Supervised PCA via Manifold Optimization

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September 23, 2019

Overview

Introduction and Previous Work

Our Work

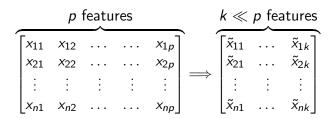
3 Experimental Results

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Introduction and Previous Work

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Dimensionality Reduction (DR)



Potential Benefits

- Better Generalization
- Higher Interpretability
- Lower Computational Cost

What are the new features?

- Feature Selection (choose a subset of original features)
- Feature Extraction (learn new features from originals)

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Principal Component Analysis (PCA)

PCA problem statement

$$\begin{aligned} & \underset{L}{\text{minimize}} & \|X - XL^T L\|_F^2 \\ & s.t. & LL^T = I_{kxk} \end{aligned}$$

$$X$$
 $n \times p$
 L
 $k \times p$
Data matrix
 X
 C
Basis for reduced X

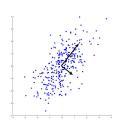


Figure: PCA of MVG data.

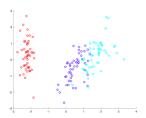


Figure: 2D PCA embedding of Iris data.

Supervised Dimensionality Reduction (SDR)

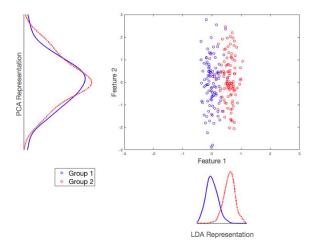


Figure: Principal Component Analysis (Unsupervised) vs. Linear Discriminant Analysis (Supervised).

A Real Example: Single Cell Data

- Significant variation attributed to housekeeping genes, or genes unrelated to feature of interest
- Important variation of minority cell populations obscured by majority cell population
- Consider Neural Stem Cell Lineage Dataset [8]

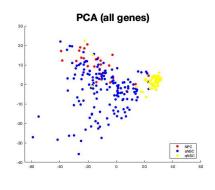
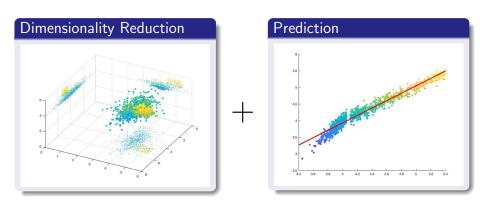


Figure: Projection of Dulken data onto first two PCs.

SDR: High Level Approach and Goals

In practice, DR is often a preliminary step before prediction. It is natural to consider performing DR and prediction jointly. One set of approaches is to add supervision to PCA (SPCA).



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Previous Work: Supervised Principal Components [1]

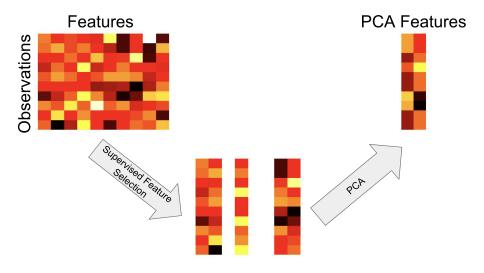


Figure: Illustrative example for Bair's method.

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Previous Work: Supervised Probabilistic PCA [2]

Observed Variables

Latent Variables

Response Variables

Figure: Latent variable generative model for supervised probabilistic principal component analysis.

Observations

Other Methods

- Supervised PCA via Hilbert-Schmidt independence criterion [3]
- Iterative supervised principal components [4]
- Supervised Singular Value Decomposition [6]
- Partial Least Squares
- Canonical Correlation Analysis

High Level Shortcomings:

- Do not consider objectives jointly
- No means of trade-off between prediction and variation

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Our Work

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Problem Statement

LSPCA Optimization Program

minimize
$$\mathcal{L}(Y, XL^T, \beta) + \lambda ||X - XL^TL||_F^2$$

s.t. $LL^T = I_{k \times k}$

$X_{n \times p}$	Data matrix
Y $n \times q$	Dependent variables
L k×p	Basis for reduced X
β	Prediction Coefficients
$k \times q$	

 λ regularization parameter

k subspace dimension, $k \leq min(n, p)$

Table: Hyperparameters

Table: Variables

Optimization on the Grassmannian

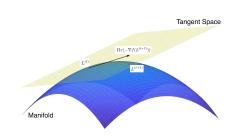


Figure: Visualization of a gradient step on the Grassmannian.

Algorithm 1 Manifold Gradient Descent for LSPCA

```
1: procedure LSPCA(X, Y, L_0, \lambda, k)
 2:
         t=0
 3: while Not Converged do
             \nabla f(L_t) = 2(1-\lambda)L_tX^TX -
    2\lambda(XL_t^T)^+YY^TP_{YL}^\perp X
     L_t^T L_t) \nabla f(L_t)^T
      U_t, \Sigma_t, V_t = SVD(H_t)
             L_{t+1}^T = L_t^T V_t \cos(\eta_t \Sigma_t) V_t^T +
     U_t \sin(\eta_t \Sigma_t) V_t^T
 8:
             t \leftarrow t + 1
 9: end while
10: Z = XL_t^T
11:
         return Z, L_t
```

12: end procedure

Interpreting LSPCA as MLE

$$y|x \sim N(\beta^T L x, \sigma_y^2 I), \quad x|z \sim N(L^T z, \sigma_x^2 I), \quad z \sim N(0, \sigma_z^2 I)$$

