; i++)
      sa[i] = (sa[i] - k + n) % n;
    for (int i = 0; i < n; i++)
      cnt[i] = 0;
    for (int i = 0; i < n; i++)
      cnt[c[i]]++;
    pos[0] = cnt[0] - 1;
    for (int i = 1; i < n; i++)
      pos[i] = pos[i - 1] + cnt[i];
    for (int i = n - 1; i >= 0; i--)
      sa_new[pos[c[sa[i]]]--] = sa[i];
    for (int i = 0; i < n; i++)
      sa[i] = sa_new[i];
    c_new[sa[0]] = 0;
    for (int i = 1; i < n; i++) {
      c_new[sa[i]] = c_new[sa[i - 1]];
      pair<int, int> prev = {c[sa[i - 1]], c[(sa[i - 1]
          + k) % n]};
      pair<int, int> now = {c[sa[i]], c[(sa[i] + k) % n
          ]};
      if (now > prev)
        c_new[sa[i]]++;
    }
    for (int i = 0; i < n; i++)
      c[i] = c_new[i];
    k *= 2;
  }
}
void calc_lcp_array(string s) {
  int n = s.size(), k = 0;
  for (int i = 0; i < n; i++) {
    int j = sa[c[i] - 1];
    while (i + k < n && j + k < n && s[i + k] == s[j +
        k])
      k++;
    lcp[c[i] - 1] = k;
    k = max(k - 1, 0ll);
  }
}
```

6 Math

6.1 ax+by=gcd*

```
pll exgcd(ll a, ll b) {
  if (b == 0)
    return pll(1, 0);
  else {
    ll p = a / b;
    pll q = exgcd(b, a % b);
    return pll(q.Y, q.X - q.Y * p);
  }
}
```

6.2 floor and ceil

```
int floor(int a, int b) { return a / b - (a % b && a <
    0 ^ b < 0); }
int ceil(int a, int b) { return a / b + (a % b && a<0 ^
     b> 0); }
```

6.3 Miller Rabin*

```
// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383  6 : pirmes <= 13
// n < 2^64               7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
bool Miller_Rabin(ll a, ll n) {
  if ((a = a % n) == 0)
    return 1;
  if ((n & 1) ^ 1)
    return n == 2;
  ll tmp = (n - 1) / ((n - 1) & (1 - n));
  ll t = __lg(((n - 1) & (1 - n))), x = 1;
  for (; tmp; tmp >>= 1, a = mul(a, a, n))
    if (tmp & 1)
      x = mul(x, a, n);
  if (x == 1 || x == n - 1)
    return 1;
  while (--t)
    if ((x = mul(x, x, n)) == n - 1)
      return 1;
  return 0;
}
```

6.4 Big number

```
template <typename T> inline string to_string(const T &
    x) {
  stringstream ss;
  return ss << x, ss.str();
}
struct bigN : vector<ll> {
  const static int base = 1000000000, width = log10(
      base);
  bool negative;
  bigN(const_iterator a, const_iterator b) : vector<ll
      >(a, b) {}
  bigN(string s) {
    if (s.empty())
      return;
    if (s[0] == '-')
      negative = 1, s = s.substr(1);
    else
      negative = 0;
    for (int i = int(s.size()) - 1; i >= 0; i -= width)
         {
      ll t = 0;
      for (int j = max(0, i - width + 1); j <= i; ++j)
        t = t * 10 + s[j] - '0';
      push_back(t);
    }
    trim();
  }
  template <typename T> bigN(const T &x) : bigN(
      to_string(x)) {}
  bigN() : negative(0) {}
  void trim() {
    while (size() && !back())
      pop_back();
    if (empty())
      negative = 0;
  }
  void carry(int _base = base) {
    for (size_t i = 0; i < size(); ++i) {
      if (at(i) >= 0 && at(i) < _base)
        continue;
      if (i + 1u == size())
        push_back(0);
      int r = at(i) % _base;
      if (r < 0)
        r += _base;
      at(i + 1) += (at(i) - r) / _base, at(i) = r;
    }
  }
  int abscmp(const bigN &b) const {
    if (size() > b.size())
      return 1;
    if (size() < b.size())
      return -1;
    for (int i = int(size()) - 1; i >= 0; --i) {
      if (at(i) > b[i])
        return 1;
      if (at(i) < b[i])
        return -1;
    }
    return 0;
  }
  int cmp(const bigN &b) const {
    if (negative != b.negative)
      return negative ? -1 : 1;
    return negative ? -abscmp(b) : abscmp(b);
  }
  bool operator<(const bigN &b) const { return cmp(b) <
      0; }
  bool operator>(const bigN &b) const { return cmp(b) >
      0; }
  bool operator<=(const bigN &b) const { return cmp(b)
      <= 0; }
  bool operator>=(const bigN &b) const { return cmp(b)
      >= 0; }
  bool operator==(const bigN &b) const { return !cmp(b)
      ; }
  bool operator!=(const bigN &b) const { return cmp(b)
      != 0; }
  bigN abs() const {
    bigN res = *this;
    return res.negative = 0, res;
  }
  bigN operator-() const {
    bigN res = *this;
    return res.negative = !negative, res.trim(), res;
  }
  bigN operator+(const bigN &b) const {
    if (negative)
      return -(-(*this) + (-b));
    if (b.negative)
      return *this - (-b);
    bigN res = *this;
    if (b.size() > size())
      res.resize(b.size());
    for (size_t i = 0; i < b.size(); ++i)
      res[i] += b[i];
    return res.carry(), res.trim(), res;
  }
  bigN operator-(const bigN &b) const {
    if (negative)
      return -(-(*this) - (-b));
    if (b.negative)
      return *this + (-b);
    if (abscmp(b) < 0)
      return -(b - (*this));
    bigN res = *this;
    if (b.size() > size())
      res.resize(b.size());
    for (size_t i = 0; i < b.size(); ++i)
      res[i] -= b[i];
    return res.carry(), res.trim(), res;
  }
  bigN operator*(const bigN &b) const {
    bigN res;
    res.negative = negative != b.negative;
    res.resize(size() + b.size());
    for (size_t i = 0; i < size(); ++i)
      for (size_t j = 0; j < b.size(); ++j)
        if ((res[i + j] += at(i) * b[j]) >= base) {
          res[i + j + 1] += res[i + j] / base;
          res[i + j] %= base;
        } // □¼ªk¥carry·|□·¸|
    return res.trim(), res;
  }
  bigN operator/(const bigN &b) const {
    int norm = base / (b.back() + 1);
    bigN x = abs() * norm;
    bigN y = b.abs() * norm;
    bigN q, r;
    q.resize(x.size());
    for (int i = int(x.size()) - 1; i >= 0; --i) {
      r = r * base + x[i];
      int s1 = r.size() <= y.size() ? 0 : r[y.size()];
      int s2 = r.size() < y.size() ? 0 : r[y.size() -
          1];
      int d = (ll(base) * s1 + s2) / y.back();
      r = r - y * d;
```

```
      while (r.negative)
        r = r + y, --d;
      q[i] = d;
    }
    q.negative = negative != b.negative;
    return q.trim(), q;
  }
  bigN operator%(const bigN &b) const { return *this -
      (*this / b) * b; }
  friend istream &operator>>(istream &ss, bigN &b) {
    string s;
    return ss >> s, b = s, ss;
  }
  friend ostream &operator<<(ostream &ss, const bigN &b
      ) {
    if (b.negative)
      ss << '-';
    ss << (b.empty() ? 0 : b.back());
    for (int i = int(b.size()) - 2; i >= 0; --i)
      ss << setw(width) << setfill('0') << b[i];
    return ss;
  }
  template <typename T> operator T() {
    stringstream ss;
    ss << *this;
    T res;
    return ss >> res, res;
  }
};
```

6.5 Fraction

```
struct fraction {
  ll n, d;
  fraction(const ll &_n = 0, const ll &_d = 1) : n(_n),
       d(_d) {
    ll t = __gcd(n, d);
    n /= t, d /= t;
    if (d < 0)
      n = -n, d = -d;
  }
  fraction operator-() const { return fraction(-n, d);
      }
  fraction operator+(const fraction &b) const {
    return fraction(n * b.d + b.n * d, d * b.d);
  }
  fraction operator-(const fraction &b) const {
    return fraction(n * b.d - b.n * d, d * b.d);
  }
  fraction operator*(const fraction &b) const {
    return fraction(n * b.n, d * b.d);
  }
  fraction operator/(const fraction &b) const {
    return fraction(n * b.d, d * b.n);
  }
  void print() {
    cout << n;
    if (d != 1)
      cout << "/" << d;
  }
};
```

6.6 Simultaneous Equations

