Aa Language Reference Manual

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April 19, 2011

1 Introduction

Aa is a low-level algorithm-assembly programming language for the description of algorithms. An **Aa** program can be modeled by a petri net of a specific class (the type-2 petri-net as introduced in [1]). A program in **Aa** can also be viewed as a description of a system which reacts with its environment through input and output ports and through message queues. Thus, an **Aa** program can either be executed on a computer, or be mapped to a logic circuit.

In the rest of this document, we outline the structure and the syntax of the **Aa** language, and also describe the semantics of an **Aa** program, especially the execution model and the behaviour of the equivalent system.

2 Program structure

A program in **Aa** consists of a sequence of declarations and module definitions.

program := (module-definition | program-object-declaration)*

Program object declarations can belong to one of three classes:

- Storage objects declared in the program are variables that can be written into from multiple points in the program. When declared at the program scope, storage objects are visible throughout the program.
- **Pipe** objects declared at the program scope are globally visible first-infirst-out buffers that can be read from anywhere in the program and can be written into from anywhere in th program. A pipe is a single-place buffer. A write to a pipe succeeds only if the single place buffer is empty. A read from the pipe succeeds only if the single place buffer is not empty (the read empties the buffer). Thus, pipes can be used for synchronization in an **Aa** program.

- A pipe that is only written into in the program, but is not read from, is assumed to have a destination outside the program. Such a pipe is an output port of the program.
- A pipe that is only read from in a program but not written into, is assumed to have a source outside the program. Such a pipe is an input port of the program.
- Constant objects declared at the program scope are globally visible and have initial values which can never be altered in the program. Thus, an assignment to a constant is an error.

A module in ${\bf Aa}$ is the basic unit of compilation, and has the following structure

```
$module [module-name]
    $in(<input-arguments>)
    $out(<output-arguments>)
$is
{
    <object-declarations>
    <sequence-of-statements>}
```

Thus, a module has a name, has input and output arguments, declares objects and consists of a sequence of statements. Objects (storage/pipe/constant) declared in the module are visible only in the module body. For example:

```
$module [sum]
    $in (a: $uint<32> b: $uint<32>)
    $out (c: $uint<32>)
$is
{
    c := (a+b)
}
```

In this example, sum is a module which has two inputs and a single output. The type of the inputs and the output is

\$uint<32>

which is an unsigned 32-bit integer (More details on types are given in Section 5).

Each statement in the sequence of statements can be abstractly viewed as a region in a petri-net, and has a set of input (or source) places and a set of output (or sink) places. The execution of the statement is triggered when there is a token present in every place in some specified subsets of its source places and when the statement finishes execution, a token is placed in some specified subset of its sink places.

The control flow in the sequence of statements in a module is serial in nature. Thus each statement has a single source place and a single sink place, with the sink place of a statement being the source place of its successor. The module as a whole can be viewed as having a single entry place and a single exit place. When a token appears in the entry place, the first statement can trigger, and when the last statement has finished, a token is placed in the exit place.

The region between { and } is termed a **scope**. Thus, a module description defines a scope. In this case, the scope has a label which is the same as the module name. As we shall see later, the statements in the statement sequence may in turn define scopes. Each scope defines a name-space. The visibility rules and access mechanisms between scopes will be described in Section 4.

3 Statements

Statements in the module-body are can be of two kinds:

- Complete or atomic statements: these are statements which have a single entry place and a single exit place. These are the only statements that can occur in a module body. These statements are further divided into *simple* statements and *block* statements.
- Incomplete or sub-atomic statements: these statements can appear only
 inside block statements, and they can have multiple source and sink places.
 Examples of these statements are statements for combining tokens (merge
 and join statements) and statements for redirecting tokens (the place statement).

3.1 Complete Statements

Complete statements can be one of the following:

• An **assignment** statement is of the form

```
target-ref := expression
```

where target-ref either specifies a declared object or an undeclared name. If it is an undeclared name, then it is an implicit variable that is attached to the assignment statement. No other statement can write to this variable, but any statement can read from this variable subject to scoping rules. Thus, every implicit variable is such that exactly one statement defines its value. When control flow reaches an assignment statement, it evaluates the expression, updates the value of the target and passes the control flow forward (we will see what this means in the sequel). Some examples of simple statements are

```
a := (^b)

b := (c + (d + e))
```

etc. Expressions can be *unary*, *binary* or *ternary*, and are described in detail in Section 6. Details of the syntax are provided in Section 13.

