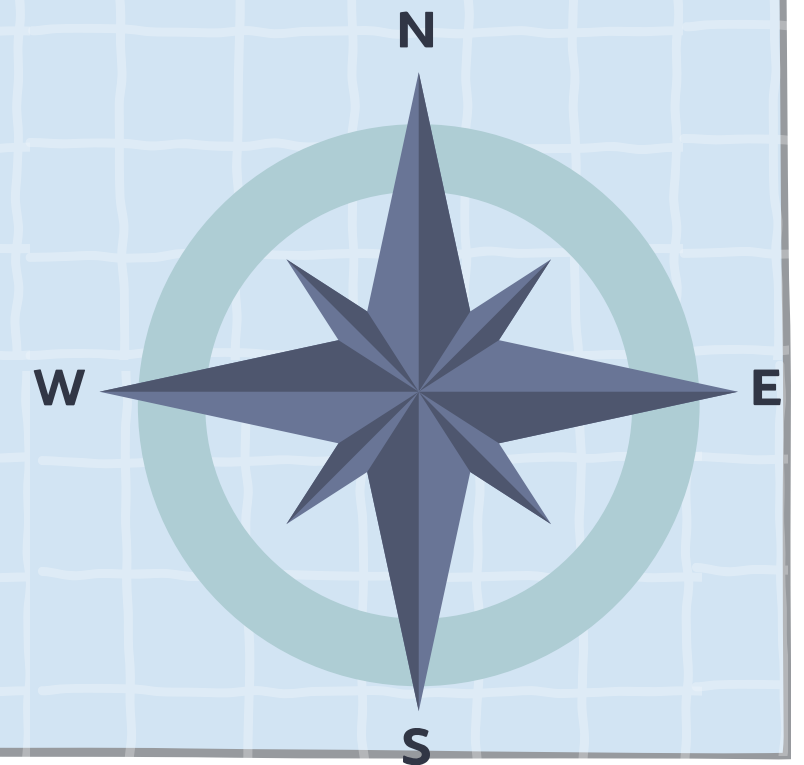
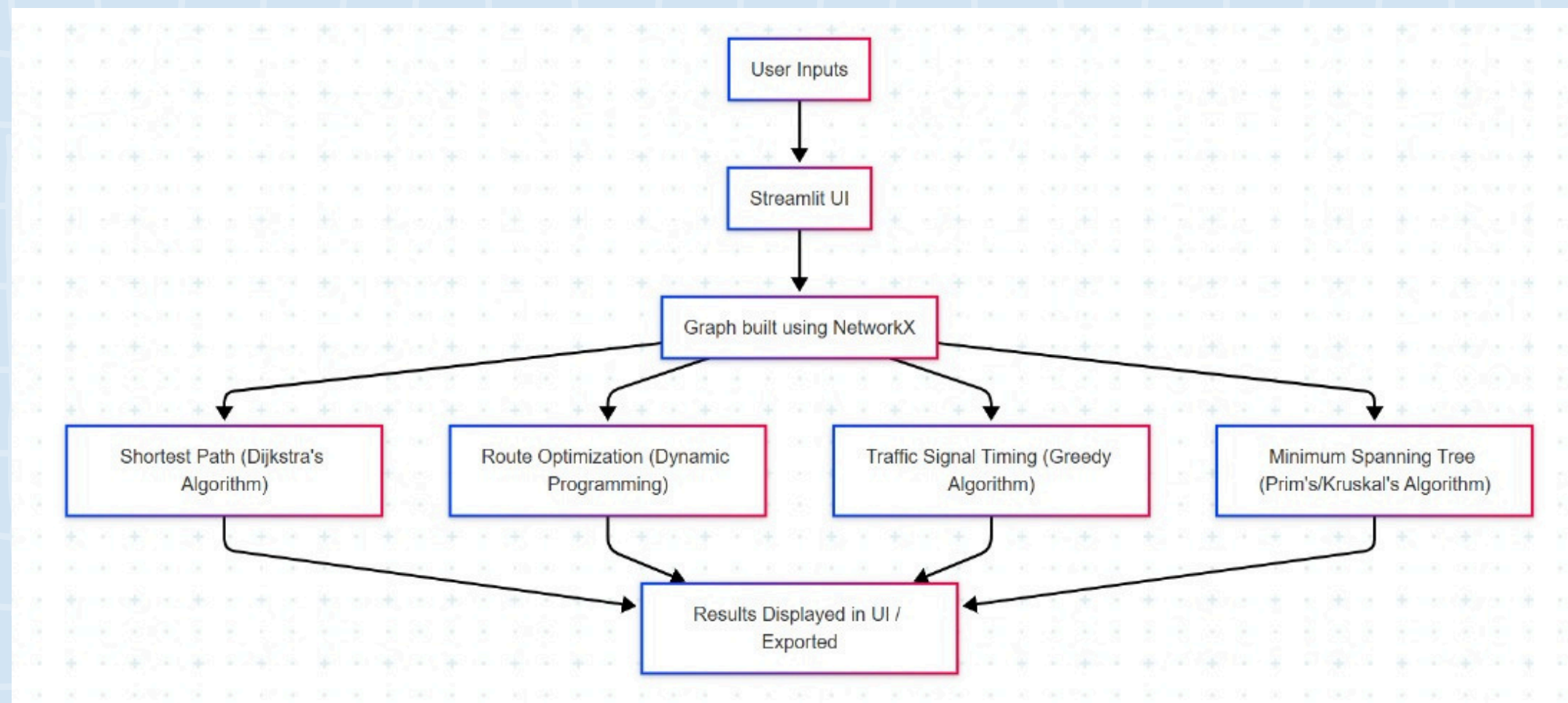


