RED series

DATASHEET

RED Series

▶ **RED-110-P**
  RED-110-L

- Line laser, **Laser class 2** (<1 mW, wavelength 670 nm) **Type -P**: Visible red laser spot, typ. Ø 0.1 mm in the focus **Type -L**: Visible red laser line, typ. 0.1 mm x 3 mm in the focus
- Automatic adjustment to the product
- Extern trigger mode
- Proof edge detection even with changing surface quality (glossy/matt, dark/bright)
- Max. scan frequency 85 kHz
- Reference distance 110 mm, working range typ. 90 mm ... 130 mm
- Insensitive to outside light due to interference filter and pulsed laser light
- RS232 interface (USB or Ethernet adaptor available)
- Windows® user interface
- 2 digital inputs, 2 digital outputs
- 1 analog output (0V ... +10V or 4 mA ... 20 mA)
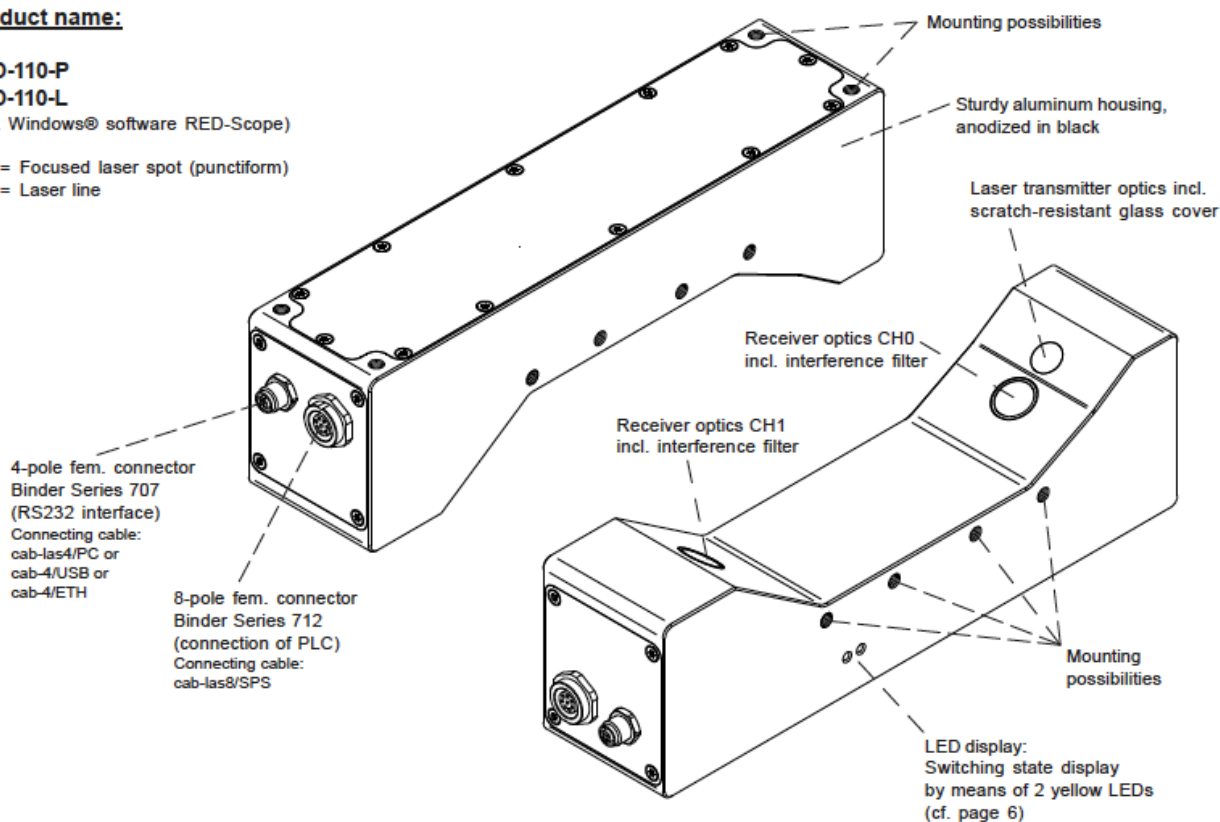- Switching state indication via 2 LEDs (OUT0 and OUT1)
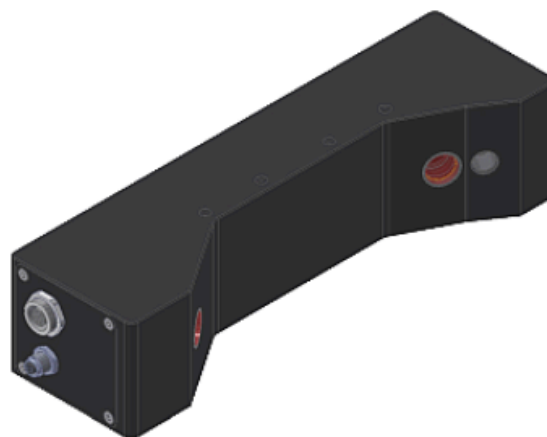
Design