• A call statement is of the form

```
call-spec module-name input-arguments output-arguments
```

The call statement thus specifies a module to which control flow is to be passed. The call statement may itself define new implicit variables through its specified targets (and thus is the only statement that can modify these newly defined implicit variables). When control flow reaches the call statement, it forwards the token to the called module, and finishes when the token exits the called module. Recursive calls and cyclical dependencies between modules through call statements are not permitted in the **Aa** language. Here is an example of a call statement

```
// pass control to a module named foo
// foo has two inputs and three outputs
$call foo (p q) (r s t)
```

Here p, q, r, s, t can be expressions.

More details of the syntax are provided in Section 13.

• The **null** statement does nothing, and just passes the token onwards. This is how it looks like

\$null

3.2 Complete Block Statements

Block statements can be used to describe complex control flows, and consist of a sequence of statements. Block statements are of the following types:

• Series block statements are of the form

The behaviour is similar to the module, in that the control token flows serially down the sequence of statements. Here is an example:

```
$seriesblock [s1]
{
    $storage b $uint<32>
    b := a
    b := ( $mux (a > c) (b+c) (b-c))
    q := ( b * 2)
}
```

In this example, the variable b was declared as a storage variable in scope s1, and hence was legally able to be the target of multiple assignment statements.

• Parallel block statements are of the form

When a token enters the parallel block statement, it is replicated into as many tokens as there are statements in the sequence, and all statements are started in parallel. When all statements have finished and released their token, the parallel block statement ends and a single token exits the parallel block statement (this is essentially a fork followed by a join). Here is an example

```
$parallelblock [p1]
{
    b := a + c
    d := a - c
}
```

The two statements will start in parallel, and the block will finish when both have finished. The order in which the two statements are executed is **not** specified.

• Fork block statements are generalizations of the parallel block region in the sense that they allow the programmer to express complex fork-join interactions. They have the following structure:

The control flow is similar to the parallel block region, in the sense that all statements in the sequence are started in parallel, and the fork block statement ends when all statements in the sequence have ended. The difference is that fork blocks can have an additional statement which allows the programmer to provide additional synchronization points. These statements are termed **join** statements and have the form

```
join-statement :=
    join-specifier list-of-labels
    fork-specifier list-of-statements
```

The meaning of this statement is that it waits until all statements in the list-of-labels have finished, then starts the list-of-statements (in parallel) and finishes. This essentially defines a node in a directed graph, with the arcs corresponding to statements in the statement-lists. The join indicates the arcs (or statements) from whom tokens have to arrive. After all tokens have arrived on the incoming arcs, tokens are sent along the outgoing arcs specified in the list of statements following the optional fork specifier. There is an implicit fork at the entry point to the fork block statement and an implicit join at the end of the fork block statement. It is thus easy to describe an arbitrary directed graph with arbitrary forks and joins. The only restriction is that this directed graph must be acyclic! This is enforced by requiring that a join statement refers only to labels of statements that appear before the join. Here is an example:

```
$forkblock [f1] {
    a := (b+c)
    $seriesblock [s1] { ... }
    $seriesblock [s2] { ... }
    $seriesblock [s3] { ... }
    $join s1 s2 $fork
        $seriesblock [s4] { ... }
    $join s3 s4
}
```

In this example, the first assignment statement as well as s1, s2, s3 are started in parallel. When both s1 and s2 have finished, s4 is started and when s3, s4 have joined and when the first assignment statement has finished, the forkblock f1 finishes execution.

• Branch block statements are constructs which allow the programmer to describe arbitrary sequential branching behaviour. They describe a control flow in which a single token is active within the block. The movement of this token is controlled by special flow control statements. A branch block is constructed as follows

The sequence of statements appearing in a branch block consist of

- Simple statements or Block statements.
- Switch statements: A switch statement has the form

```
switch-statement :=
    switch-spec switch-expression
        ( expr-value serial-statement-sequence )*
        ( default serial-statement-sequence )?
```

The switch-expression is checked, and depending on its value, one of the alternative statements is selected. Thus, the incoming token to the switch statement is passed to one of the alternatives. For example,

\$endswitch

The control token is routed to the appropriate choice sequence and if the token is not routed out of the block (by the **place** statement described below), then the token passes to the statement following the switch.

- If statements: An if statement has the form

```
if-statement :=
    if-spec test-expression
        serial-statement-sequence
    (else
        serial-statement-sequence)?
```

For example:

```
$if (a != 0) $then
  q := (r + s)
  t := 0
$else
  qdash : (r - s)
$endif
```

If the control token reaches the end of a selected segment in the if statement (that is, without being rerouted by a place statement), then the control token is passed on to the statement immediately following the if statement.

