#### **Selection Sort**

- A relatively easy to understand algorithm
- Sorts an array in <u>passes</u>
  - Each pass selects the next smallest element
  - At the end of the pass, places it where it belongs
- Efficiency is O(n²), hence called a *quadratic* sort
- Performs:
  - O(n²) comparisons
  - O(n) exchanges (swaps)

## **Selection Sort Algorithm**

- 1. for **fill** = 0 to n-2 do // steps 2-6 form a <u>pass</u>
- set posMin to fill
- 3. for next = fill+1 to n-1 do
- 4. if item at **next** < item at **posMin**
- 5. set **posMin** to **next**
- 6. Exchange item at **posMin** with one at **fill**

# **Selection Sort Example**

35	65	30	60	20	scan 0-4, smallest 20
					swap 35 and 20
20	65	30	60	35	scan 1-4, smallest 30
					swap 65 and 30
20	30	65	60	35	scan 2-4, smallest 35
					swap 65 and 35
20	30	35	60	65	scan 3-4, smallest 60
					swap 60 and 60
20	30	35	60	65	done

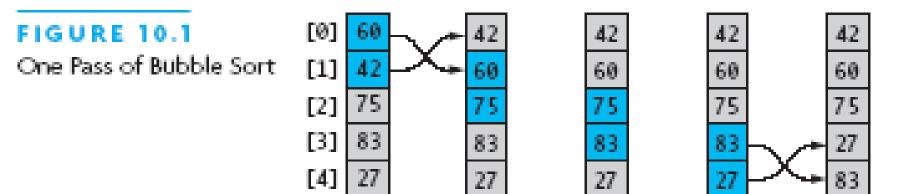
#### **Selection Sort Code**

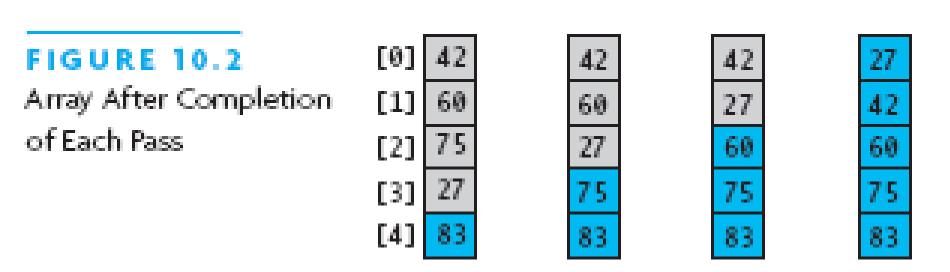
```
public static <T extends Comparable<T>>
    void sort (T[] a) {
  int n = a.length;
  for (int fill = 0; fill < n-1; fill++) {
    int posMin = fill;
    for (int nxt = fill+1; nxt < n; nxt++)
      if (a[nxt].compareTo(a[posMin])<0)</pre>
        posMin = nxt;
    T tmp = a[fill];
    a[fill] = a[posMin];
    a[posMin] = tmp;
```

#### **Bubble Sort**

- Compares adjacent array elements
  - Exchanges their values if they are <u>out of order</u>
- Smaller values <u>bubble up</u> to the top of the array
  - Larger values sink to the bottom

#### **Bubble Sort Example**





## **Bubble Sort Algorithm**

- 1. do
- 2. for each pair of adjacent array elements
- 3. if values are out of order
- 4. Exchange the values
- 5. while the array is not sorted

### **Bubble Sort Algorithm, Refined**

- 1. do
- 2. Initialize exchanges to false
- 3. for each pair of adjacent array elements
- 4. if values are out of order
- 5. Exchange the values
- 6. Set exchanges to true
- 7. while exchanges

## **Analysis of Bubble Sort**

- Excellent performance <u>in some cases</u>
  - But <u>very poor</u> performance in others!
- Works best when array is nearly sorted to begin with
- Worst case number of comparisons: O(n²)
- Worst case number of exchanges: O(n²)
- Best case occurs when the array is already sorted:
  - O(n) comparisons
  - O(1) exchanges (none actually)