Product name:

RED-110-P
RED-110-L
(incl. Windows® software RED-Scope)

P = Focused laser spot (punctiform)
L = Laser line

Mounting possibilities

Sturdy aluminum housing, anodized in black

Laser transmitter optics incl. scratch-resistant glass cover

Receiver optics CH0 incl. interference filter

Receiver optics CH1 incl. interference filter

4-pole fem. connector Binder Series 707 (RS232 interface)
Connecting cable: cab-las4/PC or cab-4/USB or cab-4/ETH

8-pole fem. connector Binder Series 712 (connection of PLC)
Connecting cable: cab-las8/SPS

Mounting possibilities

LED display: Switching state display by means of 2 yellow LEDs (cf. page 6)

Technical Data

Type	RED-110-P	RED-110-L
Voltage supply	+24VDC (± 10%), reversed polarity protected, overload protected	
Current consumption	< 220 mA	
Max. switching current	100 mA, short-circuit proof	
Transmitter (light source)	semi-conductor laser, 670 nm, AC operation, 1 mW max. opt. power, laser class 2 acc. to DIN EN 60825-1. The use of this laser sensor therefore requires no additional protective measures.	
Transmitter control	can be switched via PC software: AC operation (LED MODE-AC), DC operation (LED MODE-DC), OFF operation (LED MODE-OFF)	
Optimal measuring distance	110 mm	
Laser line geometry	focused laser spot (punctiform): typ. Ø 0.1 mm	Laser line: typ. 0.1 mm x 3 mm
Range	typ. 90 mm ... 130 mm	
Max. scan frequency	85 kHz	
Min. height of edge	typ. 0.05 mm	
Digital inputs (2x)	IN0 and IN1 (pin 3 and pin 4): digital (0V/+24V)	
Digital outputs (2x)	OUT0 and OUT1 (pin 5 and pin 6): digital (0V/+Ub), bright-/dark-switching, can be adjusted under Windows® on PC	
Analog output	0V ... +10V or 4 mA ... 20mA (pin 8)	
Band width analog signal	typ. 30 kHz (at 85 kHz scan frequency)	
Laser power correction	adjustable under Windows® on PC	
Sensitivity setting	adjustable under Windows® on PC	
Receiver	photo diode	
Optical filter	2x interference filter	
Ambient light	max. 5000 Lux	
Deadtime	dynamic, adjustable under Windows® on PC	
Pulse lengthening	0 ... 100 ms, adjustable under Windows® on PC	
Averaging	max. 32768 values, adjustable under Windows® on PC	
Switching state indication	2 yellow LEDs visualize the physical state of the outputs OUT0 and OUT1	
Housing dimensions	approx. 190 mm x 45 mm x 55 mm	
Hosuing material	aluminum, anodized in black	
Enclosure rating	IP54	
Type of connector	connection to PLC: 8-pole fem. connector (Binder 712) connection to PC: 4-pole fem. connector (Binder 707)	
Connecting cables	to PLC: cab-las8/SPS or cab-las8/SPS-w to PC/RS232 interface: cab-las4/PC or cab-las4/PC-w to PC/USB interface: cab-4/USB or cab-4/USB-w to PC/Ethernet interface: cab-4/ETH	
Operating temp. range	-20°C ... +50°C	
Storage temperature range	-20°C ... +85°C	
Interface	RS232, parameterisable under Windows®	
EMC test acc. to	DIN EN 60947-5-2 C E	

Dimensions

RED-110-P
RED-110-L

50	25	30	25	

28

55

Ø4.1

M5 - 14.2 tief – beidseitig

7°

110

34°   34°

90 mm
Start of working range
RED-110-...

