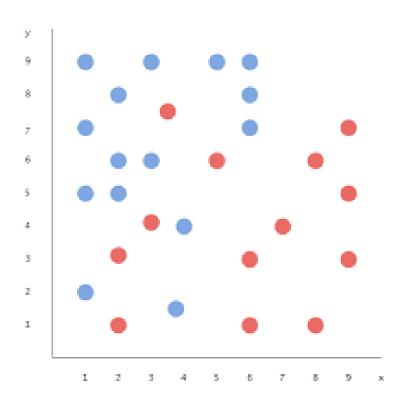
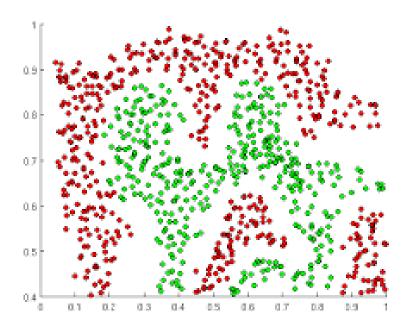
PERCEPTRON: PROOF OF CONVERGENCE

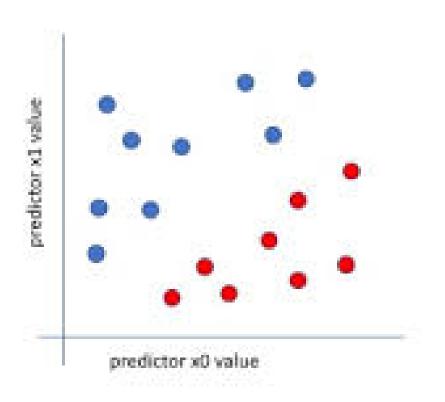
Dr. Umarani Jayaraman Assistant Professor

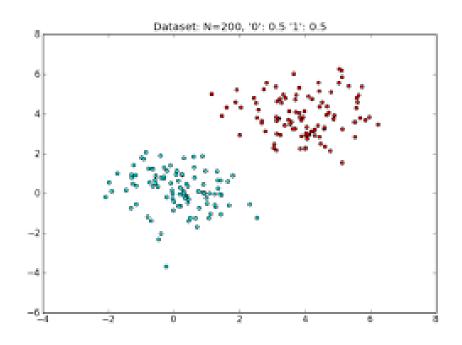
What classifier do you use?





What classifier do you use?

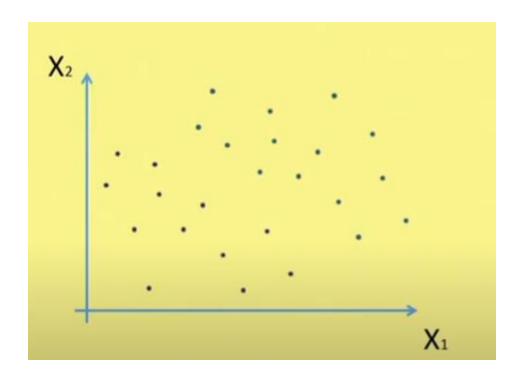




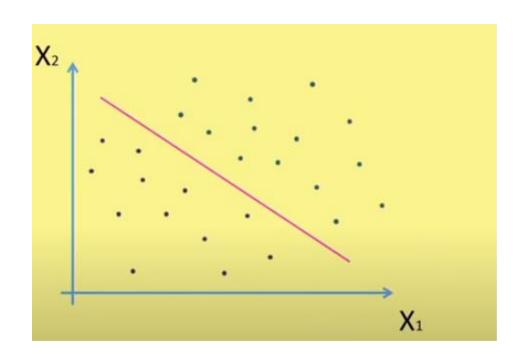
Possible solution for previous problems

- K-NN search
 - Testing: It is time consuming as it should compare the distance with all the sample
 - This methods works well if the number of samples are less
- Linear discriminant function (LDF)
 - \blacksquare It uses sample to estimate the parameter such as \mathbf{w} and $\mathbf{w_0}$
 - Testing: It just substitute the value of x in g(x) and take the decision
 - \square If g(x) > 0 then class 1, otherwise class 2

