

INPUT SIZE – $n \times m \times ch$

KERNEL SIZE – $k \times k \times ch$

Input Fetching strategy –

An image representing fetching groups until we reach the last channel

Once we start getting the cylinders, we can start MAC operation with respective kernels

3 pipes for input and calculation: `inp_pipe`(continuously fetches input), `data_pipe`(gets the input for dot products), `ker_pipe`(gets kernel values for dot products)

There will $k \times k$ pipes meant for storage of input values from previous groups. Let the storage pipes be named `S[k][k]`

Each of the storage pipes will be re-used $k-1$ times, so we need to push back the used values.

fetchGroup(r, c, chn):

```
S.clear()                                //clears previous storage
for l in range(k):
    for j in range(k):
        data_pipe.push(inp_pipe) //push 64bits of data or 1 cylinder
        S[j][i].push(inp_pipe)
```

fetchSlice(r, c, chn, p):

```
for l in range(k):
    data_pipe.push(inp_data)
    S[i][p-1].push(inp_pipe) //push the slice into storage
For l in range(k-1):
    For j in range(k):
        Cyl = S[j][(i+p)%k]
        Data_pipe.push(cyl) //push a cylinder in data_pipe
        S[j][(i+p)%k].push(cyl) //push the cylinder back in storage for further use
```

fetchKernel() :

```
for l in range k:
    for j in range k:
        cyl = kern[j][i]
        kern_pipe.push(cyl)    //pushes a cylinder in kernel_pipe
        kern[j][i].push(cyl)    //pushes the cylinder back in kernel
```

colvolution():

```
for l in k2*8:
    result += kern_pipe*data_pipe    //dot product of data and kernel pixels
return result
```

Main_func():

```
For r in range(n/k):
    For c in range(m/k):
        For chn in range(ch/8):
            If (r%k=0):
                fetchGroup()    //fetches group for new row
            else :
                if (chn = 0):
                    for l in range(k):
                        S[i][p-1].clear()    //clear the row of pth col
                    fetchSlice(p)
                    fetchKernel()    //fetches kernel values for first 8 channels
                    out += convolution(inter_pipe , kernel_pipe)
                p += 1    //incrementing the value of p for next group
            output[r][c] = out    //return the output
        out = 0
```

