GRIP Computer Vision Engine



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Abstract

GRIP (the Graphically Represented Image Processing engine) is an application to construct and deploy computer vision algorithms. Developing a vision program can be difficult because it is hard to visualize the intermediate results. Java and OpenCV were used to implement a graphical development tool. This simplifies and accelerates the creation of vision systems for experienced users and reduces the barrier to entry for inexperienced users. As a result, many teams with minimal computer vision knowledge successfully used our software in the 2016 FIRST Robotics Competition game.

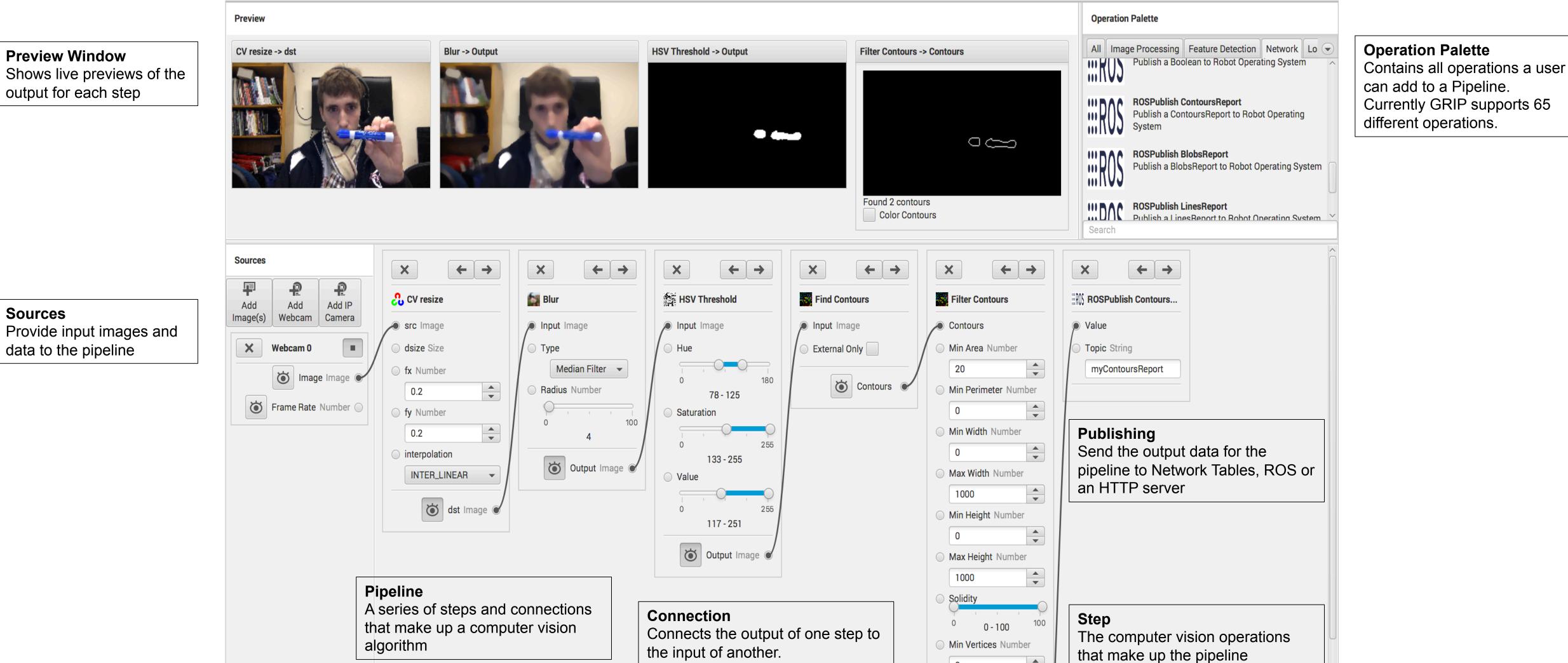
Community

GRIP is 100% Open Source under a 3 clause BSD License

- Over 7,000 downloads on GitHub with 101 Stars & 40 Forks
- Many contributors from outside of WPI
- Very active community on Gitter
- Adopted by Artaic LLC. for the robotic creation of large scale mosaics
- FIRST reports teams using computer vision in their robots has significantly increased due to the availability of GRIP



