

Question 5

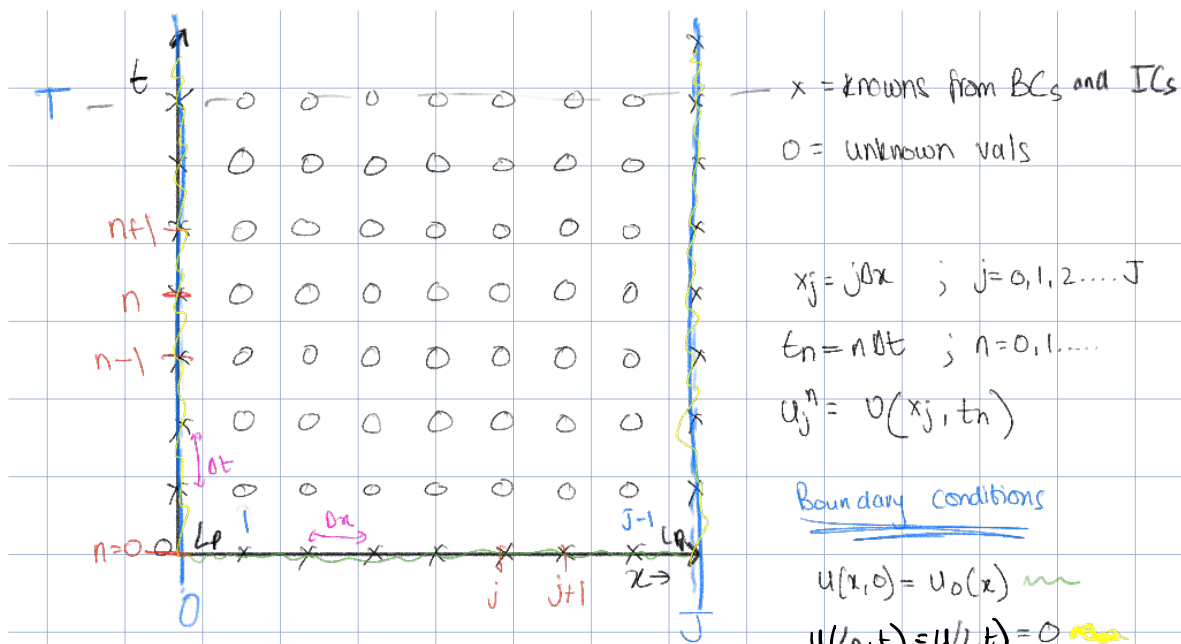
The meta scheme was defined in eq. 3 as shown:

$$\begin{aligned} & U_j^{n+1} (1 + A\theta + 2B) - U_{j-1}^{n+1} (B\theta) - U_{j+1}^{n+1} (A\theta + B\theta) \\ &= \\ & U_j^n (1 - A(1-\theta) - 2B(1-\theta)) + U_{j+1}^n (A(1-\theta) + B(1-\theta)) \\ &+ U_{j-1}^n (B(1-\theta)) \quad (\text{eq 3}) \end{aligned}$$

where $A = \frac{\alpha(t) \Delta t}{\Delta x}$

$$B = \frac{c \Delta t}{\Delta x}$$

\Rightarrow The grid indexing is shown below



To implement this equation in code,
a matrix set up in the form:

$$Ax = b$$

tridiagonal matrix \rightarrow A
 x \rightarrow u_j^m terms
 b \rightarrow known terms.

A can be taken from the LHS of the equation as the coefficients of the unknown values.

To deal with Boundary conditions,
we set the first index in the
Matrix A to be 1 and the

rest to be zero as u_0^n is known to always be zero. We also set the last index in the matrix to be 1, with all other columns in the $J+1$ column of the matrix to be zero, as shown below:

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ (-B\theta) & (1+A\theta+2B) & (A\theta+B\theta) & 0 & \dots & 0 \\ 0 & (-B\theta) & (1+A\theta+2B) & (A\theta+B\theta) & \dots & 0 \\ 0 & 0 & -(B\theta) & \dots & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \dots & 1 \end{pmatrix}$$

\leftarrow boundary rows
 rows = $(J+1)$
 columns = $(J+1)$
 \leftarrow boundary

tridiagonal matrix continued.

$$X = \begin{pmatrix} u_0^{n+1} \\ u_1^{n+1} \\ u_2^{n+1} \\ \vdots \\ u_J^{n+1} \end{pmatrix}$$

rows = $(J+1)$
 columns = (1)

The matrix b is computed using the RHS of eq-3, with the first and last values also being 0 as this satisfies our boundary conditions.

$$b = \begin{pmatrix} 0 \\ U_0^n (B - (1-\theta)) + \\ U_1^n (1 + A\theta + B\theta \\ + U_2^n (A+B)(1-\theta) \\ \vdots \\ 0 \end{pmatrix} \begin{matrix} \leftarrow \text{boundary cond} \\ \\ \\ \\ \leftarrow \text{boundary cond.} \end{matrix}$$

$\Rightarrow U_j^0$ can be calculated from the known initial conditions as $U(x, 0) = U_0(x)$

\Rightarrow the domain is divided into J points by $L - L_p / \Delta x$

\Rightarrow The number of time steps is given by T .

\Rightarrow once the U_j^0 vector is found, these values become known and can be used in the b vector. This can be used to find U_j^{n+1} .