90

130 mm
End of working range
RED-110-...

190

7.5   175

45   35

M5 - 8 tief

All dimensions in mm
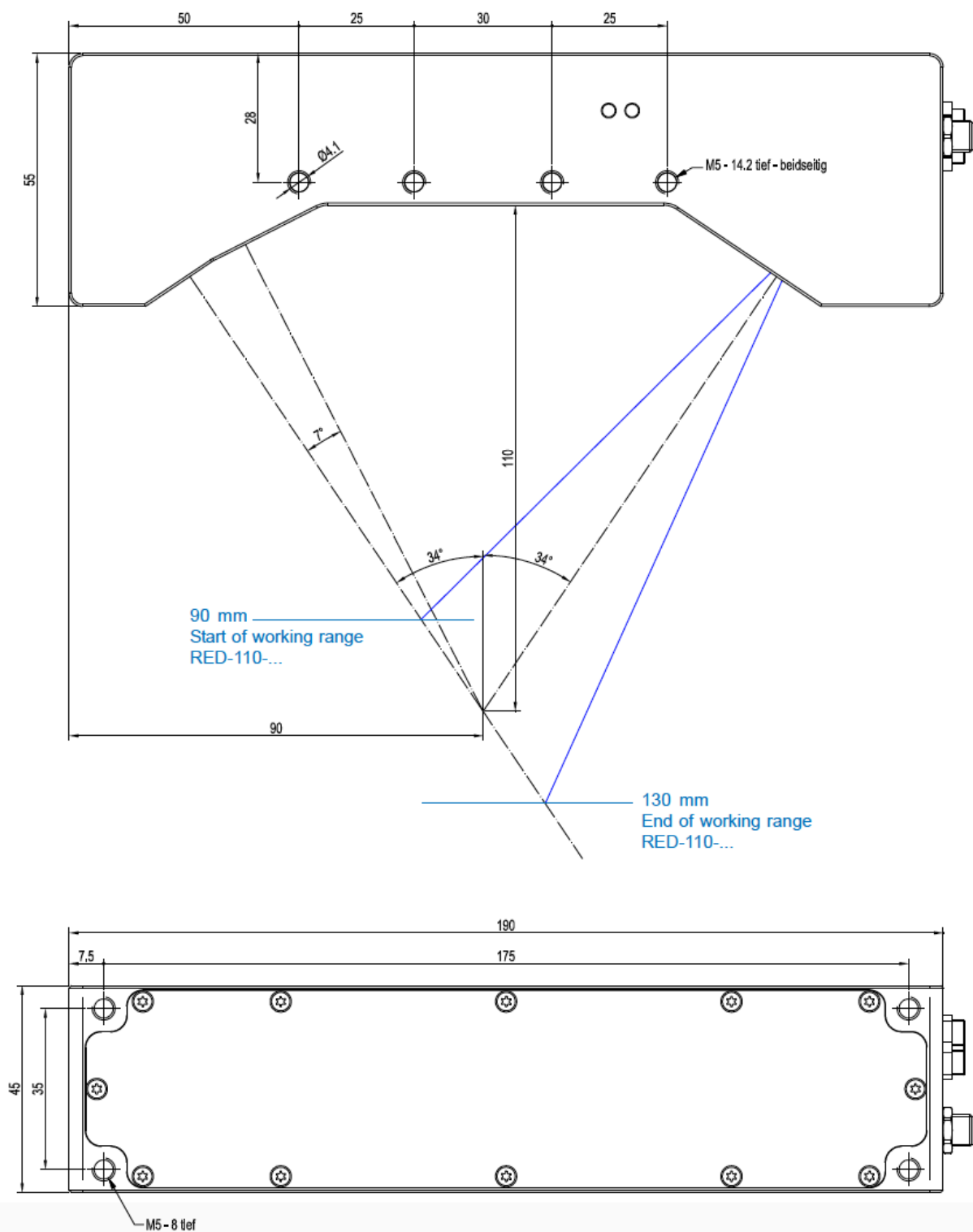
Connector Assignment

