

Project 1: Monte Carlo Methods for Solving PDEs

FUSRP 2022 Midterm Presentations

Amandin Chyba, Diba Heydary, Charles Beall, Quinn Arbolante
Advisors: Profs. Adam Stinchcombe & Mihai Nica

Overview

- Explaining the problem
- Issues with popular methods
- Monte Carlo Markov Chains
- Future work and methods

Part 1: Background and Overview of the Problem

An Overview of PDEs

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Answer: $u(x_1, x_2) = x_1 - x_2$

Laplace's Equation on the Unit Disk

- Example: Laplace's Equation in two dimensions:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

Laplace's Equation on the Unit Disk

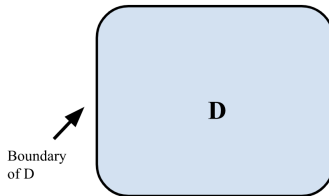
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- Can also impose a boundary condition and a particular domain D :

$$\Delta u = 0, \text{ in } D$$

$$u = g \text{ in } \partial D$$

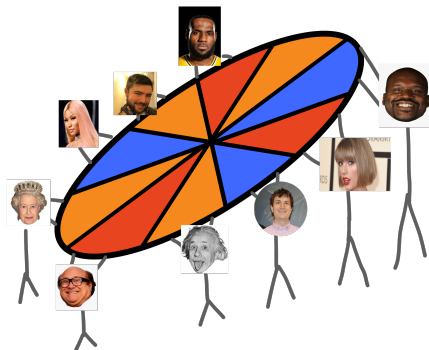


Laplace's Equation on the Unit Disk

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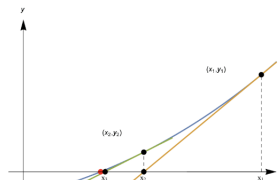
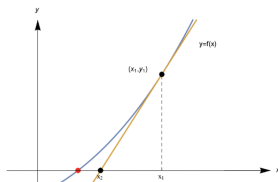
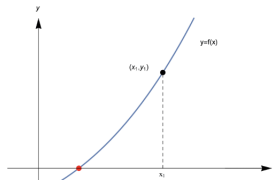
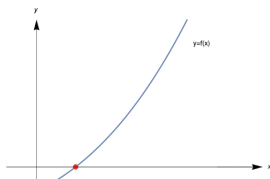


Our Broader Goals Going Forward

- We want to use numerical methods to solve PDEs.
- Numerical methods vs. analytic solutions- what is the difference?

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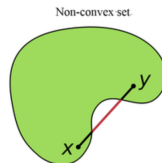
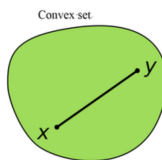
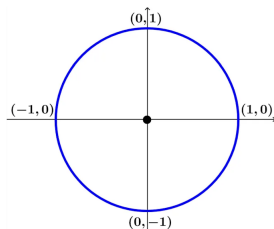
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- We also want to solve on a wider set of domains

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Part 2: Issues With Popular Methods

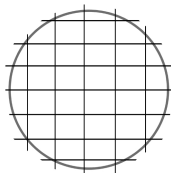
Popular Numerical Methods

① Discretize

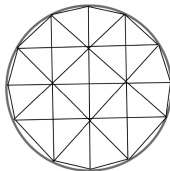
Popular Numerical Methods

1 Discretize

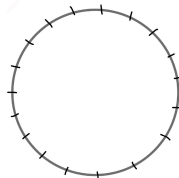
Finite Difference



Finite Element

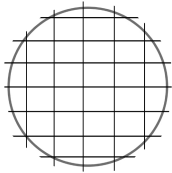
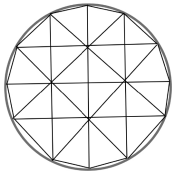
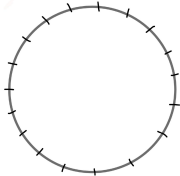


