



Operating Manual

mic+ Ultrasonic Sensors with one analogue output

mic+25/IU/TC
mic+35/IU/TC
mic+130/IU/TC
mic+340/IU/TC
mic+600/IU/TC

Product description

- The mic+ sensor with one analogue output measures the distance to an object within the detection zone contactless. A signal proportional to distance is created according to the adjusted window limits of the analogue characteristic curve.
- The sensor automatically detects the load put to the analogue output and switches to current output or voltage output respectively.
- All settings are done with two push-buttons and a three-digit LED display (TouchControl).
- Three-colour LEDs indicate all operation conditions.
- Choosing between rising and falling output characteristic is possible.
- The sensors are adjustable manually via TouchControl or via Teach-in procedure.

- Useful additional functions are set in the Add-on menu.

- Using the LinkControl adapter (optional accessory) and the LinkControl software for Windows®, all Teach-in and additional sensor parameter settings can be optionally undertaken.

The mic+ sensors have a blind zone in which distance measurement is not possible. The operating range indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its maximum range. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

Safety Notes

- Read the operating instructions prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

Proper Use

mic+ ultrasonic sensors are used for non-contact detection of objects.

Synchronisation

If the assembly distances shown in Fig. 1 for two or more sensors are exceeded the integrated synchronisation should be used. Connect Sync/Com-channels (pin 5 at the units receptable) of all sensors (10 maximum).

Installation

- ➔ Assemble the sensor at the installation location.
- ➔ Plug in the connector cable to the M12 connector, see Fig. 2.

		colour
1	+U _B	brown
3	-U _B	blue
4	-	black
2	I/U	white
5	Sync/Com	grey

Fig. 2: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

Start-up

- ➔ Connect the power supply.
- ➔ Set the parameters of the sensor manually via TouchControl (see Fig. 3 and Diagram 1)
- ➔ or use the Teach-in procedure to adjust the detect points (see Diagram 2).

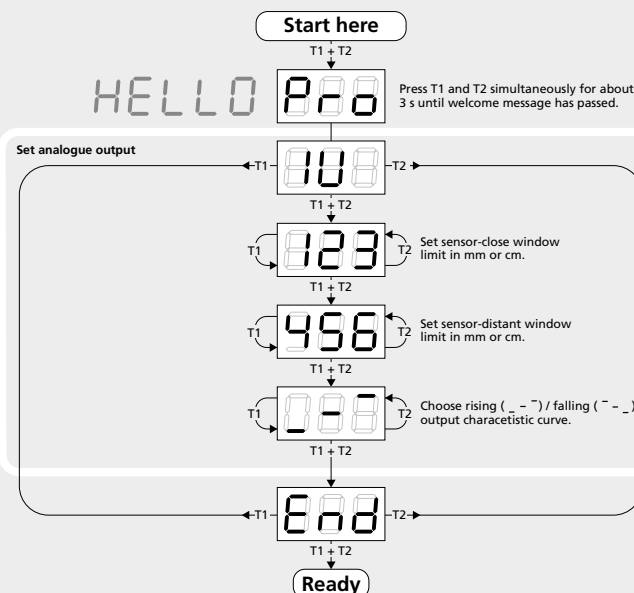
Notes

- mic+ sensors have internal temperature compensation. Because the sensors heat up on their own, the temperature compensation reaches its optimum working point after approx. 30 minutes of operation.
- If an object is within the set window limits of the analogue output, then LED D1 lights up green, if the object is outside the window limits, then LED D1 lights up red.
- The load put to the analogue output is detected automatically when turning supply voltage on.
- During normal operating mode, the measured distance value is displayed on the LED-indicator in mm (up to 999 mm) or cm (from 100 cm). Scale switches automatically and is indicated by a point on top of the digits. Alternatively a percentage scale may be set in the add-on menu. In this connection 0 % and 100 % correspond to the set window limits of the analogue output.
- If no objects are placed within the detection zone the LED-indicator shows »- - -«.
- The sensor can be set to its factory setting, see Diagram 3.
- If no push-buttons are pressed for 20 seconds during parameter setting mode the made changes are stored and the sensor returns to normal operating mode.