Connection to PLC:
8-pole fem. connector Binder Series 712

Pin:	Color:	Assignment:
1	white	GND (0V)
2	brown	+24VDC (± 10%)
3	green	IN0 (Digital 0: 0 … 1V, Digital 1: +Ub - 10%)
4	yellow	IN1 (Digital 0: 0 … 1V, Digital 1: +Ub - 10%)
5	grey	OUT0 (Digital 0: 0 … 1V, Digital 1: +Ub - 10%)
6	pink	OUT1 (Digital 0: 0 … 1V, Digital 1: +Ub - 10%)
7	blue	not connected
8	red	ANALOG (0V…+10V or 4mA…20mA)

Connecting cable:
cab-las8/SPS-(length)
cab-las8/SPS-w-(length) (angle type, 90°)
(standard length 2m)
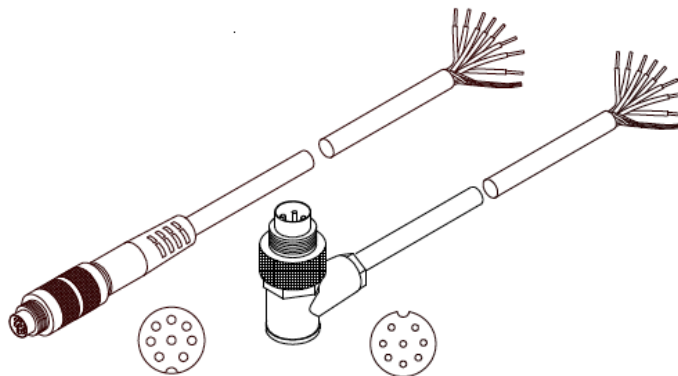
cab-las8/SPS-...
(max. length 25m, outer jacket: PUR)

cab-las8/SPS-w-...
(max. length 25m, outer jacket: PUR)

Connection to PC:
4-pole fem. connector Binder Series 707

Pin:	Assignment:
1	+24VDC (+Ub, OUT)
2	GND (0V)
3	RxD
4	TxD

Connection via RS232 interface at the PC:
Connecting cable:
cab-las4/PC-(length)
cab-las4/PC-w-(length) (angle type 90°)
(standard length 2m)

alternative:
Connection via USB interface at the PC:
Connecting cable (incl. driver software):
cab-4/USB-(length)
cab-4/USB-w-(length) (angle type 90°)
(standard length 2m)