```
struct matrix { // m variables, n equations
  int n, m;
  fraction M[MAXN][MAXN + 1], sol[MAXN];
  int solve() { //-1: inconsistent, >= 0: rank
    for (int i = 0; i < n; ++i) {
      int piv = 0;
      while (piv < m && !M[i][piv].n)
        ++piv;
      if (piv == m)
        continue;
      for (int j = 0; j < n; ++j) {
        if (i == j)
          continue;
        fraction tmp = -M[j][piv] / M[i][piv];
        for (int k = 0; k <= m; ++k)
          M[j][k] = tmp * M[i][k] + M[j][k];
      }
    }
    int rank = 0;
    for (int i = 0; i < n; ++i) {
      int piv = 0;
      while (piv < m && !M[i][piv].n)
        ++piv;
      if (piv == m && M[i][m].n)
        return -1;
      else if (piv < m)
        ++rank, sol[piv] = M[i][m] / M[i][piv];
    }
    return rank;
  }
};
```

6.7 Pollard Rho

```
// does not work when n is prime
ll f(ll x, ll mod) { return add(mul(x, x, mod), 1, mod)
    ; }
ll pollard_rho(ll n) {
  if (!(n & 1))
    return 2;
  while (1) {
    ll y = 2, x = rand() % (n - 1) + 1, res = 1;
    for (int sz = 2; res == 1; y = x, sz *= 2)
      for (int i = 0; i < sz && res <= 1; ++i)
        x = f(x, n), res = __gcd(abs(x - y), n);
    if (res != 0 && res != n)
      return res;
  }
}
```

6.8 Simplex Algorithm

```
const int MAXN = 111;
const int MAXM = 111;
const double eps = 1E-10;
double a[MAXN][MAXM], b[MAXN], c[MAXM], d[MAXN][MAXM];
double x[MAXM];
int ix[MAXN + MAXM]; // !!! array all indexed from 0
// max{cx} subject to {Ax<=b,x>=0}
// n: constraints, m: vars !!!
// x[] is the optimal solution vector
// usage :
// value = simplex(a, b, c, N, M);
double simplex(double a[MAXN][MAXM], double b[MAXN],
    double c[MAXM], int n,
               int m) {
  ++m;
  int r = n, s = m - 1;
  memset(d, 0, sizeof(d));
  for (int i = 0; i < n + m; ++i)
    ix[i] = i;
  for (int i = 0; i < n; ++i) {
    for (int j = 0; j < m - 1; ++j)
      d[i][j] = -a[i][j];
    d[i][m - 1] = 1;
    d[i][m] = b[i];
    if (d[r][m] > d[i][m])
      r = i;
  }
  for (int j = 0; j < m - 1; ++j)
    d[n][j] = c[j];
  d[n + 1][m - 1] = -1;
  for (double dd;;) {
    if (r < n) {
      int t = ix[s];
      ix[s] = ix[r + m];
      ix[r + m] = t;
      d[r][s] = 1.0 / d[r][s];
      for (int j = 0; j <= m; ++j)
        if (j != s)
          d[r][j] *= -d[r][s];
      for (int i = 0; i <= n + 1; ++i)
        if (i != r) {
          for (int j = 0; j <= m; ++j)
            if (j != s)
              d[i][j] += d[r][j] * d[i][s];
          d[i][s] *= d[r][s];
        }
    }
    r = -1;
```

```
    s = -1;
    for (int j = 0; j < m; ++j)
      if (s < 0 || ix[s] > ix[j]) {
        if (d[n + 1][j] > eps || (d[n + 1][j] > -eps &&
             d[n][j] > eps))
          s = j;
      }
    if (s < 0)
      break;
    for (int i = 0; i < n; ++i)
      if (d[i][s] < -eps) {
        if (r < 0 || (dd = d[r][m] / d[r][s] - d[i][m]
            / d[i][s]) < -eps ||
            (dd < eps && ix[r + m] > ix[i + m]))
          r = i;
      }
    if (r < 0)
      return -1; // not bounded
  }
  if (d[n + 1][m] < -eps)
    return -1; // not executable
  double ans = 0;
  for (int i = 0; i < m; i++)
    x[i] = 0;
  for (int i = m; i < n + m; ++i) { // the missing
      enumerated x[i] = 0
    if (ix[i] < m - 1) {
      ans += d[i - m][m] * c[ix[i]];
      x[ix[i]] = d[i - m][m];
    }
  }
  return ans;
}
```

6.8.1 Construction

Standard form: maximize $c^T x$ subject to $Ax \leq b$ and $x \geq 0$.
Dual LP: minimize $b^T y$ subject to $A^T y \geq c$ and $y \geq 0$.
$\bar{x}$ and $\bar{y}$ are optimal if and only if for all $i \in [1, n]$, either $\bar{x}_i = 0$ or $\sum_{j=1}^{m} A_{ji}\bar{y}_j = c_i$ holds and for all $i \in [1, m]$ either $\bar{y}_i = 0$ or $\sum_{j=1}^{n} A_{ij}\bar{x}_j = b_j$ holds.

1.In case of minimization, let $c'_i = -c_i$
2.$\sum_{1 \leq i \leq n} A_{ji}x_i \geq b_j \rightarrow \sum_{1 \leq i \leq n} -A_{ji}x_i \leq -b_j$
3.$\sum_{1 \leq i \leq n} A_{ji}x_i = b_j$

- $\sum_{1 \leq i \leq n} A_{ji}x_i \leq b_j$
- $\sum_{1 \leq i \leq n} A_{ji}x_i \geq b_j$

4.If x_i has no lower bound, replace x_i with $x_i - x'_i$

6.9 Schreier-Sims Algorithm*

```
namespace schreier {
int n;
vector<vector<vector<int>>> bkts, binv;
vector<vector<int>> lk;
vector<int> operator*(const vector<int> &a, const
    vector<int> &b) {
  vector<int> res(SZ(a));
  for (int i = 0; i < SZ(a); ++i)
    res[i] = b[a[i]];
  return res;
}
vector<int> inv(const vector<int> &a) {
  vector<int> res(SZ(a));
  for (int i = 0; i < SZ(a); ++i)
    res[a[i]] = i;
  return res;
}
int filter(const vector<int> &g, bool add = true) {
  n = SZ(bkts);
  vector<int> p = g;
  for (int i = 0; i < n; ++i) {
    assert(p[i] >= 0 && p[i] < SZ(lk[i]));
    if (lk[i][p[i]] == -1) {
      if (add) {
        bkts[i].pb(p);
        binv[i].pb(inv(p));
        lk[i][p[i]] = SZ(bkts[i]) - 1;
      }
      return i;
    }
    p = p * binv[i][lk[i][p[i]]];
  }
  return -1;
}
bool inside(const vector<int> &g) { return filter(g,
    false) == -1; }
void solve(const vector<vector<int>> &gen, int _n) {
  n = _n;
  bkts.clear(), bkts.resize(n);
  binv.clear(), binv.resize(n);
  lk.clear(), lk.resize(n);
  vector<int> iden(n);
  iota(iden.begin(), iden.end(), 0);
  for (int i = 0; i < n; ++i) {
    lk[i].resize(n, -1);
    bkts[i].pb(iden);
    binv[i].pb(iden);
    lk[i][i] = 0;
  }
  for (int i = 0; i < SZ(gen); ++i)
    filter(gen[i]);
  queue<pair<pii, pii>> upd;
  for (int i = 0; i < n; ++i)
    for (int j = i; j < n; ++j)
      for (int k = 0; k < SZ(bkts[i]); ++k)
        for (int l = 0; l < SZ(bkts[j]); ++l)
          upd.emplace(pii(i, k), pii(j, l));
  while (!upd.empty()) {
    auto a = upd.front().X;
    auto b = upd.front().Y;
    upd.pop();
    int res = filter(bkts[a.X][a.Y] * bkts[b.X][b.Y]);
    if (res == -1)
      continue;
    pii pr = pii(res, SZ(bkts[res]) - 1);
    for (int i = 0; i < n; ++i)
      for (int j = 0; j < SZ(bkts[i]); ++j) {
        if (i <= res)
          upd.emplace(pii(i, j), pr);
        if (res <= i)
          upd.emplace(pr, pii(i, j));
      }
  }
}
long long size() {
  long long res = 1;
  for (int i = 0; i < n; ++i)
    res = res * SZ(bkts[i]);
  return res;
}
} // namespace schreier
```

6.10 chineseRemainder

```
LL solve(LL x1, LL m1, LL x2, LL m2) {
  LL g = __gcd(m1, m2);
  if ((x2 - x1) % g)
    return -1; // no sol
  m1 /= g;
  m2 /= g;
  pair<LL, LL> p = gcd(m1, m2);
  LL lcm = m1 * m2 * g;
  LL res = p.first * (x2 - x1) * m1 + x1;
  return (res % lcm + lcm) % lcm;
}
```

6.11 QuadraticResidue

```
int Jacobi(int a, int m) {
  int s = 1;
  for (; m > 1;) {
    a %= m;
    if (a == 0)
      return 0;
    const int r = __builtin_ctz(a);
    if ((r & 1) && ((m + 2) & 4))
      s = -s;
    a >>= r;
    if (a & m & 2)
      s = -s;
    swap(a, m);
  }
  return s;
```