RUNTIME TERROR

MAPS



# SYSTEM ARCHITECTURE AND DESIGN



# MST

## 1. System Design:

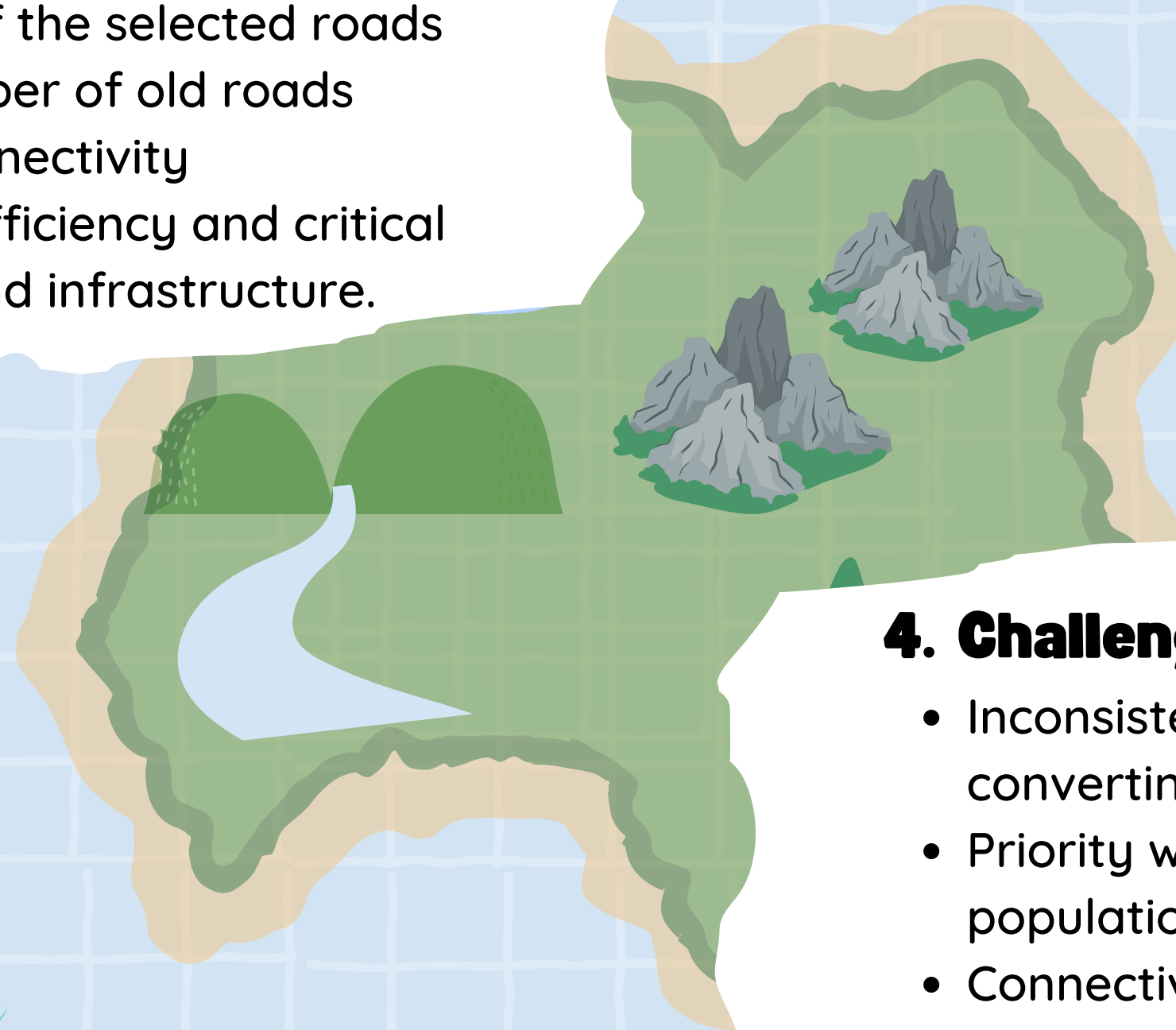
- Loads four datasets: new\_roads, neighborhoods, facilities, and roads.
- Converts all IDs to strings for consistency.
- Builds a list of potential roads, each with a dynamically adjusted cost based on:
  - High population areas (population\_factor)
  - Facility connectivity (facility\_factor)
- If apply\_priority is True, those factors are applied to reduce cost for more important roads.
- Final MST is built from these roads with optional budget limits.