Show parameters

- ➔ In normal operating mode shortly push T1. The LED display shows »PAR.«
- Each time you tap push-button T1 the actual settings of the analogue output are shown.

Diagram 1: Set sensor parameters numerically using LED display



mic+25...	≥0.35 m	≥2.50 m
mic+35...	≥0.40 m	≥2.50 m
mic+130...	≥1.10 m	≥8.00 m
mic+340...	≥2.00 m	≥18.00 m
mic+600...	≥4.00 m	≥30.00 m

Fig. 1: Assembly distances, indicating synchronisation/multiplex

Multiplex mode

The Add-on-menu allows to assign an individual address »01« to »10« to each sensor connected via the Sync/Com-channel (Pin5). The sensors perform the ultrasonic measurement sequentially from low to high address. Therefore any influence between the sensors is rejected. The address »00« is reserved to synchronisation mode and deactivates the multiplex mode. To use synchronised mode all sensors must be set to address »00«.

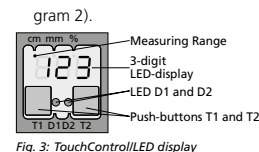


Fig. 3: TouchControl/LED display

Factory setting

- mic+ sensors are delivered factory made with the following settings:
- Rising analogue characteristic
- Window limits for the analogue output set to blind zone and operating range
- Measurement range set to maximum range

Maintenance

mic+ sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

Contact

Sensor Partners BV

James Wattlaan 15
5151 DP Drunen
The Netherlands
+31 (0)416 - 37 82 39
info@sensorpartners.com
sensorpartners.com

Sensor Partners BVBA

Z.1 Researchpark 310
B-1731, Zellik
Belgium
+32 (0)2 - 464 96 90
info@sensorpartners.com
sensorpartners.com

