

# JT16

## 16-Channel Mechanical Lidar Connection Box | User Manual

Classification: CO (Public)

Doc version: J03-en-250610



#### **Connection box**

- Users may connect the lidar with or without a connection box.
- Cable between the lidar and the connection box: 260  $\pm$  10 mm in length.

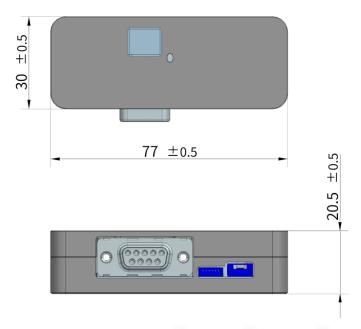


Figure 12. Connection box (unit: mm)

The cable connecting the lidar and the connection box is shown below.

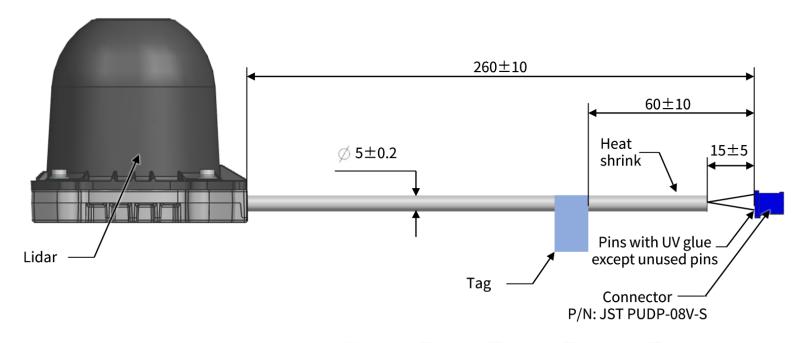


Figure 1. Cable between lidar and connection box (unit: mm)

#### **Ports**

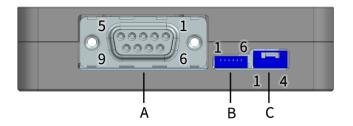


Figure 14. Connection box (front)

Port No.	Connection	Description	
Α	Mandatory	Connect to the host computer. Connector part number: Amphenol LD09S33E4GX00LF	
В	Optional	Connect to an external GNSS module; for time synchronization.  Connector part number: JST SM06B-SRSS-TB  Recommended connector for the external GPS module: JST SHR-06V-S-B	
С	Optional	Connect to the host computer; for API communication.  Connector part number: JST SM04B-GHS-TB  Recommended connector for the external module: JST GHR-04V-S	

Port B and Port C cannot be used simultaneously.

#### Port A (right to left, top to bottom):

Pin No.	Direction	Signal	Level	Description
1	Bidirectional (half	API_RX/DATA+	RS485	-
2	duplex)	API_RX/DATA-		
5	-	GND	0 V	Ground for the external GNSS module
9	Input	GNSS_5V	5 V	Power for the external GNSS module

#### Port B (left to right):

Pin No.	Direction	Signal	Level	Description
1	Input	GNSS_PPS	3.3 V CMOS	-
2	Output	GNSS_5V	5 V	Power for the external GNSS module
3	-	GND	0 V	Ground for the external GNSS module
4	Input	GNSS_NMEA	RS232	-
5	-	GND	0 V	Ground for the external GNSS module
6	-	Reserved	-	Do NOT connect this pin to external signals.

#### Port C (left to right):

Pin No.	Direction	Signal	Level	Description
1	Input	ADI TV	2 2 V CMOS	Use either Din 1 or Din 2 not both
2	Input	API_TX	3.3 V CMOS	Use either Pin 1 or Pin 2, not both.
3	-	GND	0 V	Ground
4	-	GND	0 V	Ground

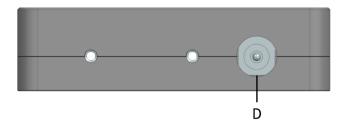


Figure 15. Connection box (back)

Port No.	Connection	Description
D	Mandatory	Connect to a 12 to 16 V DC power source.

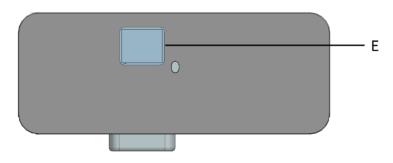


Figure 16. Connection box (top)

Port No.	Connection	Description
Е	Mandatory	Connect to the <u>lidar connector</u> . Connector part number: JST S08B-PUDSS-1

#### Connection

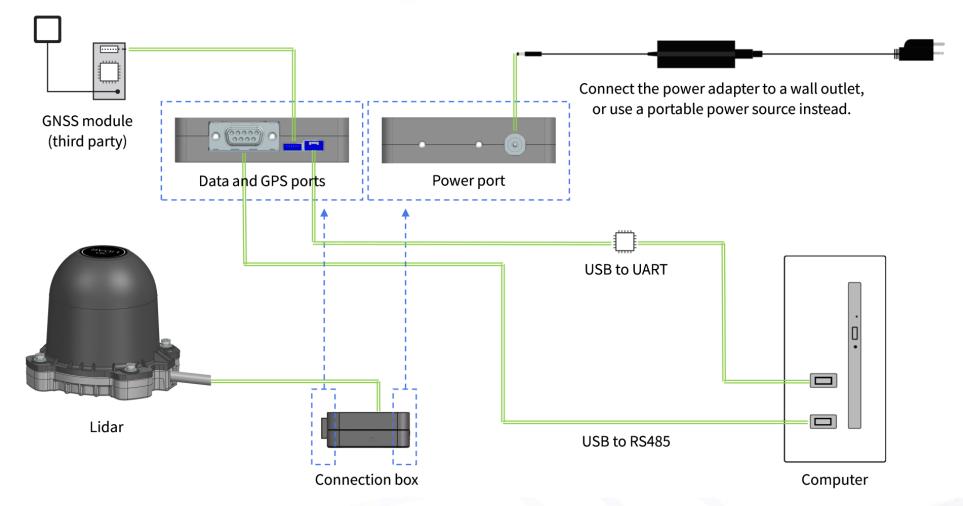


Figure 17. Connection box connection

### **Troubleshooting**

If the following procedures cannot solve your problem, please contact Hesai technical support.

Symptoms	Points to check
Indicator light is off on the connection box.	<ul> <li>Make sure that the following conditions are met:</li> <li>The power adapter is properly connected and in good condition.</li> <li>The connection box is intact.</li> <li>The input voltage and input current satisfy the requirements in <u>Connection box</u>.</li> </ul> Afterward, power on the lidar again and check if the symptom persists
Motor is not running.	<ul> <li>Make sure that the following conditions are met:</li> <li>The power adapter is properly connected and in good condition.</li> <li>The input voltage and input current satisfy the requirements in <u>Section 1.4 Specifications</u>.</li> <li>If a connection box is used, the connection box is intact.</li> <li>Afterward, power on the lidar again and check if the symptom persists.</li> </ul>

