

1.7.2 Find the Euler axis representation of the orientation given by the Euler angles $\phi=0$, $\theta=45$, $\psi=0$

This is just a 45 degree rotation about the y-axis.
Therefore, $E_x=0$, $E_y=1$, $E_z=0$, and $\Theta=45$

$$\begin{pmatrix} \oplus \\ E_x \\ E_y \\ E_z \end{pmatrix} = \begin{pmatrix} 45 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

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