## 2. Algorithm Implementation

- kurskal Uses a Disjoint Set (Union-Find) class to avoid cycles and build the MST.
- Sorts proposed roads by adjusted cost.
- Iteratively adds roads that connect disjoint components.
- Stops adding new roads when max\_budget is reached (if limit\_budget = True).
- After MST construction, ensures full connectivity by rechecking components.

### 3. Performance and Results

- The function returns:
  - `final_mst`: all selected roads (new and reused old roads)
  - `total_cost`: total cost of the selected roads
  - `len(extra_edges)`: number of old roads added to complete connectivity
- The result balances cost-efficiency and critical priorities like population and infrastructure.



### 4. Challenges and Solutions

- Inconsistent data formats → Solved by converting IDs to strings
- Priority weight tuning → Handled via `population_factor` and `facility_factor`
- Connectivity gaps after MST → Solved by reintegrating essential old roads
- Budget control → Implemented by stopping additions once `max_budget` is reached

# SHORTEST PATH



## 1. System Design

- Loads three datasets: Existing\_Roads.csv, Facilities.csv, and Neighborhoods.csv.
- Constructs a directed graph using Network with real distances as weights.
- Incorporates traffic multipliers and location coordinates.
- Supports both normal and emergency pathfinding.

## 2. Algorithm Implementation

- Implements:
  - Dijkstra's Algorithm for general shortest path.
  - A\* algorithm for emergency routing to the nearest hospital.
- Heuristic in A\* uses Euclidean distance between nodes (Latitude, Longitude).
- Graph weights are dynamically adjusted based on traffic time (e.g., morning).



#### 4. Challenges and Solutions

- Missing coordinates → Used default (0, 0) when unavailable.
- Dynamic weights → Handled via traffic multipliers per road segment.
- Multiple targets ( $A^*$ ) → Compared all hospitals to pick the nearest.
- Fallbacks on failure → Try/except used to avoid crashes if paths are not found.

