# Module 2: Introduction to Decision Theory

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#### Announcements

- 1. No late assignments on homeworks will be accepted.
- 2. Please make sure you are familar with the syllabus and course policies.

## Agenda

- What is decision theory?
- General setup
- Bayesian approach
- Frequentist and Integrated Risk
- Examples

#### General setup

Assume an unknown state S (a.k.a. the state of nature). Assume

- we receive an observation x,
- we take an action a, and
- we incur a real-valued loss  $\ell(S, a)$ .

```
egin{array}{ll} S & {
m state (unknown)} \ x & {
m observation (known)} \ a & {
m action} \ \ell(s,a) & {
m loss} \ \end{array}
```

#### Bayesian approach

- S is a random variable,
- the distribution of x depends on S,
- and the optimal decision is to choose an action a that minimizes the posterior expected loss,

$$\rho(\mathsf{a},\mathsf{x}) = \mathbb{E}(\ell(\mathsf{S},\mathsf{a})|\mathsf{x}).$$

In other words,  $\rho(a,x) = \sum_s \ell(s,a) p(s|x)$  if S is a discrete random variable, while if S is continuous then the sum is replaced by an integral.

# Bayesian approach (continued)

- 1. A **decision procedure**  $\delta$  is a systematic way of choosing actions a based on observations x. Typically, this is a deterministic function  $a = \delta(x)$  (but sometimes introducing some randomness into a can be useful).
- 2. A **Bayes procedure** is a decision procedure that chooses an a minimizing the posterior expected loss  $\rho(a, x)$ , for each x.
- 3. Note: Sometimes the loss is restricted to be nonnegative, to avoid certain pathologies.

## Example 1

- 1. State:  $S = \theta$
- 2. Observation:  $x = x_{1:n}$
- 3. Action:  $a = \hat{\theta}$
- 4. Loss:  $\ell(\theta, \hat{\theta}) = (\theta \hat{\theta})^2$  (quadratic loss, a.k.a. square loss)

## What is the optimal decision rule?

- Goal: Minimize the posterior risk
- ▶ First note that

$$\ell(\theta,\hat{\theta}) = \theta^2 - 2\theta\hat{\theta} + \hat{\theta}^2$$

It then follows that the posterior loss is

$$\rho(\hat{\theta}, x_{1:n}) = \mathbb{E}(\ell(\theta, \hat{\theta})|x_{1:n}) = \mathbb{E}((\theta - \hat{\theta})^2|x_{1:n})$$

$$= \mathbb{E}(\theta^2 - 2\theta\hat{\theta} + \hat{\theta}^2|x_{1:n})$$

$$= \mathbb{E}(\theta^2|x_{1:n}) - 2\hat{\theta}\mathbb{E}(\theta|x_{1:n}) + \hat{\theta}^2,$$

which is a convex function of  $\hat{\theta}$ .

### What is the optimal decision rule?

We just showed that

$$\rho(\hat{\theta}, x_{1:n}) = \mathbb{E}(\theta^2 | x_{1:n}) - 2\hat{\theta}\mathbb{E}(\theta | x_{1:n}) + \hat{\theta}^2$$

Setting the derivative with respect to  $\hat{\theta}$  equal to 0, and solving, we find that the minimum occurs at  $\hat{\theta} = \mathbb{E}(\theta|x_{1:n})$ , **the posterior** mean.

Let's walk through this derivation together.

## What is the optimal decision rule?

$$\frac{\partial \rho(\hat{\theta}, x_{1:n})}{\partial \hat{\theta}} = \frac{\partial \{\mathbb{E}(\theta^2 | x_{1:n}) - 2\hat{\theta}\mathbb{E}(\theta | x_{1:n}) + \hat{\theta}^2\}}{\partial \hat{\theta}} = -2\mathbb{E}(\theta | x_{1:n}) + 2\hat{\theta}$$

Now, let

$$-2\mathbb{E}(\theta|x_{1:n})+2\hat{\theta}=0,$$

which implies that

$$\hat{\theta} = \mathbb{E}(\theta|x_{1:n}).$$

Why is the solution unique?