alternative:
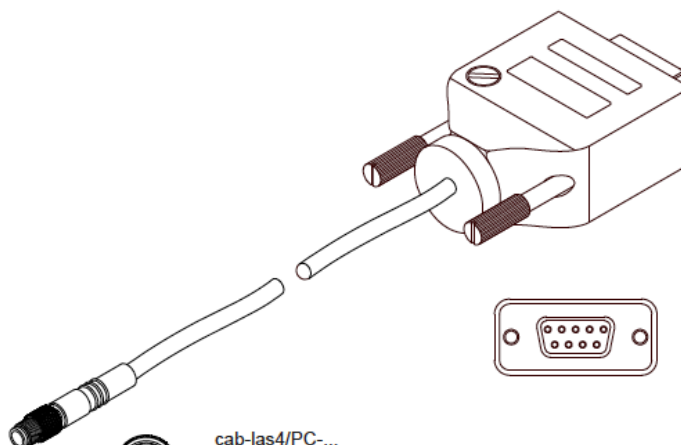*Connection to local network via Ethernet bus:*
Adapter (incl. software „SensorFinder"):
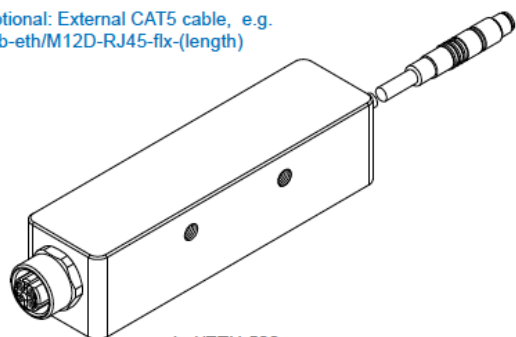cab-4/ETH-500
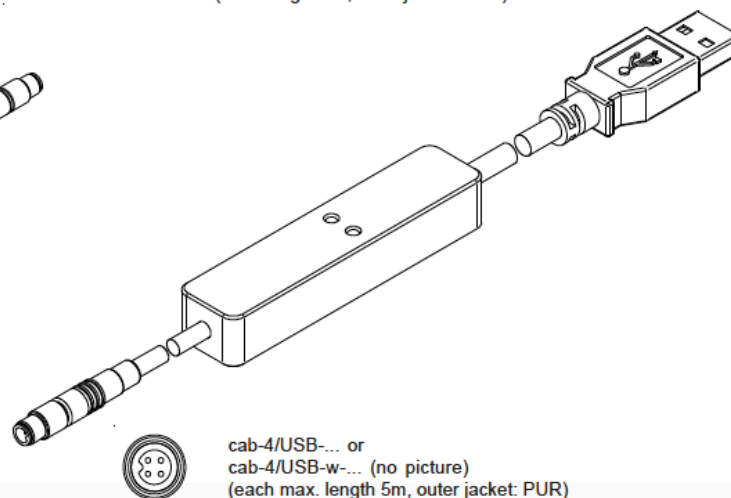(standard length 0.5m)

Optional: External CAT5 cable, e.g.
cab-eth/M12D-RJ45-flx-(length)

cab-las4/PC-...
(max. length 10m, outer jacket: PUR) or
cab-las4/PC-w-... (no picture)
(max. length 5m, outer jacket: PUR)

cab-4/ETH-500
(length 0.5m, outer jacket: PUR)
4-pole M12 fem. conn. (D-coded)
for connection of an external
CAT5 cable, e.g.
cab-eth/M12D-RJ45-flx-(length)

cab-4/USB-... or
cab-4/USB-w-... (no picture)
(each max. length 5m, outer jacket: PUR)

Function Principle

The edge detectors of RED series primarily are designed for detecting and counting edges. These may be e.g. newspapers, single sheets, cardboard boxes, sheet metals, wires, lamellas, welds, rotor blades, etc.

In its optimum operating range (e.g. 110 mm when RED-110-...) sheet edges starting from 0.1 mm are reliably detected.

The sensor is characterised by a high scanning frequency and by its ability to automatically adjust itself to differently bright and dark, as well as slow and fast objects; with a minimally set output pulse length (adjustable via software) it reaches a switching frequency of 10 kHz.

Furthermore the sensor can be used for almost all conceivable applications by selecting optimised software algorithms.

The RED sensor allows highly flexible signal acquisition. The sensor, for example, can be operated in alternating-light mode (AC mode), which means the sensor is not influenced by external light, or in constant-light mode (DC mode), which provides outstanding high-speed sensor operation. With the stepless adjustment of the integrated light source, the selectable gain of the receiver signal, and an INTEGRAL function the sensor can be adjusted to almost any surface.

A micro-controller performs 12-bit analog/digital conversion of the analog signal, which allows recording and evaluation of the signal. Furthermore the RED sensor offers various options for intelligent signal processing such as e.g. dirt accumulation compensation.

Parameters and measurement values can be exchanged between PC and sensor either through RS232 or Ethernet (using an Ethernet adaptor). Through the interface all the parameters can be stored in the non-volatile EEPROM of the sensor.

The PC software facilitates the parameterisation, diagnostics, and adjustment of the sensor system (oscilloscope function). The software furthermore provides a data recorder function that automatically records data and stores them on the hard disk of the PC.