- The place statement: The **place** statement identifies a place into which it places a token after it has executed. For example,

\$place [fastpath]

means that the incoming token is placed in a labeled place **fast-path** (the place statement never puts a token into its default exit place). The token placed in **fastpath** must be used to trigger a unique **merge** statement which is required to depend on this labeled place in the same branch block. If no such merge exists, or if multiple such merges exist, then this is an error.

Merge statements: A merge statement is specified as

which is to be interpreted as follows. The labels in the label list refer to token labels defined by **place** statements within the branch block. Whenever a token is present in any of the places in the label-list for a merge, the merge statement starts and executes a series of special assignments which multiplex values into new variables based on which arc the token arrived from. The merge statement then releases its token to the next statement.

* The merge assignments inside a merge block are all of a specific form, called the phi-statement. A phi-statement has the following form

```
$phi a := b $on $entry c $on loopback
```

This says that the target a is to take the value of b if the merge statement was started from its entry place (ie from a token passed from its predecessor) and is to take the value of c if the merge statement was started from the place "loopback". Note that if the merge statement is to be triggered by a token in its default entry place, one of the labels in the label-list for the merge must contain the identifier n

Here is an example of a branch block constructed in this manner

This is to be interpreted as follows: the merge executes whenever a token is present in its entry place or in the place labeled **loopback** The merge defines variable **q** with a value which is either 0 (if a token was present in the entry place) or r (if a token was present in the "loop" place). By the construction rules in an **Aa** program, it is impossible for there to be a token present in more than one input place to a merge.

Thus, an **Aa** program is constructed as a collection of modules, each of which is a sequence of statements. The use of series, parallel, fork and branch block statements enables the programmer to describe a highly concurrent structured system with complex branching behaviour. The resulting control flow structure is a type-2 petri-net with provable liveness and safety properties [1].

4 Scoping Rules

An **Aa** program is made of modules which in turn contain statements and so on. The program thus has a hierarchy of scopes (except for the program, each scope is delimited by { and }) with each scope being contained in another (except for the program itself, which is not contained in any scope).

The rules for scoping are as follows:

- 1. A declared variable defined in a scope is visible in all descendent scopes.
- 2. A reference to a variable b in a scope X is resolved by checking whether the variable is defined in that scope, and if not found there, by checking in the scope that contains the scope X, and so on.
- 3. A scope can read from variables that are defined in descendant scopes.
- 4. A scope can read from variables that are defined in ancestor scopes.
- 5. A scope can only write to one of the following:
 - an implicit variable defined in the scope.
 - a storage or pipe variable defined in the scope or an ancestor of the scope.

• an output argument of a module of which the scope is a descendant. In this case, there can be at most one statement in the entire module which writes to this output argument.

A variable reference in a statement may be specified as follows

a	look for	variable	a in cu	rrent scope;
	if not f	ound look	in the	parent.

- :a same as the previous case
- ../:a look for variable a starting from the parent of the current scope.
- %p:a look for variable a starting from the child scope with label p (child scope of the current scope).
- ../../:a look for variable starting from the parent of the parent of the current scope.
- %p%q:a look for variable starting from the child scope with label q of the child scope with label p of the current scope
- a[10] look for a storage variable a defined in the current scope. If not found, look for it in the parent scope, and so on. If eventually found, access the corresponding element of the composite object.

Thus, a generic variable reference has the form

scope-reference : variable-reference

and the scoping rules forbid a scope from accessing variables which are not defined in either an ancestor or a descendant of the scope.

5 Types

Types in **Aa** can be either scalar types or composite types. Scalar types can be one of

• Unsigned integers: An unsigned integer type has a width parameter and is specified as

\$uint<width>

The width parameter can be any positive number. Values corresponding to this type are to be viewed as unsigned integers represented by a binary sequence of the specified width.

Signed integers: A signed integer type has a width parameter and is specified as

\$int<width>

The width parameter can be any positive number. Values corresponding to this type are to be viewed as integers maintained in the two-s complement form by a binary sequence of the specified width.

• Pointers: A pointer is an unsigned integer with a default pointer width (set to 32 for now), which specified the type of object to which it points. For example

```
$pointer< $uint<32> >
```

is a pointer which refers to a storage object of type

\$uint<32>

• Floats: A float is parametrized by two integers, the width of the exponent, and the width of the mantissa. The specification is

\$float<exponent,mantissa>

where the exponent and mantissa must be positive integers. The float is represented by a word with exponent + mantissa + 1 bits (with the additional bit needed for the sign). The standard IEEE 754 float and double precision representations correspond to

```
$float<8,23>
```

and

```
$float<11,52>
```

respectively. Currently, these are the only float types that are supported.