Diagram 2: Set sensor parameters via Teach-in procedure

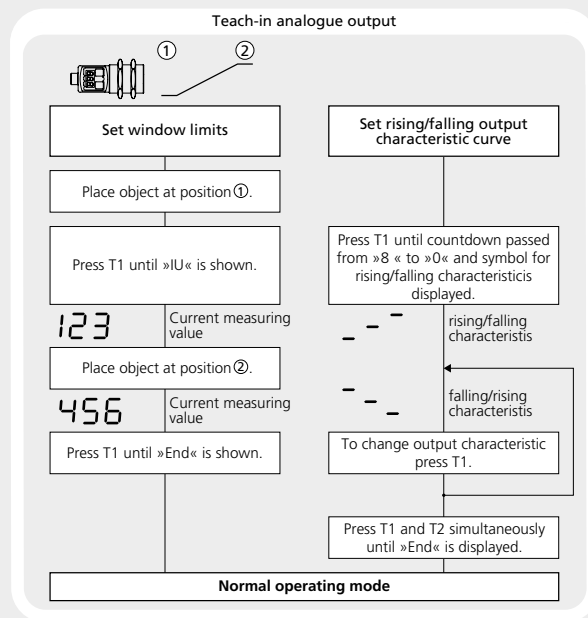


Diagram 3: Key lock and factory setting

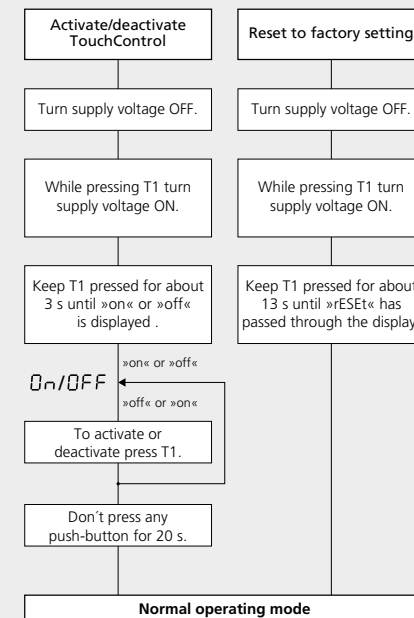
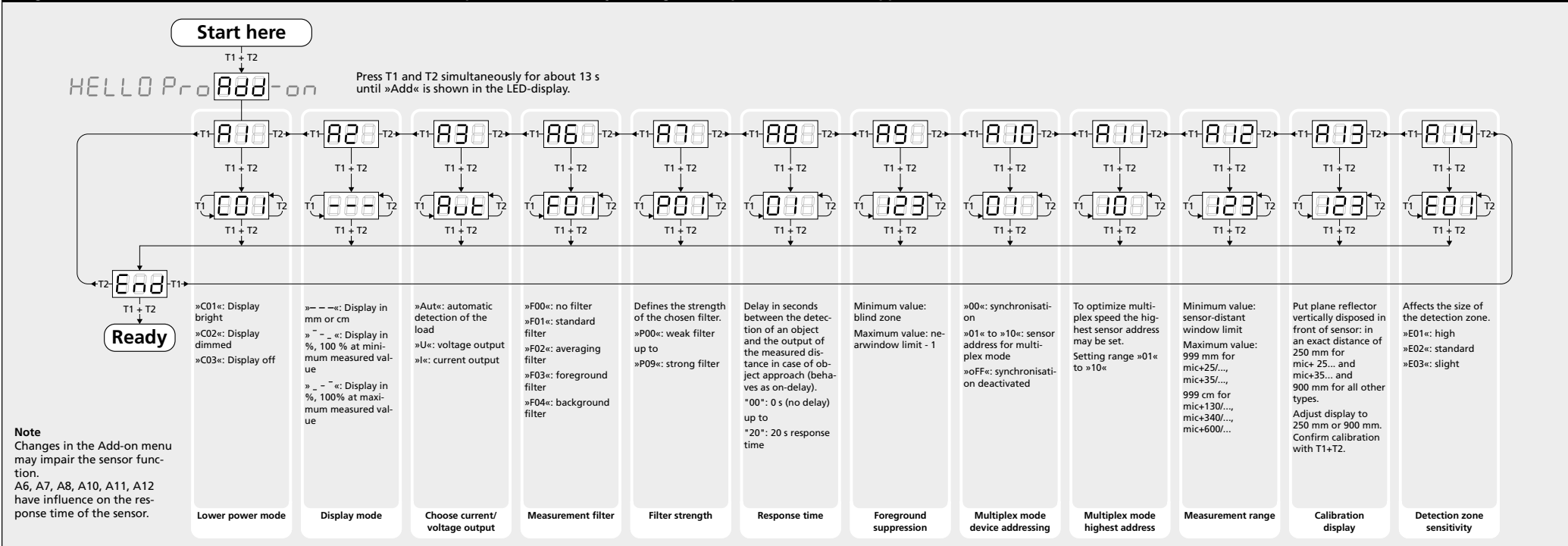
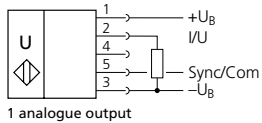


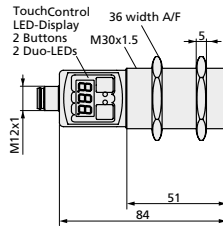
Diagram 4: Useful additional functions in Add-on menu (for experienced users only, settings not required for standard applications)



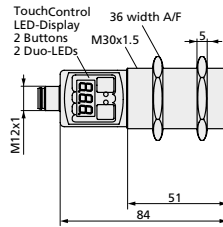
Technical data



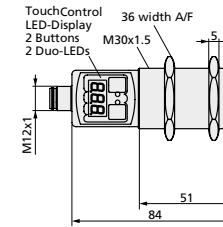
mic+25...