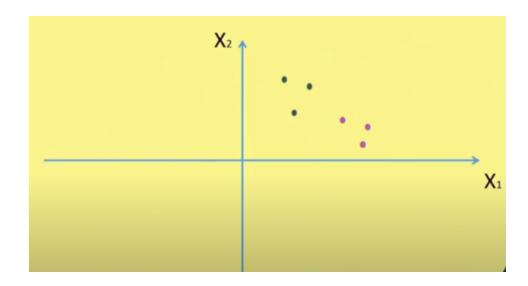
Perceptron: two class problem

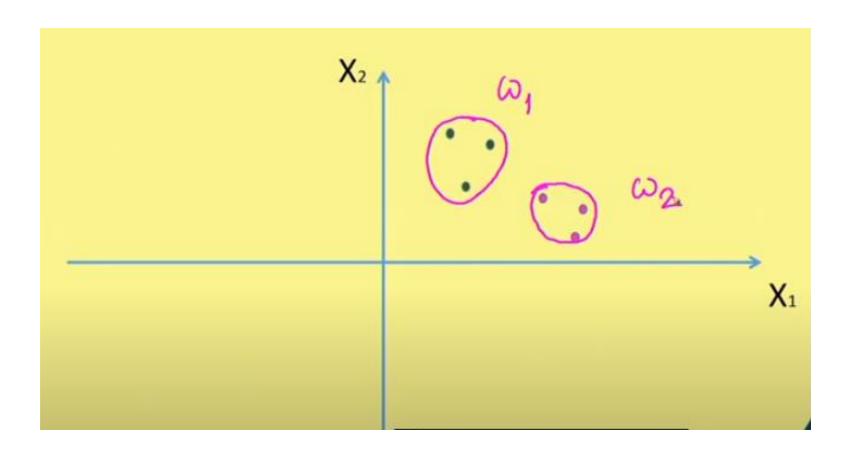


Perceptron - two class problem

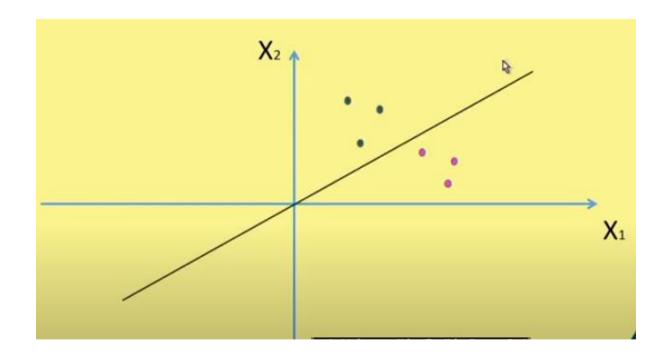


Perceptron -two class problem

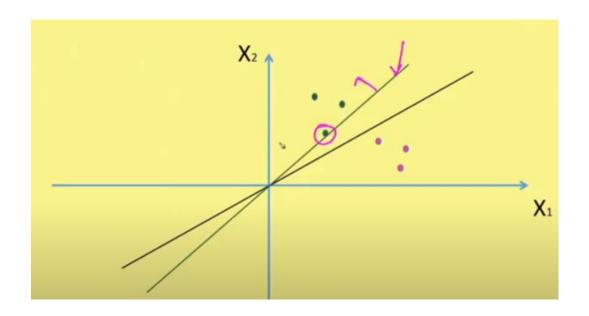




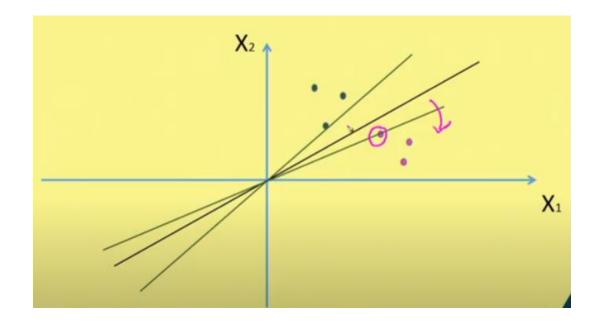
- □ This linear line clearly separates the two classes
- Also, we can see there is a limit of orientation of this particular line (decision boundary)



