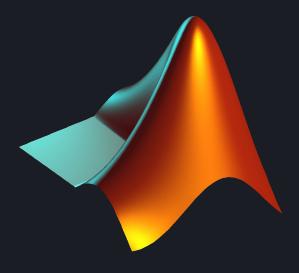
Session Content

• Automate repetitive Modeling and Simulation Tasks





Automate repetitive Modeling and Simulation Tasks

Exercise: Create P-Controller Library Using Script File

In this exercise, you will create a P-Controller library using MATLAB script files. You will first create a script to design the P-Controller block and save it as a library. Then, you will create another script to instantiate the P-Controller block and connect it to a Step Input block for testing.

Here's how you can structure the exercise:

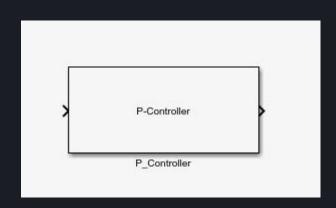
- Create a MATLAB script to design the P-Controller block and save it as a library.
- Create another MATLAB script to instantiate the P-Controller block and connect it to a Step Input block for testing.

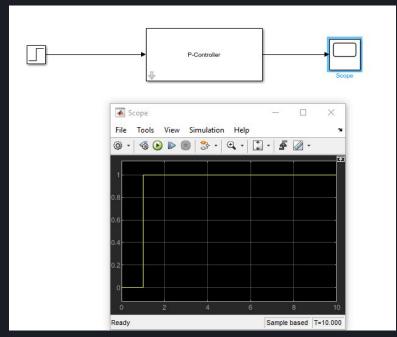




Automate repetitive Modeling and Simulation Tasks

Exercise: Create P-Controller Library Using Script File







Automate repetitive Modeling and Simulation Tasks

Exercise: Create Counter Using Script File

In this exercise, you will create a Counter using MATLAB script files. You will first create a script to design the Counter block and save it as a model.

Here's how you can structure the exercise:

• Create a MATLAB script to design the Counter block and save it as a model.

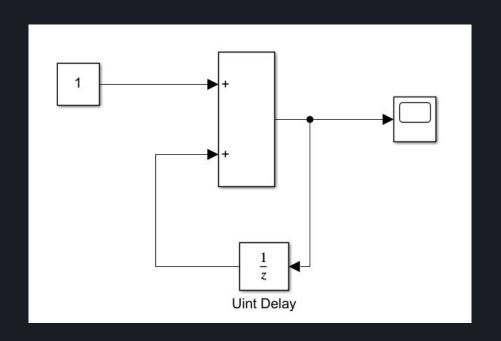




Automate repetitive Modeling and Simulation Tasks

Exercise: Create Counter Using Script File

Now, it is required to show the name of unit delay





Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

- The find_system function in MATLAB's Simulink environment is used to search for blocks and systems in a Simulink model based on specified criteria. It allows you to programmatically locate blocks and systems within a model, which can be useful for tasks such as automation, analysis, and debugging.
- model is the name of the Simulink model or a handle to the model.
- 'criteria' is a string specifying the search criteria. This can include various options such as block type, block name, block parameter values, etc.



Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

- Find all blocks of a specific type
- This will find all Gain blocks in the Simulink model named 'myModel'.

blocks = find_system('myModel', 'BlockType', 'Gain');



Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

- Find all blocks with a specific name
- This will find all blocks with the name 'Controller' in the Simulink model named 'myModel'.

blocks = find_system('myModel', 'Name', 'Controller');



Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

- Find all blocks with a specific parameter value
- This will find all blocks with the parameter 'Gain' set to '2' in the Simulink model named 'myModel'.



Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

- Find all blocks within a specific subsystem
- This will find all blocks within the subsystem named 'Subsystem1' in the Simulink model named 'myModel', considering only blocks at the first level of hierarchy.

blocks = find_system('myModel/Subsystem1', 'SearchDepth', 1);



Automate repetitive Modeling and Simulation Tasks

find_system(model,'criteria');

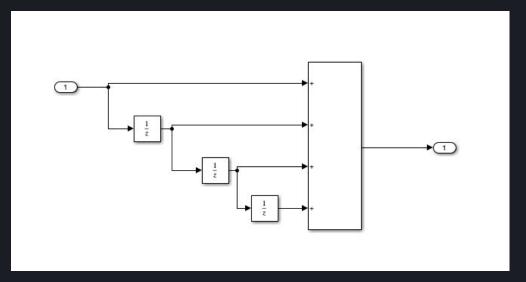
- Find all blocks matching multiple criteria
- This will find all Gain blocks with the name 'Controller' in the Simulink model named 'myModel'.