\Rightarrow `linalg.solve` is used to solve for x , and this vector is then used to update the value of b to find the U values at the next time step.

\Rightarrow This is continued until the desired timesteps (T) have been reached.

The implementation of the theta scheme is shown in the file

"gulana-q5.py"

saved in my folder.

Fourier Analysis of the error (right biased upwind case only)

advection term: $U_t - \alpha(t) U_x = 0$

$$\frac{U_j^{n+1} - U_j^n}{\Delta t} = \alpha(t) \left[\theta \left(\frac{U_{j+1}^{n+1} - U_j^{n+1}}{\Delta x} \right) + (1-\theta) \left(\frac{U_{j+1}^n - U_j^n}{\Delta x} \right) \right]$$

substitute $U_j^n = h^n e^{ijk\Delta x}$ into \uparrow
where $N = \Delta t / \Delta x$ and always greater than zero

$$U_j^{n+1} = U_j^n - N \alpha(t) \left[\theta \left(h^n e^{i(j+1)k\Delta x} - h^n e^{ijk\Delta x} \right) + (1-\theta) \left(h^n e^{i(j+1)k\Delta x} - h^n e^{ijk\Delta x} \right) \right]$$

$$\div U_j^n$$

$$h = 1 - N \alpha(t) \left[\theta (h e^{ik\Delta x} - h) + (1-\theta) (e^{ik\Delta x} - 1) \right]$$

2.

$$h-1 = -p\alpha(t) \left[(\theta h + (1-\theta)(e^{ik\Delta x} - 1)) \right]$$

$$h-1 = -p\alpha(t) \left[(\theta h + (1-\theta)(\cos k\Delta x + i\sin k\Delta x - 1)) \right]$$

$$\therefore h = \frac{1 - p\alpha(t)(1-\theta)(\cos k\Delta x - 1 + i\sin k\Delta x)}{1 + \theta p\alpha(t)(\cos k\Delta x - 1 + i\sin k\Delta x)}$$

getting rid of imaginary terms:

$$|h|^2 = \frac{(1 - p\alpha(t)(1-\theta)(\cos k\Delta x - 1))^2 + (-p\alpha(t)(1-\theta)\sin k\Delta x)^2}{(1 + \theta p\alpha(t)(\cos k\Delta x - 1))^2 + (\theta p\alpha(t)\sin k\Delta x)^2}$$

$\xrightarrow{\text{CO}}$

since $p > 0$ and $0 \leq \theta \leq 1$
 and knowing that $(\cos k\Delta x - 1) < 0$,
 the condition $h \leq 1$ is only
 valid if $\alpha(t)$ has a positive
sign for this right biased upwind
 scheme.

\Rightarrow Thus if $\alpha(t) > 0$ solution is stable

\Rightarrow if $\alpha(t) < 0$ solution is unstable

\Rightarrow It can now be seen that advection term can now add stability to system.

Diffusion term

\Rightarrow The diffusion term will follow the same Fourier analysis as in Morton and Mayers section 2.10, with an added ϵ term such that:

$$h = \frac{1 - 4(1-\theta) \nu \sin^2 \frac{1}{2} k \Delta x}{1 + 4\theta \nu \sin^2 \frac{1}{2} k \Delta x} \quad (2.77 \text{ M\&M})$$

becomes \Rightarrow

$$h = \frac{1 - 4(1-\theta)\epsilon p \sin^2 \frac{1}{2} k \Delta x}{1 + 4\theta \epsilon p \sin^2 \frac{1}{2} k \Delta x}$$

which is only unstable when $h < -1$

$$p\epsilon(1-2\theta) > \frac{1}{2}$$

stability condition for diffusion term.

if $\epsilon = 0$ the equation becomes simply the linear advection equation. the CFL condition states that the numerical domain of dependence must cover the analytical/physical domain of dependence. (D.O.D)

$$\left. \begin{array}{l} \text{thus slope of} \\ \text{numerical D.O.D} \end{array} \right\} = \frac{\Delta t}{\Delta x} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{for } \epsilon = 0$$

$$\left. \begin{array}{l} \text{slope of physical} \\ \text{D.O.D} \end{array} \right\} = \frac{1}{\alpha(t)}$$

CFL condition:

$$\left| \frac{\Delta t}{\Delta x} \right| \leq \left| \frac{1}{\alpha(t)} \right|$$

$$\therefore \Delta t \leq \frac{\Delta x}{|\alpha(t)|}$$

$$\text{CFL number} = \frac{\Delta t}{\Delta x} |\alpha(t)|$$

thus if we CFL = 1

$$1 = \frac{\Delta t}{\Delta x} |\alpha(t)|$$

\Rightarrow assuming $\alpha(t) = 1$, then for CFL = 1:

$$\Delta t = \Delta x \quad \text{for} \quad \text{CFL} = 1$$

The code is given parameters:

$$L_p = 0, L = 1, \Delta t = 0.05, \Delta x = 0.05, \alpha(t) = 1, \\ T = 50, \theta = 0, \epsilon = 0$$

The graph plotted for this condition is saved in the folder as

"guland-q5.jpeg"

which shows pure advection with an error of zero at the peak height is the same as it travels upwind. The boundary conditions are the same as those implemented for Question 4.

*To reproduce the figure, run the file as it is.