#### **Bubble Sort Code**

```
int pass = 1;
boolean exchanges;
do {
  exchanges = false;
  for (int i = 0; i < a.length-pass; i++)
    if (a[i].compareTo(a[i+1]) > 0) {
      T tmp = a[i];
      a[i] = a[i+1];
      a[i+1] = tmp;
      exchanges = true;
pass++;
} while (exchanges);
```

#### **Insertion Sort**

- Based on technique of card players to arrange a hand
  - Player keeps cards picked up so far in <u>sorted order</u>
  - When the player picks up a new card
    - Makes room for the new card
    - Then inserts it in its proper place

FIGURE 10.3 Picking Up a Hand of Cards







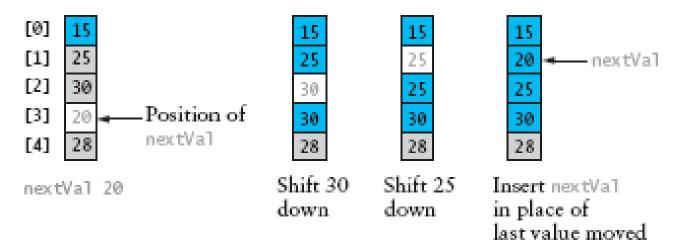
## **Insertion Sort Algorithm**

- For each element from 2nd (nextPos = 1) to last:
  - Insert element at nextPos where it belongs
  - Increases sorted subarray size by 1
- To make room:
  - Hold nextPos value in a variable
  - Shuffle elements to the right until gap at right place

#### **Insertion Sort Example**

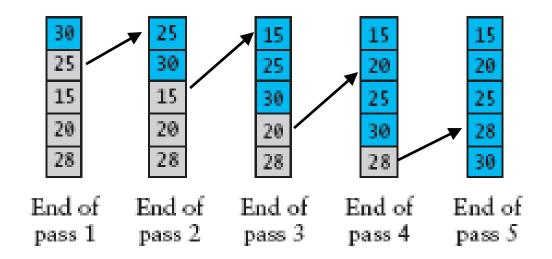
#### FIGURE 10.5

Inserting the Fourth Array Element



#### FIGURE 10.4

An Insertion Sort



#### **Insertion Sort Code**

```
public static <T extends Comparable<T>>
    void sort (T[] a) {
    for (int nextPos = 1;
        nextPos < a.length;
        nextPos++) {
        insert(a, nextPos);
    }
}</pre>
```

### **Insertion Sort Code (2)**

```
private static <T extends Comparable<T>>
    void insert (T[] a, int nextPos) {
  T nextVal = a[nextPos];
  while
    (nextPos > 0 &&
     nextVal.compareTo(a[nextPos-1]) < 0){</pre>
    a[nextPos] = a[nextPos-1];
    nextPos--;
  a[nextPos] = nextVal;
```

# **Analysis of Insertion Sort**

- Maximum number of comparisons: O(n²)
- In the best case, number of comparisons: O(n)
- # shifts for an insertion = # comparisons 1
  - When new value smallest so far, # comparisons
- A shift in insertion sort moves only <u>one item</u>
  - Bubble or selection sort exchange: <u>3 assignments</u>

### **Comparison of Quadratic Sorts**

#### None good for large arrays!

#### **TABLE 10.2**

Comparison of Quadratic Sorts

	Number of	Number of Comparisons		f Exchanges
	Best	Worst	Best	Worst
Selection sort	$O(n^2)$	$O(n^2)$	O(n)	O(n)
Bubble sort	O(n)	$O(n^2)$	O(1)	$O(n^2)$
Insertion sort	O(n)	$O(n^2)$	O(n)	$O(n^2)$