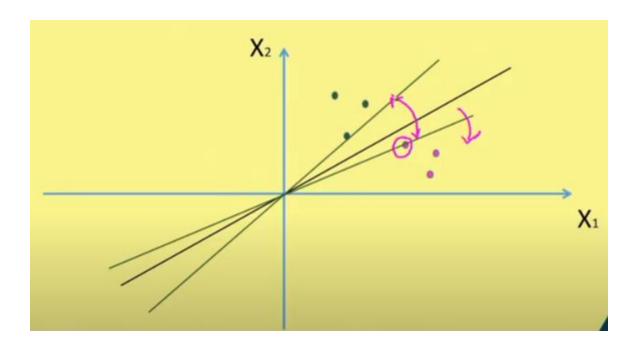
If we rotate further in anti-clock wise direction, the misclassified sample is the one marked as circle.



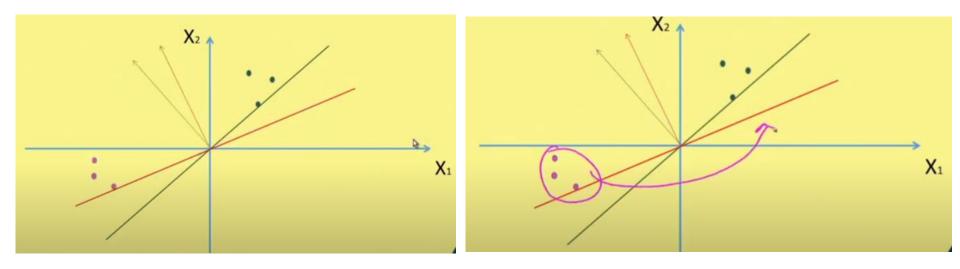
- Similarly, if we come to the other side, this is the limit
- If we rotate it further in clock wise direction; the misclassified sample is shown in circle

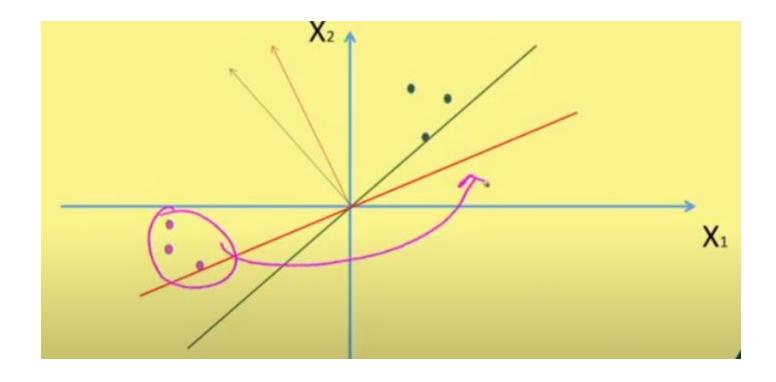


□ So the range, that we could have is shown here.

