تشغيل وتثبيت باكج الذراع على ROS noetic

```
$ sudo apt-get install ros- noetic -moveit
$ sudo apt-get install ros- noetic -joint-state-publisher ros- noetic -
joint-state-publisher-gui
$ sudo apt-get install ros- noetic -gazebo-ros-control joint-state-
publisher
$ sudo apt-get install ros- noetic -ros-controllers ros- noetic -ros-
control
```