```
}

int QuadraticResidue(int a, int p) {
  if (p == 2)
    return a & 1;
  const int jc = Jacobi(a, p);
  if (jc == 0)
    return 0;
  if (jc == -1)
    return -1;
  int b, d;
  for (;;) {
    b = rand() % p;
    d = (1LL * b * b + p - a) % p;
    if (Jacobi(d, p) == -1)
      break;
  }
  int f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
  for (int e = (1LL + p) >> 1; e; e >>= 1) {
    if (e & 1) {
      tmp = (1LL * g0 * f0 + 1LL * d * (1LL * g1 * f1 %
          p)) % p;
      g1 = (1LL * g0 * f1 + 1LL * g1 * f0) % p;
      g0 = tmp;
    }
    tmp = (1LL * f0 * f0 + 1LL * d * (1LL * f1 * f1 % p
        )) % p;
    f1 = (2LL * f0 * f1) % p;
    f0 = tmp;
  }
  return g0;
}
```

6.12 Discrete Log

```
int DiscreteLog(int s, int x, int y, int m) {
  constexpr int kStep = 32000;
  unordered_map<int, int> p;
  int b = 1;
  for (int i = 0; i < kStep; ++i) {
    p[y] = i;
    y = 1LL * y * x % m;
    b = 1LL * b * x % m;
  }
  for (int i = 0; i < m + 10; i += kStep) {
    s = 1LL * s * b % m;
    if (p.find(s) != p.end())
      return i + kStep - p[s];
  }
  return -1;
}
int DiscreteLog(int x, int y, int m) {
  if (m == 1)
    return 0;
  int s = 1;
  for (int i = 0; i < 100; ++i) {
    if (s == y)
      return i;
    s = 1LL * s * x % m;
  }
  if (s == y)
    return 100;
  int p = 100 + DiscreteLog(s, x, y, m);
  if (fpow(x, p, m) != y)
    return -1;
  return p;
}
```

6.13 PiCount

```
int64_t PrimeCount(int64_t n) {
  if (n <= 1)
    return 0;
  const int v = sqrt(n);
  vector<int> smalls(v + 1);
  for (int i = 2; i <= v; ++i)
    smalls[i] = (i + 1) / 2;
  int s = (v + 1) / 2;
  vector<int> roughs(s);
  for (int i = 0; i < s; ++i)
    roughs[i] = 2 * i + 1;
  vector<int64_t> larges(s);
  for (int i = 0; i < s; ++i)
    larges[i] = (n / (2 * i + 1) + 1) / 2;
  vector<bool> skip(v + 1);
  int pc = 0;
  for (int p = 3; p <= v; ++p) {
    if (smalls[p] > smalls[p - 1]) {
      int q = p * p;
      pc++;
      if (1LL * q * q > n)
        break;
      skip[p] = true;
      for (int i = q; i <= v; i += 2 * p)
        skip[i] = true;
      int ns = 0;
      for (int k = 0; k < s; ++k) {
        int i = roughs[k];
        if (skip[i])
          continue;
        int64_t d = 1LL * i * p;
        larges[ns] =
            larges[k] - (d <= v ? larges[smalls[d] - pc
                ] : smalls[n / d]) + pc;
        roughs[ns++] = i;
      }
      s = ns;
      for (int j = v / p; j >= p; --j) {
        int c = smalls[j] - pc;
        for (int i = j * p, e = min(i + p, v + 1); i <
            e; ++i)
          smalls[i] -= c;
      }
    }
  }
  for (int k = 1; k < s; ++k) {
    const int64_t m = n / roughs[k];
    int64_t s = larges[k] - (pc + k - 1);
    for (int l = 1; l < k; ++l) {
      int p = roughs[l];
      if (1LL * p * p > m)
        break;
      s -= smalls[m / p] - (pc + l - 1);
    }
    larges[0] -= s;
  }
  return larges[0];
}
```

6.14 Primes

```
/*
   12721 13331 14341 75577 123457 222557 556679 999983
       1097774749 1076767633
   100102021 999997771 1001010013 1000512343 987654361
       999991231 999888733
   98789101 987777733 999991921 1010101333 1010102101
       1000000000039
   1000000000000037 2305843009213693951
       4611686018427387847 9223372036854775783
   18446744073709551557
   */
```

6.15 Theorem

6.15.1 Kirchhoff's Theorem

Denote L be a $n \times n$ matrix as the Laplacian matrix of graph G, where $L_{ii} = d(i)$, $L_{ij} = -c$ where c is the number of edge (i, j) in G.

- The number of undirected spanning in G is $|\det(\tilde{L}_{11})|$.
- The number of directed spanning tree rooted at r in G is $|\det(\tilde{L}_{rr})|$.

6.15.2 Tutte's Matrix

Let D be a $n \times n$ matrix, where $d_{ij} = x_{ij}$ (x_{ij} is chosen uniformly at random) if $i < j$ and $(i, j) \in E$, otherwise $d_{ij} = -d_{ji}$. $\frac{rank(D)}{2}$ is the maximum matching on G.

6.15.3 Cayley's Formula

- Given a degree sequence $d_1, d_2, \ldots, d_n$ for each labeled vertices, there are $\frac{(n-2)!}{(d_1-1)!(d_2-1)!\cdots(d_n-1)!}$ spanning trees.
- Let $T_{n,k}$ be the number of labeled forests on n vertices with k components, such that vertex $1, 2, \ldots, k$ belong to different components. Then $T_{n,k} = kn^{n-k-1}$.

6.15.4 Erdős–Gallai theorem

A sequence of nonnegative integers $d_1 \geq \cdots \geq d_n$ can be represented as the degree sequence of a finite simple graph on n vertices if and only if $d_1 + \cdots + d_n$ is even and $\sum_{i-1}^{k} d_i \leq k(k-1) + \sum_{i=k+1}^{n} \min(d_i, k)$ holds for every $1 \leq k \leq n$.

6.15.5 Gale–Ryser theorem

A pair of sequences of nonnegative integers $a_1 \geq \cdots \geq a_n$ and $b_1, \ldots, b_n$ is bigraphic if and only if $\sum_{i=1}^{n} a_i = \sum_{i=1}^{n} b_i$ and $\sum_{i=1}^{k} a_i \leq \sum_{i=1}^{n} \min(b_i, k)$ holds for every $1 \leq k \leq n$.

6.15.6 Fulkerson–Chen–Anstee theorem

A sequence $(a_1, b_1), \ldots, (a_n, b_n)$ of nonnegative integer pairs with $a_1 \geq \cdots \geq a_n$ is digraphic if and only if $\sum_{i=1}^{n} a_i = \sum_{i=1}^{n} b_i$ and $\sum_{i=1}^{k} a_i \leq \sum_{i=1}^{k} \min(b_i, k-1) + \sum_{i=k+1}^{n} \min(b_i, k)$ holds for every $1 \leq k \leq n$.

6.15.7 Pick's theorem

給定頂點座標均是整點（或正方形格子點）的簡單多邊形，皮克定理說明了其面積A和內部格點數目i、邊上格點數目b的關係：$A = i + \frac{b}{2} - 1$

6.16 Euclidean Algorithms

- $m = \lfloor \frac{an+b}{c} \rfloor$
- Time complexity: $O(\log n)$

$$f(a,b,c,n) = \sum_{i=0}^{n} \lfloor \frac{ai+b}{c} \rfloor$$
$$= \begin{cases} \lfloor \frac{a}{c} \rfloor \cdot \frac{n(n+1)}{2} + \lfloor \frac{b}{c} \rfloor \cdot (n+1) & \\ +f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm - f(c, c-b-1, a, m-1), & \text{otherwise} \end{cases}$$

$$g(a,b,c,n) = \sum_{i=0}^{n} i \lfloor \frac{ai+b}{c} \rfloor$$
$$= \begin{cases} \lfloor \frac{a}{c} \rfloor \cdot \frac{n(n+1)(2n+1)}{6} + \lfloor \frac{b}{c} \rfloor \cdot \frac{n(n+1)}{2} & \\ +g(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ \frac{1}{2} \cdot (n(n+1)m - f(c, c-b-1, a, m-1) & \\ -h(c, c-b-1, a, m-1)), & \text{otherwise} \end{cases}$$

$$h(a,b,c,n) = \sum_{i=0}^{n} \lfloor \frac{ai+b}{c} \rfloor^2$$
$$= \begin{cases} \lfloor \frac{a}{c} \rfloor^2 \cdot \frac{n(n+1)(2n+1)}{6} + \lfloor \frac{b}{c} \rfloor^2 \cdot (n+1) & \\ +\lfloor \frac{a}{c} \rfloor \cdot \lfloor \frac{b}{c} \rfloor \cdot n(n+1) & \\ +h(a \bmod c, b \bmod c, c, n) & \\ +2\lfloor \frac{a}{c} \rfloor \cdot g(a \bmod c, b \bmod c, c, n) & \\ +2\lfloor \frac{b}{c} \rfloor \cdot f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm(m+1) - 2g(c, c-b-1, a, m-1) & \\ -2f(c, c-b-1, a, m-1) - f(a, b, c, n), & \text{otherwise} \end{cases}$$

7 Polynomial

7.1 Fast Fourier Transform