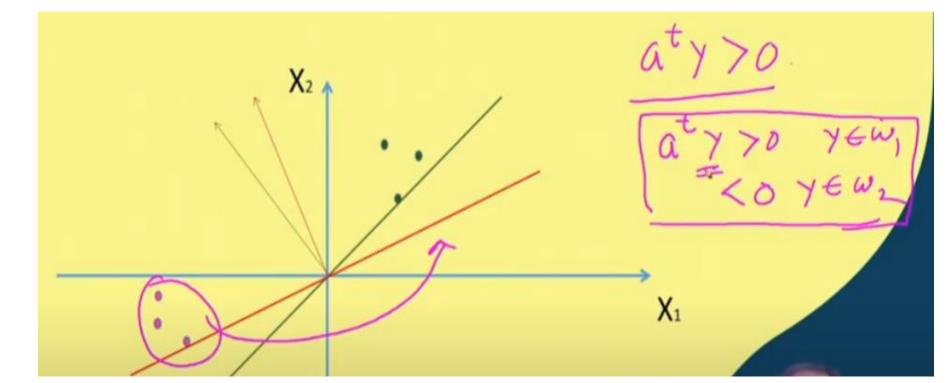


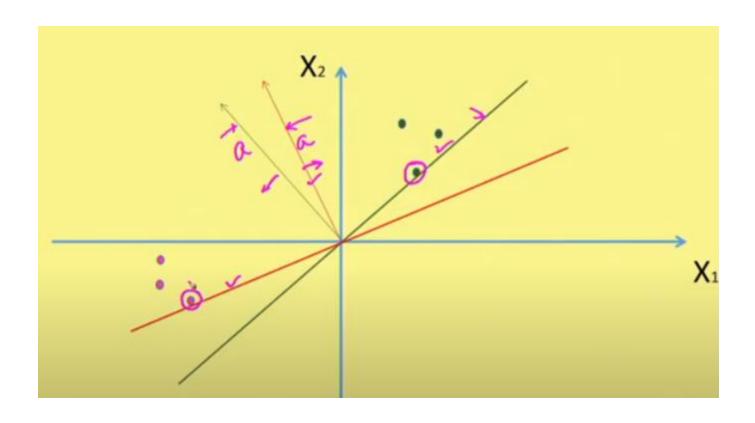
□ After taking negation of all sample for class 2



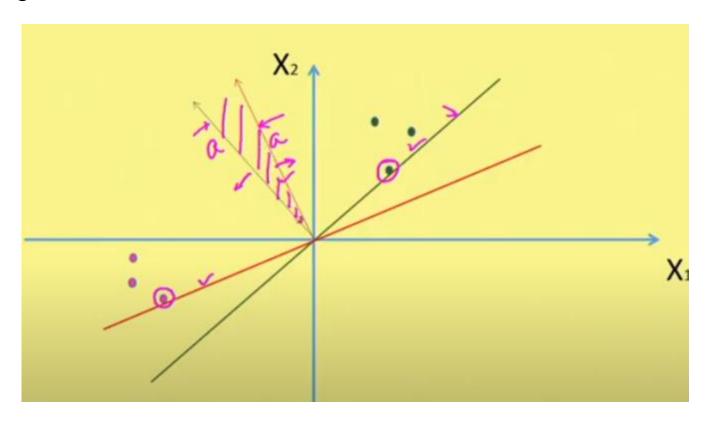


- □ For design purpose alone we use a^ty>0
- \Box For testing we use if $a^{t}y>0$, then y is class 1
- \Box If if $a^{t}y < 0$, then y is class 2