#### **TABLE 10.3**

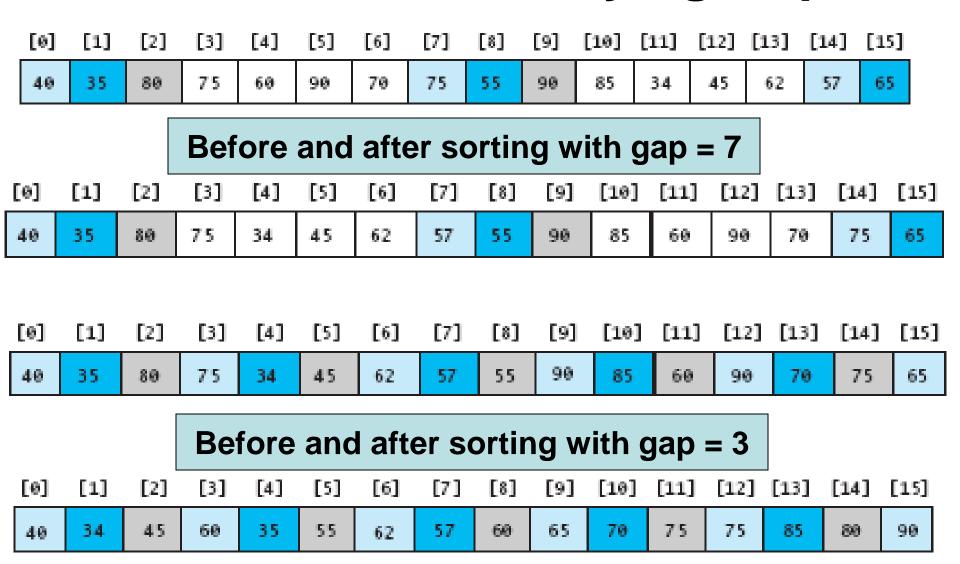
Comparison of Rates of Growth

п	n²	n log n
8	64	24
16	256	64
32	1,024	160
64	4,096	384
128	16,384	896
2.56	65,536	2,048
512	262,144	4,608

#### **Shell Sort: A Better Insertion Sort**

- Shell sort is a variant of insertion sort
  - It is named after Donald Shell
  - Average performance: O(n<sup>3/2</sup>) or better
- Divide and conquer approach to insertion sort
  - Sort many smaller subarrays using insertion sort
  - Sort progressively larger arrays
  - Finally sort the entire array
- These arrays are elements separated by a <u>gap</u>
  - Start with <u>large gap</u>
  - Decrease the gap on each "pass"

# **Shell Sort: The Varying Gap**



## **Analysis of Shell Sort**

#### Intuition:

Reduces work by moving elements farther earlier

- Its general analysis is an open research problem
- Performance depends on sequence of gap values
- For sequence 2<sup>k</sup>, performance is O(n<sup>2</sup>)
- Hibbard's sequence (2<sup>k</sup>-1), performance is O(n<sup>3/2</sup>)
- We start with n/2 and repeatedly divide by 2.2
  - Empirical results show this is O(n<sup>5/4</sup>) or O(n<sup>7/6</sup>)
  - No <u>theoretical</u> basis (proof) that this holds

# **Shell Sort Algorithm**

- 1. Set gap to n/2
- 2. while gap > 0
- 3. for each element from gap to end, by gap
- 4. Insert element in its gap-separated sub-array
- 5. if gap is 2, set it to 1
- 6. otherwise set it to gap / 2.2

## **Shell Sort Algorithm: Inner Loop**

3.1 set nextPos to position of element to insert
3.2 set nextVal to value of that element
3.3 while nextPos > gap and
element at nextPos-gap is > nextVal
3.4 Shift element at nextPos-gap to nextPos
3.5 Decrement nextPos by gap
3.6 Insert nextVal at nextPos

#### **Shell Sort Code**

```
public static <T extends <Comparable<T>>
    void sort (T[] a) {
  int gap = a.length / 2;
  while (gap > 0) {
    for (int nextPos = gap;
         nextPos < a.length; nextPos++)</pre>
      insert(a, nextPos, gap);
    if (gap == 2)
      qap = 1;
    else
      gap = (int)(gap / 2.2);
```

