



OSDome

Hemispherical View High-Resolution Imaging Lidar

FIRMWARE VERSION: 3.1.x

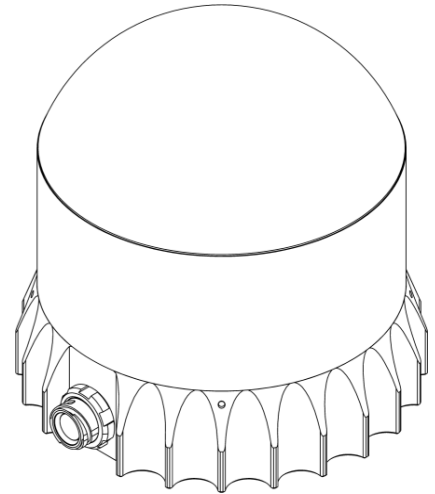
HARDWARE VERSION: REV7

SUMMARY

The OSDome offers a complete 180° hemispherical field of view, up to 20 m of range at 10% reflectivity, and high resolution. The OSDome delivers full coverage for indoor people tracking, and near-range detection for mobile robots and vehicles.

HIGHLIGHTS

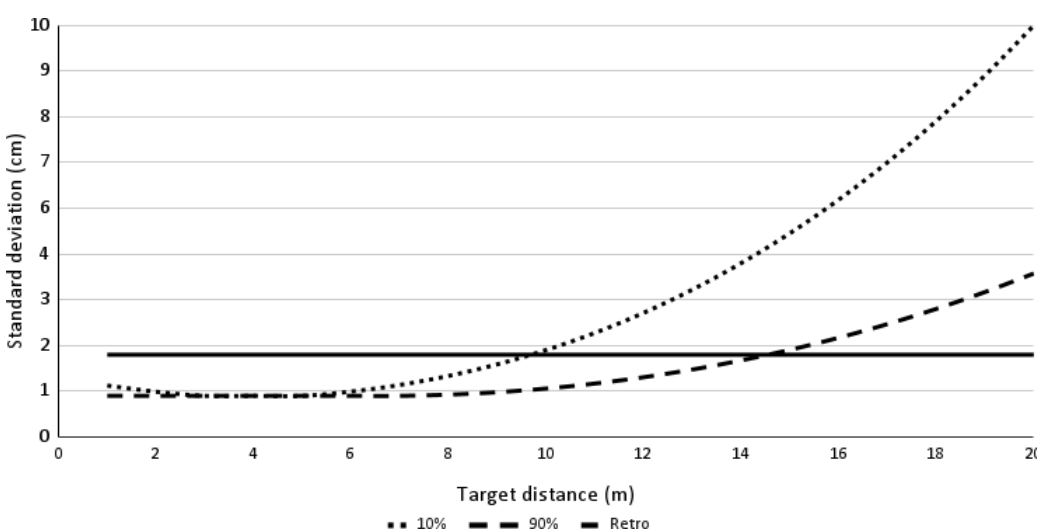
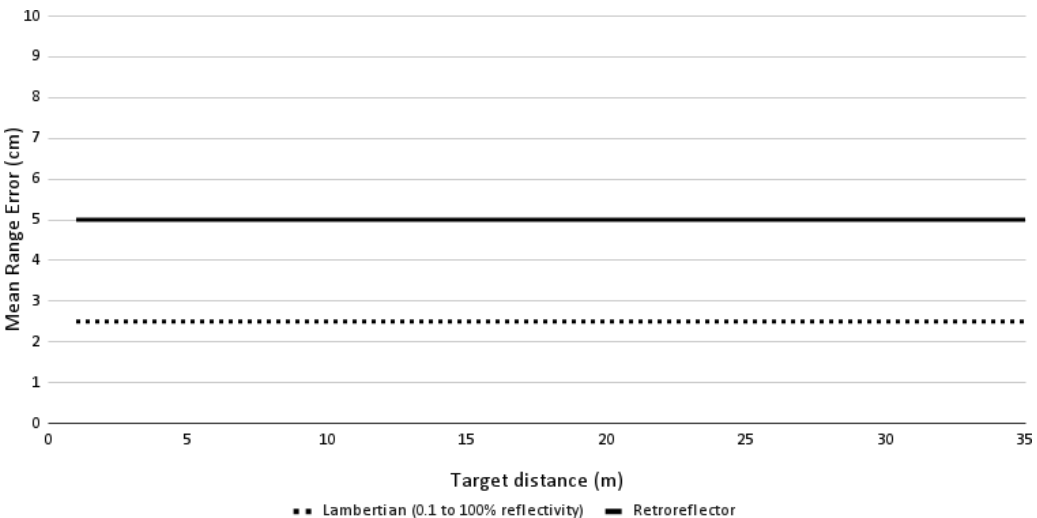
- Configurable Minimum Range and Return Ordering
- Low Data Rate Profile now available with Dual Returns
- Camera-grade near-infrared and signal data
- Multi-sensor crosstalk suppression
- Ouster Studio for pointcloud evaluation
- Ouster SDK, ROS, and C++ drivers for SW development



