Linear Regression

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Predictive Modeling and Data Mining: STA 521

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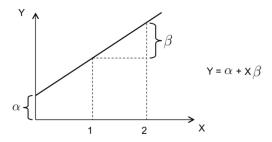
- Knowledge of linear regression is assumed.
- ▶ How can we do variable selection?
- Bayes factors.
- Gibbs sampling.

In a [Gaussian] linear regression,

$$y \mid \mathbf{x} \sim N(\mathbf{x}'\boldsymbol{\beta}, \sigma^2)$$

Conditional mean is $\mathbb{E}[y|\mathbf{x}] = \mathbf{x}'\boldsymbol{\beta}$.

With just one x, we have simple linear regression.



 $\mathbb{E}[y]$ increases by β for every unit increase in x.

We assume Y observations and covariates X.

Recall that

$$Y_{n\times 1} = X_{n\times p}\beta_{p\times 1} + \epsilon_{n\times 1}$$

$$\epsilon \sim N(0, \sigma^2 I_n).$$

Recall that $E(Y \mid X)$ is linear in it's parameter values.

For a thorough review see Hoff or your notes from STA 521.

Oxygen uptake

- ► Twelve healthy men that don't exercise recruited to study effects of 2 exercise programs on oxygen uptake
- Program one: 12 weeks of flat running
- Program two: 12 weeks of step aerobics

We estimate the coefficients $\hat{\beta} \in \mathbb{R}^p$ by least squares:

$$\hat{\beta} = \operatorname*{argmin}_{\beta \in \mathbb{R}^p} \|y - X \hat{\beta}\|_2^2$$

This gives

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

(Check: does this match the expressions for univariate regression, without and with an intercept?)

The fitted values are

$$\hat{y} = X\hat{\beta} = X(X^TX)^{-1}X^Ty$$

This is a linear function of y, $\hat{y} = Hy$, where $H = X(X^TX)^{-1}X^T$ is sometimes called the hat matrix

Let SSR denote sum of squared residuals.

$$\min_{\beta} SSR(\hat{\beta}) = \min_{\beta} \|y - X\hat{\beta}\|_2^2$$

Then

$$\frac{\partial SSR(\hat{\beta})}{\partial d\hat{\beta}} = \frac{\partial (y - X\hat{\beta})^T (y - X\hat{\beta})}{\partial d\hat{\beta}} \tag{1}$$

$$= \frac{\partial \mathbf{Y}^T \mathbf{Y} - 2\hat{\beta}^T \mathbf{X}^T \mathbf{Y} + \hat{\beta}^T \mathbf{X}^T \mathbf{X} \hat{\beta}}{\partial d\hat{\beta}}$$
(2)

$$= -2\mathbf{X}^T \mathbf{Y} + 2\mathbf{X}^T \mathbf{X} \hat{\beta} \tag{3}$$

This implies
$$-\mathbf{X}^T\mathbf{Y} + \mathbf{X}^T\mathbf{X}\hat{\beta} = 0 \implies \hat{\beta} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{Y}$$
.

Called the ordinary least squares estimator. When is it unique?

$$\hat{\beta} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{Y}.$$

$$E(\hat{\beta}) = \beta.$$

$$\operatorname{Var}(\hat{\beta}) = \operatorname{Var}\{(\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{Y}\}$$

$$= (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \sigma^2 I_n \boldsymbol{X} (\boldsymbol{X}^T \boldsymbol{X})^{-1}$$
(5)

$$=\sigma^2(\boldsymbol{X}^T\boldsymbol{X})^{-1} \tag{6}$$

$$\hat{\beta} \sim MVN(\beta, \sigma^2(\boldsymbol{X}^T\boldsymbol{X})^{-1}).$$

Suppose

$$Y \mid X, \beta, \sigma^2 \sim MVN(X\beta, \sigma^2 I)$$
 (7)

$$\beta \sim MVN(\beta_o, \Sigma_o)$$
 (8)

What is the form of the distribution of $\beta \mid \boldsymbol{Y}, \boldsymbol{X}, \sigma^2$? Recall it's $MVN(\mu_n, \Sigma_n)$

Let's think about the covariance first.

$$\Sigma_n = [\Sigma_o^{-1} + \boldsymbol{X}^T \boldsymbol{X} \sigma^2]^{-1}.$$

Now let's think about the mean.

$$\mu_n = [\Sigma_o^{-1} + X^T X \sigma^2]^{-1} (\mathbf{X}^T \mathbf{Y} / \sigma^2 + \Sigma_o^{-1} \beta_o)$$

Suppose we don't know σ^2 .