```
template <int MAXN> struct FFT {
  using val_t = complex<double>;
  const double PI = acos(-1);
  val_t w[MAXN];
  FFT() {
    for (int i = 0; i < MAXN; ++i) {
      double arg = 2 * PI * i / MAXN;
      w[i] = val_t(cos(arg), sin(arg));
    }
  }
  void bitrev(val_t *a, int n);                    // see
       NTT
  void trans(val_t *a, int n, bool inv = false); // see
       NTT;
  // remember to replace LL with val_t
};
```

7.2 Number Theory Transform

```
//(2^16)+1, 65537, 3
// 7*17*(2^23)+1, 998244353, 3
// 1255*(2^20)+1, 1315962881, 3
// 51*(2^25)+1, 1711276033, 29
template <int MAXN, LL P, LL RT> // MAXN must be 2^k
struct NTT {
  LL w[MAXN];
  LL mpow(LL a, LL n);
  LL minv(LL a) { return mpow(a, P - 2); }
  NTT() {
    LL dw = mpow(RT, (P - 1) / MAXN);
    w[0] = 1;
    for (int i = 1; i < MAXN; ++i)
      w[i] = w[i - 1] * dw % P;
  }
  void bitrev(LL *a, int n) {
    int i = 0;
    for (int j = 1; j < n - 1; ++j) {
      for (int k = n >> 1; (i ^= k) < k; k >>= 1)
        ;
      if (j < i)
        swap(a[i], a[j]);
    }
  }
  void operator()(LL *a, int n, bool inv = false) { //
       0 <= a[i] < P
    bitrev(a, n);
    for (int L = 2; L <= n; L <<= 1) {
      int dx = MAXN / L, dl = L >> 1;
      for (int i = 0; i < n; i += L) {
        for (int j = i, x = 0; j < i + dl; ++j, x += dx
             ) {
          LL tmp = a[j + dl] * w[x] % P;
          if ((a[j + dl] = a[j] - tmp) < 0)
            a[j + dl] += P;
          if ((a[j] += tmp) >= P)
            a[j] -= P;
        }
      }
    }
    if (inv) {
      reverse(a + 1, a + n);
      LL invn = minv(n);
      for (int i = 0; i < n; ++i)
        a[i] = a[i] * invn % P;
    }
  }
};
```

7.3 Fast Walsh Transform*

```
/* x: a[j], y: a[j + (L >> 1)]
or: (y += x * op), and: (x += y * op)
xor: (x, y = (x + y) * op, (x - y) * op)
invop: or, and, xor = -1, -1, 1/2 */
void fwt(int *a, int n, int op) { // or
  for (int L = 2; L <= n; L <<= 1)
    for (int i = 0; i < n; i += L)
      for (int j = i; j < i + (L >> 1); ++j)
        a[j + (L >> 1)] += a[j] * op;
}
const int N = 21;
int f[N][1 << N], g[N][1 << N], h[N][1 << N], ct[1 << N
    ];
void subset_convolution(int *a, int *b, int *c, int L)
    {
  // c_k = \sum_{i | j = k, i & j = 0} a_i * b_j
  int n = 1 << L;
  for (int i = 1; i < n; ++i)
    ct[i] = ct[i & (i - 1)] + 1;
  for (int i = 0; i < n; ++i)
    f[ct[i]][i] = a[i], g[ct[i]][i] = b[i];
  for (int i = 0; i <= L; ++i)
    fwt(f[i], n, 1), fwt(g[i], n, 1);
  for (int i = 0; i <= L; ++i)
    for (int j = 0; j <= i; ++j)
      for (int x = 0; x < n; ++x)
        h[i][x] += f[j][x] * g[i - j][x];
  for (int i = 0; i <= L; ++i)
    fwt(h[i], n, -1);
  for (int i = 0; i < n; ++i)
    c[i] = h[ct[i]][i];
}
```

7.4 Newton's Method

Given $F(x)$ where

$$F(x) = \sum_{i=0}^{\infty} \alpha_i (x-\beta)^i$$

for β being some constant. Polynomial P such that $F(P) = 0$ can be found iteratively. Denote by Q_k the polynomial such that $F(Q_k) = 0 \pmod{x^{2^k}}$, then

$$Q_{k+1} = Q_k - \frac{F(Q_k)}{F'(Q_k)} \pmod{x^{2^{k+1}}}$$

8 Geometry

8.1 Default Code

```
typedef pair<double, double> pdd;
typedef pair<pdd, pdd> Line;
struct Cir {
  pdd O;
  double R;
};
const double eps = 1e-8;
pdd operator+(const pdd &a, const pdd &b) { return pdd(
    a.X + b.X, a.Y + b.Y); }
pdd operator-(const pdd &a, const pdd &b) { return pdd(
    a.X - b.X, a.Y - b.Y); }
pdd operator*(const pdd &a, const double &b) { return
    pdd(a.X * b, a.Y * b); }
pdd operator/(const pdd &a, const double &b) { return
    pdd(a.X / b, a.Y / b); }
double dot(const pdd &a, const pdd &b) { return a.X * b
    .X + a.Y * b.Y; }
double cross(const pdd &a, const pdd &b) { return a.X *
     b.Y - a.Y * b.X; }
double abs2(const pdd &a) { return dot(a, a); }
double abs(const pdd &a) { return sqrt(dot(a, a)); }
int sign(const double &a) { return fabs(a) < eps ? 0 :
    a > 0 ? 1 : -1; }
int ori(const pdd &a, const pdd &b, const pdd &c) {
  return sign(cross(b - a, c - a));
}
bool collinearity(const pdd &p1, const pdd &p2, const
    pdd &p3) {
  return fabs(cross(p1 - p3, p2 - p3)) < eps;
}
bool btw(const pdd &p1, const pdd &p2, const pdd &p3) {
  if (!collinearity(p1, p2, p3))
    return 0;
  return dot(p1 - p3, p2 - p3) < eps;
}
bool seg_intersect(const pdd &p1, const pdd &p2, const
    pdd &p3, const pdd &p4) {
  int a123 = ori(p1, p2, p3);
  int a124 = ori(p1, p2, p4);
  int a341 = ori(p3, p4, p1);
  int a342 = ori(p3, p4, p2);
  if (a123 == 0 && a124 == 0)
    return btw(p1, p2, p3) || btw(p1, p2, p4) || btw(p3
        , p4, p1) ||
           btw(p3, p4, p2);
  return a123 * a124 <= 0 && a341 * a342 <= 0;
}
pdd intersect(const pdd &p1, const pdd &p2, const pdd &
    p3, const pdd &p4) {
  double a123 = cross(p2 - p1, p3 - p1);
  double a124 = cross(p2 - p1, p4 - p1);
  return (p4 * a123 - p3 * a124) / (a123 - a124);
}
pdd perp(const pdd &p1) { return pdd(-p1.Y, p1.X); }
pdd foot(const pdd &p1, const pdd &p2, const pdd &p3) {
  return intersect(p1, p2, p3, p3 + perp(p2 - p1));
}
```

8.2 Convex hull*

```
void hull(vector<pll> &dots) {
  sort(dots.begin(), dots.end());
  vector<pll> ans(1, dots[0]);
  for (int ct = 0; ct < 2; ++ct, reverse(ALL(dots)))
    for (int i = 1, t = SZ(ans); i < SZ(dots); ans.pb(
        dots[i++]))
      while (SZ(ans) > t && ori(ans[SZ(ans) - 2], ans.
          back(), dots[i]) <= 0)
        ans.pop_back();
  ans.pop_back(), ans.swap(dots);
}
```

8.3 External bisector

```
pdd external_bisector(pdd p1, pdd p2, pdd p3) { // 213
  pdd L1 = p2 - p1, L2 = p3 - p1;
  L2 = L2 * abs(L1) / abs(L2);
  return L1 + L2;
}
```

8.4 Heart

```
pdd excenter(pdd p0, pdd p1, pdd p2, double &radius) {
  p1 = p1 - p0, p2 = p2 - p0;
  double x1 = p1.X, y1 = p1.Y, x2 = p2.X, y2 = p2.Y;
  double m = 2. * (x1 * y2 - y1 * x2);
  center.X = (x1 * x1 * y2 - x2 * x2 * y1 + y1 * y2 * (
      y1 - y2)) / m;
  center.Y = (x1 * x2 * (x2 - x1) - y1 * y1 * x2 + x1 *
       y2 * y2) / m;
  return radius = abs(center), center + p0;
}

pdd incenter(pdd p1, pdd p2, pdd p3, double &radius) {
  double a = abs(p2 - p1), b = abs(p3 - p1), c = abs(p3
      - p2);
  double s = (a + b + c) / 2, area = sqrt(s * (s - a) *
       (s - b) * (s - c));
  pdd L1 = external_bisector(p1, p2, p3), L2 =
      external_bisector(p2, p1, p3);
  return radius = area / s, intersect(p1, p1 + L1, p2,
      p2 + L2),
}

pdd escenter(pdd p1, pdd p2, pdd p3) { // 213
  pdd L1 = external_bisector(p1, p2, p3),
      L2 = external_bisector(p2, p2 + p2 - p1, p3);
  return intersect(p1, p1 + L1, p2, p2 + L2);
}

pdd barycenter(pdd p1, pdd p2, pdd p3) { return (p1 +
    p2 + p3) / 3; }

pdd orthocenter(pdd p1, pdd p2, pdd p3) {
  pdd L1 = p3 - p2, L2 = p3 - p1;
  swap(L1.X, L1.Y), L1.X *= -1;
  swap(L2, X, L2.Y), L2.X *= -1;
  return intersect(p1, p1 + L1, p2, p2 + L2);
}
```

8.5 Minimum Enclosing Circle*

