

# Robust Singular Values based on L1-norm PCA

Team: Linear Men

Team members:

Makhin Artem

Kuznetsov Mikhail

Mumladze Maximilian

Zelentsov Aleksei

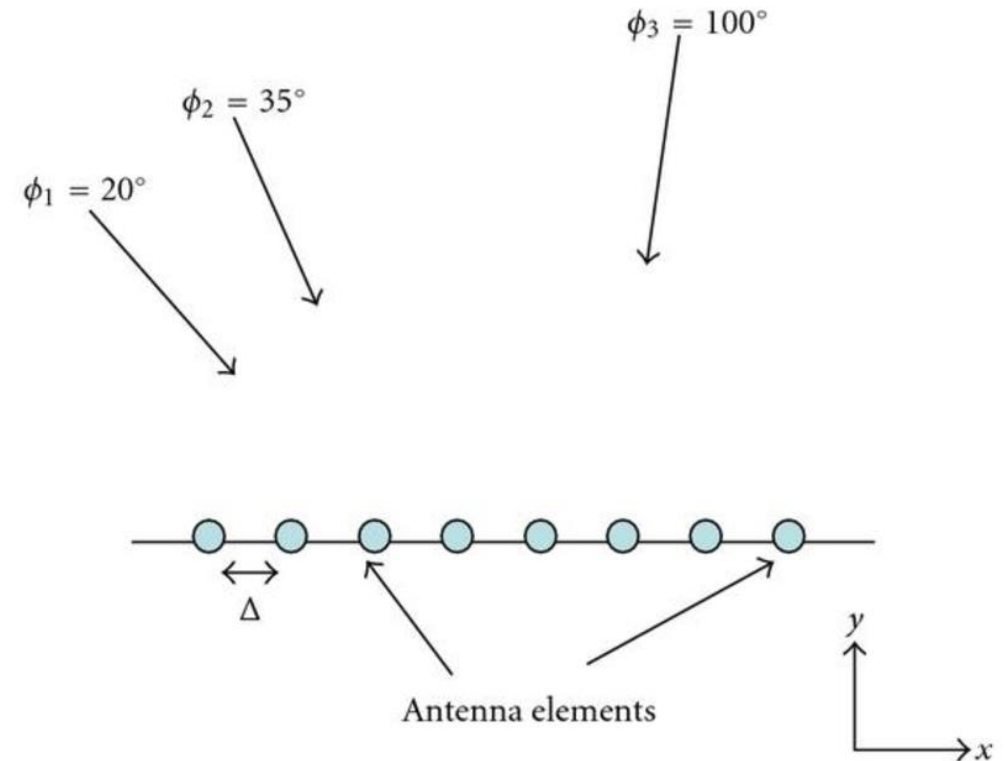


# Problem

- L2 for PCA is sensitive against outliers
- SVD inherits this outlier sensitivity.
- **We need a robust solution.**
- We implemented SVD and Singular Value (SV) estimation using L1-cSVD.

**Robust SV estimation** is useful for many engineering problems:

- Channel capacity estimation
- DOA estimation
- Restructuring of Deep NN Acoustic models



# Solution

There were solutions for **Robust PCA**, using **L1-PCs**

But the results do not diagonalize the data matrix (**No SVs**)

In this paper, authors utilize previous algos to define a new method called **L1-cSVD** for finding **SVs**

**Basically, we want to find**  $\mathbf{X} \approx \mathbf{U}_{L1} \mathbf{\Sigma}_{L1} \mathbf{V}_{L1}^T$ ,

Where singular vectors are **L1-PCs**

For  $\mathbf{X}$  to be diagonalizable, the problem becomes

$$(\mathbf{\Sigma}_{L1}, \mathbf{V}_{L1}) = \underset{\substack{\mathbf{V} \in \mathbb{S}^{N \times K}, \\ \mathbf{\Sigma} \in \text{diag}(\mathbb{R}^K)}}{\text{argmin}} \|\mathbf{X}^T \mathbf{U}_{L1} - \mathbf{V} \mathbf{\Sigma}\|_{1,1}.$$

This is a **non-convex opt. problem**, so using different techniques, authors come up with the algorithm on the right

Done by **Makhin Artem**

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**Algorithm 1** L1-cSVD (proposed)