Let $\gamma = 1/\sigma^2$.

$$Y \mid X, \beta, \sigma^2 \sim MVN(X\beta, \sigma^2 I)$$
 (9)
 $\beta \sim MVN(\beta_o, \Sigma_o)$ (10)
 $\gamma \sim IG(\nu_o/2, \nu_o \sigma_o^2/2).$ (11)

Then

$$p(\gamma \mid \boldsymbol{Y}, \boldsymbol{X}, \beta)$$
(12)

$$= p(\gamma)p(\boldsymbol{Y} \mid b\boldsymbol{X}, \boldsymbol{Y}, \beta)$$
(13)

$$\propto \gamma^{(\nu_o + n)/2 - 1} \exp\{-\gamma \times \nu_o \sigma_o^2 / 2\}$$
(14)

$$\times \gamma^{n/2} \exp\{-\gamma \times SSR(\beta) / 2\}$$
(15)

$$\propto \gamma^{(\nu_o + n)/2 - 1} \exp\{-\gamma (\nu_o \sigma_o^2 / 2 + SSR(\beta) / 2)\}$$
(16)

Thus,

$$\gamma \mid \boldsymbol{Y}, \boldsymbol{X}, \beta \sim IG((\nu_o + n)/2, (\nu_o \sigma_o^2/2 + SSR(\beta))/2)$$

In order to update $p(\beta, \sigma^2 \mid \pmb{Y}, \pmb{X})$ sample through a two-stage Gibbs sampler.

This is similar to other examples before, and the details can be found in Hoff. (Cycle through the MVN and the IG).

Model selection

- ▶ Often we have a large number of covariates.
- ▶ Using all of them induces poor statistical performance.
- How can we reduce the covariates and have good inference and prediction?
- Common method: Backwards and stepwise regression (slow).

Bayesian model comparison

Suppose that we believe some of the regression coefficients are 0.

Come up with a prior distribution that reflects the probability of this occuring.

Consider

$$y_i = z_1 b_1 x_{i,1} + \dots z_p b_p x_{i,p},$$

where b_p is a real number and z_j indicate which regression coefficients are nonzero.

Note: $\beta_j = b_j \times z_j$.

Bayesian model selection works by obtaining a posterior distribution for z.

Suppose a prior p(z) over models

Then

$$p(\boldsymbol{z} \mid \boldsymbol{Y}, \boldsymbol{X}) = \frac{p(\boldsymbol{z})p(\boldsymbol{Y} \mid \boldsymbol{X}, \boldsymbol{z})}{\sum_{\boldsymbol{z}} p(\boldsymbol{z})p(\boldsymbol{Y} \mid \boldsymbol{X}, \boldsymbol{z})}$$

Suppose we want to compare two models. Consider

$$odds(z_a, z_b \mid \boldsymbol{Y}, \boldsymbol{X}) = \frac{p(z_a \mid \boldsymbol{Y}, \boldsymbol{X})}{p(z_b \mid \boldsymbol{Y}, \boldsymbol{X})} = \frac{p(z_a)}{p(z_b)} \times \frac{p(\boldsymbol{Y} \mid \boldsymbol{X}, z_a)}{p(\boldsymbol{Y} \mid \boldsymbol{X}, z_b)}$$

This is posterior odds = prior odds \times "Bayes factor"

"Bayes factor": how much the data favor model z_a over model z_b

To obtain a posterior distribution over models, we must compute $p(Y \mid X, z)$ for *each* model under consideration.

We must compute

$$p(\mathbf{Y} \mid \mathbf{X}, \mathbf{z}) = \int \int p(\mathbf{Y}, \beta, \sigma^2, | \mathbf{X}, \mathbf{z})$$

$$\int \int p(\mathbf{Y} \mid \mathbf{X}, \mathbf{z}) p(\beta \mid \mathbf{X}, \mathbf{z}) p(\sigma^2).$$
(18)

To do the *least amount of calculus*, we can put a *g-prior* on β

$$\beta \mid \boldsymbol{X}, \boldsymbol{z} \sim MVN(0, g \ \sigma^2(\boldsymbol{X}^T\boldsymbol{X})^{-1}).$$

What is a g-prior?

(Hoff, Section 9.2, p. 156-157). Based upon the prior should be invariant to changes in the scale of the covariates.

- ▶ Defined $\ddot{X} = HX$ for some matrix H.
- ▶ Suppose we obtain a posterior of β from \boldsymbol{Y} and \boldsymbol{X} .
- ▶ According to the idea of invariance above, then the posterior of β and $H\beta$ should be the same.
- ▶ Homework: Condition is met if $\beta_o = 0$ and $\Sigma_o = k(\boldsymbol{X}^T\boldsymbol{X})^{-1}$ for k > 0.

