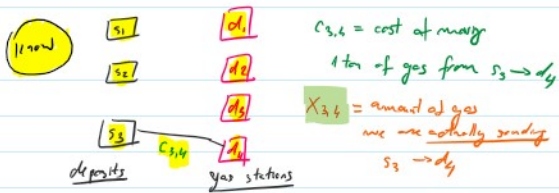


LINEAR PROGRAMMING



$X = (x_{11}, \dots, x_{34})$ optimal allocation

(LP)
$$\min \left(\sum_{i=1}^3 \sum_{j=1}^2 c_{ij} x_{ij} \right)$$
 (Total Cost)

Constraints:

- $\sum_i x_{i1} \leq s_i$ (we have enough gas in s_i for the allocation)
- $\sum_j x_{ij} \geq d_j$ ("demand d_j is met")
- $x_{ij} \geq 0$ (real numbers) ("physical constraints")

Linear constraints, Constants, Linear function.

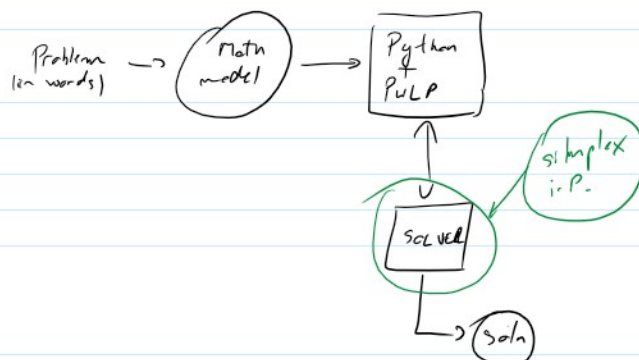
$\leq, \geq, = \checkmark$
 $<, >, \neq \times$

Exp.
$$\begin{cases} \max (2x + 3y) \\ x + y \leq 3 \\ 2x + y \leq 4 \\ x, y \geq 0 \end{cases}$$

GOOD NEWS LP has efficient algorithms

- in theory
- in practice

ALGORITHMS **SIMPLEX alg.**
INTERIOR POINT METHODS



BAD NEWS FEWER) PROBLEMS CAN BE MODELED
AS L.P.

ILP

LP with the restriction that
we only care about solns
where all variables take
integral values

different algorithms

Bad News

ILP harder

theory
practice

ILP is NP-complete problem

order of magnitude
smaller than LP

Good News

Way more problems can be modeled
as ILP (ILP is NP-complete)

ILP being NP-complete?

(COMPUTATIONAL COMPLEXITY)

P ≠ NP problem

Algorithms

$O(n \log n)$ $O(n^2)$, $O(n^3)$

"good algorithm" $O(n^k)$ for some $k > 0$

DECISION
PROBLEMS

INPUT X
ANSWER YES/NO

P = class of decision problems that have
algs with complexity $O(n^k)$

"easy (decision)
problems"

$LP \in P$ (KHACHIAN
"ellipsoid method")

New York Times
good in theory, not so in practice

SIMPLEX (DANTZIG)
ALG. '47

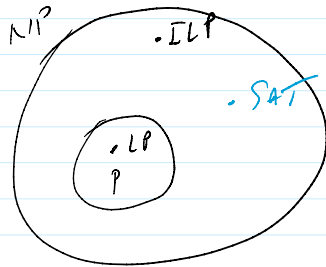
bad in theory
but
good in practice

problem
LP

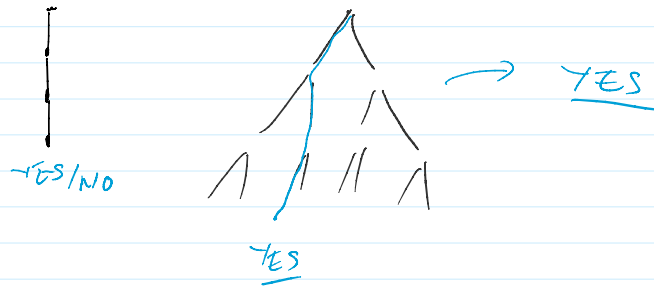
→ change
LP a little
bit

(exponential)

likely easy
pb for SIMPLE



NP nondeterministic polynomial time.

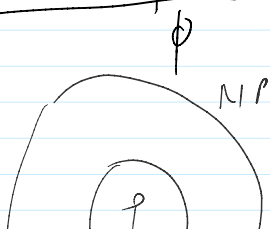
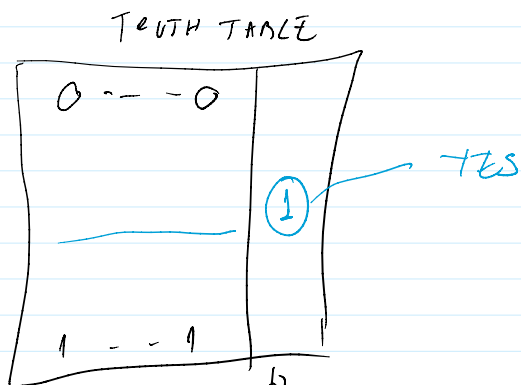


guess soln \rightarrow easy to verify
that it is
soln indeed

EXAMPLE SAT (satisfiability problem)

INPUT Logical formula $\phi(x_1, \dots, x_n)$

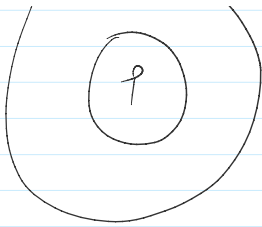
TO DECIDE Can I assign values
TRUE / FALSE to x_1, \dots, x_n
to satisfy ϕ ?