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**Input:** Data matrix  $\mathbf{X}_{D \times N}$ , number of SVs  $K$

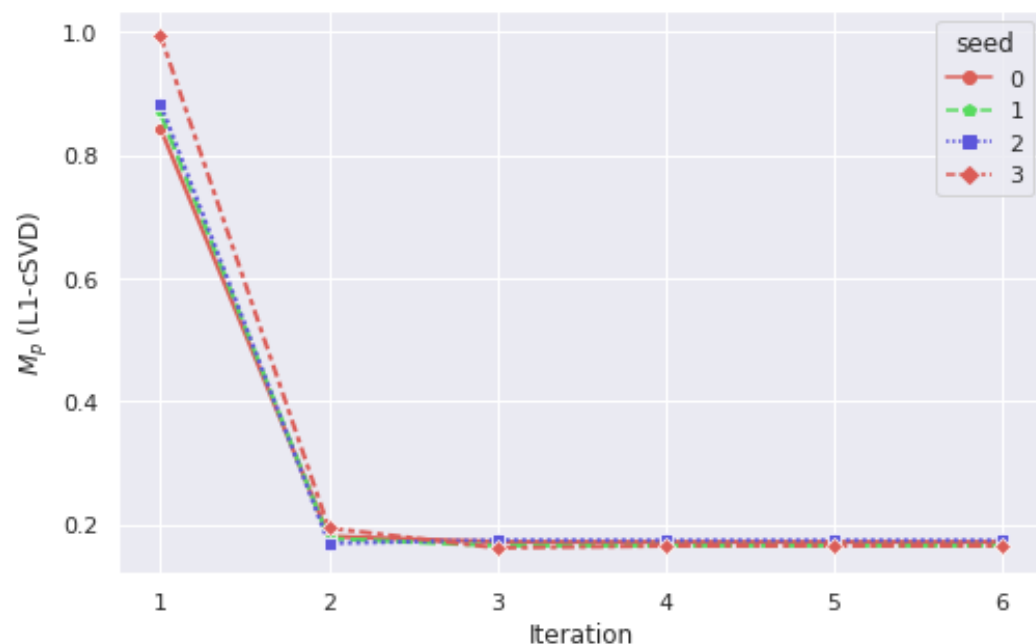
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1:  $\mathbf{U} \leftarrow \text{L1PCA}(\mathbf{X})$ 
2:  $\mathbf{A} \leftarrow \mathbf{X}^T \mathbf{U}$ 
3: initialization  $\mathbf{\Sigma} \leftarrow \text{zeros}(K, K)$ , orthonormal  $\mathbf{V}$ 
4: while not converged do
5:   for  $i = 1$  to  $K$  do
6:     for  $j = 1$  to  $N$  do
7:        $s_j \leftarrow ([\mathbf{A}]_{j,i} / [\mathbf{V}]_{j,i})$ 
