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Name of Task: Real Time Video Stream using OpenCV with Java

Requirements:

- Real-Time Video Stream Analysis
- Task: Create a system to analyze and process real-time video streams.
- Requirements: Use Java along with libraries like OpenCV for video processing and analysis
- Implement features such as object detection, motion tracking, or facial recognition.
- Develop a frontend to visualize processed video streams and analysis results
- Deliverables
- Source code for video processing and analysis.
- Integration with video sources (e.g., cameras or video feeds).

Source Code:

• VideoStreamMain.java File

```
package com.openCV;
mport org.opencv.core.Core;
mport org.opencv.core.Mat;
mport org.opencv.core.MatOfRect;
mport org.opencv.core.Rect;
mport org.opencv.core.Scalar;
mport org.opencv.core.Size;
mport org.opencv.imgproc.lmgproc;
mport org.opencv.objdetect.CascadeClassifier;
mport org.opencv.videoio.VideoCapture;
mport javafx.application.Application;
mport javafx.embed.swing.SwingFXUtils;
mport javafx.scene.Scene;
mport javafx.scene.image.lmageView;
mport javafx.scene.layout.BorderPane;
mport javafx.stage.Stage;
mport javax.swing.SwingUtilities;
mport java.awt.image.BufferedImage;
mport org.opencv.video.BackgroundSubtractorMOG2;
mport org.opencv.video.Video;
mport org.opencv.videoio.VideoWriter;
```

```
mport javafx.scene.control.Button;
mport javafx.scene.layout.HBox;
    System.loadLibrary(Core.NATIVE_LIBRARY_NAME);
 private VideoCapture capture;
  private CascadeClassifier faceDetector;
  private CascadeClassifier pedestrianDetector;
  private ImageView imageView;
 private BackgroundSubtractorMOG2 bgSubtractor;
 //Saving vdo to file
  private VideoWriter videoWriter;
  public void start(Stage primaryStage) {
    faceDetector = new
CascadeClassifier("D:\\Fullstack\\VDO_Streamer\\opencv\\build\\etc\\haarcascades\\haarcascade_frontalface_def
ault.xml");
    pedestrianDetector = new
CascadeClassifier("D:\\Fullstack\\VDO_Streamer\\opencv\\build\\etc\\haarcascades\\haarcascade_fullbody.xml");
    bgSubtractor = Video.createBackgroundSubtractorMOG2();
    //Saving vdo to file
    if (faceDetector.empty()|| pedestrianDetector.empty()) {
       System.err.println("Error loading cascade file for face detection.");
       System.exit(0);
    capture = new VideoCapture(0);
    if (!capture.isOpened()) {
       System.err.println("Error opening video capture.");
       System.exit(0);
    imageView = new ImageView();
    Button startButton = new Button("Start");
    Button stopButton = new Button("Stop");
```

```
startButton.setOnAction(e -> new Thread(this::processVideo).start());
   stopButton.setOnAction(e -> {
      capture.release();
      System.exit(0);
   HBox controls = new HBox(10, startButton, stopButton);
   BorderPane root = new BorderPane();
   root.setCenter(imageView);
   root.setBottom(controls);
   Scene scene = new Scene(root, 800, 600);
    primaryStage.setScene(scene);
    primaryStage.setTitle("Real Time Video Stream With Face Detection");
   primaryStage.show();
   int codec = VideoWriter.fourcc('M', 'J', 'P', 'G'); // MJPG codec
   videoWriter = new VideoWriter("D:/Fullstack/VDO_Streamer/output.avi", codec, 30, new Size(640, 480));
    new Thread(this::processVideo).start();
 private void processVideo() {
    Mat frame = new Mat();
   Mat grayFrame = new Mat();
   MatOfRect faces = new MatOfRect();
   MatOfRect pedestrians = new MatOfRect();
   Mat foregroundMask = new Mat(); // This will store the foreground mask
   while (capture.read(frame)) {
       // Convert the frame to grayscale
      Imgproc.cvtColor(frame, grayFrame, Imgproc.COLOR_BGR2GRAY);
      Imgproc.equalizeHist(grayFrame, grayFrame);
      Imgproc.GaussianBlur(grayFrame, grayFrame, new Size(5, 5), 0);
      bgSubtractor.apply(frame, foregroundMask);
      faceDetector.detectMultiScale(grayFrame, faces, 1.1, 3, 0, new Size(30, 30), new Size(300, 300));
      pedestrianDetector.detectMultiScale(grayFrame, pedestrians, 1.1, 3, 0, new Size(30, 30), new Size(300,
      System.out.println("Number of faces detected: " + faces.toArray().length);
      java.util.List<org.opencv.core.MatOfPoint> contours = new java.util.ArrayList<>0;
      Imgproc.findContours(foregroundMask, contours, new Mat(), Imgproc.RETR_EXTERNAL,
mgproc.CHAIN_APPROX_SIMPLE);
```

```
int movingObjectCount = contours.size();
     System.out.println("Number of moving objects detected: " + movingObjectCount);
     Imgproc.threshold(foregroundMask, foregroundMask, 25, 255, Imgproc.THRESH_BINARY);
     java.util.List < org.opencv.core.MatOfPoint > filteredContours = new java.util.ArrayList < > ();
     for (org.opencv.core.MatOfPoint contour : contours) {
       if (Imgproc.contourArea(contour) > 500) { // Minimum area threshold
          filteredContours.add(contour);
       }
     for (Rect rect : faces.toArray()) {
       Imgproc.rectangle(frame, rect.tl(), rect.br(), new Scalar(0, 255, 0), 3);
     for (Rect rect : pedestrians.toArray()) {
       Imgproc.rectangle(frame, rect.tl(), rect.br(), new Scalar(255, 0, 0), 3);
     videoWriter.write(frame);
     BufferedImage image = matToBufferedImage(frame);
     javafx.scene.image.lmage fxlmage = SwingFXUtils.toFXlmage(image, null);
     SwingUtilities.invokeLater(() -> imageView.setImage(fxImage));
  capture.release();
  videoWriter.release();
private BufferedImage matToBufferedImage(Mat mat) {
  int type = BufferedImage. TYPE_BYTE_GRAY;
  if (mat.channels() > 1) {
     type = BufferedImage.TYPE_3BYTE_BGR;
  BufferedImage image = new BufferedImage(mat.width(), mat.height(), type);
  mat.get(0, 0, ((java.awt.image.DataBufferByte) image.getRaster().getDataBuffer()).getData());
  return image;
public static void main(String[] args) {
  launch(args);
```

• Pom.xml file