Hierarchical Clustering Objective



Frederik Mallmann-Trenn 6CCS3AIN

What are the hierarchical algorithms actually doing?

AN EARLY PROTOTYPE FOR GENERATING CLINICAL TRIAL OUTCOME SHORTCUTS.



What quantity are these algorithms optimizing?

- For flat clustering, algorithms designed to optimize some objective function
 - Remember: for **flat clustering** the goal was to find k points μ_1, \ldots, μ_k that minimize, e.g.
 - 1. k-median objective $\sum_{i=1}^{N} \left(\min_{j \in [k]} d(\mathbf{x}_i, \mu_j) \right)$ 2. k-means objective $\sum_{i=1}^{N} \left(\min_{j \in [k]} d(\mathbf{x}_i, \mu_j) \right)^2$
- For hierarchical clustering, algorithms have been studied procedurally
 - Thus, comparisons between hierarchical clustering algorithms are only qualitative!

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- [Dasgupta '16]
 - "The lack of an objective function has prevented a theoretical understanding"
- Dasgupta introduced an objective function to model the hierarchical clustering problem

Dasgupta's Cost Function

Input: a weighted similarity graph G

■ Edge weights represent similarities

Output: T a tree with leaves labelled by nodes of G

Cost of the output: Sum of the costs of the nodes of T

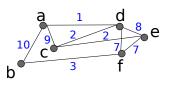
Cost of a node N of the tree:

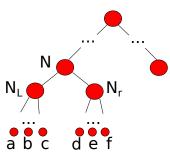
$$L = \{ u \mid u \text{ is leaf of subtree rooted at } N_L \}$$

$$R = \{v \mid v \text{ is leaf of subtree rooted at } N_R\}$$

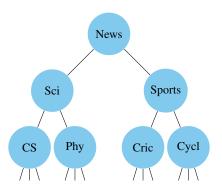
$$cost(N) = (|L| + |R|) \cdot \sum_{\substack{u \in L \\ v \in R}} similarity(u, v)$$

The total cost is the sum of costs of all subtrees. **Intuition**: Better to cut a high similarity edge at a lower level





Results

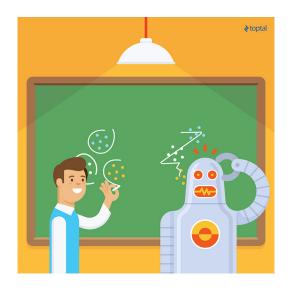


Hierarchical Clustering: Objective Functions and Algorithms Vincent Cohen-Addad, Varun Kanade, Frederik Mallmann-Trenn, Claire Mathieu JACM 2019

Result 1: Is Dasgupta the only reasonable function?

- We characterize the set of 'good' objective functions based on axioms.
 - Disconnected components must be separated first
 - Symmetry
 - Only the 'true' hierarchical clustering should minimize the cost function (if there is one).
- In some sense Dasgupta is the most natural

Result 2: Algorithms



Hope: Recursive Sparsest Cut

- Dissimilarity graph:
 - We show Avg. Linkage has a 3/2-approximation factor
 - We also show that other practical algorithms have a $\Omega(n^{1/4})$ -approximation factor

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Algorithm: Recursive Sparsest Cut

Input: Weighted graph G = (V, E, w)

$$\{A, V \backslash A\} \leftarrow \text{cut with sparsity} \leqslant \phi \cdot \min_{S \subseteq V} \frac{w(S, V \backslash S)}{|S| \cdot |V \backslash S|}$$

Recurse on subgraphs $G[A], G[V \backslash A]$ to obtain trees $T_A, T_{V \backslash A}$

Output: Return tree whose root has subtrees T_A , $T_{V\setminus A}$

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- We show $O(\phi)$ -approximation
- Improves the $O(\log n \cdot \phi)$ -approximation [Dasgupta '16]
- Current best known value for ϕ is $O(\sqrt{\log n})$ [ARV '09]

- For worst case inputs, Recursive Sparsest Cut gives $O(\phi)$ -approximation
- Assuming the "Small Set Expansion Hypothesis", no polytime O(1)-approx.



Real-world graphs are often not worst-case