8:        $M_j \leftarrow \|[\mathbf{A}]_{:,i} - s[\mathbf{V}]_{:,i}\|_1$ 
9:     end for
10:     $j_{\text{opt}} \leftarrow \underset{j \in [1:N]}{\text{argmin}} \{M_j\}$ 
11:     $[\mathbf{\Sigma}]_{i,i} \leftarrow s_{j_{\text{opt}}}$ 
12:   end for
13:    $(\mathbf{U}', \mathbf{\Sigma}', \mathbf{V}') \leftarrow \text{SVD}(\mathbf{A} \mathbf{\Sigma}^{-1})$ 
14:    $\mathbf{V} \leftarrow \mathbf{U}' \mathbf{V}'^T$ 
15: end while
```

**Output:**  $\mathbf{U}_{L1} \leftarrow \mathbf{U}$ ,  $\mathbf{\Sigma}_{L1} \leftarrow \mathbf{\Sigma}$ ,  $\mathbf{V}_{L1} \leftarrow \mathbf{V}$

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# Experiments, pt.1-2

## Convergence Analysis



$$M_P = \|\mathbf{U}^T \mathbf{X} - \Sigma \mathbf{V}^T\|_{1,1} / \|\mathbf{U}^T \mathbf{X}\|_{1,1}$$

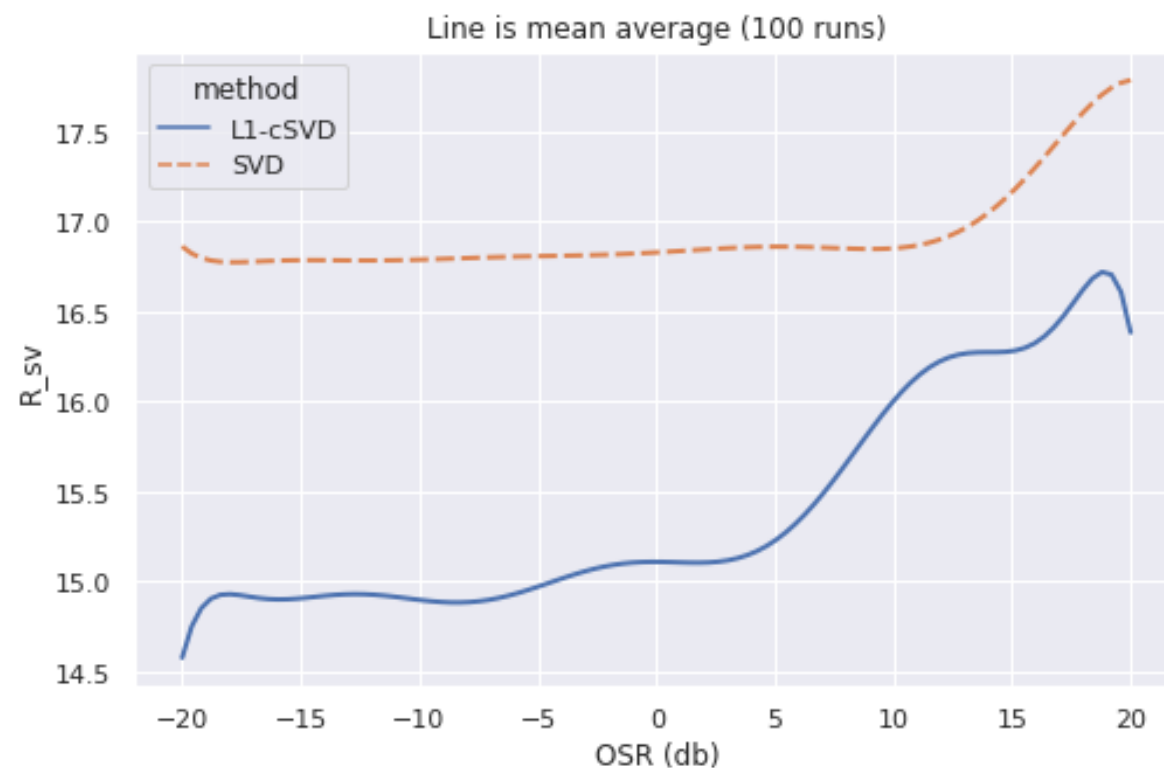
We see that for all 4 initializations, **L1-cSVD** converges

Done by **Kuznetsov Mikhail**

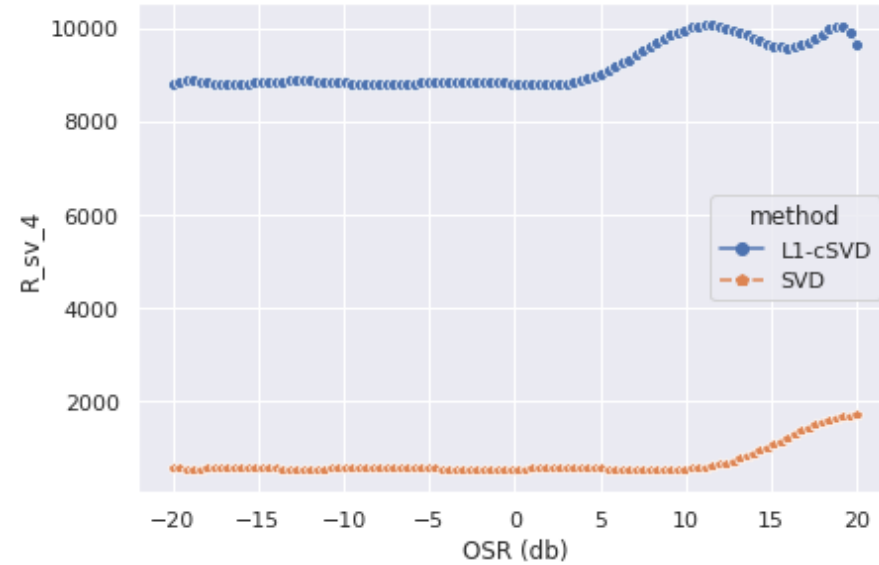
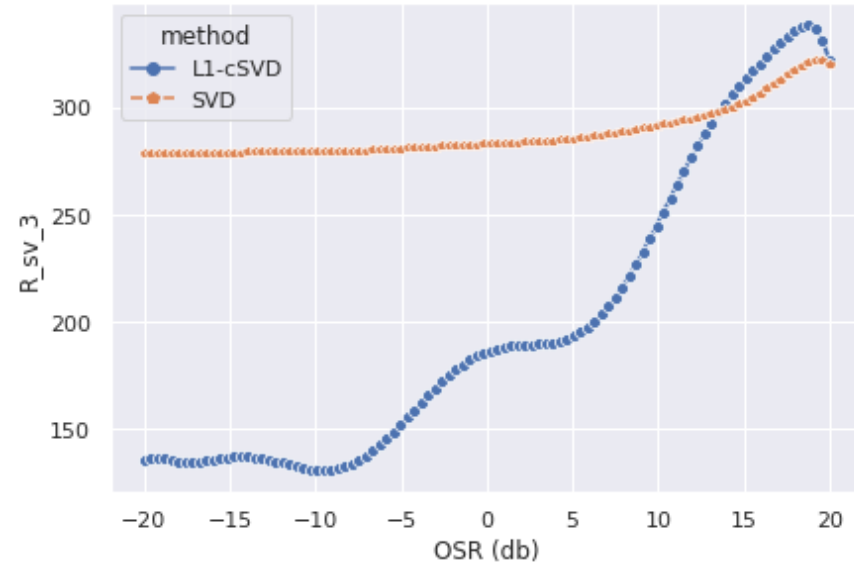
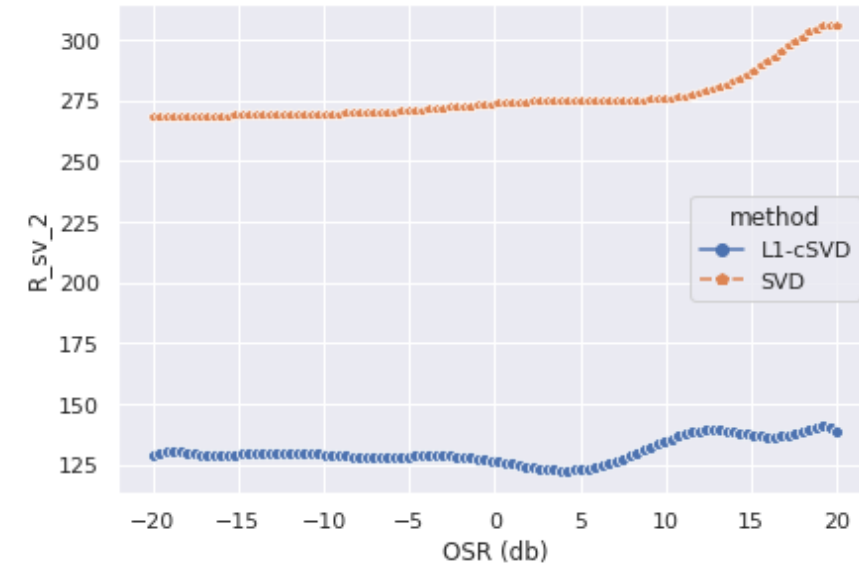
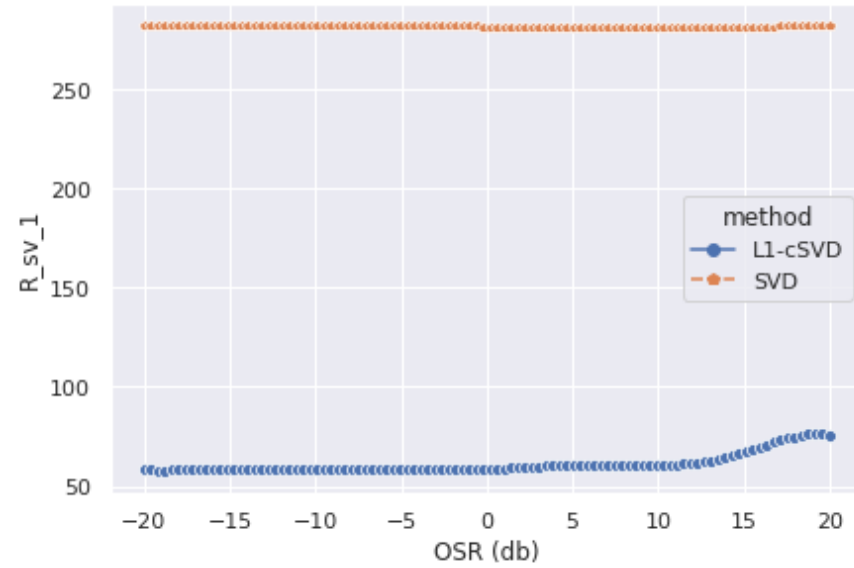