Function principle of the RED-... sensor:

The laser sensors of RED series comprise a laser transmitter (laser diode, l=670 nm) and two receivers. As shown in the picture below, the laser beam is focused at an angle onto the edge (of the magazine) opposite to the direction of feed. When an edge arrives, it blocks the beam path to receiver CH1, whereas the signal at receiver CH0 slightly increases due to the more favourable angle of impingement!
The standardised value of SIGNALS CH0 and CH1 is used as the starting signal SIG for all the further algorithms of the sensor.

- The evaluated signal can be output via a voltage output or via a current output. With the help of the software, different evaluation modes for the analogue signal can be selected.

- The state of the output signal is output via 2 digital outputs depending on the evaluation mode.

- A digital input allows external „teaching" of the sensor.

- Another input enables a „freezing" of the analog output signal with a positive signal edge.

$$SIG = \frac{CH1}{CH0 + CH1} * 4095$$
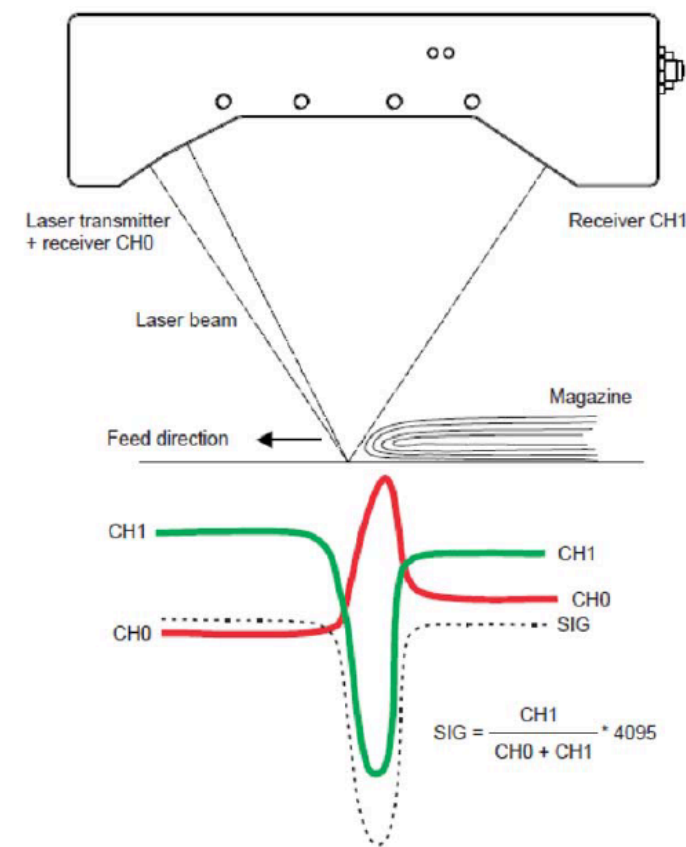
## LED Display

LED display:

By means of the two LEDs the physical state of the two outputs OUT0 and OUT1 is visualized.