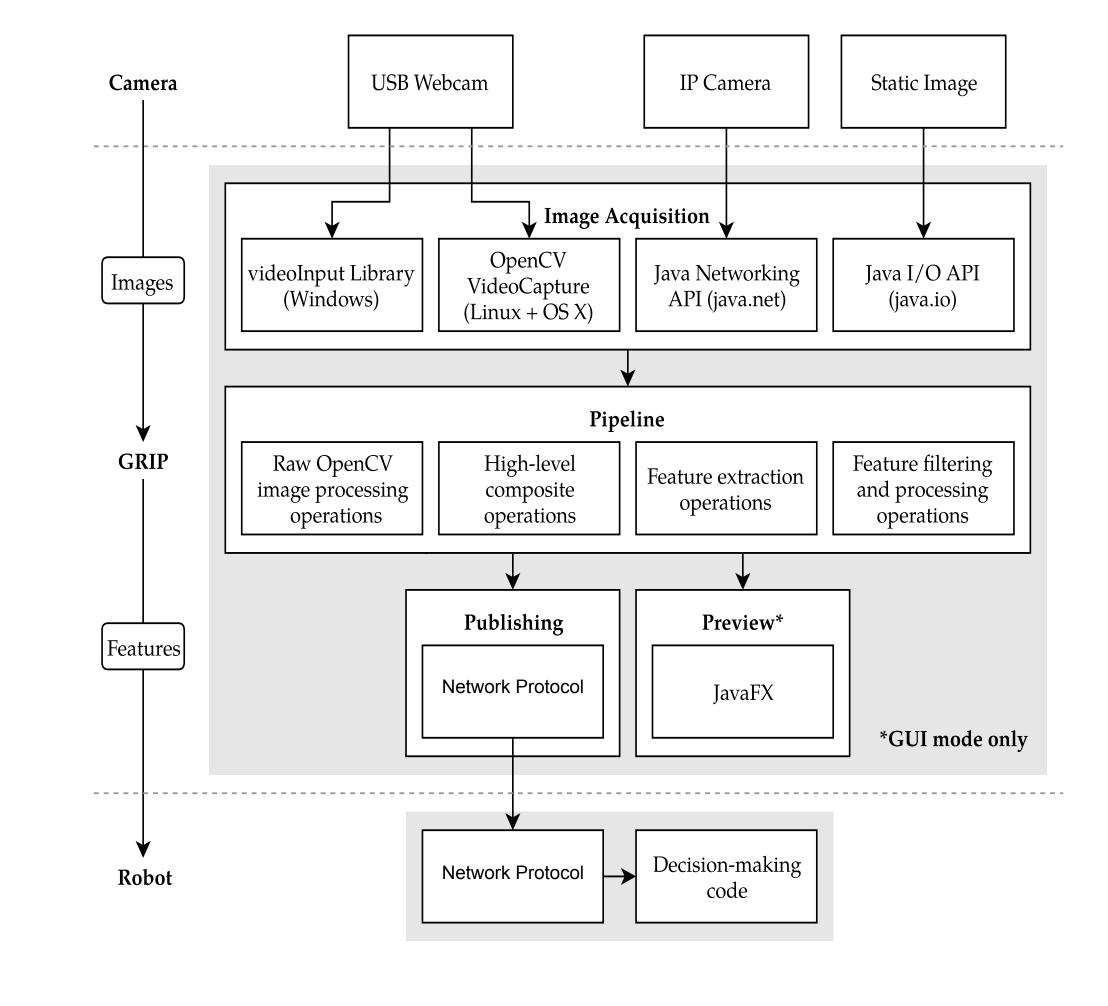
UI Overview



GRIP is divided into two modules -

GRIP is divided into two modules - the core and the graphical user interface (GUI). The core is responsible for performing the actual computer vision. The GUI allows the user to both manipulate the set of operations and preview the outputs of the core.

Architecture



Build System

Automated build/release system with Gradle

Pipeline Running

- All pull requests tested and approved by Travis CI & AppVeyor
- Static code analysis by Codacy
- Compile time error checking with Error Prone
- Automated Junit tests for the Core Module

Automated UI Tests with TestFX

Min Ratio Number

- or Code coverage metrics with Jacoco and CodeCov
 - Automatic releases published by Travis CI & AppVeyor
 - Full integration with Gitter chat
- Dependency version monitoring with VersionEye

Supported Operating Systems

- Windows (x86/64)
- Mac OSX
- Linux (Ubuntu & Fedora)
- Embedded Linux ARM (Headless)

