

DESIGN OF CLASSIFIERS

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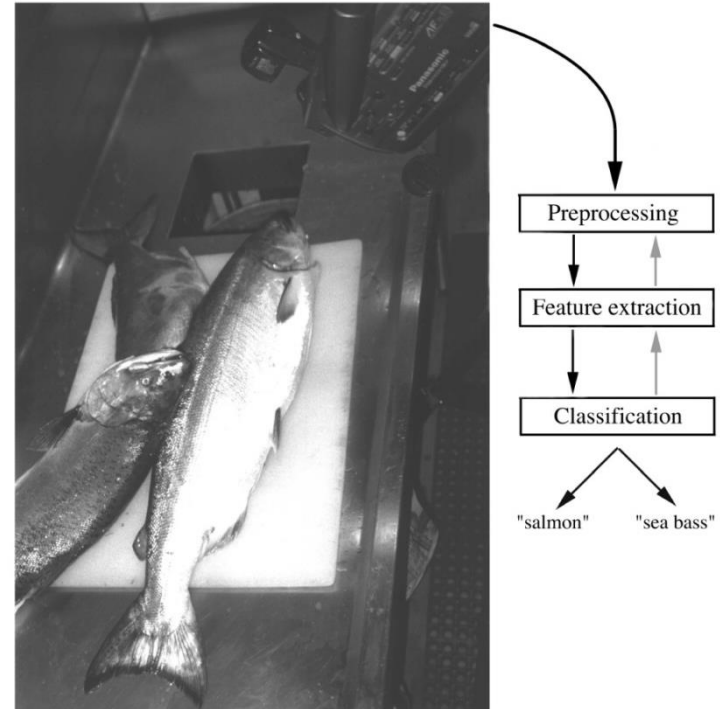
A simple PR problem

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Problem: Sorting incoming fish on a conveyor belt.

Assumption: Two kind of fish:

- (1) sea bass
- (2) salmon



salmon



sea bass



salmon



salmon



sea bass



sea bass



Challenges of PR- Feature Extraction

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- Correlated features / Redundant Features
- Large number of features /Curse of dimensionality
- Noise in measurements/ Noisy or Missing Features
- Large variation within class: A lot of variability in patterns (feature vector) of a single class, the **intra-class similarity is low**
- Feature vectors of patterns from different classes can be arbitrarily close, and **inter-class similarity is high**
- Given this much variability, it **is not so easy to design the classifier**

Problem of classification

- Classification: the process of assigning an object to one of the known classes (true class)
- It does the task by **Learning**
- Ideally, a classifier should have
 - ▣ **Good generalization**

What do we have?

- The only information is available for the design is –
A training set of sample/example pattern
- Training set: (X_i, y_i)
- Here X_i is a sample of class y_i



How do we generate the training set?

- Generation of the training set- take representative patterns of the known category called **data collection**
- Obtain the feature vectors from those data (choice of feature measurements)
- Now **learn** an appropriate function h as the classifier
- Test and validate the classifier on more/unseen data

A simple PR problem

- **Problem:** Sorting incoming fish on a conveyor belt.
- **Assumption:** Two kind of fish:
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Design of classifier:

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

□ x_1 : length

□ x_2 : lightness

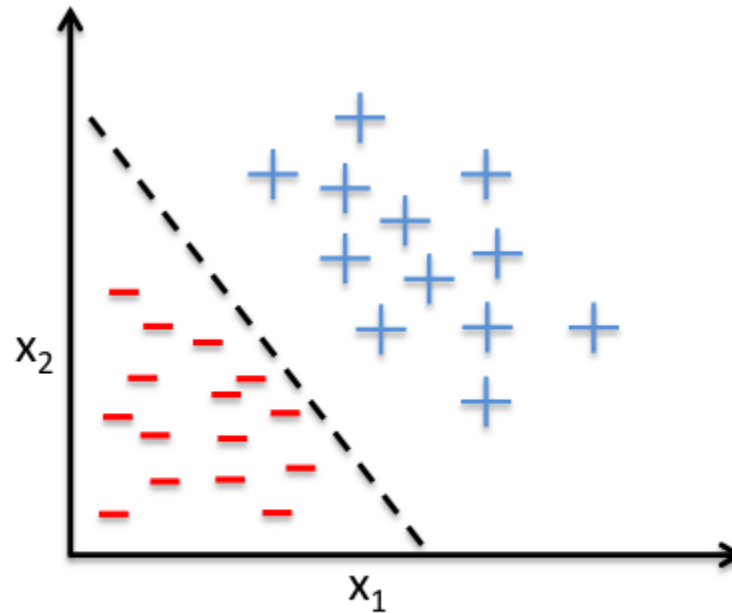
- A classifier $ax_1 + bx_2$
- If $ax_1 + bx_2 > T$ then **sea bass**, otherwise it is **salmon**
- a, b, T are known as **learning parameters**
- What values to use for a, b, T ?

Design of classifier:

□ The classifier is **linear** here

□ x_1 : length

□ x_2 : lightness

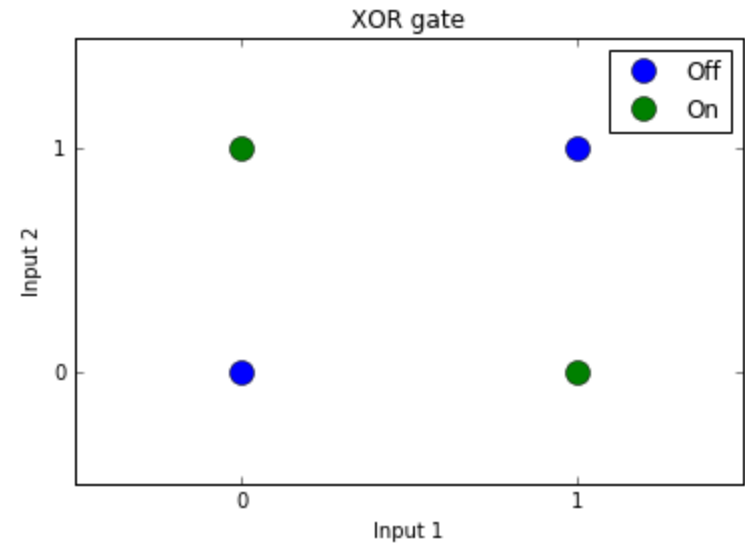


Example of a linear decision boundary
for binary classification.

Another example

□ XOR Gate

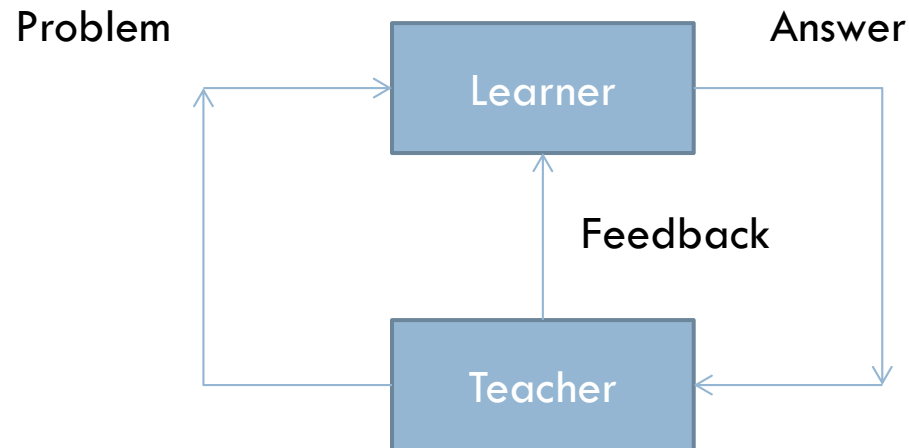
x_1	x_2	$x_1 \text{ XOR } x_2$
0	0	0
0	1	1
1	0	1
1	1	0



