IIOT 2404: Internet of Things Application Lab LAB--03

OBJECTIV	Interface ESP32 with Ultrasonic Sensor and show output at 0.96' OLED Display
E/ AIM	and in BLYNK.
SOFTWA RE REQUIRE D	Arduino IDE
CODE	<pre>#define BLYNK_TEMPLATE_ID "TMPL3rfdZNcyO" #define BLYNK_TEMPLATE_NAME "ULTRASONIC" #define BLYNK_AUTH_TOKEN "dBoRlw2lDdHl-HARklFF1MAwdyiBWQwZ"  #include <wire.h> #include <adafruit_gfx.h> #include <adafruit_ssd1306.h> #include <wifi.h></wifi.h></adafruit_ssd1306.h></adafruit_gfx.h></wire.h></pre>
	<pre>#include <blynksimpleesp32.h> #define SCREEN_WIDTH 128 // OLED display width, in pixels #define SCREEN_HEIGHT 64 // OLED display height, in pixels</blynksimpleesp32.h></pre>
	<pre>// Declaration for an SSD1306 display connected to I2C (SDA, SCL pins) Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &amp;Wire, -1);</pre>
	<pre>const int trigPin = 5; const int echoPin = 18;</pre>
	<pre>// Define sound speed in cm/uS #define SOUND_SPEED 0.034 #define CM_TO_INCH 0.393701</pre>
	<pre>long duration; int distanceCm; float distanceInch; // Changed to float for precision</pre>
	<pre>// Wi-Fi credentials char ssid[] = "S23"; // Your Wi-Fi SSID char pass[] = "aman09877"; // Your Wi-Fi password</pre>

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## **LAB-03**

```
void setup() {
 Serial.begin(115200);
 pinMode(trigPin, OUTPUT); // Sets the trigPin as an Output
  pinMode(echoPin, INPUT); // Sets the echoPin as an Input
 // Initialize display
 if (!display.begin(SSD1306 SWITCHCAPVCC, 0x3C)) {
    Serial.println(F("SSD1306 allocation failed"));
   for (;;);
 delay(500);
 display.clearDisplay();
 display.setTextSize(1);
 display.setTextColor(WHITE);
 // Connect to Blynk
 Blynk.begin(BLYNK AUTH TOKEN, ssid, pass);
}
void loop() {
 // Blynk run
 Blynk.run();
 // Clears the trigPin
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 // Sets the trigPin on HIGH state for 10 microseconds
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 // Reads the echoPin, returns the sound wave travel time
in microseconds
 duration = pulseIn(echoPin, HIGH);
 // Calculate the distance in cm
 distanceCm = duration * SOUND SPEED / 2;
 // Convert to inches (using float)
 distanceInch = distanceCm * CM TO INCH;
```

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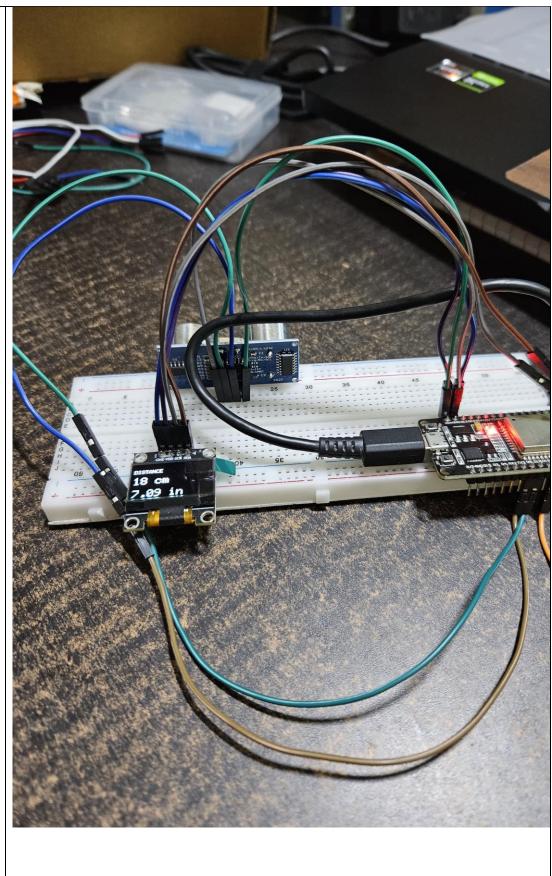
## **LAB-03**

```
// Prints the distance in the Serial Monitor
 Serial.print("Distance (cm): ");
 Serial.println(distanceCm);
 Serial.print("Distance (inch): ");
 Serial.println(distanceInch);
 // Display distance on OLED
 display.clearDisplay();
 display.setCursor(0, 10);
 display.setTextSize(1);
 display.print("DISTANCE");
 display.setCursor(0, 25);
 display.setTextSize(2);
 display.print(distanceCm);
 display.print(" cm");
 display.setCursor(0, 50);
 display.setTextSize(2);
 display.print(distanceInch, 2); // Printing float value
with 2 decimal places
 display.print(" in");
 display.display();
 // Send distance to Blynk (Virtual Pin V3 for cm and V4
for inch)
 Blynk.virtualWrite(V3, distanceCm); // Sending integer
value for cm
 Blynk.virtualWrite(V4, distanceInch); // Sending float
value for inches
 delay(500);
}
```

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OUTPUT/ PHOTO



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# **LAB-03**