OPTICAL PERFORMANCE

Range (80% Lambertian reflectivity, 1024 @ 10 Hz mode)	45 m @ 100 klx sunlight, >90% detection probability
Range (10% Lambertian reflectivity, 1024 @ 10 Hz mode)	20 m @ 100 klx sunlight, >90% detection probability
Minimum Range	0.0 m (0.3 m optional, and 0.5 m default)
Vertical Resolution	32, 64, or 128 channels
Horizontal Resolution	512, 1024, or 2048 (configurable)
Rotation Rate	10 or 20 Hz (configurable)
Field of View	Vertical: 180° Horizontal: 360°
Angular Sampling Accuracy	Vertical: $\pm 0.01^\circ$ / Horizontal: $\pm 0.01^\circ$
False Positive Rate	1/10,000
Range Resolution	0.1 cm Note: For <i>Low Data Rate Profile</i> the Range Resolution = 0.8 cm
Vertical Angular Resolution	Up to 0.7° angular resolution
# of Returns	up to 2
Return Order	Strongest to Weakest, Farthest to Nearest, and Nearest to Farthest



<p>Range Precision (Typical on Lambertian and Retroreflective targets beyond 1 m, 1024 @ 10 Hz mode, 1 standard deviation)</p> <p>Note: Precision is calculated based on the standard deviation of 100 measurements on a static target at a given range</p>	<p>Min: ±1.0 cm, Max: ±10 cm</p>  <table><caption>Approximate data for Range Precision graph</caption><tr><th>Target distance (m)</th><th>10% Standard deviation (cm)</th><th>90% Standard deviation (cm)</th><th>Retro Standard deviation (cm)</th></tr><tr><td>0</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>2</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>4</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>6</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>8</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>10</td><td>1.0</td><td>1.0</td><td>1.0</td></tr><tr><td>12</td><td>1.0</td><td>1.0</td><td>2.5</td></tr><tr><td>14</td><td>1.0</td><td>1.0</td><td>4.0</td></tr><tr><td>16</td><td>1.0</td><td>1.0</td><td>6.0</td></tr><tr><td>18</td><td>1.0</td><td>1.0</td><td>8.0</td></tr><tr><td>20</td><td>1.0</td><td>1.0</td><td>10.0</td></tr></table>	Target distance (m)	10% Standard deviation (cm)	90% Standard deviation (cm)	Retro Standard deviation (cm)	0	1.0	1.0	1.0	2	1.0	1.0	1.0	4	1.0	1.0	1.0	6	1.0	1.0	1.0	8	1.0	1.0	1.0	10	1.0	1.0	1.0	12	1.0	1.0	2.5	14	1.0	1.0	4.0	16	1.0	1.0	6.0	18	1.0	1.0	8.0	20	1.0	1.0	10.0
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<p>Range Accuracy (Typical on Lambertian and Retroreflective targets beyond 1 m, 1024 @ 10 Hz mode)</p> <p>Note: Accuracy is calculated based on the error between the mean of 100 measurements on a static target at a given range and the true range</p>	<p>±2.5 cm for lambertian targets, ±5 cm for retroreflective targets</p>  <table><caption>Approximate data for Range Accuracy graph</caption><tr><th>Target distance (m)</th><th>Lambertian Mean Range Error (cm)</th><th>Retro Mean Range Error (cm)</th></tr><tr><td>0</td><td>2.5</td><td>5.0</td></tr><tr><td>5</td><td>2.5</td><td>5.0</td></tr><tr><td>10</td><td>2.5</td><td>5.0</td></tr><tr><td>15</td><td>2.5</td><td>5.0</td></tr><tr><td>20</td><td>2.5</td><td>5.0</td></tr><tr><td>25</td><td>2.5</td><td>5.0</td></tr><tr><td>30</td><td>2.5</td><td>5.0</td></tr><tr><td>35</td><td>2.5</td><td>5.0</td></tr></table>	Target distance (m)	Lambertian Mean Range Error (cm)	Retro Mean Range Error (cm)	0	2.5	5.0	5	2.5	5.0	10	2.5	5.0	15	2.5	5.0	20	2.5	5.0	25	2.5	5.0	30	2.5	5.0	35	2.5	5.0																					
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LASER