OUT1

OUT0
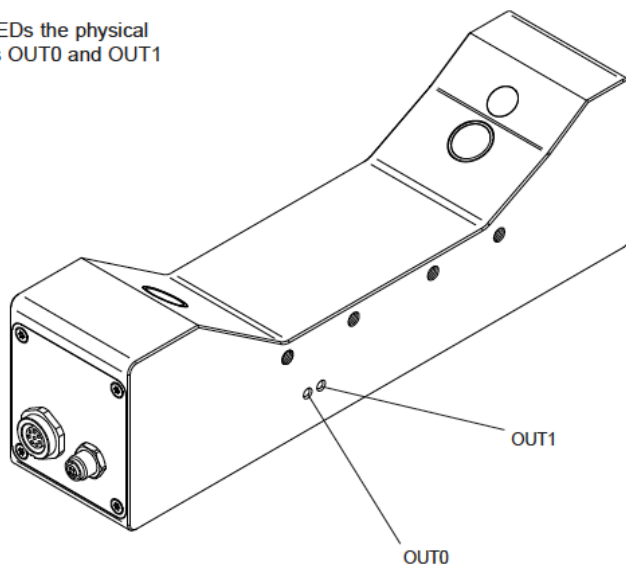
Laser Warning

The laser edge detectors RED-110-... comply with laser class 2 according to EN 60825-1. The use of these laser transmitters therefore requires no additional protective measures.
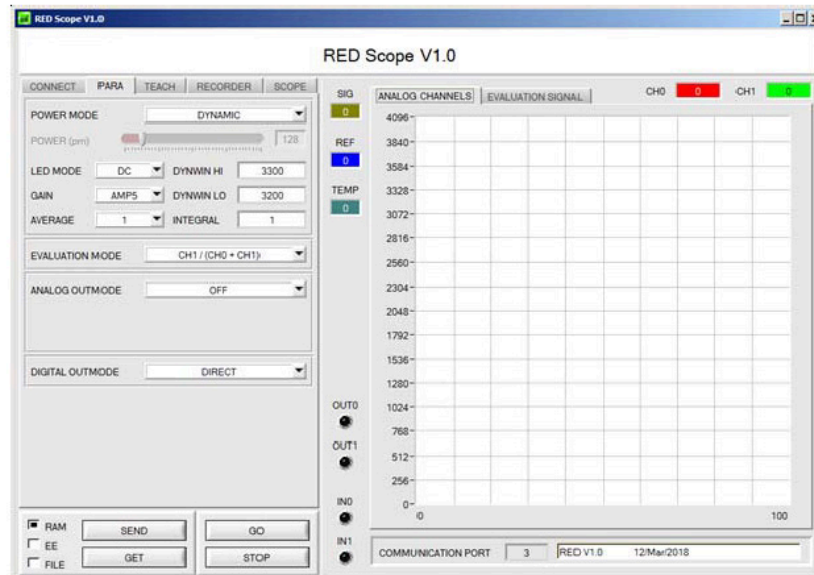
The laser edge detectors RED-110-... are supplied with a laser warning label.

LASER RADIATION
DO NOT STARE INTO THE BEAM
CLASS II LASER PRODUCT
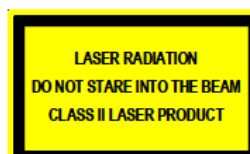
Parameterization

Windows® user interface:
(The current software version is available for download on our website.)

The PC software RED-Scope facilitates the parameterization, the diagnosis, and the adjustment of the sensor system (oscilloscope function). Moreover, the software features a data recorder function that allows the automatic recording of recorded data and the saving of those at the hard disk of the PC.
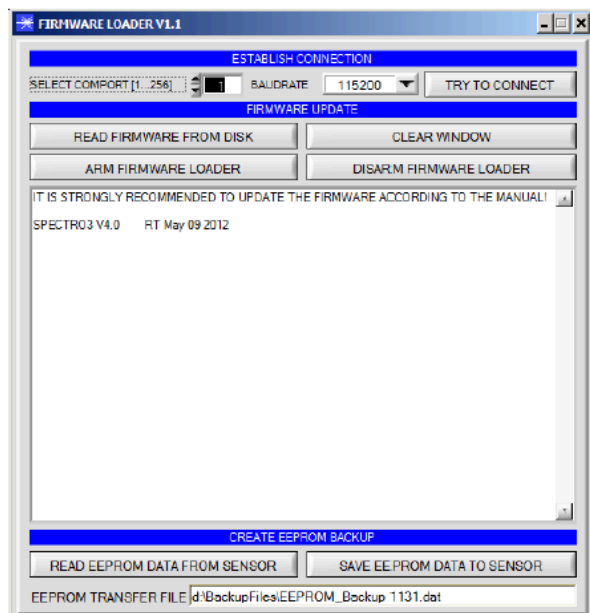
Parameters and measurement values can be exchanged between PC and sensor either through RS232 or Ethernet (using an Ethernet adaptor). Through the interface all the parameters can be stored in the non-volatile EEPROM of the sensor.

The SCOPE tab visualises an oscilloscope.

Firmware Update

Firmware update by means of the software „FirmwareLoader":

The software „Firmware Loader" allows the user to perform an automatic firmware update. The update will be carried out through the RS232 interface.

An initialisation file (xxx.ini) and a firmware file (xxx.elf.S) are required for performing a firmware update. These files can be obtained from your supplier. In some cases an additional firmware file for the program memory (xxx.elf.p.S) is also needed, and this file will be automatically provided together with the other two files.