```
pdd Minimum_Enclosing_Circle(vector<pdd> dots, double &
    r) {
  pdd cent;
  random_shuffle(ALL(dots));
  cent = dots[0], r = 0;
  for (int i = 1; i < SZ(dots); ++i)
    if (abs(dots[i] - cent) > r) {
      cent = dots[i], r = 0;
      for (int j = 0; j < i; ++j)
        if (abs(dots[j] - cent) > r) {
          cent = (dots[i] + dots[j]) / 2;
          r = abs(dots[i] - cent);
          for (int k = 0; k < j; ++k)
            if (abs(dots[k] - cent) > r)
              cent = excenter(dots[i], dots[j], dots[k
                  ], r);
        }
    }
  return cent;
}
```

8.6 Polar Angle Sort*

```
pdd center; // sort base
int Quadrant(pdd a) {
  if (a.X > 0 && a.Y >= 0)
    return 1;
  if (a.X <= 0 && a.Y > 0)
```

```
    return 2;
  if (a.X < 0 && a.Y <= 0)
    return 3;
  if (a.X >= 0 && a.Y < 0)
    return 4;
}
bool cmp(pll a, pll b) {
  a = a - center, b = b - center;
  if (Quadrant(a) != Quadrant(b))
    return Quadrant(a) < Quadrant(b);
  if (cross(b, a) == 0)
    return abs2(a) < abs2(b);
  return cross(a, b) > 0;
}
bool cmp(pdd a, pdd b) {
  a = a - center, b = b - center;
  if (fabs(atan2(a.Y, a.X) - atan2(b.Y, b.X)) > eps)
    return atan2(a.Y, a.X) < atan2(b.Y, b.X);
  return abs(a) < abs(b);
}
```

8.7 Intersection of two circles*

```
bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
  pdd o1 = a.O, o2 = b.O;
  double r1 = a.R, r2 = b.R, d2 = abs2(o1 - o2), d =
      sqrt(d2);
  if (d < max(r1, r2) - min(r1, r2) || d > r1 + r2)
    return 0;
  pdd u = (o1 + o2) * 0.5 + (o1 - o2) * ((r2 * r2 - r1
      * r1) / (2 * d2));
  double A =
      sqrt((r1 + r2 + d) * (r1 - r2 + d) * (r1 + r2 - d
          ) * (-r1 + r2 + d));
  pdd v = pdd(o1.Y - o2.Y, -o1.X + o2.X) * A / (2 * d2)
      ;
  p1 = u + v, p2 = u - v;
  return 1;
}
```

8.8 Intersection of polygon and circle

```
// Divides into multiple triangle, and sum up
// test by HDU2892
const double PI = acos(-1);
double _area(pdd pa, pdd pb, double r) {
  if (abs(pa) < abs(pb))
    swap(pa, pb);
  if (abs(pb) < eps)
    return 0;
  double S, h, theta;
  double a = abs(pb), b = abs(pa), c = abs(pb - pa);
  double cosB = dot(pb, pb - pa) / a / c, B = acos(cosB
      );
  double cosC = dot(pa, pb) / a / b, C = acos(cosC);
  if (a > r) {
    S = (C / 2) * r * r;
    h = a * b * sin(C) / c;
    if (h < r && B < PI / 2)
      S -= (acos(h / r) * r * r - h * sqrt(r * r - h *
          h));
  } else if (b > r) {
    theta = PI - B - asin(sin(B) / r * a);
    S = .5 * a * r * sin(theta) + (C - theta) / 2 * r *
        r;
  } else
    S = .5 * sin(C) * a * b;
  return S;
}
double area_poly_circle(const vector<pdd> poly, const
    pdd &O, const double r) {
  double S = 0;
  for (int i = 0; i < SZ(poly); ++i)
    S += _area(poly[i] - O, poly[(i + 1) % SZ(poly)] -
        O, r) *
         ori(O, poly[i], poly[(i + 1) % SZ(poly)]);
  return fabs(S);
}
```

8.9 Intersection of line and circle

```
vector<pdd> line_interCircle(const pdd &p1, const pdd &
    p2, const pdd &c,
                             const double r) {
  pdd ft = foot(p1, p2, c), vec = p2 - p1;
  double dis = abs(c - ft);
  if (fabs(dis - r) < eps)
    return vector<pdd>{ft};
  if (dis > r)
    return {};
  vec = vec * sqrt(r * r - dis * dis) / abs(vec);
  return vector<pdd>{ft + vec, ft - vec};
}
```

8.10 point in circle

```
// return p4 is strictly in circumcircle of tri(p1,p2,
    p3)
long long sqr(long long x) { return x * x; }
bool in_cc(const pll &p1, const pll &p2, const pll &p3,
     const pll &p4) {
  long long u11 = p1.X - p4.X;
  long long u12 = p1.Y - p4.Y;
  long long u21 = p2.X - p4.X;
  long long u22 = p2.Y - p4.Y;
  long long u31 = p3.X - p4.X;
  long long u32 = p3.Y - p4.Y;
  long long u13 = sqr(p1.X) - sqr(p4.X) + sqr(p1.Y) -
      sqr(p4.Y);
  long long u23 = sqr(p2.X) - sqr(p4.X) + sqr(p2.Y) -
      sqr(p4.Y);
  long long u33 = sqr(p3.X) - sqr(p4.X) + sqr(p3.Y) -
      sqr(p4.Y);
  __int128 det = (__int128)-u13 * u22 * u31 + (__int128
      )u12 * u23 * u31 +
                 (__int128)u13 * u21 * u32 - (__int128)
                     u11 * u23 * u32 -
                 (__int128)u12 * u21 * u33 + (__int128)
                     u11 * u22 * u33;
  return det > eps;
}
```

8.11 Half plane intersection

```
bool isin(Line l0, Line l1, Line l2) {
  // Check inter(l1, l2) in l0
  pdd p = intersect(l1.X, l1.Y, l2.X, l2.Y);
  return cross(l0.Y - l0.X, p - l0.X) > eps;
}
/* If no solution, check: 1. ret.size() < 3
 * Or more precisely, 2. interPnt(ret[0], ret[1])
 * in all the lines. (use (l.Y - l.X) ^ (p - l.X) > 0
 */
/* --^-- Line.X --^-- Line.Y --^-- */
vector<Line> halfPlaneInter(vector<Line> lines) {
  int sz = lines.size();
  vector<double> ata(sz), ord(sz);
  for (int i = 0; i < sz; ++i) {
    ord[i] = i;
    pdd d = lines[i].Y - lines[i].X;
    ata[i] = atan2(d.Y, d.X);
  }
  sort(ord.begin(), ord.end(), [&](int i, int j) {
    if (fabs(ata[i] - ata[j]) < eps)
      return (cross(lines[i].Y - lines[i].X, lines[j].Y
          - lines[i].X)) < 0;
    return ata[i] < ata[j];
  });
  vector<Line> fin;
  for (int i = 0; i < sz; ++i)
    if (!i || fabs(ata[ord[i]] - ata[ord[i - 1]]) > eps
        )
      fin.pb(lines[ord[i]]);
  deque<Line> dq;
  for (int i = 0; i < SZ(fin); i++) {
    while (SZ(dq) >= 2 && !isin(fin[i], dq[SZ(dq) - 2],
        dq.back()))
      dq.pop_back();
    while (SZ(dq) >= 2 && !isin(fin[i], dq[0], dq[1]))
      dq.pop_front();
    dq.push_back(fin[i]);
  }
```

```
  while (SZ(dq) >= 3 && !isin(dq[0], dq[SZ(dq) - 2], dq
      .back()))
    dq.pop_back();
  while (SZ(dq) >= 3 && !isin(dq.back(), dq[0], dq[1]))
    dq.pop_front();
  vector<Line> res(ALL(dq));
  return res;
}
```

8.12 CircleCover*