#### 3. Performance and Results

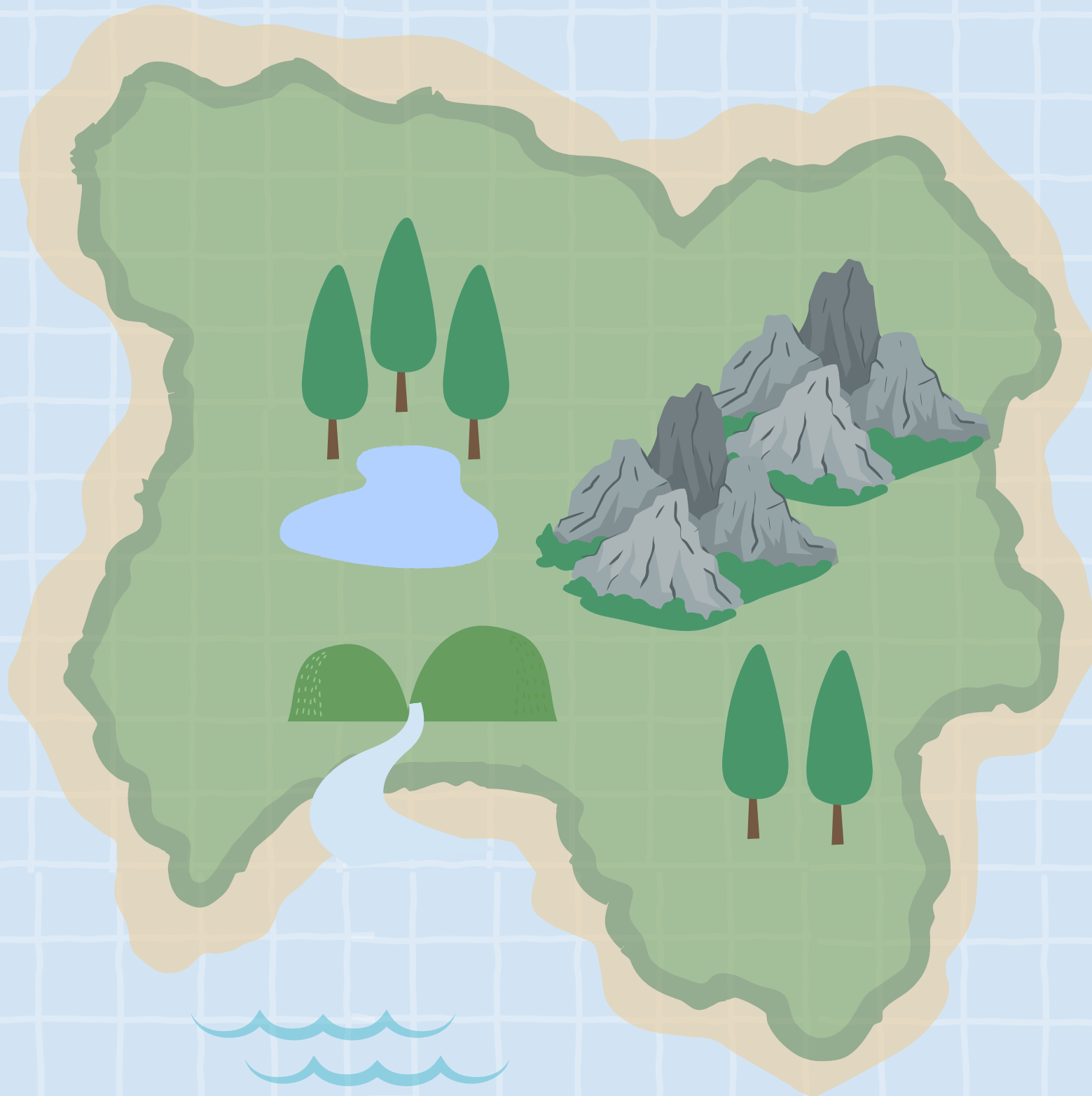
- Dijkstra: Finds the shortest route from source to target ( $N1 \rightarrow N5$ ).
- $A^*$ : Finds nearest hospital to a source ( $N3$ ) with minimum travel cost.
- Traffic-aware routing: Dijkstra with adjusted weights reflects peak hour delays.
- Prints: Path + distance (in kilometers) for each case.



# GREEDY

- The system is designed to optimize traffic signal directions by analyzing traffic volume and
- emergency route data. It processes inputs using a modular structure: data loading, direction
- estimation based on coordinates, and output
- generation per intersection per time period.

## 1. System Design



● A greedy logic is applied:

\*If an emergency vehicle route is detected at a specific intersection and time period, the green light is assigned in that direction.

If no emergency, the direction with the highest vehicle count is selected.

● Coordinate-based estimation (east/west/north/south) is used to infer directions.

● Time complexity is approximately  $O(N + I \cdot T)$ , where:

- $N$  = number of traffic records
- $I$  = number of intersections
- $T$  = 4 fixed time periods

### 3. Performance Summary

## 2. Algorithm Overview

The output `greedy_signal_results.csv` contains the optimal green light direction for each intersection.

- Ensures emergency access when needed.
- Reduces congestion by favoring busy directions.

Missing coordinates: handled with "unknown" fallback.

Period format mismatch: solved via mapping dictionary.

## 4. Challenges and Solution



# DYNAMIC PROGRAMMING

## 1. System Design

- The system consists of three integrated modules:
- Signal Control Module: Determines optimal green light directions based on traffic volume and emergency routing.
- \*Maintenance Planning Module: Uses dynamic programming (Knapsack) to select critical roads for repair under budget constraints.
- Transit Scheduling Module: Allocates buses and metro trains efficiently across routes to maximize service coverage.

## 2. Algorithm & Techniques Used

- Greedy Signal Optimization: Emergency routes are prioritized; otherwise, highest traffic direction is selected.
- Dynamic Programming (0/1 Knapsack):
- Road Maintenance: Chooses high-priority roads based on condition and traffic impact.
- Bus Scheduling: Distributes buses to routes based on passenger count and stops.
- Metro Scheduling: Allocates trains based on daily ridership and station count.



# Results and Evaluation

Data Gaps: Handled missing coordinates and unmatched time formats using default logic and mapping.

Resource Limitation: Resolved via optimal selection using dynamic programming.

Signal Optimization: CSV output provides direction per intersection and time period (greedy\_signal\_results.csv).

Maintenance Plan: Ensures cost-effective selection of roads within budget.

Transit Allocation: Boosts transit coverage while respecting vehicle constraints.

## Key Challenges and Resolutions