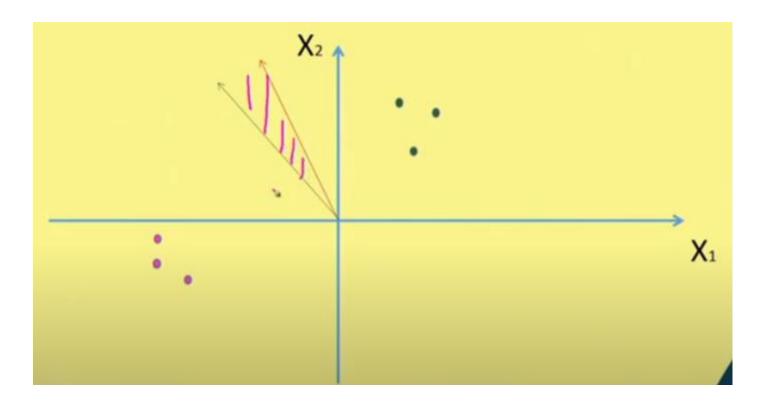




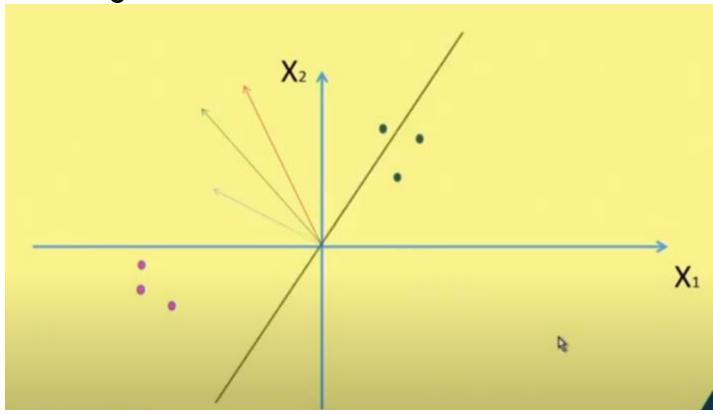
 So the solution vector 'a' must lie on this solution region.

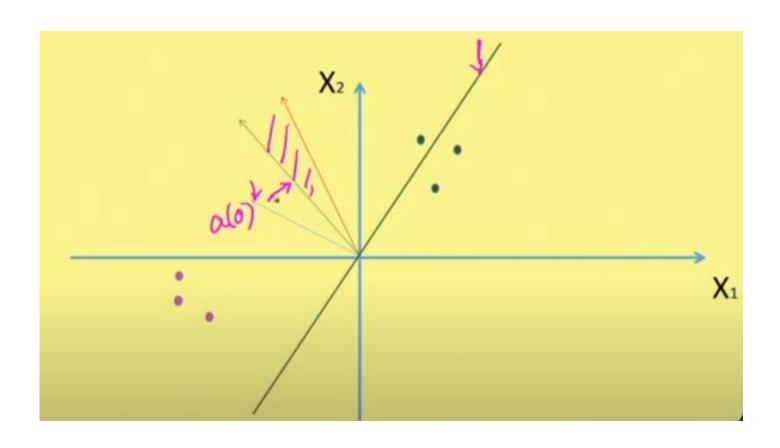


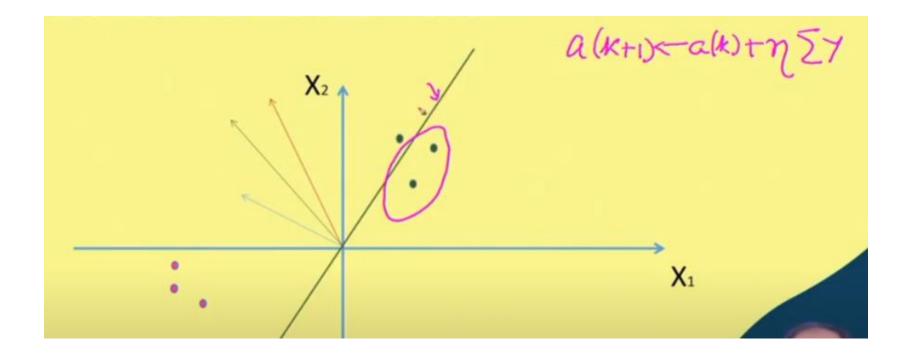
How do we make the solution vector 'a' should land in solution region?



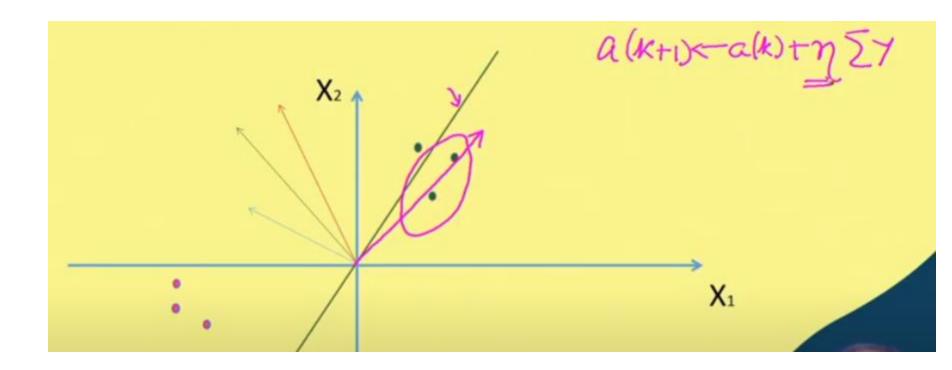
 Suppose, initial weight vector a(0) is chosen something like this