#### Resource allocation for disease prediction

Suppose public health officials in a small city need to decide how much resources to devote toward prevention and treatment of a certain disease, but the fraction  $\theta$  of infected individuals in the city is unknown.

## Resource allocation for disease prediction (continued)

Suppose they allocate enough resources to accommodate a fraction c of the population. Recall that  $\theta$  is the fraction of the infected individuals in the city.

- If c is too large, there will be wasted resources, while if it is too small, preventable cases may occur and some individuals may go untreated.
- ► After deliberation, they adopt the following loss function:

$$\ell(\theta,c) = \left\{ egin{array}{ll} |\theta-c| & ext{if } c \geq \theta \ 10|\theta-c| & ext{if } c < \theta. \end{array} 
ight.$$

## Resource allocation for disease prediction (continued)

- ▶ By considering data from other similar cities, they determine a prior  $p(\theta)$ . For simplicity, suppose  $\theta \sim \text{Beta}(a, b)$  (i.e.,  $p(\theta) = \text{Beta}(\theta|a, b)$ ), with a = 0.05 and b = 1.
- ▶ They conduct a survey assessing the disease status of n = 30 individuals,  $x_1, ..., x_n$ .

This is modeled as  $X_1, \ldots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(\theta)$ , which is reasonable if the individuals are uniformly sampled and the population is large. Suppose all but one are disease-free, i.e.,  $\sum_{i=1}^n x_i = 1$ .

#### The Bayes procedure

The **Bayes procedure** is to minimize the posterior expected loss

$$\rho(c,x) = \mathbb{E}(\ell(\theta,c)|x) = \int \ell(\theta,c)p(\theta|x)d\theta$$

where  $x = x_{1:n}$ .

- 1. We know  $p(\theta|x)$  as an updated Beta, so we can numerically compute this integral for each c.
- 2. Figure 1 shows  $\rho(c,x)$  for our example.
- 3. The minimum occurs at  $c \approx 0.08$ , so under the assumptions above, this is the optimal amount of resources to allocate.
- 4. How would one perform a sensitivity analysis of the prior assumptions?

#### Resource allocation for disease prediction in R

```
# set seed
set.seed(123)
# data
sum x = 1
n = 30
# prior parameters
a = 0.05; b = 1
# posterior parameters
an = a + sum x
bn = b + n - sum x
th = seq(0,1,length.out = 100)
like = dbeta(th, sum x+1, n-sum x+1)
prior = dbeta(th,a,b)
post = dbeta(th, sum_x+a, n-sum_x+b)
```

## Likelihood, Prior, and Posterior



#### The loss function

```
# compute the loss given theta and c
loss_function = function(theta, c){
  if (c < theta){
    return(10*abs(theta - c))
  } else{
    return(1 = abs(theta - c))
  }
}</pre>
```

#### Posterior risk

```
# compute the posterior risk given c
# s is the number of random draws
# compute the posterior risk given c
# s is the number of random draws
posterior risk = function(c, s = 30000){
  # randow draws from beta distribution
 theta = rbeta(s, an, bn)
  loss <- apply(as.matrix(theta),1,loss_function,c)</pre>
  # average values from the loss function
  risk = mean(loss)
```

## Posterior Risk (continued)

```
# a sequence of c in [0, 0.5]
c = seq(0, 0.5, by = 0.01)
post_risk <- apply(as.matrix(c),1,posterior_risk)
head(post_risk)</pre>
```

**##** [1] 0.33917940 0.25367603 0.18868962 0.14489894 0.11693

# Posterior expected loss/posterior risk for disease prevelance

```
# plot posterior risk against c
pdf(file="posterior-risk.pdf")
plot(c, post risk, type = 'l', col='blue',
    lwd = 3, ylab = 'p(c, x)')
dev.off()
## pdf
##
```

# minimum of posterior risk occurs at c = 0.08

```
## [1] 0.08
```

(c[which.min(post risk)])