Composite types in ${\bf Aa}$ can be either array types or record types.

• Array types in **Aa** have the form

```
$array [d1][d2]...[dn] $of <element-type-spec>
```

The values $d1, d2, \dots dn$ must be positive integers, and element-type-spec must refer to a type. For exampe,

```
$array [10][10] of $array [10] $of $uint<32>
```

is an two-dimensional array type whose elements are one dimensional arrays of 32-bit unsigned integers.

• Record types in **Aa** have the form

```
$record <type-1> <type-2> ... <type-n>
```

An element of such a record type is an aggregate whose first element is of type type-1, second element is of type type-2 and so on. For example:

```
$record <$uint<32> > <$array [10] $of $uint<32> >
```

6 Expressions

Expressions in $\mathbf{A}\mathbf{a}$ fall into the following classes

- Constant literal references.
- Simple object references.
- Indexed object references.
- Pointer de-reference expressions.
- Address-of expressions.
- Unary expressions.
- Binary expressions.
- Ternary expressions.

6.1 Constant literal references

Constants can be specified in one of many ways, depending on their type.

• Integers can be specified in their decimal form, as for example

23

-8

or in binary form, as for example

_b10111

When specified in binary form, the twos-complement value of the integer being specified should be used. • Floats are specified in the exponentiated form

```
_f2.3000e+10
_f-1.354e+10
```

where the mantissa has to have exactly one digit to the left of the decimal point.

• Composite constants are specified as a space separated list of values.

```
( 12 32 43 10)
( (1 5) (2 8) (9 100) )
```

etc. The elements are listed in row major form. Thus a[2][2] is listed as

```
a[0][0] a[0][1] a[1][0] a[1][1]
```

6.2 Simple object references

References to an object have the form

```
<scope-specifier>:<object-specifier>
```

The scope specifier can either specify a parent scope of the scope in which the expression appears, or a child scope of the scope in which the expression appears (as described in Section 4). The scope-specifier can be omitted if the reference is to be resolved starting from the same scope as the expression. For example:

../:a

6.3 Indexed object references

These have the form

```
<scope-specifier>:<root-object-specifier>[i1][i2]...[im]
```

The scope and root-object-specifier are interpreted in the same manner as before. The indices $i1,i2,\ldots im$ must be non-negative integers. The object-specifier must be one of

• A storage object whose type is composite. For example, if *a* is a storage object whose type is a two-dimensional composite type, then

```
a[0][1]
```

is interpreted in the usual manner. Thus, when the root-object-specifier is a declared storage object, the indexed expression evaluates to an element of the object.

• A scalar object of type pointer. For example if ptr is a pointer to an object of type T, then

```
ptr[1]
```

is a pointer which will point to the adjacent object of type T if we assume that ptr points to an array of objects of type T. This is similar to the following evaluation in \mathbf{C}

Thus, the evaluation of an indexed expression whose root is a pointer evaluates to a pointer of some element type.

7 Pointer de-reference expressions

If \mathbf{ptr} is a pointer to a scalar object, then the expression

```
->(ptr)
```

refers to the value of the object pointed to by **ptr**. Such an expression can occur **only** as the target or source of a simple assignment statement. For example

```
a := ->(ptr)
->(ptr) := (a+1)
```

8 Address-of expressions

If a is a declared **storage** object, then

@(a)

is a pointer which points to **a**. Such an expression can occur **only** as a source of a simple assignment statement. For example

```
ptr := @(a)
```

9 Unary expressions

These can be of three types:

• The **cast** expression is of the form

```
($cast (<type-spec>) <expression>)
For example
($cast ($uint<10>) ../:a)
```

The cast expression takes the value of the specified expression and converts it to a value of the specified type. This is equivalent to a type-cast in \mathbf{C} , as for example in

```
float a;
int b = (int) a;
```

• The **bitcast** expression is of the form

```
($bitcast (<type-spec>) <expression>)
For example
($bitcast ($uint<10>) a)
```

The bitcast expression takes takes the bits corresponding to the value of the specified expression and treats them as being of the specified cast type. This is similar to the following in ${\bf C}$

```
float a;
int b = *((int*) &a);
```

except that in \mathbf{Aa} , the destination type need not be the same size as the source type (higher order bits are truncated or padded with 0 as necessary).