□ The classifier is **non-linear** here

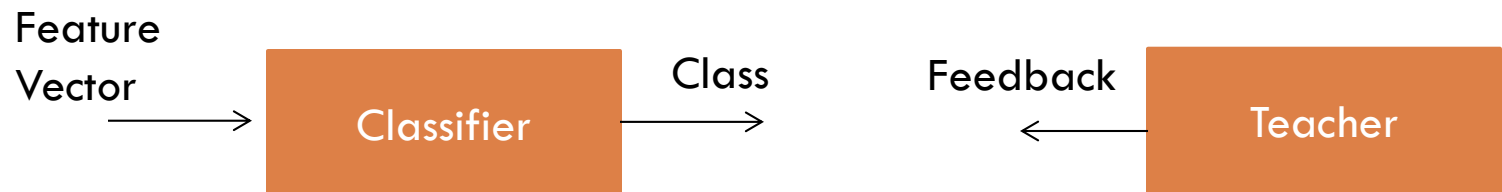
Learning from samples/examples

- Designing a classifier is a typical problem of **learning from samples/ examples**
- Also called learning with a teacher
- Nature of feedback from a teacher can be different in the context of PR



Learning from examples

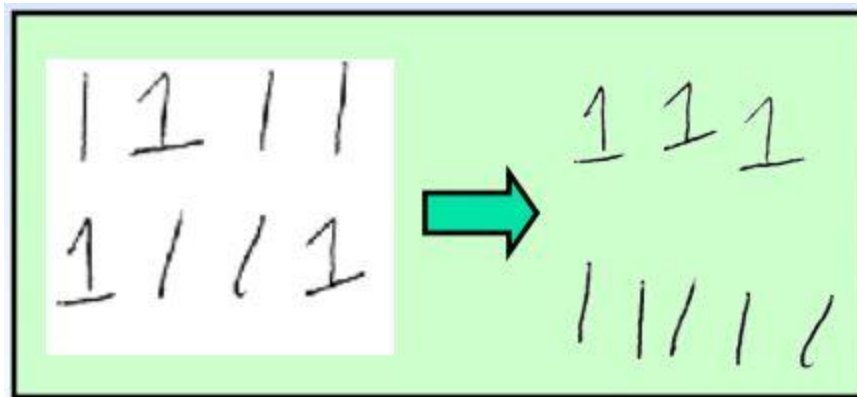
- In the context of PR



- **Supervised Learning:** The teacher gives the **true class label** for each feature vector
- **Unsupervised Learning:** No teacher input (clustering problem)
- **Reinforcement Learning:** Noisy assessment of performance (eg: correct/incorrect)

Learning from examples

- Unsupervised Learning: No teacher input (clustering problem)
- Clustering (**learning categories**)

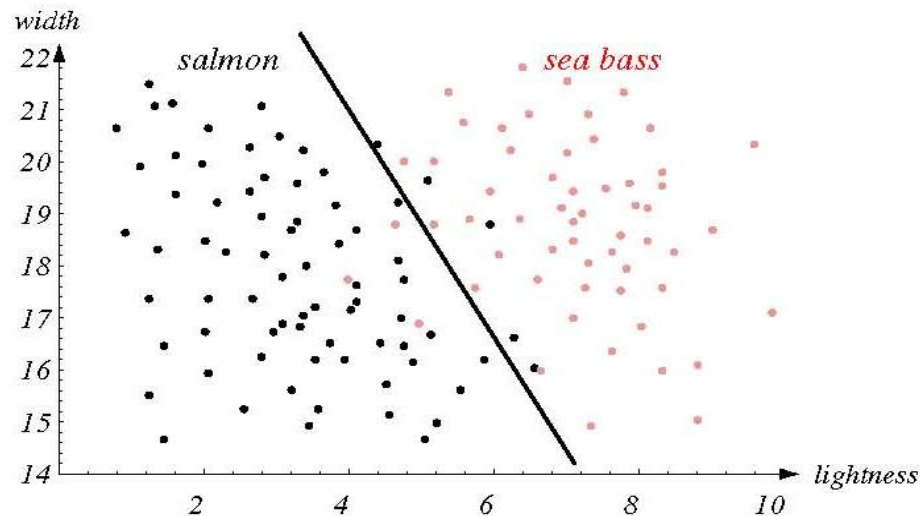


Learning from examples

- When the class labels of training patterns as given by teacher are noisy, we consider it as supervised learning with noise or **classification noise**
- **We design a classifier with training samples (learning from examples)**
- Many classifier algorithms do **supervised learning**