blocks = find_system('myModel', 'BlockType', 'Gain', 'Name', 'Controller');



Automate repetitive Modeling and Simulation Tasks

Exercise: Required to show the name of unit delay

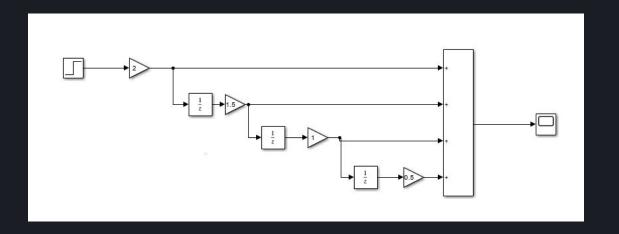






Automate repetitive Modeling and Simulation Tasks

Exercise: Required to set the sample of all gain blocks





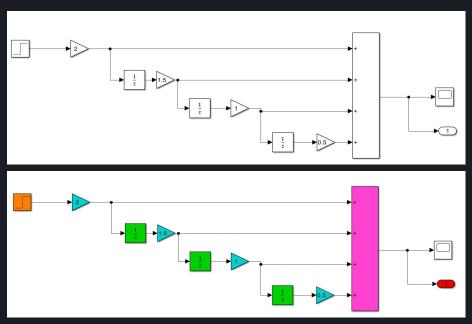


Automate repetitive Modeling and Simulation Tasks

Exercise: Required to programmatically color the blocks based upon their blocks types

- in case "Step" orange background.
- in case "Gain" Cyan background
- in case "UnitDelay" Green background
- in case "Sum" Magenta background
- in case "outport" Red background







Automate repetitive Modeling and Simulation Tasks

Exercise: Required to programmatically subsystem Multiply By x

 Implement function take model name and value of x then create the model contain subsystem

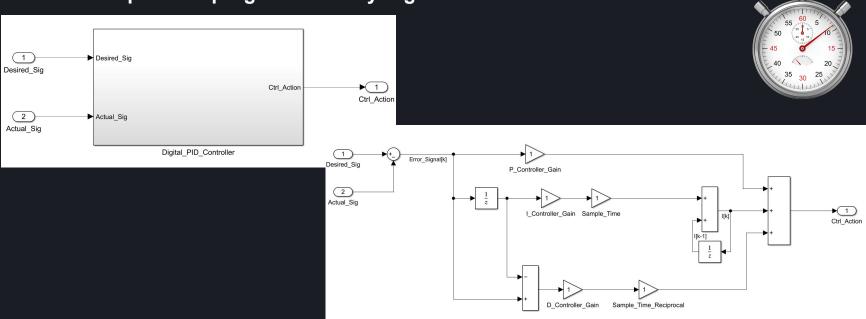






Automate repetitive Modeling and Simulation Tasks

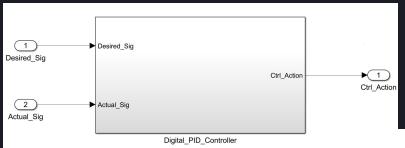
Exercise: Required to programmatically Digital PID Controller



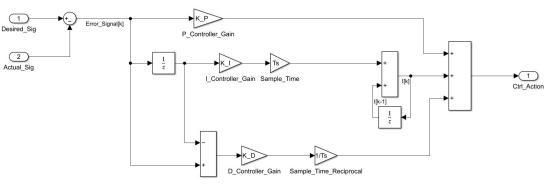


Automate repetitive Modeling and Simulation Tasks

Exercise: Required to programmatically Digital PID Controller





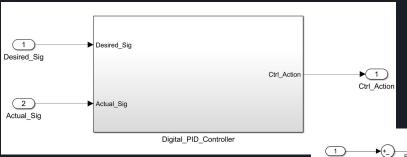




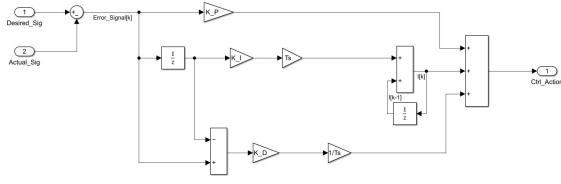
Model-Based Development Program

Automate repetitive Modeling and Simulation Tasks

Exercise: Required to programmatically Digital PID Controller









Model-Based Development Program