Laser Product Class	Class 1 eye-safe per IEC/EN 60825-1: 2014
Laser Wavelength	865 nm
Beam Diameter Exiting Sensor	5 mm
Beam Divergence	0.35° (FWHM)

LIDAR OUTPUT

Connection	UDP over gigabit Ethernet
Points Per Second	1,310,720 (32 channel) 2,621,440 (64 channel) 5,242,880 (128 channel)
Data Rate (megabits per second) (Low Data Rate Profile, 1 return, 1024 @ 10 Hz mode)	up to 11.83 Mbps (32 channel) up to 22.32 Mbps (64 channel) up to 43.29 Mbps (128 channel)
Data Rate (megabits per second) (Low Data Rate Profile, 2 returns, 1024 @ 10 Hz mode)	up to 22.32 Mbps (32 channel) up to 43.29 Mbps (64 channel) up to 85.24 Mbps (128 channel)



Data Rate (megabits per second) (Single Return Profile, 1024 @ 10 Hz mode)	up to 32.81 Mbps (32 channel) up to 64.26 Mbps (64 channel) up to 127.18 Mbps (128 channel)
Data Rate (megabits per second) (Dual Return Profile, 1024 @ 10 Hz mode)	up to 43.29 Mbps (32 channel) up to 85.24 Mbps (64 channel) up to 169.12 Mbps (128 channel)
Data Per Point	Range, Signal, Reflectivity, Near-infrared, Channel, Azimuth angle, and Timestamp
Timestamp Resolution	< 1 μ s
Data Latency	< 10 ms
Data Integrity	End to End CRC that covers entire data packet

IMU OUTPUT

Connection	UDP over 1000Base-T or 1000Base-T1
Samples Per Second	100
Data Per Sample	3 axis gyro, 3 axis accelerometer
Timestamp Resolution	< 1 μ s
Data Latency	< 10 ms
Additional Details	InvenSense IAM-20680HT; datasheet for more details: https://invensense.tdk.com/download-pdf/iam-20680ht-datasheet/

CONTROL INTERFACE

Connection	HTTP API	
Time Synchronization	Input sources: <ul style="list-style-type: none">• IEEE1588 Precision Time Protocol (PTP); Accuracy: <1 ms error• gPTP; Accuracy: <1 ms error• NMEA \$GPRMC UART message support• External PPS; Accuracy: <1 ms error• Internal 10 ppm drift clock; Accuracy: <20 ppm error Output sources: <ul style="list-style-type: none">• Configurable 1 - 60 Hz output pulse	
Lidar Operating Modes	<ul style="list-style-type: none">• x 512 @ 10 Hz or 20 Hz• x 1024 @ 10 Hz or 20 Hz• x 2048 @ 10 Hz	
Additional Programmability	<ul style="list-style-type: none">• Multi-sensor phase lock• Queryable intrinsic calibration information:<ul style="list-style-type: none">• Beam angles• IMU pose correction matrix	<ul style="list-style-type: none">• Return ordering• Minimum range• Azimuth masking• Low-power standby mode




MECHANICAL/ELECTRICAL

Power Consumption	14 - 20 W <ul style="list-style-type: none">• 16 W nominal• 28 W peak at startup if operating at -40 °C Note: Ouster recommends use of a power supply of no less than 30 W if using in cold conditions
Connector	Standard 1000BASE-T or Automotive Standard 1000BASE-T1
Operating Voltage	9.5 V - 51 V <ul style="list-style-type: none">• Suitable for 12 VDC to 24 VDC nominal systems• Not suitable for 48 V nominal battery based systems• Under-voltage WARNING level alert occurs at 9.5 VDC at the connector• Under-voltage ERROR level alert occurs at 9.0 VDC at the connector• Below 9.0 VDC at connector, sensor may shutdown• Over-voltage conditions/alarms occur at 51 VDC at the connector• Over-voltage lockout onset at 58 VDC (± 1 V) at the connector• Over-voltage lockout release at 55 VDC (± 1 V) at the connector