## Performance Analysis

We test algos on **SV estimation** using noisy data  $R_{sv} = \frac{\|\Sigma^{\text{estimated}} - \Sigma^{\text{clean}}\|_{2,2}}{\|\Sigma^{\text{clean}}\|_{2,2}},$

**L1-cSVD** performs better than **SVD**



# Experiments, pt.1-2



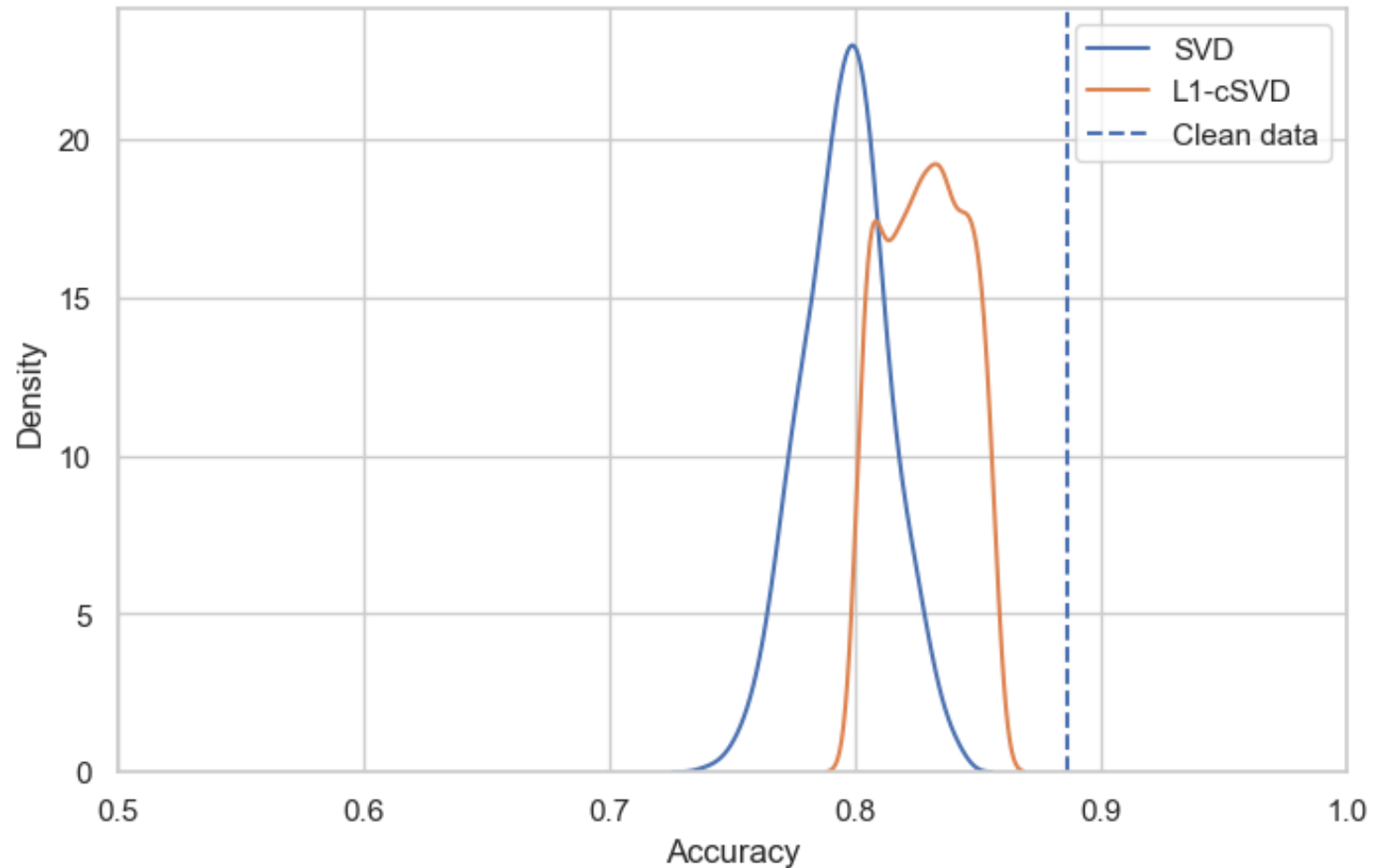
# Experiments, pt. 3

## Bayesian Classifier

We use Vowel dataset from PMLB, **augmented with outliers**

And then we train a classifier using **standard SVD** and **L1-cSVD**

**Our algorithm performs better on corrupted data**



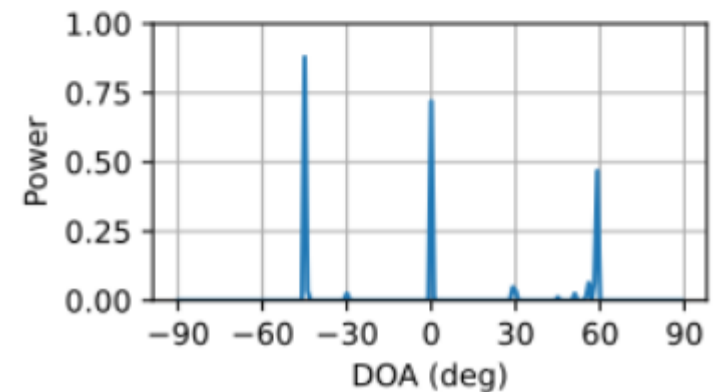