Design of classifier

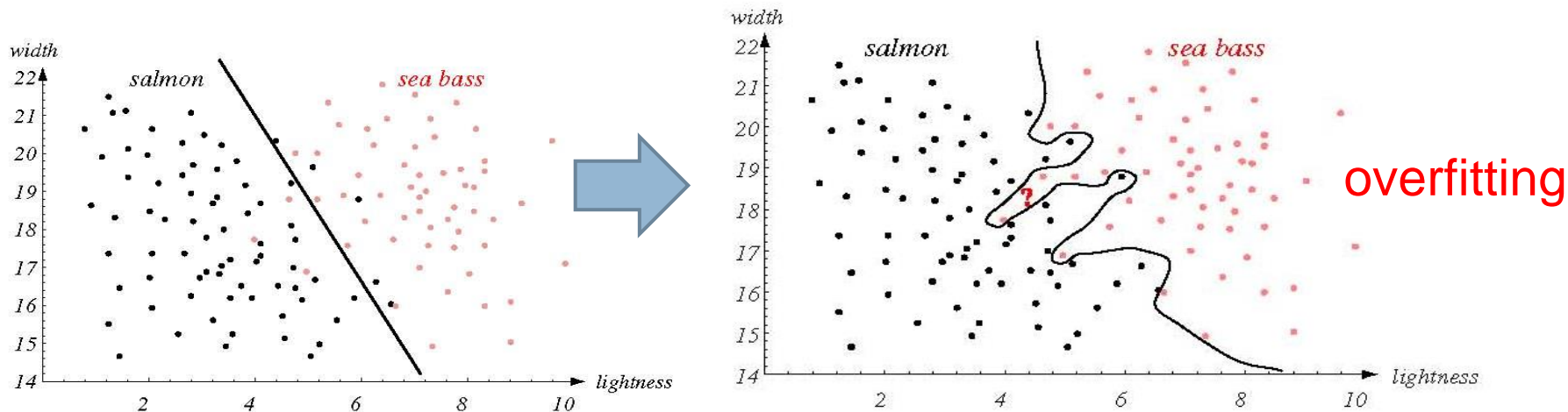
- If the classes are linearly not separable then partition the *feature space* into two regions by finding the **decision boundary** that minimizes the error.



- **How** should we find the optimal decision boundary?

Design of classifier- complex model

- We can get perfect classification performance on the training data by choosing **complex models**.
- Complex models are **tuned** to the particular training samples, rather than on the characteristics of the true model.