Dimensions	Diameter: 87 mm (3.42 in) Height: <ul style="list-style-type: none">• Without baseplate: 85.27 mm (3.35 in)• With baseplate: 107.77 mm (4.2 in)
Weight	470 g (16.6 oz)
Mounting	Bottom: 4x M3 screws, 2x locating 2 mm pin holes

OPERATIONAL

Operating Temperature	-40 °C to +60 °C (with mount) Between +53 °C and +60 °C, sensor automatically reduces range (max 20% range reduction)
Storage Temperature	-40 °C to +105 °C
Ingress Protection	IP68 (1 m submersion for 1 hour, with I/O cable attached) IP69K (with I/O cable attached)
Shock	IEC 60068-2-27 (Amplitude: 100 g, Shape: 11 ms half-sine, 3 shocks x 6 directions)
Vibration	IEC 60068-2-64 (Amplitude: 1 G-rms, Shape: 10 - 1000 Hz, Mounting: sprung masses, 3 axes w/ 8 hr duration each)
Compliance	<p>For US</p> <p>Laser Safety:</p> <ul style="list-style-type: none">• IEC/EN 60825-1:2014 Class 1 eye safe• FDA US 21CFR1040 Notice 56 Class 1 <p>Product Safety:</p> <ul style="list-style-type: none">• UL 62368-1• UL 60950-22 (outdoor use)• CSA-C22.2 No. 62368-1-19• CSA-C22.2 No. 60950-22-07 (outdoor use) <p>EMC: FCC 47CFR Part 15, Subpart B, Class A</p> <p>For EU</p> <p>Laser Safety: EN/IEC 60825-1:2014 Class 1 eye safe</p> <p>Product Safety: EN/IEC 62368-1</p> <p>EMC:</p> <ul style="list-style-type: none">• EN 55032:2012/AC 2013; CISPR 32:2015• EN 55024:2010; CISPR 24:2010• EN 61000-3-2:2014• EN 61000-3-3:2013 <p>  </p>



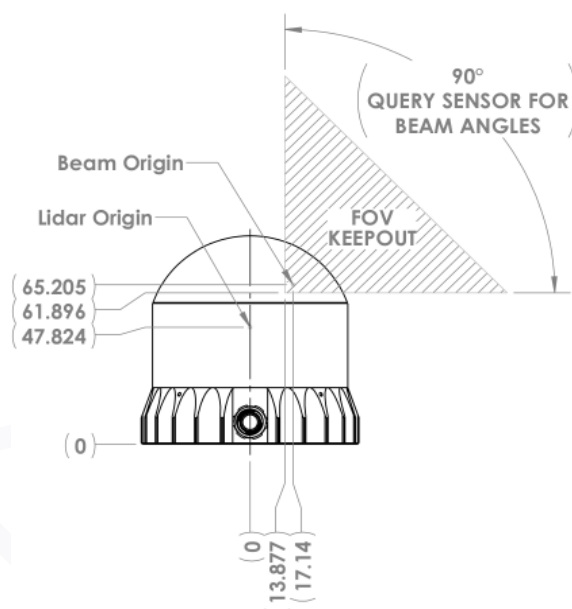
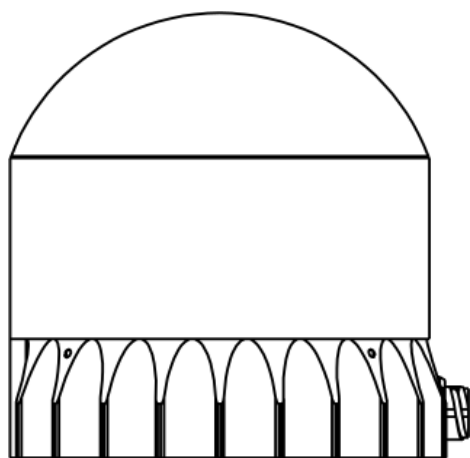
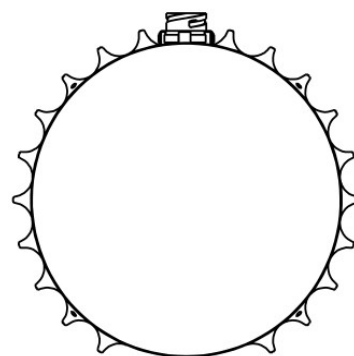
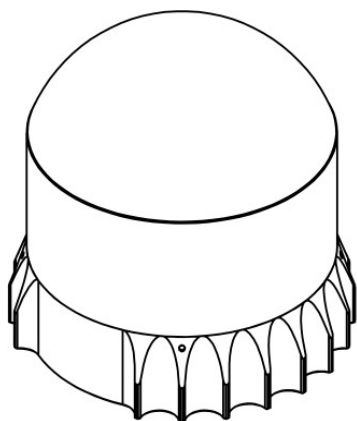
ACCESSORIES

