```
from google.colab import drive
drive.mount('/content/drive')
     Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mour
with open('/content/drive/My Drive/data.txt', 'r') as f:
  print("file opened")
     file opened
!pip install git+git://github.com/andreinechaev/nvcc4jupyter.git
     Collecting git+git://github.com/andreinechaev/nvcc4jupyter.git
       Cloning git://github.com/andreinechaev/nvcc4jupyter.git to /tmp/pip-req-build-uqk41vm?
       Running command git clone -q git://github.com/andreinechaev/nvcc4jupyter.git /tmp/pip-
     Building wheels for collected packages: NVCCPlugin
       Building wheel for NVCCPlugin (setup.py) ... done
       Created wheel for NVCCPlugin: filename=NVCCPlugin-0.0.2-cp36-none-any.whl size=4307 sh
       Stored in directory: /tmp/pip-ephem-wheel-cache-2y7qi78d/wheels/10/c2/05/ca241da37bff;
     Successfully built NVCCPlugin
     Installing collected packages: NVCCPlugin
     Successfully installed NVCCPlugin-0.0.2
%load ext nvcc plugin
     created output directory at /content/src
     Out bin /content/result.out
%%cu
#include<bits/stdc++.h>
using namespace std;
int main() {
    cout<<"Hello This is Amar Kumar - CED17I029"<<endl;</pre>
    return 0;
}
     Hello This is Amar Kumar - CED17I029
%%cu
#include<bits/stdc++.h>
#include<chrono>
using namespace std::chrono;
using namespace std;
```

const int num_data_points = 1000;

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const int num_bizza_center = io;
const int num_iteration = 1000;
global void calculateDistance(float *x1, float *y1, float x2, float y2, float *res, int t
    int id = threadIdx.x;
    for(int i=id ; i<num_pizza_center ; i+=th){</pre>
        res[i] = (x2-x1[i])*(x2-x1[i]) + (y2-y1[i])*(y2-y1[i]);
    }
int main( int argc, char* argv[] ){
    float *x, *y, *kx, *ky;
    float *dist;
    float *d_x,*d_y, *d_kx, *d_ky;
    float *d_dist;
    //# defining size for various data
    size_t dpsize = num_data_points*sizeof(float);
    size t pcsize = num pizza center*sizeof(float);
    //# allocating host memory
    x = (float*)malloc(dpsize);
    y = (float*)malloc(dpsize);
    kx = (float*)malloc(pcsize);
    ky = (float*)malloc(pcsize);
    dist = (float*)malloc(pcsize);
    //# allocating cuda(device) memory
    cudaMalloc(&d x, dpsize);
    cudaMalloc(&d_y, dpsize);
    cudaMalloc(&d kx, pcsize);
    cudaMalloc(&d ky, pcsize);
    cudaMalloc(&d dist, pcsize);
    // #read input from file
    freopen("/content/drive/My Drive/data.txt", "r", stdin);
    for(int i=0 ; i<num data points ; ++i){</pre>
        cin>>x[i]>>y[i];
    for(int i=0 ; i<num_pizza_center ; ++i){</pre>
        cin>>kx[i]>>ky[i];
    }
    //cout<<"1. fine"<<endl;</pre>
    //# Copy host vectors to device
    cudaMemcpy( d_x, x, dpsize, cudaMemcpyHostToDevice);
    cudaMemcpy( d_y, y, dpsize, cudaMemcpyHostToDevice);
    cudaMemcpy( d_kx, kx, pcsize, cudaMemcpyHostToDevice);
    cudaMemcpy( d_ky, ky, pcsize, cudaMemcpyHostToDevice);
    int tt[10] ={1,2,4,8,16,32,64,128,256,500};
    for(int t=0; t<10; ++t){
        auto start = high_resolution_clock::now();
```

```
for(int i=0; i<num_iteration; ++i){</pre>
            vector<pair<float,float>> points[num_pizza_center];
            //# for each data point, serve it under that pizza center which is nearest to it
            for(int j=0 ; j<num data points ; ++j){</pre>
                int temp1 = x[j], temp2 = y[j];
                //cout<<temp1<<" , "<<temp2<<endl;</pre>
                calculateDistance<<<1,2>>>(d_kx, d_ky, temp1, temp2,d_dist,2);
                cudaMemcpy( dist, d_dist, pcsize, cudaMemcpyDeviceToHost );
                int index = distance(dist,min element(dist,dist+num pizza center));
                points[index].push_back({x[j],y[j]});
            }
            // # updated mean position(pizza center location)
            for(int it1=0 ; it1<num_pizza_center ; ++it1){</pre>
                float xavg = 0, yavg = 0;
                for(auto x:points[it1]){
                    xavg+=x.first;
                    yavg+=x.second;
                }
                kx[it1] = xavg/points[it1].size();
                ky[it1] = yavg/points[it1].size();
            }
            cudaMemcpy( d_kx, kx, pcsize, cudaMemcpyHostToDevice);
            cudaMemcpy( d_ky, ky, pcsize, cudaMemcpyHostToDevice);
            /*if(i==num iteration -1){
                cout<<"final updted mean position"<<endl;</pre>
                for(int it2=0 ; it2<num pizza center ; ++it2){</pre>
                    cout<<"("<<kx[it2]<<" , "<<ky[it2]<<")"<<endl;
                }
            }*/
        auto stop = high_resolution_clock::now();
        auto duration = duration cast<microseconds>(stop - start);
        cout << "Time taken by function: "<< duration.count() << " microseconds" << endl;</pre>
    }
    //# Release device memory
    cudaFree(d_x); cudaFree(d_y); cudaFree(d_kx); cudaFree(d_ky); cudaFree(d_dist);
    //# Release host memory
    free(x); free(y); free(kx); free(ky); free(dist);
    return 0;
}
    Time taken by function: 22680218 microseconds
     Time taken by function: 22688623 microseconds
     Time taken by function: 22646035 microseconds
     Time taken by function: 22656562 microseconds
```

```
Time taken by function: 22609342 microseconds
Time taken by function: 22737826 microseconds
Time taken by function: 22742092 microseconds
Time taken by function: 22593556 microseconds
```

Time taken by function: 22556165 microseconds Time taken by function: 22628016 microseconds