

# Lab 8: Gibbs sampling for mixture models using data augmentation STA 360/602, March 28

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## A Three Component Mixture Model

Consider a three component mixture of normal distribution with a common prior on the mixture component means, the error variance and the variance within mixture component means. The prior on the mixture weights  $w$  is a three component Dirichlet distribution. (The data for this problem can be found in “Lab6Mixture.csv”).

$$\begin{aligned} p(Y_i | \mu_1, \mu_2, \mu_3, w_1, w_2, w_3, \varepsilon^2) &= \sum_{j=1}^3 w_j N(\mu_j, \varepsilon^2) \\ \mu_j | \mu_0, \sigma_0^2 &\sim N(\mu_0, \sigma_0^2) \\ \mu_0 &\sim N(0, 3) \\ \sigma_0^2 &\sim IG(2, 2) \\ (w_1, w_2, w_3) &\sim \text{Dirichlet}(\mathbf{1}) \\ \varepsilon^2 &\sim IG(2, 2), \end{aligned}$$

for  $i = 1, \dots, n$ .

Specifically,

- $w_1, w_2$  and  $w_3$  are the mixture weight of mixture components 1, 2 and 3 respectively
- $\mu_1, \mu_2$  and  $\mu_3$  are the means of the mixture components
- $\varepsilon^2$  is the variance parameter of the error term around the mixture components.

Since we’re building a hierarchical model for the means of the individual component, we have a common hyperprior, where,  $\mu_0$  is the mean parameter

of this hyperprior,  $\sigma_0^2$  is its variance parameter. Both of these have priors as well, but the parameters of those priors are fixed, where  $\mu_0$  has a Normal prior with mean 0 and variance 3,  $\sigma_0^2$  has an Inverse-Gamma prior with shape and rate parameter of (2,2) respectively. Similarly,  $\varepsilon^2$  has an Inverse-Gamma prior with shape and rate parameter of (2,2) respectively. While they have the same parametrisation, they do not share a prior). The mixture weights  $w_1, w_2, w_3$  jointly come from a Dirichlet distribution, with parameter vector (1, 1, 1).  $w_1, w_2, w_3, \mu_1, \mu_2, \mu_3, \varepsilon^2, \mu_0$  and  $\sigma_0^2$  are all random variables that we will estimate when we fit the model.

## Task 1

Derive the joint posterior  $p(w_1, w_2, w_3, \mu_1, \mu_2, \mu_3, \varepsilon^2, \mu_0, \sigma_0^2 | Y_1, \dots, Y_N)$  up to a normalizing constant.

## Task 2

Derive the full conditionals for all the parameters up to a normalizing constant.

- $p(w_1, w_2, w_3 | \mu_1, \mu_2, \mu_3, \varepsilon^2, Y_1, \dots, Y_N) \propto$
- $p(\mu_1 | \mu_2, \mu_3, w_1, w_2, w_3, Y_1, \dots, Y_N, \varepsilon^2, \mu_0, \sigma_0^2) \propto$
- $p(\mu_2 | \mu_1, \mu_3, w_1, w_2, w_3, Y_1, \dots, Y_N, \varepsilon^2, \mu_0, \sigma_0^2) \propto$
- $p(\mu_3 | \mu_1, \mu_2, w_1, w_2, w_3, Y_1, \dots, Y_N, \varepsilon^2, \mu_0, \sigma_0^2) \propto$
- $p(\varepsilon^2 | \mu_1, \mu_2, \mu_3, w_1, w_2, w_3, Y_1, \dots, Y_N) \propto$
- $p(\mu_0 | \mu_1, \mu_2, \mu_3, \sigma_0^2) \propto$
- $p(\sigma_0^2 | \mu_0, \mu_1, \mu_2, \mu_3) \propto$

## The data augmentation scheme

Since neither the joint posterior nor any of the full conditionals involving the likelihood are of a form that's easy to sample, we introduce a data augmentation scheme. A common solution is to introduce an additional set of random variables  $\{Z_i\}_{i=1}^N$  that assign each observation to one of the mixture components with the probability of assignment being the respective mixture weight. If we condition on  $Z_i$  we can then write the likelihood of  $Y_i$  as

$$p(Y_i | Z_i, \mu_1, \mu_2, \mu_3, \varepsilon^2) = \sum_{j=1}^N N(\mu_j, \varepsilon^2) \delta_j(Z_i) = N(\mu_{Z_i}, \varepsilon^2)$$

$$P(Z_i = j) = w_j.$$

This means that conditional on  $Z_i$  we no longer have a sum of Normal pdfs in our likelihood, resulting in a significant simplification. Conditional on the  $\{Z_i\}$  updates will be straightforward, only depending on the mixture component that any given  $Y_i$  is currently assigned to. The drawback is that we also have to update  $\{Z_i\}_{i=1}^N$  as well, introducing extra steps into our sampler. Also note that the Dirichlet distribution is a conjugate prior for categorical variables.

### Task 3

Where necessary, (re)derive the full conditionals under the data augmentation scheme.

### Task 4

In task 3 you derived all the full conditionals, and due to data augmentation scheme they are all in a form that is easy to sample. Use these full conditionals to implement Gibbs sampling using the data from “Lab6Mixture.csv”.

### Task 5

Given tasks 1-4 and the provided solutions,

- Show traceplots for all estimated parameters
- Show means and 95% credible intervals for the marginal posterior distributions of all the parameters

Now suppose you re-run the sampler using 3 different starting values, are your results in a,b the same? Justify your reasoning by with visualizations.