```
const int N = 1021;
struct CircleCover {
  int C;
  Cir c[N];
  bool g[N][N], overlap[N][N];
  // Area[i] : area covered by at least i circles
  double Area[N];
  void init(int _C) { C = _C; }
  struct Teve {
    pdd p;
    double ang;
    int add;
    Teve() {}
    Teve(pdd _a, double _b, int _c) : p(_a), ang(_b),
        add(_c) {}
    bool operator<(const Teve &a) const { return ang <
        a.ang; }
  } eve[N * 2];
  // strict: x = 0, otherwise x = -1
  bool disjuct(Cir &a, Cir &b, int x) {
    return sign(abs(a.O - b.O) - a.R - b.R) > x;
  }
  bool contain(Cir &a, Cir &b, int x) {
    return sign(a.R - b.R - abs(a.O - b.O)) > x;
  }
  bool contain(int i, int j) {
    /* c[j] is non-strictly in c[i]. */
    return (sign(c[i].R - c[j].R) > 0 ||
            (sign(c[i].R - c[j].R) == 0 && i < j)) &&
           contain(c[i], c[j], -1);
  }
  void solve() {
    fill_n(Area, C + 2, 0);
    for (int i = 0; i < C; ++i)
      for (int j = 0; j < C; ++j)
        overlap[i][j] = contain(i, j);
    for (int i = 0; i < C; ++i)
      for (int j = 0; j < C; ++j)
        g[i][j] = !(overlap[i][j] || overlap[j][i] ||
            disjuct(c[i], c[j], -1));
    for (int i = 0; i < C; ++i) {
      int E = 0, cnt = 1;
      for (int j = 0; j < C; ++j)
        if (j != i && overlap[j][i])
          ++cnt;
      for (int j = 0; j < C; ++j)
        if (i != j && g[i][j]) {
          pdd aa, bb;
          CCinter(c[i], c[j], aa, bb);
          double A = atan2(aa.Y - c[i].O.Y, aa.X - c[i
              ].O.X);
          double B = atan2(bb.Y - c[i].O.Y, bb.X - c[i
              ].O.X);
          eve[E++] = Teve(bb, B, 1), eve[E++] = Teve(aa
              , A, -1);
          if (B > A)
            ++cnt;
        }
      if (E == 0)
        Area[cnt] += pi * c[i].R * c[i].R;
      else {
        sort(eve, eve + E);
        eve[E] = eve[0];
        for (int j = 0; j < E; ++j) {
          cnt += eve[j].add;
          Area[cnt] += cross(eve[j].p, eve[j + 1].p) *
              .5;
          double theta = eve[j + 1].ang - eve[j].ang;
          if (theta < 0)
            theta += 2. * pi;
          Area[cnt] += (theta - sin(theta)) * c[i].R *
              c[i].R * .5;
        }
      }
    }
  }
};
```

8.13 3Dpoint*

```
struct Point {
  double x, y, z;
  Point(double _x = 0, double _y = 0, double _z = 0) :
      x(_x), y(_y), z(_z) {}
  Point(pdd p) { x = p.X, y = p.Y, z = abs2(p); }
};
Point operator-(const Point &p1, const Point &p2) {
  return Point(p1.x - p2.x, p1.y - p2.y, p1.z - p2.z);
}
Point cross(const Point &p1, const Point &p2) {
  return Point(p1.y * p2.z - p1.z * p2.y, p1.z * p2.x -
       p1.x * p2.z,
               p1.x * p2.y - p1.y * p2.x);
}
double dot(const Point &p1, const Point &p2) {
  return p1.x * p2.x + p1.y * p2.y + p1.z * p2.z;
}
double abs(const Point &a) { return sqrt(dot(a, a)); }
Point cross3(const Point &a, const Point &b, const
    Point &c) {
  return cross(b - a, c - a);
}
double area(Point a, Point b, Point c) { return abs(
    cross3(a, b, c)); }
double volume(Point a, Point b, Point c, Point d) {
  return dot(cross3(a, b, c), d - a);
}
pdd proj(Point a, Point b, Point c, Point u) {
  // proj. u to the plane of a, b, and c
  Point e1 = b - a;
  Point e2 = c - a;
  e1 = e1 / abs(e1);
  e2 = e2 - e1 * dot(e2, e1);
  e2 = e2 / abs(e2);
  Point p = u - a;
  return pdd(dot(p, e1), dot(p, e2));
}
```

8.14 Convexhull3D*

```
struct CH3D {
  struct face {
    int a, b, c;
    bool ok;
  } F[8 * N];
  double dblcmp(Point &p, face &f) {
    return dot(cross3(P[f.a], P[f.b], P[f.c]), p - P[f.
        a]);
  }
  int g[N][N], num, n;
  Point P[N];
  void deal(int p, int a, int b) {
    int f = g[a][b];
    face add;
    if (F[f].ok) {
      if (dblcmp(P[p], F[f]) > eps)
        dfs(p, f);
      else
        add.a = b, add.b = a, add.c = p, add.ok = 1,
        g[p][b] = g[a][p] = g[b][a] = num, F[num++] =
            add;
    }
  }
  void dfs(int p, int now) {
    F[now].ok = 0;
    deal(p, F[now].b, F[now].a), deal(p, F[now].c, F[
        now].b),
        deal(p, F[now].a, F[now].c);
  }
  bool same(int s, int t) {
    Point &a = P[F[s].a];
    Point &b = P[F[s].b];
    Point &c = P[F[s].c];
```

```
    return fabs(volume(a, b, c, P[F[t].a])) < eps &&
           fabs(volume(a, b, c, P[F[t].b])) < eps &&
           fabs(volume(a, b, c, P[F[t].c])) < eps;
  }
  void init(int _n) { n = _n, num = 0; }
  void solve() {
    face add;
    num = 0;
    if (n < 4)
      return;
    if ([&]() {
          for (int i = 1; i < n; ++i)
            if (abs(P[0] - P[i]) > eps)
              return swap(P[1], P[i]), 0;
          return 1;
        }() ||
        [&]() {
          for (int i = 2; i < n; ++i)
            if (abs(cross3(P[i], P[0], P[1])) > eps)
              return swap(P[2], P[i]), 0;
          return 1;
        }() ||
        [&]() {
          for (int i = 3; i < n; ++i)
            if (fabs(dot(cross(P[0] - P[1], P[1] - P
                [2]), P[0] - P[i])) > eps)
              return swap(P[3], P[i]), 0;
          return 1;
        }())
      return;
    for (int i = 0; i < 4; ++i) {
      add.a = (i + 1) % 4, add.b = (i + 2) % 4, add.c =
          (i + 3) % 4,
      add.ok = true;
      if (dblcmp(P[i], add) > 0)
        swap(add.b, add.c);
      g[add.a][add.b] = g[add.b][add.c] = g[add.c][add.
          a] = num;
      F[num++] = add;
    }
    for (int i = 4; i < n; ++i)
      for (int j = 0; j < num; ++j)
        if (F[j].ok && dblcmp(P[i], F[j]) > eps) {
          dfs(i, j);
          break;
        }
    for (int tmp = num, i = (num = 0); i < tmp; ++i)
      if (F[i].ok)
        F[num++] = F[i];
  }
  double get_area() {
    double res = 0.0;
    if (n == 3)
      return abs(cross3(P[0], P[1], P[2])) / 2.0;
    for (int i = 0; i < num; ++i)
      res += area(P[F[i].a], P[F[i].b], P[F[i].c]);
    return res / 2.0;
  }
  double get_volume() {
    double res = 0.0;
    for (int i = 0; i < num; ++i)
      res += volume(Point(0, 0, 0), P[F[i].a], P[F[i].b
          ], P[F[i].c]);
    return fabs(res / 6.0);
  }
  int triangle() { return num; }
  int polygon() {
    int res = 0;
    for (int i = 0, flag = 1; i < num; ++i, res += flag
        , flag = 1)
      for (int j = 0; j < i && flag; ++j)
        flag &= !same(i, j);
    return res;
  }
  Point getcent() {
    Point ans(0, 0, 0), temp = P[F[0].a];
    double v = 0.0, t2;
    for (int i = 0; i < num; ++i)
      if (F[i].ok == true) {
        Point p1 = P[F[i].a], p2 = P[F[i].b], p3 = P[F[
            i].c];
        t2 = volume(temp, p1, p2, p3) / 6.0;
        if (t2 > 0)
          ans.x += (p1.x + p2.x + p3.x + temp.x) * t2,
              ans.y += (p1.y + p2.y + p3.y + temp.y) *
                  t2,
              ans.z += (p1.z + p2.z + p3.z + temp.z) *
                  t2, v += t2;
      }
    ans.x /= (4 * v), ans.y /= (4 * v), ans.z /= (4 * v
        );
    return ans;
  }
  double pointmindis(Point p) {
    double rt = 99999999;
    for (int i = 0; i < num; ++i)
      if (F[i].ok == true) {
        Point p1 = P[F[i].a], p2 = P[F[i].b], p3 = P[F[
            i].c];
        double a =
            (p2.y - p1.y) * (p3.z - p1.z) - (p2.z - p1.
                z) * (p3.y - p1.y);
        double b =
            (p2.z - p1.z) * (p3.x - p1.x) - (p2.x - p1.
                x) * (p3.z - p1.z);
        double c =
            (p2.x - p1.x) * (p3.y - p1.y) - (p2.y - p1.
                y) * (p3.x - p1.x);
        double d = 0 - (a * p1.x + b * p1.y + c * p1.z)
            ;
        double temp =
            fabs(a * p.x + b * p.y + c * p.z + d) /
                sqrt(a * a + b * b + c * c);
        rt = min(rt, temp);
      }
    return rt;
  }
};
```

8.15 Tangent line of two circles