Boundary Integral Equation



Popular Numerical Methods

1 Discretize

Finite Difference	Finite Element	Boundary Integral Equation
		

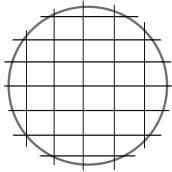
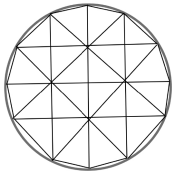
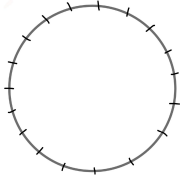
Note:

$$\begin{cases} \Delta u(\mathbf{x}) = 0 & \mathbf{x} \in \Omega \\ u(\mathbf{x}) = g(\mathbf{x}) & \mathbf{x} \in \Gamma \end{cases}$$

$$\Rightarrow u(\mathbf{x}) = \int_{\Gamma} K(\mathbf{x}, \mathbf{y}) g(\mathbf{y}) dS_{\mathbf{y}} \quad \mathbf{x} \in \Omega$$

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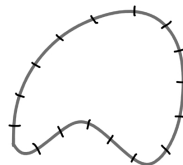
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2 Solve the system of equations

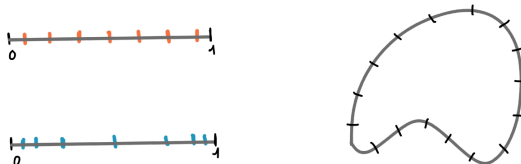
Issues

- choosing optimal quadrature for complicated boundaries is non-trivial (e.g. **uniform**/**Chebyshev** nodes)

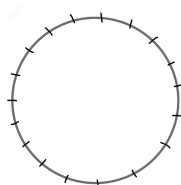


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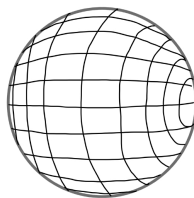
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- slow evaluation in high dimensions (e.g. $\dim \geq 3$)



$\dim=2$

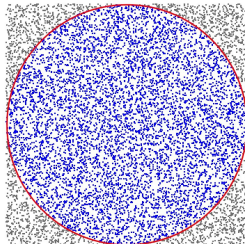


$\dim=3$

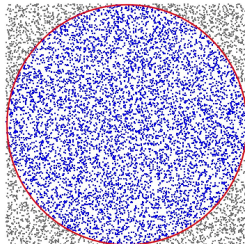
Example: approximate π

Monte Carlo Methods

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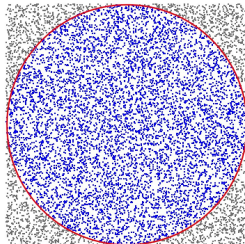


$$A_{circle} = \pi r^2$$

$$A_{square} = 4r^2$$

$$\frac{A_{circle}}{A_{square}} = \frac{\pi}{4}$$

Example: approximate π



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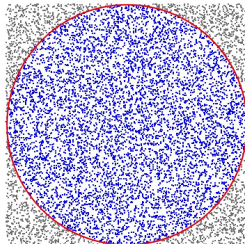
$$A_{square} = 4r^2$$

$$\frac{A_{circle}}{A_{square}} = \frac{\pi}{4}$$

$$\hat{p} = 4 \cdot \frac{\sum blue}{\sum blue + \sum brown}$$

$$\sigma = 2 \cdot \sqrt{\frac{\hat{p}(1 - \hat{p})}{n}}$$

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Note: scales well to higher dimensions

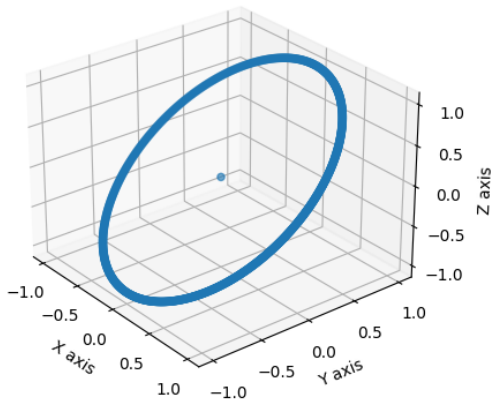
Part 3: Metropolis-Hastings

Introducing Probability to the Equation

Let's try to solve Laplace's PDE on a unit disk with the boundary constraint $g(\theta) = \sin(\theta)$. We'll solve at point $(0.5, \frac{\pi}{2})$.