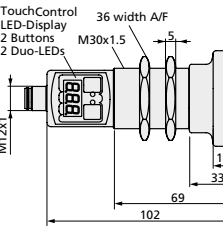
mic+35...



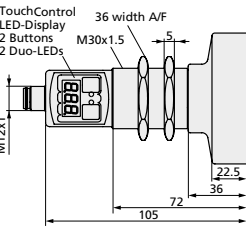
mic+130...



mic+340...



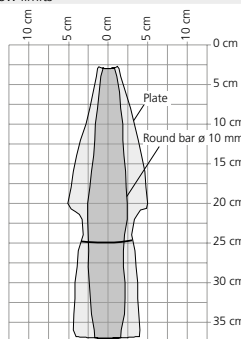
mic+600...



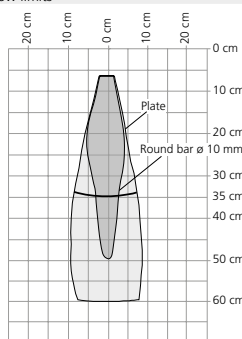
blind zone 0 to 30 mm
operating range 250 mm
maximum range 350 mm
angle of beam spread see detection zone
transducer frequency 320 kHz
resolution 0.025 to 0.10 mm, depending on the window limits

detection zones

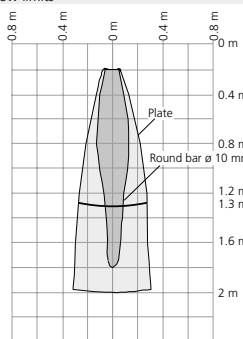
for different objects:
The dark grey areas represent the zone where it is easy to recognise the normal reflector (round bar). This indicates the typical operating range of the sensors. The light grey areas represent the zone where a very large reflector – for instance a plate – can still be recognised. The requirement here is for an optimum alignment to the sensor. It is not possible to evaluate ultrasonic reflections outside this area.



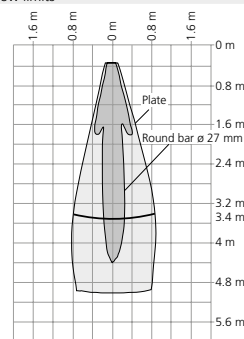
blind zone 0 bis 65 mm
operating range 350 mm
maximum range 600 mm
angle of beam spread see detection zone
transducer frequency 400 kHz
resolution 0.025 to 0.17 mm, depending on the window limits



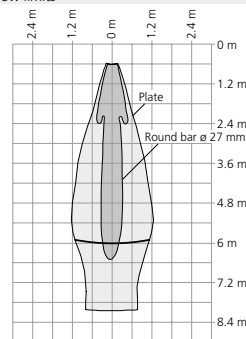
blind zone 0 to 200 mm
operating range 1,300 mm
maximum range 2,000 mm
angle of beam spread see detection zone
transducer frequency 200 kHz
resolution 0.18 to 0.57 mm, depending on the window limits



blind zone 0 to 350 mm
operating range 3,400 mm
maximum range 5,000 mm
angle of beam spread see detection zone
transducer frequency 120 kHz
resolution 0.18 to 1.5 mm, depending on the window limits



blind zone 0 to 600 mm
operating range 6,000 mm
maximum range 8,000 mm
angle of beam spread see detection zone
transducer frequency 80 kHz
resolution 0.18 to 2.4 mm, depending on the window limits



reproducibility ±0.15 %
accuracy ±1 % (Temperature drift internal compensated, may be deactivated²⁾, 0.17%/K without compensation)
operating voltage U_B 9 to 30 V DC, short-circuit-proof, Class 2
voltage ripple ±10 %
no-load supply current ≤ 80 mA
housing Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content

class of protection to EN 60529

norm conformity

type of connection

controls

indicators

programmable

operating temperature

storage temperature

weight

response time¹⁾

time delay before availability

order No. mic+25/IU/TC
current output 4 to 20 mA R_i ≤ 100 Ω at 9 V ≤ U_B ≤ 20 V
R_i ≤ 500 Ω at U_B ≥ 20 V
Rising/falling output characteristic
R_i ≥ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