## **Shell Sort Code (2)**

```
private static <T extends Comparable<T>>
    void insert
      (T[] a, int NextPos, int gap) {
  T val = a[nextPos];
  while ((nextPos >= gap) &&
      (val.compareTo(a[nextPos-gap])<0)) {</pre>
    a[nextPos] = a[nextPos-gap];
    nextPos -= gap;
  a[nextPos] = val;
```

### Merge Sort

- A <u>merge</u> is a common data processing operation:
  - Performed on <u>two sequences</u> of data
    - Items in both sequences use same compareTo
    - Both sequences in ordered of this compareTo
- Goal: Combine the two sorted sequences in one larger sorted sequence
- Merge sort merges longer and longer sequences

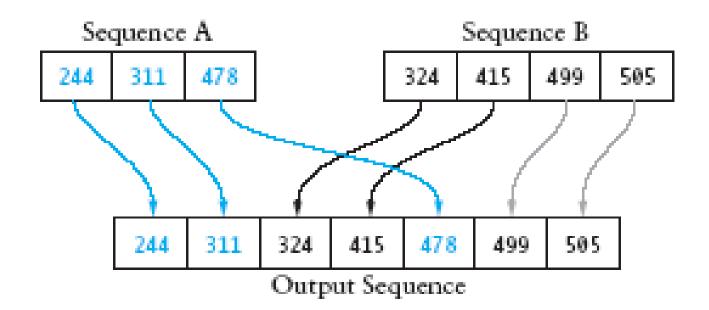
# Merge Algorithm (Two Sequences)

#### Merging two sequences:

- 1. Access the first item from both sequences
- 2. While neither sequence is finished
  - 1. Compare the current items of both
  - 2. Copy smaller current item to the output
  - 3. Access next item from that input sequence
- 3. Copy any remaining from first sequence to output
- 4. Copy any remaining from second to output

# Picture of Merge

FIGURE 10.6 Merge Operation



# **Analysis of Merge**

- Two input sequences, total length n elements
  - Must move each element to the output
  - Merge time is O(n)
- Must store <u>both input</u> and <u>output</u> sequences
  - An array cannot be merged <u>in place</u>
  - Additional space needed: O(n)

# Merge Sort Algorithm

#### Overview:

- Split array into two halves
- Sort the left half (recursively)
- Sort the right half (recursively)
- Merge the two sorted halves

# Merge Sort Algorithm (2)

#### Detailed algorithm:

- if tSize ≤ 1, return (no sorting required)
- set hSize to tSize / 2
- Allocate LTab of size hSize
- Allocate RTab of size tSize hSize
- Copy elements 0 .. hSize 1 to LTab
- Copy elements hSize .. tSize 1 to RTab
- Sort LTab recursively
- Sort RTab recursively
- Merge LTab and RTab into a

# Merge Sort Example

#### FIGURE 10.7

Trace of Merge Sort



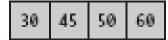












- 1. Split array into two 4-element arrays
- 2. Split left array into two 2-element arrays
- 3. Split left array (50, 60) into two 1-element arrays
- 4. Merge two 1-element arrays into a 2-element array
- Split right array from Step 2 into two 2-element arrays
- 6. Merge two 1-element arrays into a 2-element array
- 7. Merge two 2-element arrays into a 4-element array

# Merge Sort Analysis

- Splitting/copying n elements to subarrays: O(n)
- Merging back into original array: O(n)
- Recursive calls: 2, each of size n/2
  - Their total non-recursive work: O(n)
- Next level: 4 calls, each of size n/4
  - Non-recursive work again O(n)
- Size sequence: n, n/2, n/4, ..., 1
  - Number of levels = log n
  - Total work: O(n log n)

