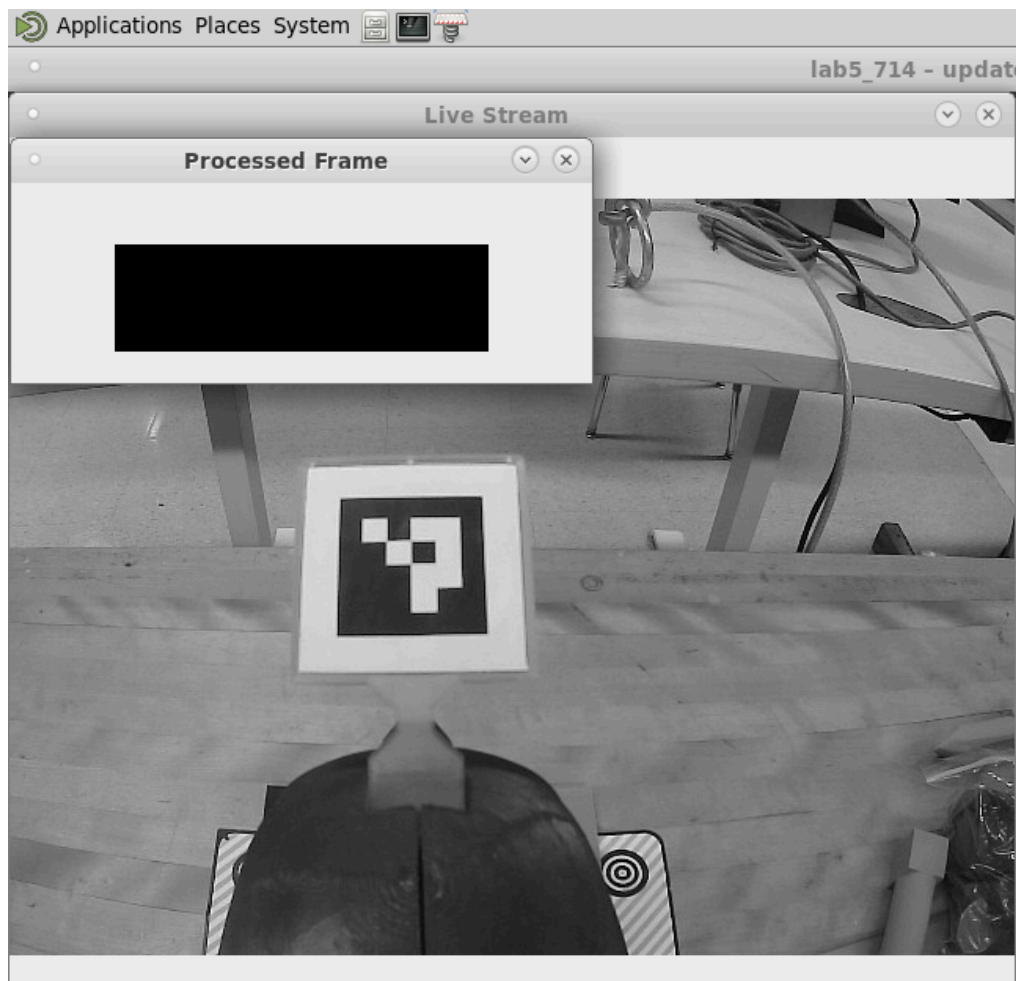




Fig 1: Robot joint movement



Robot camera point of view