voltage output 0 to 10 V R_i ≤ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

reproducibility ±0.15 %
accuracy ±1 % (Temperature drift internal compensated, may be deactivated²⁾, 0.17%/K without compensation)
operating voltage U_B 9 to 30 V DC, short-circuit-proof, Class 2
voltage ripple ±10 %
no-load supply current ≤ 80 mA
housing Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content

class of protection to EN 60529

norm conformity

type of connection

controls

indicators

programmable

operating temperature

storage temperature

weight

response time¹⁾

time delay before availability

order No. mic+35/IU/TC
current output 4 to 20 mA R_i ≤ 100 Ω at 9 V ≤ U_B ≤ 20 V
R_i ≤ 500 Ω at U_B ≥ 20 V
Rising/falling output characteristic
R_i ≥ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

voltage output 0 to 10 V R_i ≤ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

reproducibility ±0.15 %
accuracy ±1 % (Temperature drift internal compensated, may be deactivated²⁾, 0.17%/K without compensation)
operating voltage U_B 9 to 30 V DC, short-circuit-proof, Class 2
voltage ripple ±10 %
no-load supply current ≤ 80 mA
housing Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content

class of protection to EN 60529

norm conformity

type of connection

controls

indicators

programmable

operating temperature

storage temperature

weight

response time¹⁾

time delay before availability

order No. mic+130/IU/TC
current output 4 to 20 mA R_i ≤ 100 Ω at 9 V ≤ U_B ≤ 20 V
R_i ≤ 500 Ω at U_B ≥ 20 V
Rising/falling output characteristic
R_i ≥ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

voltage output 0 to 10 V R_i ≤ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

reproducibility ±0.15 %
accuracy ±1 % (Temperature drift internal compensated, may be deactivated²⁾, 0.17%/K without compensation)
operating voltage U_B 9 to 30 V DC, short-circuit-proof, Class 2
voltage ripple ±10 %
no-load supply current ≤ 80 mA
housing Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content

class of protection to EN 60529

norm conformity

type of connection

controls

indicators

programmable

operating temperature

storage temperature

weight

response time¹⁾

time delay before availability

order No. mic+340/IU/TC
current output 4 to 20 mA R_i ≤ 100 Ω at 9 V ≤ U_B ≤ 20 V
R_i ≤ 500 Ω at U_B ≥ 20 V
Rising/falling output characteristic
R_i ≥ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

voltage output 0 to 10 V R_i ≤ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

reproducibility ±0.15 %
accuracy ±1 % (Temperature drift internal compensated, may be deactivated²⁾, 0.17%/K without compensation)
operating voltage U_B 9 to 30 V DC, short-circuit-proof, Class 2
voltage ripple ±10 %
no-load supply current ≤ 80 mA
housing Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content

class of protection to EN 60529

norm conformity

type of connection

controls

indicators

programmable

operating temperature

storage temperature

weight

response time¹⁾

time delay before availability

order No. mic+600/IU/TC
current output 4 to 20 mA R_i ≤ 100 Ω at 9 V ≤ U_B ≤ 20 V
R_i ≤ 500 Ω at U_B ≥ 20 V
Rising/falling output characteristic
R_i ≥ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

voltage output 0 to 10 V R_i ≤ 100 kΩ at U_B ≥ 15 V, short-circuit-proof
Rising/falling output characteristic

¹⁾ Can be programmed via TouchControl and LinkControl.

²⁾ Can be deactivated via LinkControl.



Enclosure Type 1
For use only in industrial
machinery NFPA 79 applications.

The proximity switches shall be used with a
Listed (CUL/IT) cable/connector assembly rat-
ed minimum 32 Vdc, minimum 290 mA, in
the final installation.



Registration
no. 75330-19
Approved on
June 25th, 2019



2014/30/EU



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