### Merge Sort Code

```
public static <T extends Comparable<T>>
    void sort (T[] a) {
  if (a.length <= 1) return;</pre>
  int hSize = a.length / 2;
  T[] lTab = (T[])new Comparable[hSize];
  T[] rTab =
    (T[]) new Comparable[a.length-hSize];
  System.arraycopy(a, 0, 1Tab, 0, hSize);
  System.arraycopy(a, hSize, rTab, 0,
                    a.length-hSize);
  sort(lTab); sort(rTab);
  merge(a, lTab, rTab);
```

## Merge Sort Code (2)

```
private static <T extends Comparable<T>>
    void merge (T[] a, T[] l, T[] r) {
  int i = 0; // indexes 1
  int j = 0; // indexes r
  int k = 0; // indexes a
  while (i < 1.length && j < r.length)
    if (l[i].compareTo(r[j]) < 0)
      a[k++] = l[i++];
    else
      a[k++] = r[j++];
  while (i < 1.length) a[k++] = 1[i++];
  while (j < r.length) a[k++] = r[j++];
```

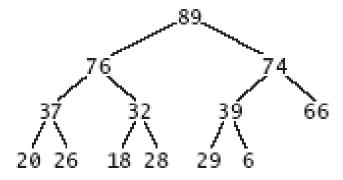
### Heapsort

- Merge sort time is O(n log n)
  - But requires (temporarily) n extra storage items
- Heapsort
  - Works <u>in place</u>: no additional storage
  - Offers same O(n log n) performance
- Idea (not quite in-place):
  - Insert each element into a priority queue
  - Repeatedly remove from priority queue to array
    - Array slots go from 0 to n-1

## **Heapsort Picture**

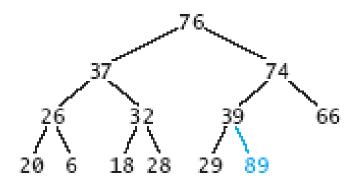
#### FIGURE 10.8

Example of a Heap with Largest Value in Root



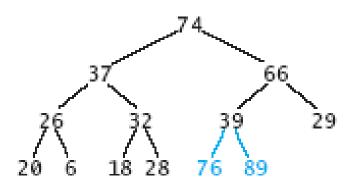
#### FIGURE 10.9

Heap After Removal of Largest Item



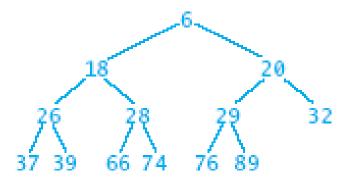
#### **FIGURE 10.10**

Heap After Removal of Two Largest Items



#### **FIGURE 10.11**

Heap After Removal of All Its Items



# **Heapsort Picture (2)**

#### **FIGURE 10.12**

Internal Representation of the Heap Shown in Figure 10.8

													[12]
8	9	76	74	37	32	39	66	20	26	18	28	29	6

#### **FIGURE 10.13**

Internal Representation of the Heaps Shown in Figures 10.9 through 10.11

[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]
76	37	74	26	32	39	66	20	6	18	28	29	89
[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]
74	37	66	26	32	39	29	20	6	18	28	76	89
						:						
[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]
6	18	20	26	28	29	32	37	39	66	74	76	89

# Algorithm for In-Place Heapsort

- Build heap starting from unsorted array
- While the heap is not empty
  - Remove the first item from the heap:
    - Swap it with the last item
  - Restore the heap property

### **Heapsort Code**

```
public static <T extends Comparable<T>>
    void sort (T[] a) {
 buildHp(a);
  shrinkHp(a);
private static ... void buildHp (T[] a) {
  for (int n = 2; n \le a.length; n++) {
    int chld = n-1; // add item and reheap
    int prnt = (chld-1) / 2;
    while (prnt >= 0 &&
           a[prnt].compareTo(a[chld])<0) {
      swap(a, prnt, chld);
      chld = prnt; prnt = (chld-1)/2
```