We form the joint distribution

$$f_{x,y}(x,y) = f_{y|x}(y|x) \int_{-\infty}^{\infty} f_{x|z}(x) f_{z}(z) dz$$

$$\propto \exp(-\frac{1}{2\sigma_{y}^{2}} ||y - \beta' Lx||_{2}^{2} - \frac{\sigma_{z}^{2}}{2\sigma_{x}^{2}(\sigma_{x}^{2} + \sigma_{z}^{2})}) x'(\frac{\sigma_{x}^{2} + \sigma_{z}^{2}}{2\sigma_{z}^{2}} I - L'L)x).$$

In the case $\sigma_{x} = \sigma_{z}$

$$-\log(\ell(L,\beta)) \propto \|Y - XL^T\beta\|_F^2 + \frac{\sigma_y^2}{2\sigma_x^2} \|X - XL^TL\|_F^2.$$

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Experimental Results

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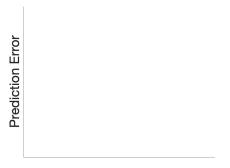


Figure: Multi-objective evaluation criteria.

In addition to prediction accuracy, we consider proportion of variation explained as an evaluation criteria. This is analogous to how the k is often chosen in PCA.

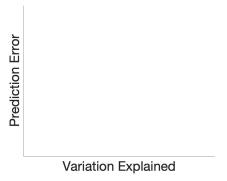


Figure: Multi-objective evaluation criteria.

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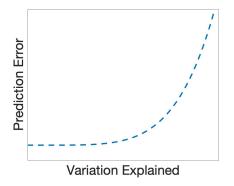


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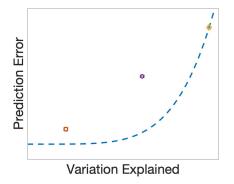


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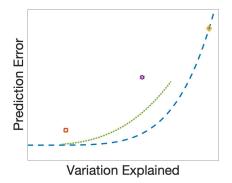
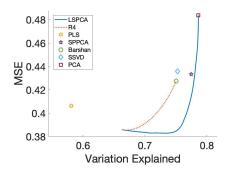
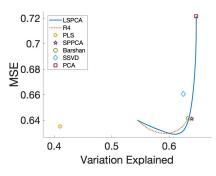


Figure: Multi-objective evaluation criteria.

Regression with Synthetic Data





variation explained on synthetic data generated according to LSPCA model.

Figure: Tradeoff between prediction and Figure: Tradeoff between prediction and variation explained on synthetic data generated according to SPPCA model.

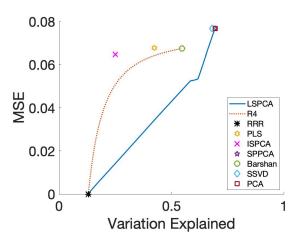


Figure: Tradeoff between prediction and variation explained on Music Dataset [5].

Classification Results

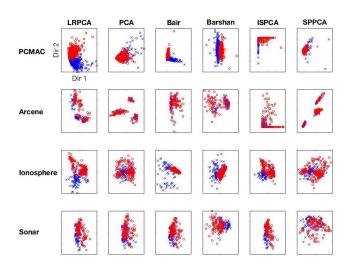


Figure: Visualization of binary classification datasets using the first two learned features of each method. Colors serve as class labels.

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Classification Results

Table: Classification accuracy on binary classification datasets for k=2. Results are averaged over 5 independent runs. Standard deviation of classification accuracy is given in parentheses.

Dataset	LRPCA	PCA	Bair	Barshan	ISPCA	LDA
PCMAC	0.893(0.0143)	0.520(0.075)	0.577(0.109)	0.893(0.0139)	0.727(0.039)	0.690(0.045)
Arcene	0.693(0.037)	0.660(0.029)	0.693(0.077)	0.693(0.052)	0.700(0.082)	0.823(0.040)
lonosphere	0.868(0.036)	0.630(0.051)	0.811(0.086)	0.856(0.067)	0.797(0.069)	0.865(0.024)
Sonar	0.717(0.024)	0.552(0.090)	0.588(0.120)	0.681(0.034)	0.705(0.062)	0.693(0.065)

Table: Variation explained on binary classification datasets for k=2. Results are averaged over 5 independent runs. Format: train variation explained / test variation explained.

Dataset	LRPCA	PCA	Bair	Barshan	ISPCA	LDA
PCMAC	0.229/0.095	0.274/0.092	0.199/0.067	0.071/0.052	0.103/0.039	0.008/0.015
		0.568/0.269				
Ionosphere	0.586/0.582	0.624/0.650	0.452/0.458	0.395/0.390	0.477/0.486	0.177/0.177
Sonar	0.565/0.543	0.628/0.609	0.517/0.511	0.374/0.361	0.373/0.379	0.058/0.056

Interpretable (Predictive) Features

Linear Prediction

minimize
$$\sum_{i=1}^{N} \log(1 + e^{-y_i \mathbf{x}_i^T \mathbf{L}^T \boldsymbol{\beta}}) + \lambda \|X - X L^T L\|_F^2$$
s.t. $L L^T = I_{k \times k}$

- Form filter from basis and coefficients
- Threshold filter to find most meaningful components

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Interpretable Features for MNIST

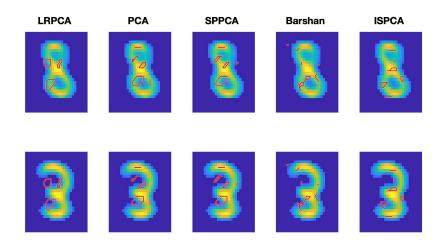


Figure: Visualization of most important features for classification of threes and eights. Obtained by thresholding

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Future Work

- Extension to Domain Adaptation and Semi-Supervised Learning
- Statistical Behavior of Estimator
- Stronger Algorithmic Guarantee

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