• The bit-wise complement expression is of the form

```
( ~ <expression> )
```

The symbol for the complement is the same as the one used in the C programming language, and the evaluation of the expression proceeds in the usual way.

The parentheses around a unary expression are **required**.

10 Binary expressions

```
These are of the form
(<expression> <operation-id> <expression>)
The following binary operations are supported
// arithmetic operators
PLUS
MINUS
MUL
DIV
SHL
                  <<
SHR
// bit-wise logical operators
NOT
                  -
OR
AND
                 &
XOR
                 ~|
NOR
NAND
XNOR
// comparison operators
EQUAL
NOTEQUAL
LESS
                  <
LESSEQUAL
                  <=
GREATER
GREATEREQUAL
// concatenation operator
CONCATENATION
                 &&
     c = (a \&\& b) means that the bits of
     a and b are concatenated to produce
     the bits of c. a,b must be of type
     $uint<>
// bit-select operator
BITSELECT
                 []
    c = (a [] i) means that c gets the
    value of the bit of a with index i
    (index 0 is the least significant bit)
```

The evaluation of a binary expression proceeds in the usual way. Note that when specifying an expression, you **must** use parentheses around each expression.

11 Ternary expressions

There is only one form for the ternary expression.

```
( $mux <test-expression> <true-expression> <false-expression> )
```

The test-expression is evaluated, and if true, the true-expression is evaluated, and if false, the false-expression is evaluated. Note the parentheses delimiting the expression. For example

```
($mux a (b+1) (c+d))
\section{Foreign Modules}

A module can be marked as foreign by using the
\$foreign keyword.
\begin{verbatim}
$foreign $ module [GetValue]
$in (ptr $pointer<32>)
$out (val $uint<32>)
```

The **Aa** compiler then considers that the module GetValue is defined "elsewhere" and does not try to link to it directly. This linking is done outside by other tools which use the results of the **Aa** compilation process.

12 Examples

Here is a very simple program

This consists of a single module, which accumulates a value into an array position

An example which is a little bit more complicated:

```
// an array of 32-bit unsigned integers.
$storage mem:$array[1024] $of $uint<32>
// module returns the sum of mem[I] from
// I=low to I=high
$module [sum_mod]
    $in (low:$uint<10> high:$uint<10>)
    $out (sum:$uint<32>)
$is
   d := (high-low)
   mp := ((high-low)/2)
   $branchblock[trivcheck]
   {
       // d from parent scope
       if (d > 0) then
           // do two summations in parallel
           // parallel summations
           $parallelblock[parsum]
               $branchblock[sb1]{
                    $storage I:$uint<10>
                    $merge $entry loopback
                       $phi s := 0 $on $entry s1 $on loopback
    $endmerge
                    $if (I < mp) $then
                       I := (I+1)
                       s1 := (mux (I == 0) 0 (s + mem[I]))
                       $place [loopback]
                    $endif
               }
               $branchblock[sb2]{
                    $storage J:$uint<10>
                    J := (mp + 1)
                    $merge $entry loopback
                       $phi s := 0 $on $entry s1 $on loopback
    $endmerge
                    $if (J < high) $then
                         J := (J+1)
                         s1 := (\max (J == (mp+1)) 0 (s + mem[J]))
                         $place [loopback]
                    $endif
               }
           }
```

```
// combine results from parallel statement above
    snontriv := (%parsum%sb1:s + %parsum%sb2:s)
    $place [nontrivsum]

$else

    // summation is trivial
    striv := mem[low]
    $place [trivsum]

$endif

$merge nontrivsum trivsum
    // which sum do you pick? depends on which path was taken
    $phi sum := snontriv $on nontrivsum striv $on trivsum

$endmerge
}
```

This example describes an algorithm which computes the sum of a section of an array by dividing the problem into two partial summations.

13 Syntax

The syntax for \mathbf{Aa} follows the following principles

- All keywords begin with the \$ sign.
- The region between { and } defines a new scope.
- Statements are space separated (no semicolons at all).
- Expressions are fully parenthitized. Thus (a+b) is a legal expression, but a+b is not.

The parser is implemented using an LL(k) parser (written as rules to be parsed by antlr2 [2]). The grammar for the parser is (using the EBNF notation) given in the html file **AaParser.html** which is part of this distribution. The set of tokens recognized by the lexical analyzer (or lexer). is available in the html file **AaLexer.html**.

References

- [1] Sameer D. Sahasrabuddhe, "A competitive pathway from high-level programs to hardware," Ph.D. thesis, IIT Bombay, 2009.
- [2] http://www.antlr2.org.