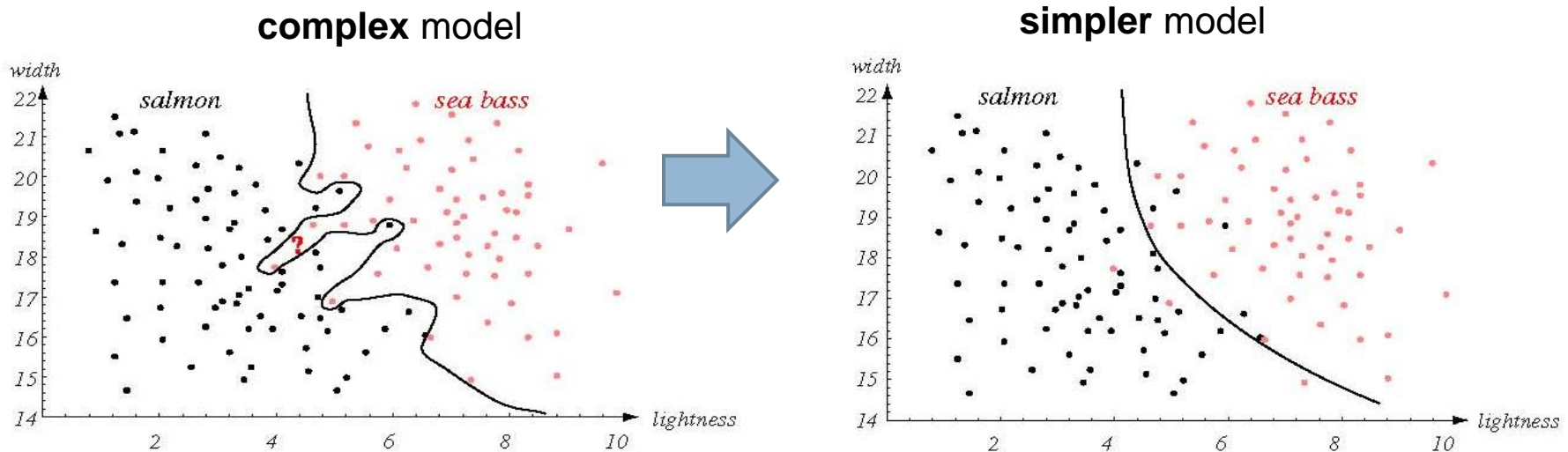
How well can the model **generalize** to unknown samples?

Design of classifier- complex model

- If an algorithm works well on the training set but fails to generalize on test data (unseen data), it is called the **problem of generalization or overfitting.**

Generalization

- Generalization is defined as the ability of a classifier to produce correct results on unseen (**novel**) patterns.
- How can we improve generalization performance ?
 - **More** training examples (i.e., better model estimates).
 - **Simpler** models usually yield better performance.



Generalization - example

- 12 total breeds of dogs within those pictures
- Out of 10 are in training and 2 for testing



Training Data



Testing Data

Generalization - example

- This concept of learning from some data and **correctly** applying the gained knowledge on other data is called **generalization**.

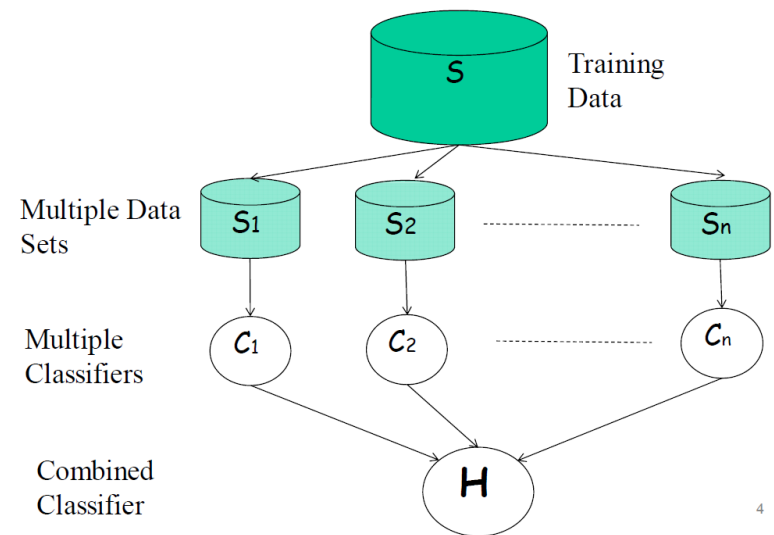
Generalization

- Many techniques are available to improve generalization
 - ▣ Regularization- L1 and L2
 - ▣ Dropout
 - ▣ Early stopping

Design of classifier

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- **Ensembles of Classifiers**
- Performance can be improved using a "pool" of classifiers.
- How should we **build** and **combine** different classifiers ?



Summary

- Classifiers
- Linear and non-linear classifiers
- Supervised learning
- Unsupervised learning
- Reinforcement learning
- generalization

THANK YOU