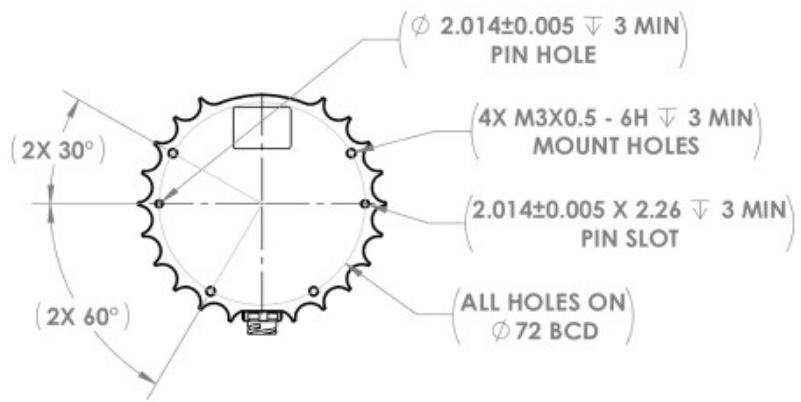
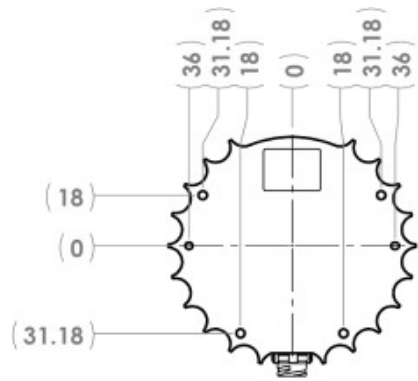
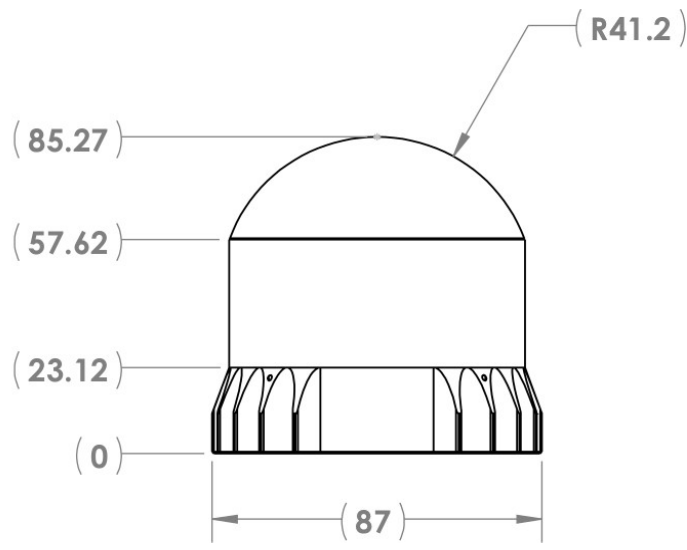
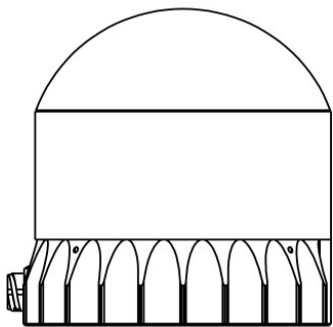
Interface Box	Polycarb/FR4, 100 g, 75 mm x 50 mm x 25 mm (LxWxH), 2 m CAT6 cable, 24 V power adapter, 5 m sensor cable
Optional Mount	Aluminum, 530 g, 110 mm x 110 mm x 20.5 mm (LxWxH), 4 x M8 thru holes

SOFTWARE

Sample Drivers	Ouster SDK, ROS, C++
Visualizer	Ouster Studio

EXTERIOR DIMENSIONS





*Specifications are subject to change without notice.