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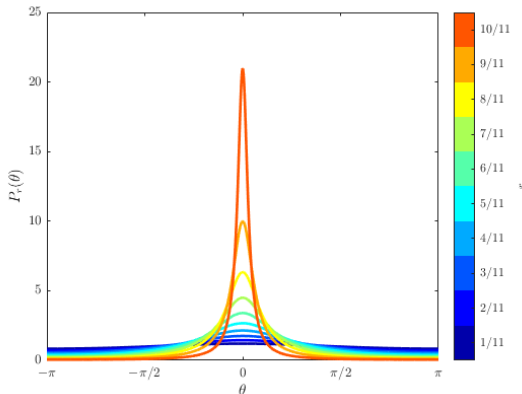


Introducing Probability to the Equation

The analytic solution to Laplace's equation on the unit disc is given by:

$$u(r, \theta) = \frac{1}{2\pi} \int_0^{2\pi} P(r, \theta - \varphi) g(\varphi) d\varphi$$

where P is the Poisson kernel.



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Where $X \sim P(r, \theta - x)$.

Introducing Probability to the Equation

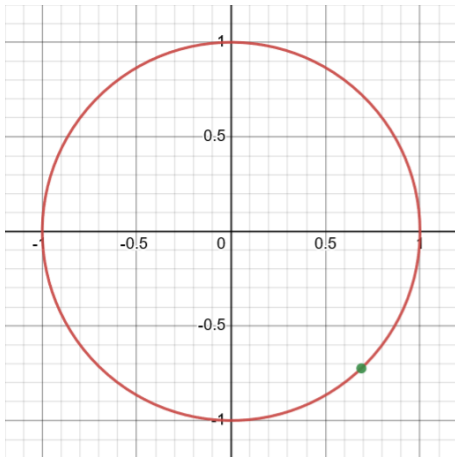
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Where $X \sim P(r, \theta - x)$. But how do we sample from the Poisson kernel?

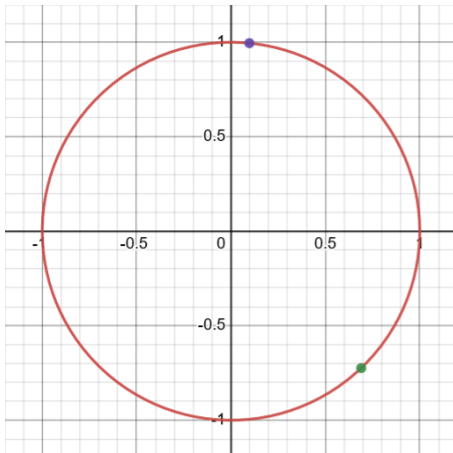
Metropolis-Hastings Algorithm

We can construct a sequence of random variables whose distribution approaches the Poisson kernel!



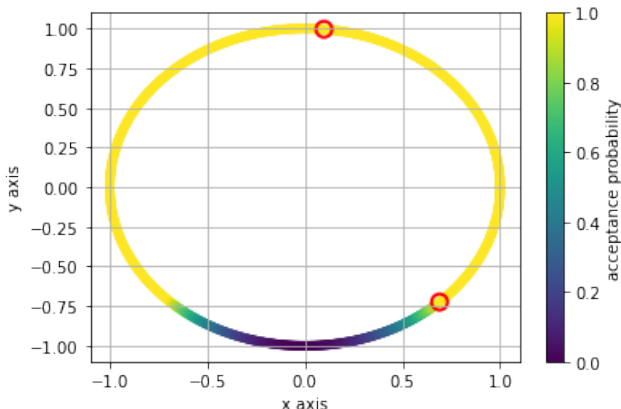
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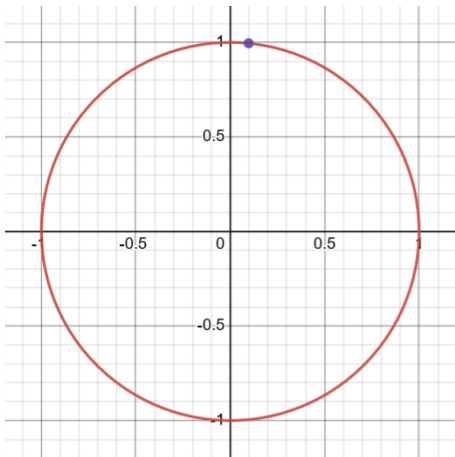
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$$A(x'|x) = \min\left(1, \frac{P(r, \theta - x')}{P(r, \theta - x)}\right) = 1$$