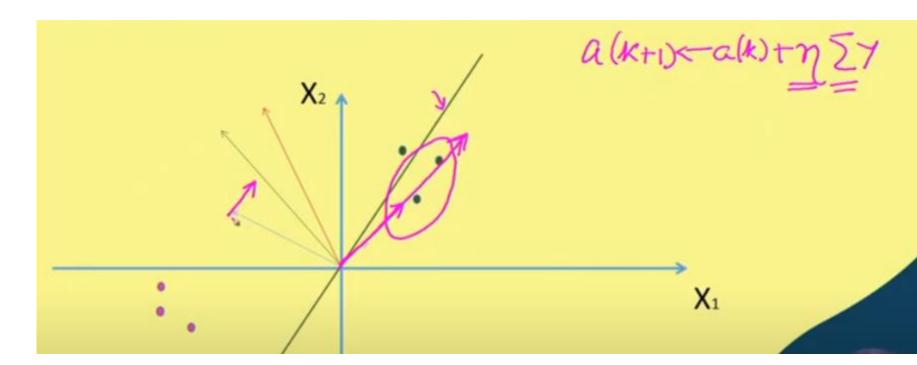




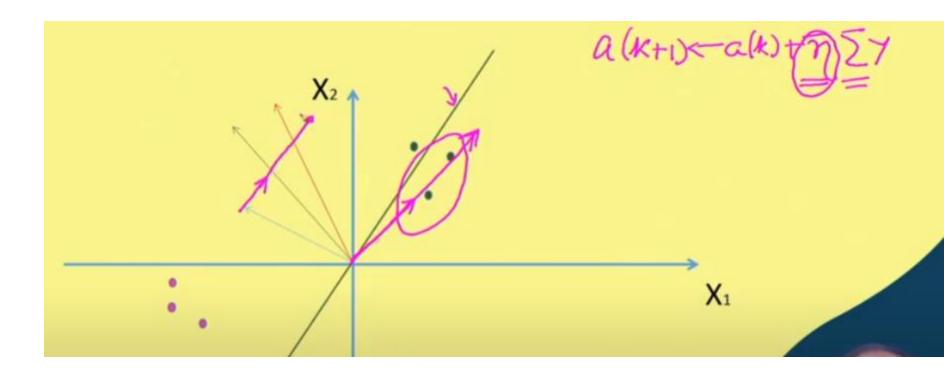
All mis-classified samples are in the direction shown



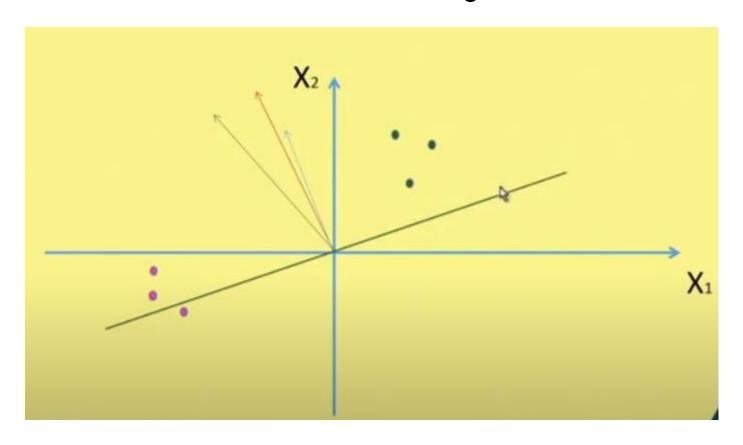
 So, a(0) is moved in the direction as shown and slowly it land in the solution region.