Popular choice: let $k = g\sigma^2$ for g > 0. This is the g-prior.

Given the g-prior

$$\beta \mid \boldsymbol{X}, \boldsymbol{z} \sim MVN(0, g \ \sigma^2(\boldsymbol{X}^T \boldsymbol{X})^{-1}),$$

 $p(Y \mid X, z)$ can be worked out in closed form (details p. 165).

Go through the details on your own.

This results in being able to compute

$$\frac{p(Y \mid X, z_a)}{p(Y \mid X, z_b)} = (1+n)^{(p_{z_b} - p_{z_a})/2} \times \left(\frac{s_{z_a}^2}{s_{z_b}^2}\right)^{1/2}$$
(19)

$$\times \left(\frac{s_{z_b}^2 + SSR_g^{z_b}}{s_{z_b}^2 + SSR_g^{z_a}}\right)^{(n+1)/2} \tag{20}$$

We have a ratio of the marginal probabilities, giving us a balance between model complexity and model fit.

Suppose p_{z_b} is large compared to p_{z_a} .

This causes a penalization of model z_b

Note that a large value of $SSR_g^{z_b}$ compared to $SSR_g^{z_a}$ will penalize model $z_a.$

\boldsymbol{z}	model	$\log p(m{y} \mathbf{X}, m{z})$	$p(z y, \mathbf{X})$
$\overline{(1,0,0,0)}$	β_1	-44.33	0.00
(1,1,0,0)	$ \beta_1 + \beta_2 \times \text{group}_i $	-42.35	0.00
(1,0,1,0)	$\beta_1 + \beta_3 \times age_i$	-37.66	0.18
(1,1,1,0)	$ \beta_1 + \beta_2 \times \text{group}_i + \beta_3 \times \text{age}_i $	-36.42	0.63
(1,1,1,1)	$\left \beta_1 + \beta_2 \times \operatorname{group}_i + \beta_3 \times \operatorname{age}_i + \beta_4 \times \operatorname{group}_i \times \operatorname{age}_i \right $	-37.60	0.19

Table 9.1. Marginal probabilities of the data under five different models.

Figure 1: The most probable model is the one corresponding ${\pmb z}=(1,1,1,0)$

What is the biggest downside of this approach?

How do we fix it easily using what we've learned so far in the course?

Suppose p is large. Then 2^p models to consider.

Instead let's use a Gibbs sampler to search through the space of models for values where z has a high posterior probability.

Generate a new value of z via

$$p(z_j \mid \boldsymbol{Y}, \boldsymbol{X}, \boldsymbol{z}_{-j}).$$

The full conditional that $z_j = 1$ can be written as $o_j/(o_j + 1)$.

$$o_j = \frac{p(z_j = 1 \mid \boldsymbol{Y}, \boldsymbol{X}, \boldsymbol{z}_{-j})}{p(z_j = 0 \mid \boldsymbol{Y}, \boldsymbol{X}, \boldsymbol{z}_{-j})}$$
(21)

$$= \frac{p(z_j = 1)p(Y \mid X, z_{-j}, z_j = 1)}{p(z_j = 0)p(Y \mid X, z_{-j}, z_j = 0)}$$
(22)

Note: we may also want to obtain posterior samples of β and σ^2 .

Using the conditional distributions from Section 9.2, we can sample from these directly.

The Gibbs sampling scheme requires using Section 9.2 and 9.3 (covered in lab).

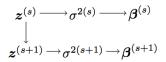


Figure 2: Start with $z^{(s)}$. Then in random order update z_j from its full conditional.

Generate

$$\{z^{(s+1)}, \sigma^{2(s+1)}, \beta^{(s+1)}\}:$$

- 1. Set $z = z^{(s)}$
- 2. For $j \in \{1, \dots, p\}$ in random order, replace z_j with a sample from

$$p(z_j \mid \boldsymbol{z}_{-j}, \boldsymbol{Y}, \boldsymbol{X})$$

- 3. Set $z^{(s+1)} = z^{(s)}$
- 4. Sample $\sigma^{2(s)} \sim p(\sigma^2 \mid \boldsymbol{z}^{(s+1)}, \boldsymbol{Y}, \boldsymbol{X})$
- 5. Sample $\beta^{(s+1)} \sim p(\beta \mid \boldsymbol{z}^{(s+1)}, \sigma^{2(s+1)}, \boldsymbol{Y}, \boldsymbol{X})$

Lab this week: Linear regression and understanding model selection using the diabetes data.