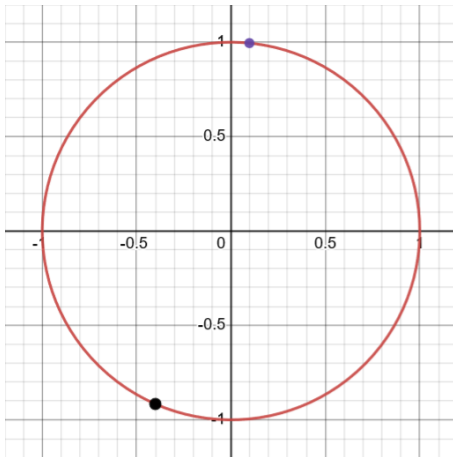
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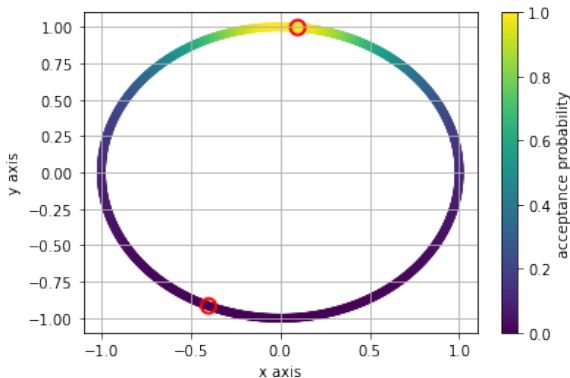
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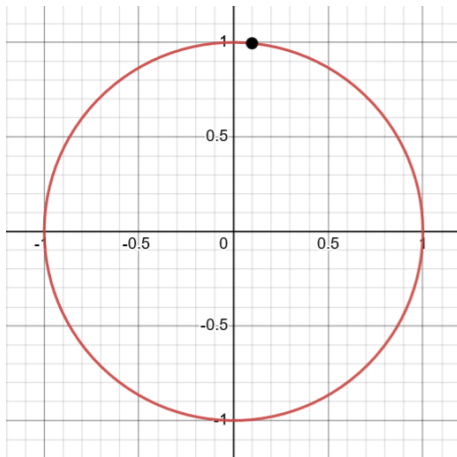
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$$A(x'|x) = \min\left(1, \frac{P(r, \theta - x')}{P(r, \theta - x)}\right) \approx 0.1176$$

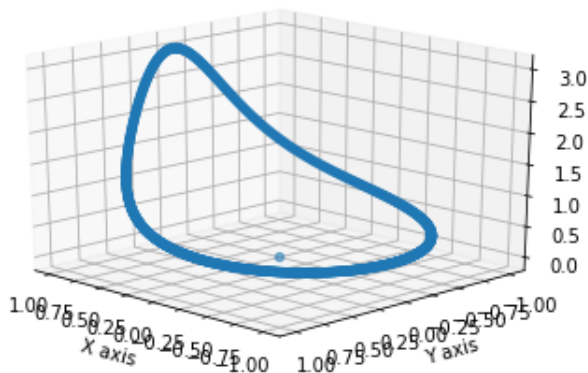
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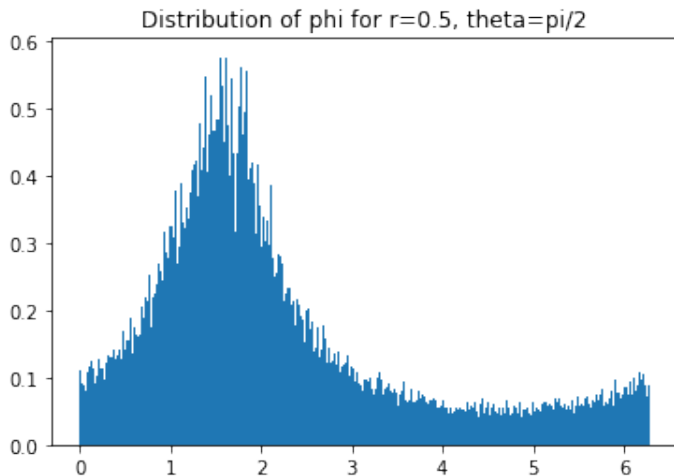