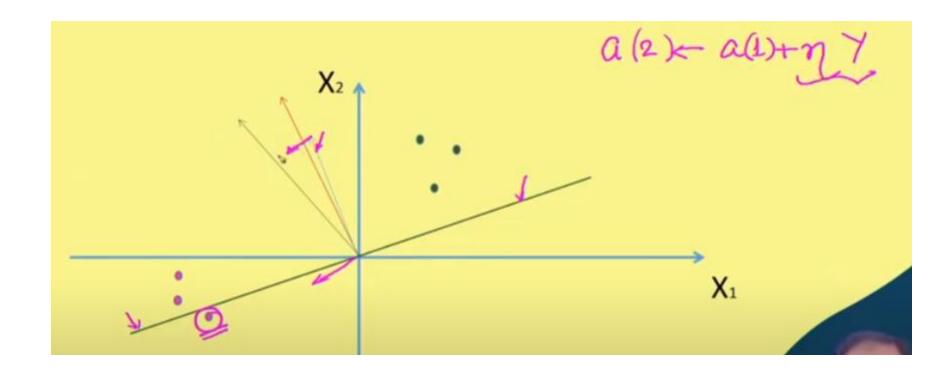


If the learning rate η is very large then solution vector is over shooted.

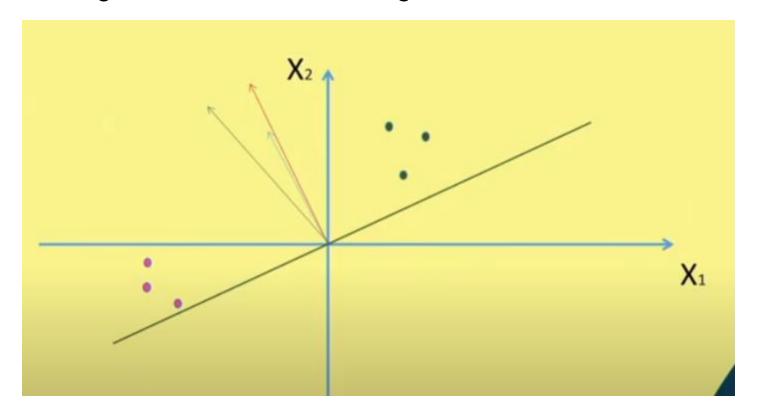


If the learning rate η is very large then solution vector is crossed the solution region.





This approach clearly says that by taking gradient descent approach it is possible the weight vector converge in the solution region.

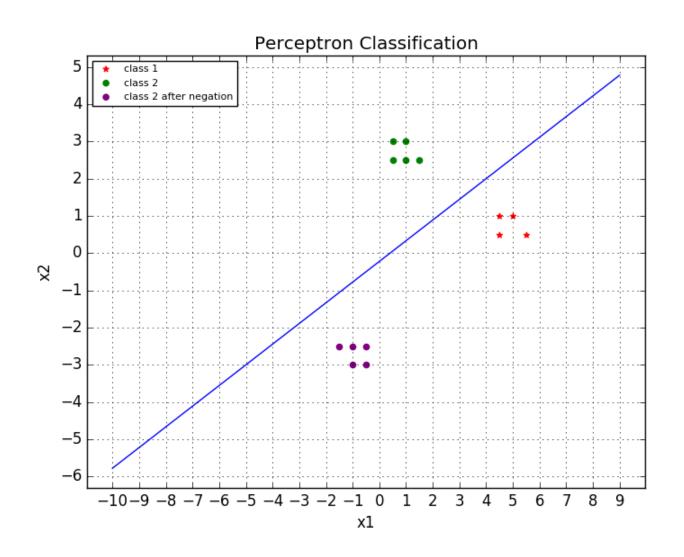


Perceptron criteria

- \square The approach can be $J(a) = \sum -(a^{T}y)$
- Using gradient decent algorithm
- □ It works well if the classes are linearly separable

MSE criteria

- If the classes are linearly separable, then it is possible to have linear decision boundary like this
- If the classes are not linearly separable then the approach is based on minimum error criteria (Mean Square Error criteria)



Summary

Convergence Procedure of Perceptron Algorithm

Thank you