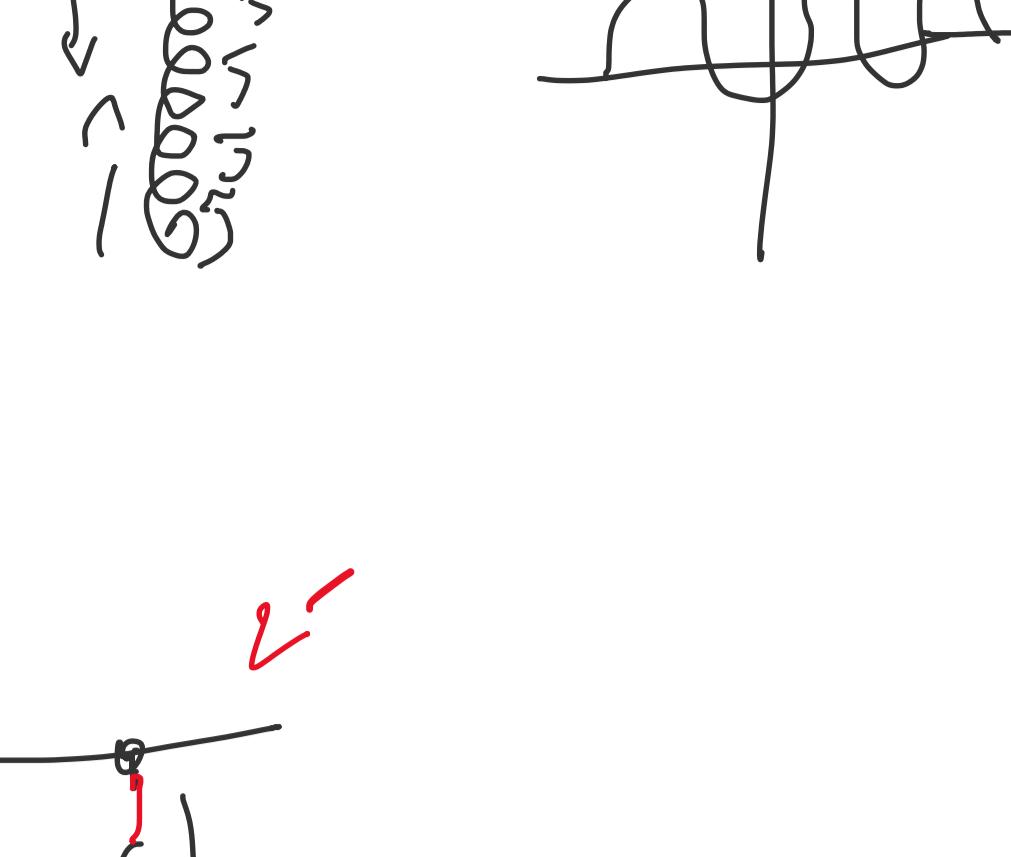


Oscillatory motion:

- Simple Harmonic motion: A mass-spring system exhibits simple harmonic motion when it oscillates about an equilibrium position



- Motion is periodic; can be expressed as:

$$x(t) = A \cos(\omega t + \phi)$$

A = amplitude

ω = angular frequency

ϕ = phase constant



- Amplitude is the max displacement from the equilibrium position

- Period (T) is the time taken to complete one full cycle of motion

- Frequency is the number of cycles per second, related to period ($T = \frac{1}{f}$)

$$T = \frac{1}{f} \rightarrow f = \frac{1}{T}$$

- Energy is SHM:

- Total ME in simple harmonic oscillator is conserved and is the sum of kinetic and potential energy.

$$ME = KE + PE + \frac{1}{2} kA^2$$

Damping:

- Affect of friction or resistance that reduces the amplitude of oscillation over time.

- Types of damping:

- Underdamped: system oscillates with a gradually decreasing amplitude:

$$x(t) = A_0 e^{-\beta t} \cos(\omega_d t + \phi)$$

- β = damping coefficient per unit mass
- ω_d = damped angular frequency

- Critically damped: system returns to equilibrium as quickly as possible without oscillating. This is the ideal case for systems that need to stabilize quickly

- Overdamped: system returns to equilibrium without oscillation but more slowly

- Energy loss: In damped systems, energy is lost to the environment (e.g. as thermal energy) which causes amplitude to decrease

Resonance:

- Occurs when system is driven by external periodic force at a frequency that matches the system's natural frequency leading to a drastic increase in amplitude

$$f_d = f_0$$

$$f_b \approx f_0$$

- Characteristics:

- At resonance, even a small periodic driving force can produce large oscillations

- The amplitude of oscillation can become very large, potentially leading to system failure

- Mathematical representation:

$$x(t) = A_0 \cos(\omega_0 t + \phi) + \frac{F_0}{m(\omega_0^2 - \omega^2)} \sin(\omega t)$$

- F_0 = amplitude of driving force

- m = mass of oscillator

- ω = frequency of driving force

Example:

A mass-spring system consists of a mass of 0.5 kg attached to a spring with a spring constant of 200 N/m. The system is set into motion with an initial displacement of 0.1 m from its equilibrium position.

- Calculate the period of oscillation for the mass-spring system.
- If the system experiences a damping force proportional to the velocity with a damping coefficient of 5 N·s/m, determine the damped frequency of oscillation.

- If the system is subjected to an external periodic driving force with a frequency of 1.5 Hz, discuss whether resonance will occur and explain your reasoning.

Solution:Givens:

$$\text{Mass } m = 0.5 \text{ kg}$$

$$\text{Spring constant } k = 200 \text{ N/m}$$

$$\text{Initial displacement, } x_0 = 0.1 \text{ m}$$

$$\text{Damping coefficient } \beta = 5 \text{ N·s/m}$$

$$\text{Driving frequency } f_d = 1.5 \text{ Hz}$$

Unknowns:

$$\rightarrow T = ?$$

$$\rightarrow f_d = ?$$

$$\beta = ?$$

- Period formula:

$$T = 2\pi \sqrt{\frac{m}{k}} \rightarrow T = 2\pi \sqrt{\frac{0.5}{200}} = \frac{1}{E}$$

$$= 2\pi (0.05)$$

$$= 0.314 \text{ s}$$

- Determine damped frequency of oscillation:

$$\omega_0 = \frac{2\pi}{T} \rightarrow \omega_0 = \frac{2\pi}{0.314} = 20 \text{ rad/s}$$

$$\omega_0 = \frac{2\pi}{T} = \frac{1}{E} \times 2\pi$$

$$\omega_0 = 2\pi \times \frac{1}{E}$$

$$\omega_d = \sqrt{\omega_0^2 - \beta^2}$$

$$= \sqrt{20^2 - 5^2}$$

$$= 19.36 \text{ rad/s} \rightarrow 1.5 \text{ Hz}$$

- Discuss resonance:

$$f_d = 1.5 \text{ Hz}$$

$$f_0 = \frac{2\pi}{T}$$

$$= \frac{2\pi}{0.314}$$

$$= 3.18 \text{ Hz}$$

$$f_d < f_0 \rightarrow 1.5 \text{ Hz} < 3.18 \text{ Hz}$$

Resonance does not occur since f_d is not close to f_0 .

$$f_d = 3.45 \text{ Hz}$$

$$f_d = 3.45 \text{ Hz}$$

$$f_d = f_0$$