```
vector<Line> go(const Cir &c1, const Cir &c2, int sign1
    ) {
  // sign1 = 1 for outer tang, -1 for inter tang
  vector<Line> ret;
  double d_sq = norm2(c1.O - c2.O);
  if (d_sq < eps)
    return ret;
  double d = sqrt(d_sq);
  Pt v = (c2.O - c1.O) / d;
  double c = (c1.R - sign1 * c2.R) / d;
  if (c * c > 1)
    return ret;
  double h = sqrt(max(0.0, 1.0 - c * c));
  for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
    Pt n = {v.X * c - sign2 * h * v.Y, v.Y * c + sign2
        * h * v.X};
    Pt p1 = c1.O + n * c1.R;
    Pt p2 = c2.O + n * (c2.R * sign1);
    if (fabs(p1.X - p2.X) < eps and fabs(p1.Y - p2.Y) <
        eps)
      p2 = p1 + perp(c2.O - c1.O);
    ret.push_back({p1, p2});
  }
  return ret;
}
```

8.16 minMaxEnclosingRectangle

```
pdd solve(vector<pll> &dots) {
  vector<pll> hull;
  const double INF = 1e18, qi = acos(-1) / 2 * 3;
  cv.dots = dots;
  hull = cv.hull();
  double Max = 0, Min = INF, deg;
  ll n = hull.size();
  hull.pb(hull[0]);
  for (int i = 0, u = 1, r = 1, l; i < n; ++i) {
    pll nw = hull[i + 1] - hull[i];
    while (cross(nw, hull[u + 1] - hull[i]) > cross(nw,
        hull[u] - hull[i]))
      u = (u + 1) % n;
    while (dot(nw, hull[r + 1] - hull[i]) > dot(nw,
        hull[r] - hull[i]))
```

```
      r = (r + 1) % n;
    if (!i)
      l = (r + 1) % n;
    while (dot(nw, hull[l + 1] - hull[i]) < dot(nw,
        hull[l] - hull[i]))
      l = (l + 1) % n;
    Min = min(
        Min, (double)(dot(nw, hull[r] - hull[i]) - dot(
            nw, hull[l] - hull[i])) *
                 cross(nw, hull[u] - hull[i]) / abs2(nw
                     ));
    deg = acos((double)dot(hull[r] - hull[l], hull[u] -
         hull[i]) /
               abs(hull[r] - hull[l]) / abs(hull[u] -
                   hull[i]));
    deg = (qi - deg) / 2;
    Max = max(Max, (double)abs(hull[r] - hull[l]) * abs
        (hull[u] - hull[i]) *
                     sin(deg) * sin(deg));
  }
  return pdd(Min, Max);
}
```

8.17 minDistOfTwoConvex

```
// p, q is convex
double TwoConvexHullMinDist(Point P[], Point Q[], int n
    , int m) {
  int YMinP = 0, YMaxQ = 0;
  double tmp, ans = 999999999;
  for (i = 0; i < n; ++i)
    if (P[i].y < P[YMinP].y)
      YMinP = i;
  for (i = 0; i < m; ++i)
    if (Q[i].y > Q[YMaxQ].y)
      YMaxQ = i;
  P[n] = P[0], Q[m] = Q[0];
  for (int i = 0; i < n; ++i) {
    while (tmp = Cross(Q[YMaxQ + 1] - P[YMinP + 1], P[
        YMinP] - P[YMinP + 1]) >
                 Cross(Q[YMaxQ] - P[YMinP + 1], P[YMinP
                     ] - P[YMinP + 1]))
      YMaxQ = (YMaxQ + 1) % m;
    if (tmp < 0)
      ans = min(ans, PointToSegDist(P[YMinP], P[YMinP +
          1], Q[YMaxQ]));
    else
      ans = min(ans,
                TwoSegMinDist(P[YMinP], P[YMinP + 1], Q
                    [YMaxQ], Q[YMaxQ + 1]));
    YMinP = (YMinP + 1) % n;
  }
  return ans;
}
```

8.18 Minkowski Sum*

```
vector<pll> Minkowski(vector<pll> A, vector<pll> B) {
  hull(A), hull(B);
  vector<pll> C(1, A[0] + B[0]), s1, s2;
  for (int i = 0; i < SZ(A); ++i)
    s1.pb(A[(i + 1) % SZ(A)] - A[i]);
  for (int i = 0; i < SZ(B); i++)
    s2.pb(B[(i + 1) % SZ(B)] - B[i]);
  for (int p1 = 0, p2 = 0; p1 < SZ(A) || p2 < SZ(B);)
    if (p2 >= SZ(B) || (p1 < SZ(A) && cross(s1[p1], s2[
        p2]) >= 0))
      C.pb(C.back() + s1[p1++]);
    else
      C.pb(C.back() + s2[p2++]);
  return hull(C), C;
}
```

8.19 RotatingSweepLine

```
void rotatingSweepLine(vector<pii> &ps) {
  int n = SZ(ps);
  vector<int> id(n), pos(n);
  vector<pii> line(n * (n - 1) / 2);
  int m = 0;
  for (int i = 0; i < n; ++i)
    for (int j = i + 1; j < n; ++j)
      line[m++] = pii(i, j);
  sort(ALL(line), [&](const pii &a, const pii &b) ->
      bool {
    if (ps[a.X].X == ps[a.Y].X)
      return 0;
    if (ps[b.X].X == ps[b.Y].X)
      return 1;
    return (double)(ps[a.X].Y - ps[a.Y].Y) / (ps[a.X].X
        - ps[a.Y].X) <
           (double)(ps[b.X].Y - ps[b.Y].Y) / (ps[b.X].X
               - ps[b.Y].X);
  });
  iota(id, id + n, 0);
  sort(ALL(id), [&](const int &a, const int &b) {
      return ps[a] < ps[b]; });
  for (int i = 0; i < n; ++i)
    pos[id[i]] = i;
  for (int i = 0; i < m; ++i) {
    auto l = line[i];
    // meow
    tie(pos[l.X], pos[l.Y], id[pos[l.X]], id[pos[l.Y]])
        =
        make_tuple(pos[l.Y], pos[l.X], l.Y, l.X);
  }
}
```

9 Else

9.1 Mo's Alogrithm(With modification)

```
struct QUERY { // BLOCK=N^{2/3}
  int L, R, id, LBid, RBid, T;
  QUERY(int l, int r, int id, int lb, int rb, int t)
      : L(l), R(r), id(id), LBid(lb), RBid(rb), T(t) {}
  bool operator<(const QUERY &b) const {
    if (LBid != b.LBid)
      return LBid < b.LBid;
    if (RBid != b.RBid)
      return RBid < b.RBid;
    return T < b.T;
  }
};
vector<QUERY> query;
int cur_ans, arr[MAXN], ans[MAXN];
void addTime(int L, int R, int T) {}
void subTime(int L, int R, int T) {}
void add(int x) {}
void sub(int x) {}
void solve() {
  sort(ALL(query));
  int L = 0, R = 0, T = -1;
  for (auto q : query) {
    while (T < q.T)
      addTime(L, R, ++T);
    while (T > q.T)
      subTime(L, R, T--);
    while (R < q.R)
      add(arr[++R]);
    while (L > q.L)
      add(arr[--L]);
    while (R > q.R)
      sub(arr[R--]);
    while (L < q.L)
      sub(arr[L++]);
    ans[q.id] = cur_ans;
  }
}
```

9.2 Mo's Alogrithm On Tree

```
const int MAXN = 40005;
vector<int> G[MAXN]; // 1-base
int n, B, arr[MAXN], ans[100005], cur_ans;
int in[MAXN], out[MAXN], dfn[MAXN * 2], dft;
int deep[MAXN], sp[__lg(MAXN * 2) + 1][MAXN * 2], bln[
    MAXN], spt;
bitset<MAXN> inset;
struct QUERY {
  int L, R, Lid, id, lca;
  QUERY(int l, int r, int _id) : L(l), R(r), lca(0), id
      (_id) {}
  bool operator<(const QUERY &b) {
```

```
    if (Lid != b.Lid)
      return Lid < b.Lid;
    return R < b.R;
  }
};
vector<QUERY> query;
void dfs(int u, int f, int d) {
  deep[u] = d, sp[0][spt] = u, bln[u] = spt++;
  dfn[dft] = u, in[u] = dft++;
  for (int v : G[u])
    if (v != f)
      dfs(v, u, d + 1), sp[0][spt] = u, bln[u] = spt++;
  dfn[dft] = u, out[u] = dft++;
}
int lca(int u, int v) {
  if (bln[u] > bln[v])
    swap(u, v);
  int t = __lg(bln[v] - bln[u] + 1);
  int a = sp[t][bln[u]], b = sp[t][bln[v] - (1 << t) +
      1];
  if (deep[a] < deep[b])
    return a;
  return b;
}
void sub(int x) {}
void add(int x) {}
void flip(int x) {
  if (inset[x])
    sub(arr[x]);
  else
    add(arr[x]);
  inset[x] = ~inset[x];
}
void solve() {
  B = sqrt(2 * n), dft = spt = cur_ans = 0, dfs(1, 1,
      0);
  for (int i = 1, x = 2; x < 2 * n; ++i, x <<= 1)
    for (int j = 0; j + x <= 2 * n; ++j)
      if (deep[sp[i - 1][j]] < deep[sp[i - 1][j + x /
          2]])
        sp[i][j] = sp[i - 1][j];
      else
        sp[i][j] = sp[i - 1][j + x / 2];
  for (auto &q : query) {
    int c = lca(q.L, q.R);
    if (c == q.L || c == q.R)
      q.L = out[c == q.L ? q.R : q.L], q.R = out[c];
    else if (out[q.L] < in[q.R])
      q.lca = c, q.L = out[q.L], q.R = in[q.R];
    else
      q.lca = c, c = in[q.L], q.L = out[q.R], q.R = c;
    q.Lid = q.L / B;
  }
  sort(ALL(query));
  int L = 0, R = -1;
  for (auto q : query) {
    while (R < q.R)
      flip(dfn[++R]);
    while (L > q.L)
      flip(dfn[--L]);
    while (R > q.R)
      flip(dfn[R--]);
    while (L < q.L)
      flip(dfn[L++]);
    if (q.lca)
      add(arr[q.lca]);
    ans[q.id] = cur_ans;
    if (q.lca)
      sub(arr[q.lca]);
  }
}
```

9.3 DynamicConvexTrick*

