

Assignment

History of Digital Image Processing (DIP)

The history of digital image processing can be traced back to its first application which was in the Newspaper Industry when pictures were to be transferred from London to New York via a submarine cable.

The Bartlane cable for picture transmission was used in the early 1900s to shorten the time used to transfer images across the Atlantic from one week to less than two (2) hours.

Although, during this time, the early Bartlane systems were capable of coding images in five (5) distinct levels of gray. This capability was increased to 15 levels in 1929.

Text Book: ① Digital Image Processing by
Rafael C. Gonzalez & Richard E.
Woods

* Facial
Recognition
using
MATLAB

② DIP using MATLAB by Gonzalez,
Woods & Edding

③ Computer Vision Algorithms and
Application by Richard Szeliski

* ④ Image Processing: Principles and
Application by Tinku Acharya &
Ajoy K. Ray.

Assignment (each chapter, make a minimum
of 10 references. make sure you put
in your own words)

Chapter 1

1.0 Introduction

1.1 What is Digital Image Processing

1.2 Origin of Digital Image Processing

1.3 Examples of fields that use
DIP

1.4 Application of DIP

1.5 Problems associated with DIP

1.6 Fundamental steps in DIP.

1.7 Components of an Image processing
System

Chapter 2

Put more than one reference in title
Ref style: APA

2.0 Digital Image fundamentals

2.1 Human Visual Perception

- Structure of the Human eye

- Image formation in the eye

2.2 Image sensing and acquisition

2.3 Image sampling and quantization.

2.4 Basic relationship between pixels

2.5 Digital Image file format.

Chapter 3

3.0 Image enhancement and restoration

3.1 Noise and Degradation in an image

3.2 Types of Noise in an image

3.3 Image Enhancement

- Spatial Domain

- Frequency Domain

3.4 Image Restoration

Discuss the following filters

① Contrast Stretching

② Histogram Equalization

③ Image Subtraction

④ Image Averaging

- ⑤ Median filter
- ⑥ Gaussian filter
- ⑦ Homomorphic filter
- ⑧ Wiener filter
- ⑨ Inverse filter

Sample Question

Illustrate with a diagram, the basic steps of DIP.

Fundamentals or Basic steps in DIP

- ① Image acquisition.
- ② Problem domain
- ③ Image enhancement
- ④ Image Restoration
- ⑤ Color Image processing
- ⑥ Wavelength / Multi-Resolution processing
- ⑦ Compression
- ⑧ Morphological processing
- ⑨ Segmentation
- ⑩ Representation & description (feature selection)

⑪ Recognition

Components of Image processing system

- ① Image sensor
- ② Specialize Image Processing hardware
- ③ Specialized Image processing software
- ④ Networking used for Image transmission and communication within remote site
- ⑤ Hardcopy
- ⑥ Computer:
 - i) General purpose
 - ii) Specialized
- ⑦ Main storage
- ⑧ Image Display [monitor]

Network Used for Image Transmission and Communication with remote site via the Internet

Basic Relationship between pixels

4-Neighbor (Connected Component)
 $N_4(P)$ (Only horizontal & vertical pixels)

8-Neighbor (Connected Component)
 $N_8(P)$ (Diagonal pixels are included)

Example

$\begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$	Image Type: Binary (between 0 & 1)
$\begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$	Image Type: Grayscale (between 0 & 255)

* For adjacency connection, a pixel can only be connected to its same value.

* Mixed adjacency diagonal connectivity does

not apply Take the straight path

* check the formula for computing the area of an image

* The area of an image is computed based on the pattern.

Histogram Equalization (To increase the brightness or contrast)
This is a spatial filter used for image enhancement.

Example.

3	2	4	5
7	7	8	2
3	1	2	3
5	4	6	7

Apply histogram equalization on the given image in a scale of 20.