Results

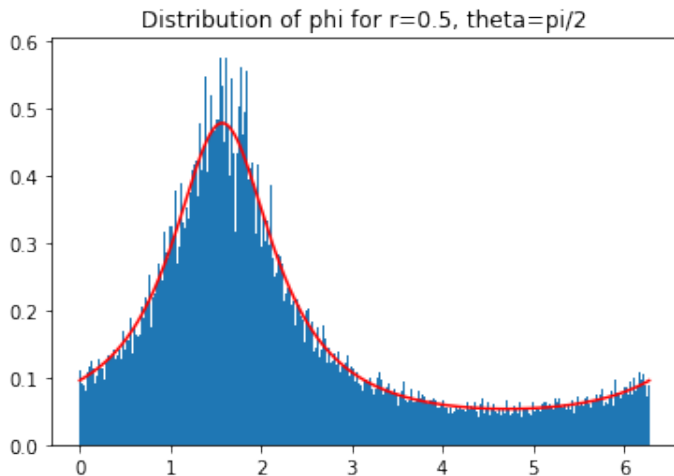
Here's a graph of the Poisson kernel:



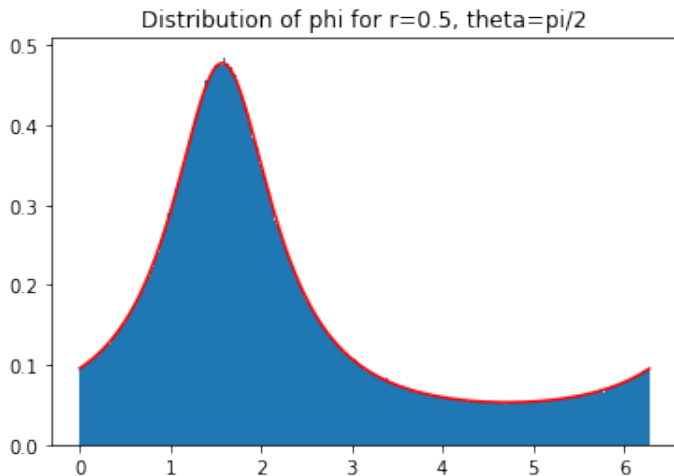
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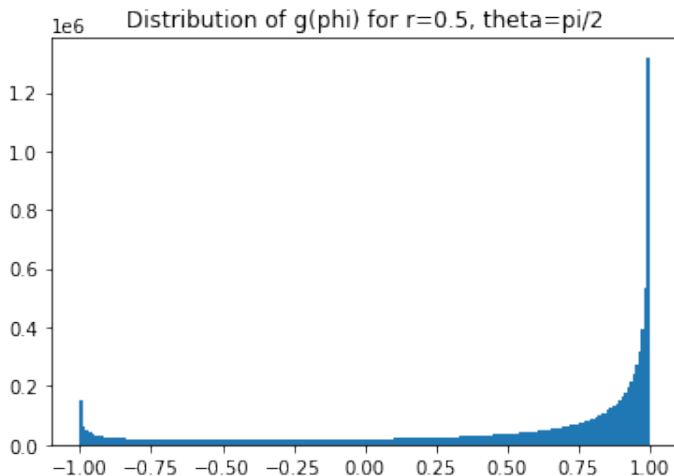


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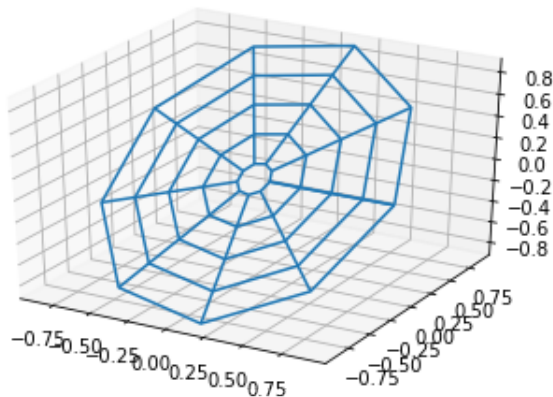
Results

After getting the sequence, we apply g to the sequence and take the mean.