# Posterior expected loss/posterior risk for disease prevelance

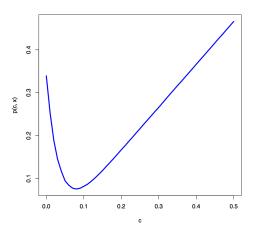


Figure 1:

### Frequentist and Integrated Risk

- 1. Consider a decision problem in which  $S = \theta$ .
- 2. The  $\it risk$  (or  $\it frequentist risk$ ) associated with a decision procedure  $\delta$  is

$$R(\theta, \delta) = \mathbb{E}(\ell(\theta, \delta(X)) \mid \theta = \theta),$$

where X has distribution  $p(x|\theta)$ . In other words,

$$R(\theta, \delta) = \int \ell(\theta, \delta(x)) \, \rho(x|\theta) \, dx$$

if X is continuous, while the integral is replaced with a sum if X is discrete.

3. The *integrated risk* associated with  $\delta$  is

$$r(\delta) = \mathbb{E}(\ell(\theta, \delta(X))) = \int R(\theta, \delta) \, p(\theta) \, d\theta.$$

- 1. The frequentist risk provides a useful way to compare decision procedures in a prior-free way.
- 2. In addition to the Bayes procedure above, consider two other possibilities: choosing  $c=\bar{x}$  (sample mean) or c=0.1 (constant).

3. Figure 2 shows each procedure as a function of  $\sum x_i$ , the observed number of diseased cases. For the prior we have chosen, the Bayes procedure always picks c to be a little bigger than  $\bar{x}$ .

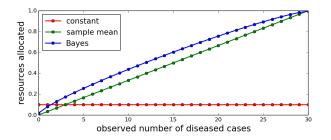


Figure 2: Resources allocated c, as a function of the number of diseased individuals observed,  $\sum x_i$ , for the three different procedures.

4. Figure 3 shows the risk  $R(\theta, \delta)$  as a function of  $\theta$  for each procedure. Smaller risk is better. (Recall that for each  $\theta$ , the risk is the expected loss, averaging over all possible data sets. The observed data doesn't factor into it at all.)

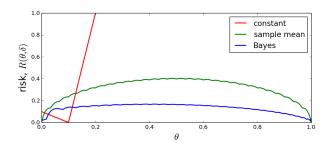


Figure 3: Risk functions for the three different procedures.

- 5. The constant procedure is fantastic when  $\theta$  is near 0.1, but gets very bad very quickly for larger  $\theta$ . The Bayes procedure is better than the sample mean for nearly all  $\theta$ 's. These curves reflect the usual situation—some procedures will work better for certain  $\theta$ 's and some will work better for others.
- 6. A decision procedure which is *inadmissible* is one that is dominated everywhere. That is,  $\delta$  is *inadmissible* if there is no  $\delta'$  such that

$$R(\theta, \delta') \leq R(\theta, \delta)$$

for all  $\theta$  and  $R(\theta, \delta') < R(\theta, \delta)$  for at least one  $\theta$ . (A decision procedure that is not *inadmissible* is said to be *admissible*).

- 7. Bayes procedures are admissible under very general conditions.
- 8. Admissibility is nice to have, but it doesn't mean a procedure is necessarily good. Silly procedures can still be admissible—e.g., in this example, the constant procedure c=0.1 is admissible too!

#### Exercise

Consider  $X_1, \ldots, X_n \mid \theta \stackrel{iid}{\sim} N(\theta, \sigma^2)$  Suppose that we assume very weak prior information on  $\theta$ . That is, suppose that  $p(\theta) \propto 1$ .

- ▶ What does the likelihood and prior distribution look like (what is your intuition)? Now let's verify this in markdown.
- ▶ What is the posterior distribution for  $\theta$ ?

# Exercise (continued)

$$p(x_{1:n} \mid \theta) = \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left(-\frac{1}{2\sigma^2} \sum_i (x_i - \theta)^2\right)$$
(1)
$$\left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left(-\frac{1}{2\sigma^2} \sum_i (x_i + \bar{x} - \bar{x} - \theta)^2\right)$$
(2)
$$\left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left(-\frac{n}{2\sigma^2}(\theta - \bar{x})^2\right)$$
(3)