```
// only works for integer coordinates!!
struct Line {
  mutable ll a, b, p;
  bool operator<(const Line &rhs) const { return a <
      rhs.a; }
  bool operator<(ll x) const { return p < x; }
};
struct DynamicHull : multiset<Line, less<>> {
  static const ll kInf = 1e18;
  ll Div(ll a, ll b) { return a / b - ((a ^ b) < 0 && a
       % b); }
  bool isect(iterator x, iterator y) {
    if (y == end()) {
      x->p = kInf;
      return 0;
    }
    if (x->a == y->a)
      x->p = x->b > y->b ? kInf : -kInf;
    else
      x->p = Div(y->b - x->b, x->a - y->a);
    return x->p >= y->p;
  }
  void addline(ll a, ll b) {
    auto z = insert({a, b, 0}), y = z++, x = y;
    while (isect(y, z))
      z = erase(z);
    if (x != begin() && isect(--x, y))
      isect(x, y = erase(y));
    while ((y = x) != begin() && (--x)->p >= y->p)
      isect(x, erase(y));
  }
  ll query(ll x) {
    auto l = *lower_bound(x);
    return l.a * x + l.b;
  }
};
```

9.4 DLX*

```
#define TRAV(i, link, start) for (int i = link[start];
    i != start; i = link[i])
template <bool A, bool B = !A> // A: Exact
struct DLX {
  int lt[NN], rg[NN], up[NN], dn[NN], cl[NN], rw[NN],
      bt[NN], s[NN], head, sz,
      ans;
  int columns;
  bool vis[NN];
  void remove(int c) {
    if (A)
      lt[rg[c]] = lt[c], rg[lt[c]] = rg[c];
    TRAV(i, dn, c) {
      if (A) {
        TRAV(j, rg, i)
        up[dn[j]] = up[j], dn[up[j]] = dn[j], --s[cl[j
            ]];
      } else {
        lt[rg[i]] = lt[i], rg[lt[i]] = rg[i];
      }
    }
  }
  void restore(int c) {
    TRAV(i, up, c) {
      if (A) {
        TRAV(j, lt, i)
        ++s[cl[j]], up[dn[j]] = j, dn[up[j]] = j;
      } else {
        lt[rg[i]] = rg[lt[i]] = i;
      }
    }
    if (A)
      lt[rg[c]] = c, rg[lt[c]] = c;
  }
  void init(int c) {
    columns = c;
    for (int i = 0; i < c; ++i) {
      up[i] = dn[i] = bt[i] = i;
      lt[i] = i == 0 ? c : i - 1;
      rg[i] = i == c - 1 ? c : i + 1;
      s[i] = 0;
    }
    rg[c] = 0, lt[c] = c - 1;
    up[c] = dn[c] = -1;
    head = c, sz = c + 1;
  }
  void insert(int r, const vector<int> &col) {
    if (col.empty())
      return;
    int f = sz;
    for (int i = 0; i < (int)col.size(); ++i) {
```

```
      int c = col[i], v = sz++;
      dn[bt[c]] = v;
      up[v] = bt[c], bt[c] = v;
      rg[v] = (i + 1 == (int)col.size() ? f : v + 1);
      rw[v] = r, cl[v] = c;
      ++s[c];
      if (i > 0)
        lt[v] = v - 1;
    }
    lt[f] = sz - 1;
  }
  int h() {
    int ret = 0;
    memset(vis, 0, sizeof(bool) * sz);
    TRAV(x, rg, head) {
      if (vis[x])
        continue;
      vis[x] = true, ++ret;
      TRAV(i, dn, x) TRAV(j, rg, i) vis[cl[j]] = true;
    }
    return ret;
  }
  void dfs(int dep) {
    if (dep + (A ? 0 : h()) >= ans)
      return;
    if (rg[head] == head)
      return ans = dep, void();
    if (dn[rg[head]] == rg[head])
      return;
    int w = rg[head];
    TRAV(x, rg, head) if (s[x] < s[w]) w = x;
    if (A)
      remove(w);
    TRAV(i, dn, w) {
      if (B)
        remove(i);
      TRAV(j, rg, i) remove(A ? cl[j] : j);
      dfs(dep + 1);
      TRAV(j, lt, i) restore(A ? cl[j] : j);
      if (B)
        restore(i);
    }
    if (A)
      restore(w);
  }
  int solve() {
    for (int i = 0; i < columns; ++i)
      dn[bt[i]] = i, up[i] = bt[i];
    ans = 1e9, dfs(0);
    return ans;
  }
};
```

9.5 Matroid Intersection

Start from $S = \emptyset$. In each iteration, let

- $Y_1 = \{x \notin S \mid S \cup \{x\} \in I_1\}$
- $Y_2 = \{x \notin S \mid S \cup \{x\} \in I_2\}$

If there exists $x \in Y_1 \cap Y_2$, insert x into S. Otherwise for each $x \in S, y \notin S$, create edges

- $x \to y$ if $S - \{x\} \cup \{y\} \in I_1$.
- $y \to x$ if $S - \{x\} \cup \{y\} \in I_2$.

Find a shortest path (with BFS) starting from a vertex in Y_1 and ending at a vertex in Y_2 which doesn't pass through any other vertices in Y_2, and alternate the path. The size of S will be incremented by 1 in each iteration. For the weighted case, assign weight $w(x)$ to vertex x if $x \in S$ and $-w(x)$ if $x \notin S$. Find the path with the minimum number of edges among all minimum length paths and alternate it.

9.6 AdaptiveSimpson

```
using F_t = function<double(double)>;
pdd simpson(const F_t &f, double l, double r, double fl
    , double fr,
            double fm = nan("")) {
  if (isnan(fm))
    fm = f((l + r) / 2);
  return {fm, (r - l) / 6 * (fl + 4 * fm + fr)};
}
double simpson_ada(const F_t &f, double l, double r,
    double fl, double fm,
                   double fr, double eps) {
  double m = (l + r) / 2, s = simpson(f, l, r, fl, fr,
      fm).second;
  auto [flm, sl] = simpson(f, l, m, fl, fm);
  auto [fmr, sr] = simpson(f, m, r, fm, fr);
  double delta = sl + sr - s;
  if (abs(delta) <= 15 * eps)
    return sl + sr + delta / 15;
  return simpson_ada(f, l, m, fl, flm, fm, eps / 2) +
         simpson_ada(f, m, r, fm, fmr, fr, eps / 2);
}
double simpson_ada(const F_t &f, double l, double r) {
  return simpson_ada(f, l, r, f(l), f((l + r) / 2), f(r
      ), 1e-9 / 7122);
}
double simpson_ada2(const F_t &f, double l, double r) {
  double h = (r - l) / 7122, s = 0;
  for (int i = 0; i < 7122; ++i, l += h)
    s += simpson_ada(f, l, l + h);
  return s;
}
```

9.7 Closest Pair

```
pair<double, double> p[50007], t[50007];
double solve(int l, int r) {
  if (l == r)
    return INF;
  int mid = (l + r) >> 1;
  double x = p[mid].first;
  double d = min(solve(l, mid), solve(mid + 1, r));
  int i = l, j = mid + 1, id = l;
  while (i <= mid || j <= r) {
    if (i <= mid && (j > r || p[i].second < p[j].second
        ))
      t[id++] = p[i++];
    else
      t[id++] = p[j++];
  }
  for (int i = l; i <= r; i++)
    p[i] = t[i];
  vector<pair<double, double>> v;
  for (int i = l; i <= r; i++)
    if (abs(p[i].first - x) < d)
      v.push_back(p[i]);
  for (int i = 0; i < v.size(); i++) {
    for (int j = i + 1; j < v.size(); j++) {
      if (v[j].second - v[i].second >= d)
        break;
      d = min(d,
              sqrt((v[i].first - v[j].first) * (v[i].
                  first - v[j].first) +
                   (v[i].second - v[j].second) * (v[i].
                       second - v[j].second)));
    }
  }
  return d;
}
main() {
  sort(p + 1, p + n + 1);
  solve(1, n);
}
```