### **Heapsort Code (2)**

```
private static ... void shrinkHp (T[] a) {
  int n = a.length;
  for (int n = a.length-1; n > 0; --n) {
    swap(a, 0, n); // max -> next posn
    int prnt = 0;
    while (true) {
      int 1c = 2 * prnt + 1;
      if (lc >= n) break;
      int rc = lc + 1;
      int maxc = lc;
      if (rc < n &&
          a[lc].compareTo(a[rc]) < 0)
        maxc = rc;
```

### **Heapsort Code (3)**

```
if (a[prnt].compareTo(a[maxc])<0) {</pre>
         swap(a, prnt, maxc);
         prnt = maxc;
       } else {
         break;
private static ... void swap
     (T[] a, int i, int j) {
  T \text{ tmp} = a[i]; a[i] = a[j]; a[j] = tmp;
```

### **Heapsort Analysis**

- Insertion cost is log i for heap of size i
  - Total insertion cost = log(n)+log(n-1)+...+log(1)
  - This is O(n log n)
- Removal cost is also log i for heap of size i
  - Total removal cost = O(n log n)
- Total cost is O(n log n)

### Quicksort

- Developed in 1962 by C. A. R. Hoare
- Given a <u>pivot value:</u>
  - Rearranges array into two parts:
    - Left part ≤ pivot value
    - Right part > pivot value
- Average case for Quicksort is O(n log n)
  - Worst case is O(n²)

### **Quicksort Example**











75 77

### **Algorithm for Quicksort**

first and last are end points of region to sort

- if first < last</li>
- Partition using pivot, which ends in pivIndex
- Apply Quicksort recursively to left subarray
- Apply Quicksort recursively to right subarray

Performance: O(n log n) provide **pivIndex** not always too close to the end

Performance O(n²) when pivIndex always near end

### **Quicksort Code**

```
public static <T extends Comparable<T>>
    void sort (T[] a) {
  qSort(a, 0, a.length-1);
private static <T extends Comparable<T>>
    void qSort (T[] a, int fst, int lst) {
  if (fst < lst) {</pre>
    int pivIndex = partition(a, fst, lst);
    qSort(a, fst, pivIndex-1);
    qSort(a, pivIndex+1, lst);
```

### **Algorithm for Partitioning**

- 1. Set pivot value to a[fst]
- 2. Set up to fst and down to lst
- 3. do
- 4. Increment **up** until a[**up**] > pivot or **up** = lst
- Decrement down until a[down] <= pivot or down = fst</li>
- 6. if **up** < **down**, swap a[**up**] and a[**down**]
- 7. while up is to the left of down
- swap a[fst] and a[down]
- 9. return **down** as pivIndex

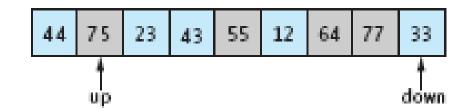
### Trace of Algorithm for Partitioning

#### **FIGURE 10.14**

Locating First Values to Exchange





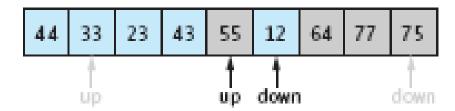


#### **FIGURE 10.15**

Array After the First Exchange

pivot



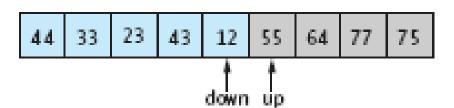


#### **FIGURE 10.16**

Array After the Second Exchange

### pivot





### **Partitioning Code**

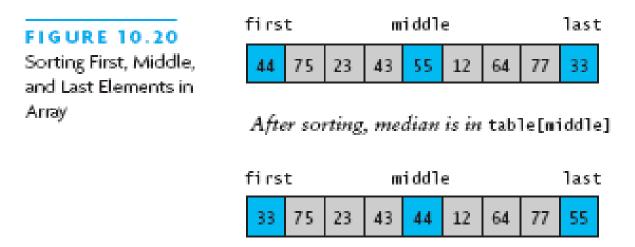
```
private static <T extends Comparable<T>>
    int partition
       (T[] a, int fst, int lst) {
  T pivot = a[fst];
  int u = fst;
  int d = lst;
  do {
    while ((u < lst) \&\&
            (pivot.compareTo(a[u]) >= 0))
      u++;
    while (pivot.compareTo(a[d]) < 0)</pre>
      d++;
    if (u < d) swap(a, u, d);
  \} while (u < d);
```

