

PRACTICAL 7

//AIM:- WAP and Algorithm of Dijkstra

//Algorithm

1 Initialize-single-source(G-S)

2 $S \leftarrow \emptyset$

3 $Q \leftarrow V[G]$

4 While $Q \neq \emptyset$

$U \leftarrow \text{ExtraMin}(Q)$

$S \leftarrow S \cup \{U\}$

 For each vertex $v \in \text{adj}(u)$

 Do relax (u, v, w)

//PROGRAM

```
#include <iostream>
using namespace std;
#include <limits.h>
```

```
#define V 9
```

```
int minDistance(int dist[], bool sptSet[])
{
```

```
    // Initialize min value
```

```
    int min = INT_MAX, min_index;
```

```
    for (int v = 0; v < V; v++)
```

```
        if (sptSet[v] == false && dist[v] <= min)
```

```
            min = dist[v], min_index = v;
```

```
    return min_index;
```

```
}
```

```

void printSolution(int dist[])
{
    cout << "Vertex \t Distance from Source" << endl;
    for (int i = 0; i < V; i++)
        cout << i << " \t\t" << dist[i] << endl;
}

```

```

void dijkstra(int graph[V][V], int src)
{
    int dist[V]; // The output array. dist[i] will hold the shortest
    // distance from src to i

    bool sptSet[V]; // sptSet[i] will be true if vertex i is included in shortest
    // path tree or shortest distance from src to i is finalized

    // Initialize all distances as INFINITE and sptSet[] as false
    for (int i = 0; i < V; i++)
        dist[i] = INT_MAX, sptSet[i] = false;

    // Distance of source vertex from itself is always 0
    dist[src] = 0;

    // Find shortest path for all vertices
    for (int count = 0; count < V - 1; count++) {

        int u = minDistance(dist, sptSet);

        // Mark the picked vertex as processed
        sptSet[u] = true;

        // Update dist value of the adjacent vertices of the picked vertex.
        for (int v = 0; v < V; v++)

            // Update dist[v] only if it is not in sptSet, there is an edge from
            // u to v, and total weight of path from src to v through u is
            // smaller than current value of dist[v]
            if (!sptSet[v] && graph[u][v] && dist[u] != INT_MAX
                && dist[u] + graph[u][v] < dist[v])
                dist[v] = dist[u] + graph[u][v];
    }

    // print the constructed distance array

```

```

    printSolution(dist);
}

// driver program to test above function
int main()
{

    /* Let us create the example graph discussed above */
    int graph[V][V] = { { 0, 4, 0, 0, 0, 0, 0, 8, 0 },
                        { 4, 0, 8, 0, 0, 0, 0, 11, 0 },
                        { 0, 8, 0, 7, 0, 4, 0, 0, 2 },
                        { 0, 0, 7, 0, 9, 14, 0, 0, 0 },
                        { 0, 0, 0, 9, 0, 10, 0, 0, 0 },
                        { 0, 0, 4, 14, 10, 0, 2, 0, 0 },
                        { 0, 0, 0, 0, 0, 2, 0, 1, 6 },
                        { 8, 11, 0, 0, 0, 0, 1, 0, 7 },
                        { 0, 0, 2, 0, 0, 0, 6, 7, 0 } };

    dijkstra(graph, 0);

    return 0;
}

```

//OUTPUT

```

Run: Aloop
C:\Users\Lenovo\.jdk\openjdk-17.0.1\bin\java.exe "-javaagent:C:\Users\Lenovo\AppData\Local\JetBrains\IntelliJ IDEA Community Edition 2021.3\lib\idea
The shortest path from node :
0 to 0 is 0
0 to 1 is 8
0 to 2 is 6
0 to 3 is 5
0 to 4 is 3

Process finished with exit code 0

```

//COMPLEXITY

Time Complexity $O(V^2)$