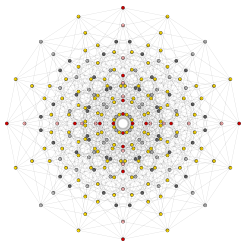
Results

Here's the solution for a bunch of points on the unit disc:

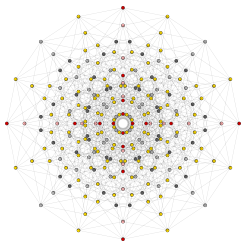


Part 4: Future Work and Methods

Future Directions

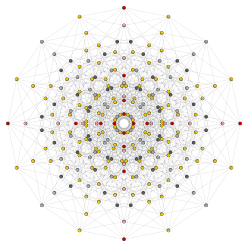


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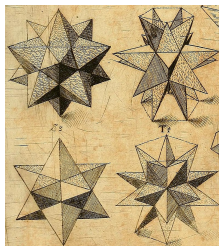


Higher Dimensions

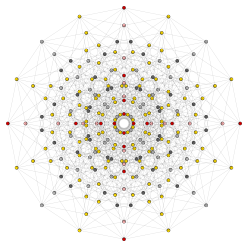
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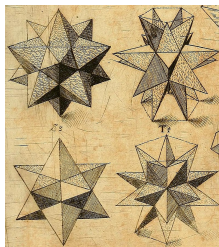
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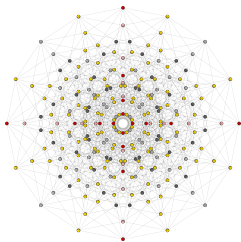


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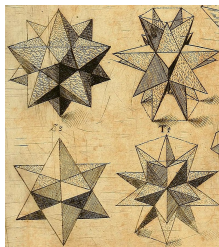


Non-convex Boundary

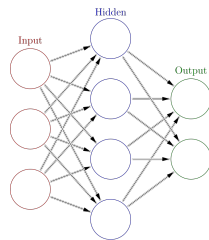
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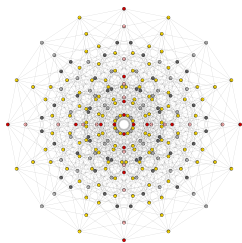
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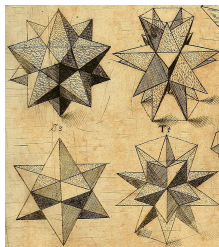
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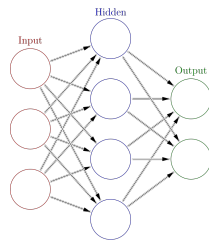
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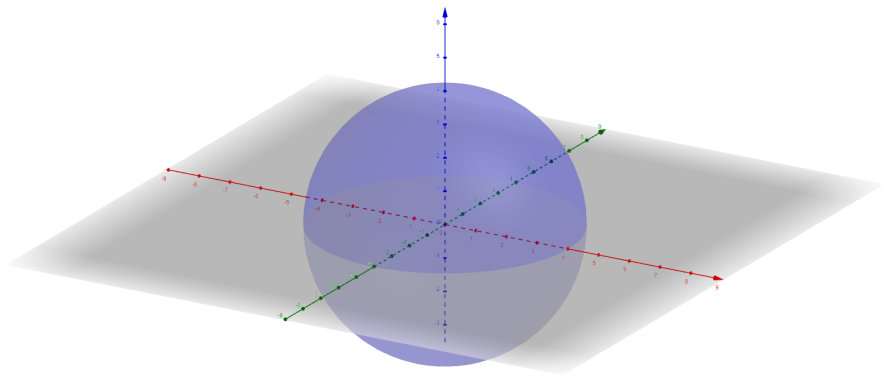


Non-convex Boundary



Reinforcement Learning

Unknown Distribution?



Thank you!

1. E, W., Li, T. & Vanden-Eijnden, E. (2019). *Applied Stochastic Analysis*. AMS, Providence, R.I. Print.
2. Sabelfeld, K. & Simonov, N. (2016). *Stochastic Methods for Boundary Value Problems: Numerics for High-dimensional PDEs and Applications*. Berlin, Boston: De Gruyter. [Link](#)