# **Partitioning Code (2)**

```
swap(a, fst, d);
return d;
```

### **Revised Partitioning Algorithm**

- Quicksort is O(n²) when each split gives 1 empty array
- This happens when the array is already sorted
- Solution approach: pick better pivot values
- Use three "marker" elements: first, middle, last
- Let pivot be one whose value is between the others

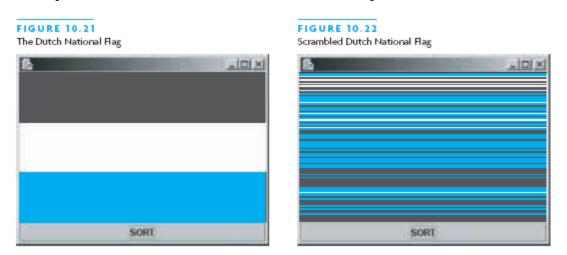


### **Testing Sortiing Algorithms**

- Need to use a variety of test cases
  - Small and large arrays
  - Arrays in random order
  - Arrays that are already sorted (and reverse order)
  - Arrays with duplicate values
- Compare performance on each type of array

### The Dutch National Flag Problem

- Variety of partitioning algorithms have been published
- One that partitions an array into three segments was introduced by Edsger W. Dijkstra
- Problem: partition a disordered three-color flag into three contiguous segments
- Segments represent < = > the pivot value

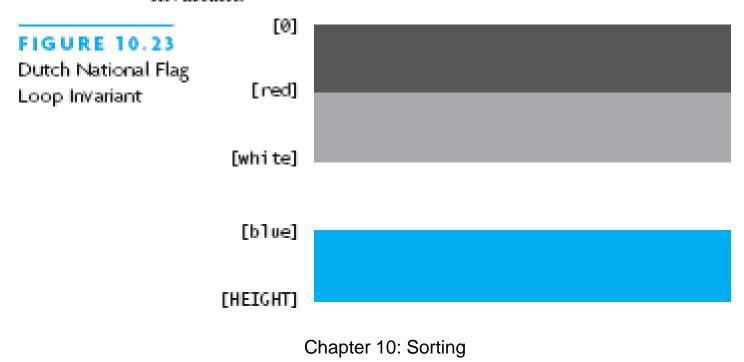


### The Dutch National Flag Problem

### Algorithm

We can solve our problem by establishing the loop invariant and then executing a loop that both preserves the loop invariant and shrinks the unknown region.

- Set red to 0, white to HEIGHT 1, and blue to HEIGHT 1. This establishes
  our loop invariant with the unknown region the whole flag and the red,
  white, and blue regions empty.
- while red < white</li>
- Shrink the distance between red and white while preserving the loop invariant.



### **Chapter Summary**

- Three quadratic sorting algorithms:
  - Selection sort, bubble sort, insertion sort
- Shell sort: good performance for up to 5000 elements
- Quicksort: average-case O(n log n)
  - If the pivot is picked poorly, get worst case: O(n²)
- Merge sort and heapsort: guaranteed O(n log n)
  - Merge sort: space overhead is O(n)
- Java API has good implementations

# **Chapter Summary (2)**

**TABLE 10.4** 

Comparison of Sort Algorithms

	Number of Comparisons							
	Best	Average	Worst					
Selection sort	$O(n^2)$	$O(n^2)$	$O(n^2)$					
Bubble sort	O(n)	$O(n^2)$	$O(n^2)$					
Insertion sort	O(n)	$O(n^2)$	$O(n^2)$					
Shell sort	$O(n^{7/6})$	$O(n^{5/4})$	$O(n^2)$					
Merge sort	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$					
Heapsort	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$					
Quicksort	$O(n \log n)$	$O(n \log n)$	$O(n^2)$					