$P \stackrel{?}{=} NP$

1,000,000 \$
(reward
(CLAY INSTITUTE))

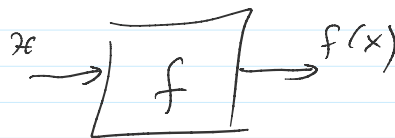
Probably SAT does not



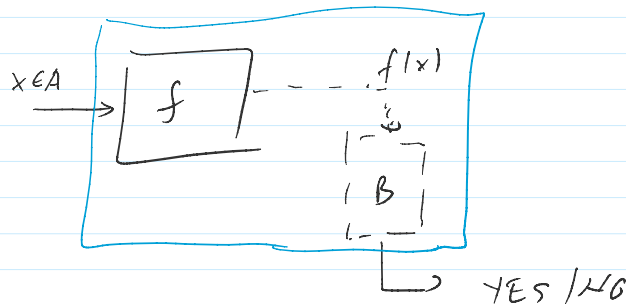
Probably SAT does not
have poly time algorithm
 $\left\{ \begin{array}{l} \text{Probably ILP does } \underline{\text{not}} \\ \text{have poly time alg} \end{array} \right\}$

A, B decision problems

$A \leq B$ (A reduces to B)
 \exists poly time alg f



$$x \in A \Leftrightarrow f(x) \in B$$



A reduces to B

B is "harder" / "more expressive" than A

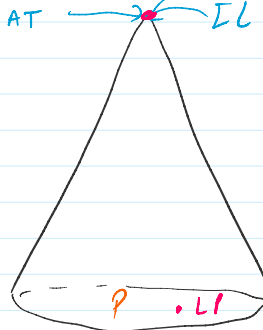
$$A \leq A$$

$$A \leq B, B \leq C \Rightarrow A \leq C$$

$A \leq B$ and $B \in P$
then $A \in P$

SAT — ILP

NP



(T) (Cook-Karp)

.....

①

(COOK - KARP)

SAT / ILP

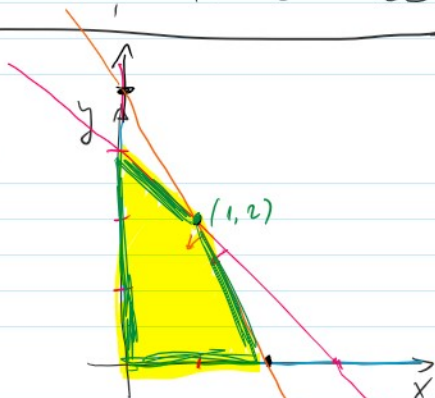
NP-complete

SAT \in NP
 $\forall A \in \text{NP } A \leq \text{SAT}$

I can solve every problem in NP using a
 (SAT solver) (ILP solver)

LINEAR PROGRAMMING, GEOMETRICALLY

$$\begin{cases} \max (2x + 3y) \\ x + y \leq 3 \\ 2x + y \leq 4 \\ x, y \geq 0 \end{cases}$$



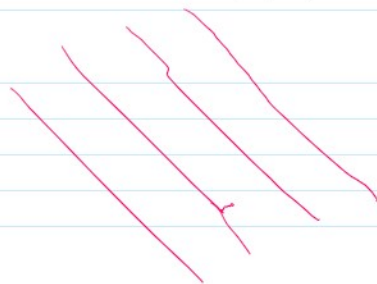
feasible satisfies all constraints
soln not nec. optimal

P = feasible solns \rightarrow polygon

vertices (0,0)
 (2,0)
 (0,3)
 (1,2)

$2x + 3y = \lambda$ line

When λ changes



Conclusion max is reached at some vertex
 of the polygon.

(0,0)

$\frac{2x + 3y}{0}$

OPTIMAL

$(0,0)$	0
$(2,0)$	4
$(0,3)$	9
$(1,2)$	8

OPTIMAL
SOLN

$x=0$
 $y=3$ OPT
Soln

WHAT CAN GO WRONG?

(1) Problem is INCOMPATIBLE (INFEASIBLE)

Exp Gas station Pb.

TOTAL GAS 1 ton

Total demand 2 tons

(2) INFINITELY MANY ^{OPTIMAL} SOLTS,



(3) INFINITE OPTIMUM

$$\begin{cases} \max (x) \\ x \geq 1 \\ x \geq 0 \end{cases}$$

(4) n variables

GOOD NEWS set of feasible solns in Polyhedron
 \mathbb{R}^n

BAD NEWS exponentially many (or n)
vertices.