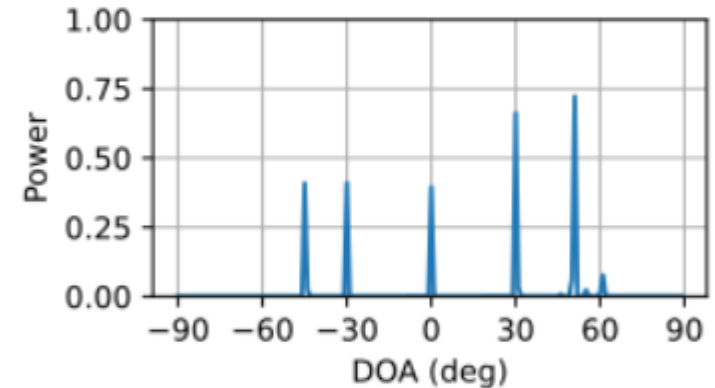
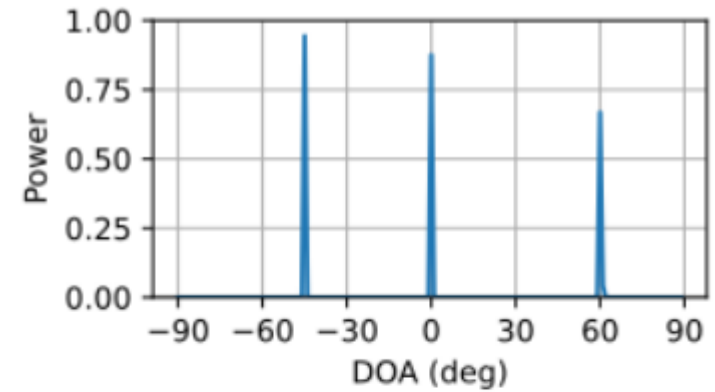
# Experiments, pt. 4

## Direction of Arrival Estimation

We create incoming signals and add **outlier noise**

We obtain a spatial spectrum through l1-SVD using **standard SVD** and **L1-cSVD** for dim. reduction

Once again, our algorithm performs better on corrupted data



# Conclusion

Using several examples, we've shown that **L1-cSVD** performs better **Singular Values Estimation** on datasets with gross and sparse outliers than other solutions