Pixel Intensity	1	2	3	4	5	6	7	8
No of pixel	1	3	3	2	2	1	3	1
Probability	$\frac{1}{16}$	$\frac{3}{16}$	$\frac{3}{16}$	$\frac{2}{16}$	$\frac{2}{16}$	$\frac{1}{16}$	$\frac{3}{16}$	$\frac{1}{16}$
cumulative Probability (C-P)	$\frac{1}{16}$	$\frac{1}{16} + \frac{3}{16}$	$\frac{1}{16} + \frac{3}{16} + \frac{3}{16}$	$\frac{1}{16} + \frac{3}{16} + \frac{3}{16} + \frac{2}{16}$				
C-P x 20								
Floor rounding	1	5	8	11	13	15	18	20

$$\begin{bmatrix} 3 & 2 & 4 & 5 \\ 1 & 1 & 8 & 2 \\ 3 & 1 & 2 & 3 \\ 5 & 4 & 6 & 7 \end{bmatrix} \Rightarrow \begin{bmatrix} 8 & 5 & 11 & 13 \\ 18 & 18 & 20 & 5 \\ 8 & 1 & 5 & 8 \\ 13 & 11 & 15 & 18 \end{bmatrix}$$

Median filter

Apply a median filter on the image mask or kernel given below. Use a 3×3 kernel

18	22	33	25
34	128	24	172
22	19	32	31
17	33	32	20

Soln

First 3×3

18 19 22 24 34 33

128

Median = $\frac{128}{2} = 24$

Second 3×3

19 22 24 25 31 32 33 128 172

24 \Rightarrow 31

Third 3×3

17 19 22 24 32 32 34 128

19 \Rightarrow 32

fourth 3×3

1/9 2/6 2/4 3/1 3/2 3/3
1/2/8 1/12
 $32 \Rightarrow 32$

Color Space

This is a method by which we can create and visualize colors. As humans, we ~~can~~ ^{may} define a color by its attributes of brightness, ^{hue and colorfulness} ~~but~~. A computer may define a color using the amount of red, green, and blue phosphor emission required to match color. For example, a printing press may achieve a color by the reflectance and absorbance of Cyan, Magenta, etc. There are different types which are:

- ① HSI (Hue Saturation and Intensity)
- ② RGB

NB: Take note of the formula for converting from RGB to HSI

$$r = \frac{R}{R+G+B}; \quad g = \frac{G}{R+G+B}; \quad b = \frac{B}{R+G+B}$$

$$h = \cos^{-1} \left[\frac{0.5(r-g) + (r-b)}{[r-g]^2 + [(r-b)(g-b)]^{1/2}} \right] \quad h \in [0, \pi] \quad \text{for } b \leq g$$

$$h = 2\pi - \cos^{-1} \left[\dots \right] \quad \text{for } b > g$$

(Saturation) $s = 1 - 3 \min(r, g, b)$

(Intensity) $i = \frac{1}{3}(R+G+B)$

Example

Given an image:

r	g	b
$(100, 100, 100)$	$(150, 0, 0)$	$(0, 150, 0)$
$(255, 0, 0)$	$(255, 255, 255)$	$(0, 0, 0)$
$(100, 150, 200)$	$(0, 0, 255)$	$(100, 200, 50)$

To compute HSI value of A_3
(100, 150, 200)

where $R=100$; $G=150$; $B=200$
 $r=?$, $g=?$, $b=?$

soln.

$$r = \frac{R}{R+G+B} = \frac{100}{100+150+200} = 0.2222$$

$$g = \frac{G}{R+G+B} = \frac{150}{100+150+200} = 0.3333$$

$$b = \frac{B}{R+G+B} = \frac{200}{100+150+200} = 0.4444$$

$b > g$ Therefore

$$h = 2\pi - \cos^{-1} \left[\frac{0.5(r-g) + (r-b)}{[(r-g)^2 + (r-b)(g-b)]^{1/2}} \right]$$

$$\begin{aligned} & 0.5(0.2222 - 0.3333) + (0.2222 - 0.4444) \\ & (0.2222 - 0.3333)^2 + \sqrt{(0.2222 - 0.4444)(0.3333 - 0.4444)} \\ & = 0.0 \end{aligned}$$

Morphological Image Processing

Types of Morphological operation

~~Erosion~~ Dilation

~~Erosion~~

Closing

Opening

~~Erosion~~ Dilation

Dilation

The ~~Erosion~~ of a binary image A and a structuring element (mask or filter) B is given as:

B is given as:

$$A \oplus B = \bigcup_z \{ (\hat{B})_z \cap A \neq \emptyset \}$$

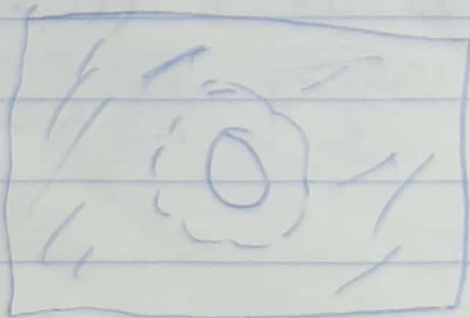
Where,

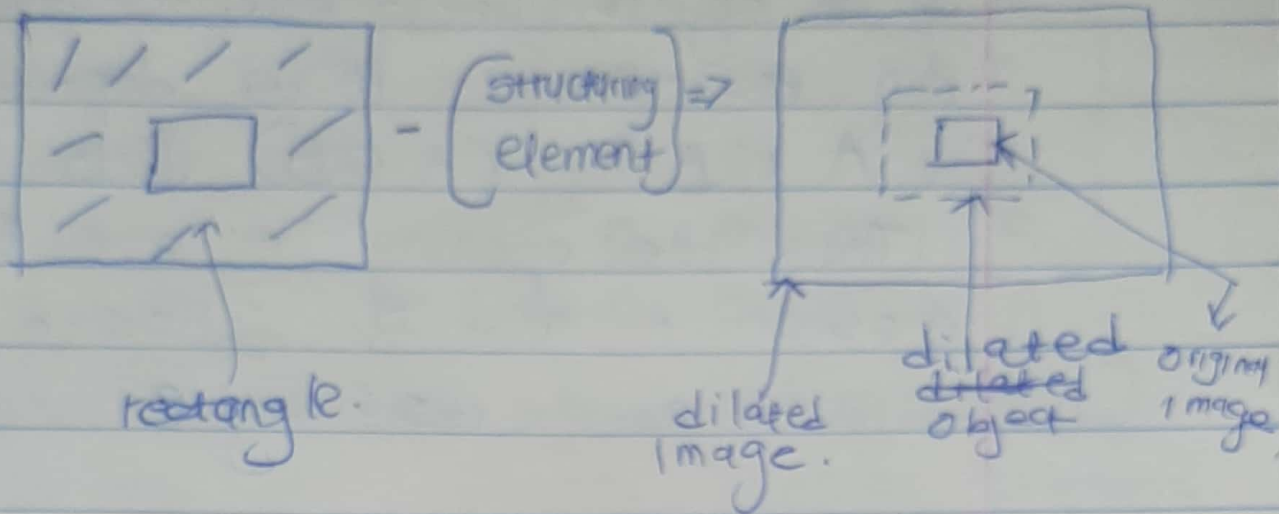
A = Image

B = Structuring element

z = displacement

\hat{B} = reflection of B





Erosion

The Erosion of a Binary Image A and a structuring element B is defined as:

$$A \ominus B = \{z \mid (B)_z \subseteq A\}$$

NB Erosion shrinks an image

The eqn indicates that the erosion of A and B is a subset of z such that B translated by z is contained in A .

Opening

Opening generally smooths the contour

of an object, break narrow strips, and thin protrusion. It is defined by:

$$A \circ B = (A \ominus B) \oplus B$$

Thus, the opening A and B is the erosion A and B , followed by the dilation of the result by B .

Closing

This tends to smooth section of contours but as opposed to opening, it generally fuses narrow breaks, eliminates small holes and fills gaps in the contour.

$$A \cdot B = (A \oplus B) \ominus B$$

Thus the closing A and B is the dilation of A and B followed by the erosion of the result by B .

Example

Given Image $\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

and structuring element $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$
compute the dilation, erosion, opening
and closing

Solution

- i) For erosion, multiply and take the minimum value as the new value

$$\begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \\ = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}.$$

The minimum value is 0, use it to replace the middle element.

- ii) For dilation, multiply and take the maximum value as the new value.

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

CPE 544

— Image Segmentation (Region Based, Edge Based), AI

Region Based: ① Global Thresholding
② Local Thresholding. ③ Active Contour

Edge based: ① Graph cut ② Gaussian

* Look @ the different types of Image Segmentation

* Understand Object detection



* Why do we need Image Segmentation?

It is very helpful in healthcare Industries unlike object detection. It can be used to identify the shape of a cancerous cell but object detection only creates a bounding box.

Image segmentation Based on clustering
E.g. KMeans is one of the most commonly used clustering.

* State on Image segmentation under clustering

* State the steps involved

* Try to read up GLCM and LBP

- Look at principle of operation
- Look at distance between pixels
- Look at how to implement θ value

GLCM

LBP

LBP

* Look at feature extraction method

* Try to read up SVM. (SVM is supervised)