



# Storage Strategies

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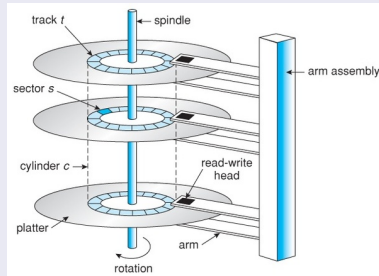
# Magnetic Disk

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## Information Storage Medium

- The primary medium for long term on-line storage of data
- Disk storage is referred to as direct-access storage, because it is possible to read from the disk randomly
- Disk storage survive power failure and system crash





# Magnetic Disk

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## Information Storage Medium

- Data on a hard disk is arranged in concentric rings or tracks on one or more platters
- Read-Write head is positioned very close to platter surface
- Over 16,000 tracks per platter are on typical hard disk
- Each track is divided into arc-shaped sectors
- A sector is the smallest unit of data that can be read or written
- Sector size typically 512 bytes
- Data is written to and read from disk block by block.
- The block size is set to a multiple of the sector size
- Typical disk block sizes are 4KB or 8KB



# Performance Measures of Disk

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## Information Storage Medium

- **Access time** is the time from when a read or write request is issued to when data transfer begin
- To access data on a given sector of disk, the arm first must move so that it is positioned over the correct track
- **rotational latency time** Later wait for sector to come under the read/write head
- **Data transfer rate** is the rate at which data can be retrieved from or store to the disk
- **Access time** is the sum of seek time, rotational delay, and transfer time



# RAID

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## Information Storage Medium

- A variety of disk organization techniques collectively called as redundant arrays of independent disk
- RAID have been proposed to achieved improved performance and reliability
- 
- **Data transfer rate** is the rate at which data can be retrieved from or store to the disk
- **Access time** is the sum of seek time, rotational delay, and transfer time



# RAID

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## Information Storage Medium

- The solution to the problem of reliability is to introduce redundancy, which can be done using the technique of mirroring or shadowing
- There are a number of variates (RAID-Levels) differing w.r.t the following characteristics:
- (a) Striping unit (data interleaving)
  - how to scatter or split (primary) data across disk?
  - fine bit level stripping or coarse block level striping?
- (b) How to compute and distribute redundant information?
  - what kind of redundant information (parity, ECC)?
  - where to allocate redundant information (separate/few disk/all disk array)?



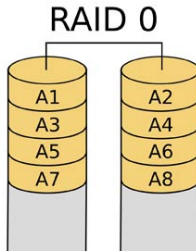
# RAID Level 0

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## Information Storage Medium

- In this level, there is no redundancy, just stripping.
- The five disks are taken as one unit and the data are scattered over all the disks
- Advantage/Disadvantage of this storage strategy
  - least storage overhead
  - no extra effort for write-access
  - not the best read performance





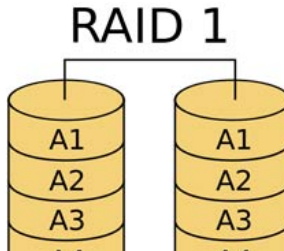
# RAID Level 1

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## Information Storage Medium

- In this level, there is mirroring.
- It requires redundant information to be stored in double storage space
- Advantage/Disadvantage of this storage strategy
  - double necessary storage space
  - double write access
  - optimized read-performance due to alternative I/O path







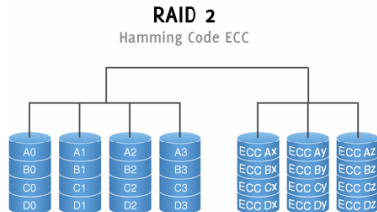
# RAID Level 2

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## Information Storage Medium

- In this level, there is memory-style error correcting code (ECC)
- It requires additional disk space to store the ECC
- Advantage/Disadvantage of this storage strategy
  - Computer error-correcting codes for data of n disks
  - failure recovery: determine lost disk by using the n-1 extra disk
  - correct its contents from 1 of those





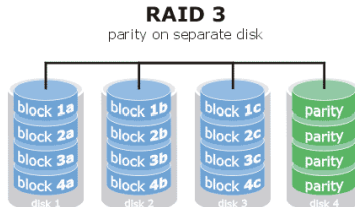
# RAID Level 3

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## Information Storage Medium

- In this level, there is bit interleaved parity
- Advantage/Disadvantage of this storage strategy
  - one parity disk suffices, since controller can easily identify faulty disk
  - distribute data bitwise onto data disk
  - read and write access goes to all disk, no inter-I/O parallelism, but high bandwidth





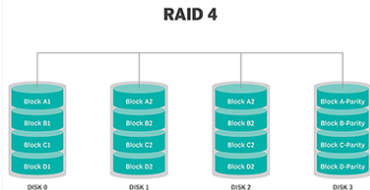
# RAID Level 4

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## Information Storage Medium

- In this level, there is block-interleaved parity.
- Block are seen as various arcs on the disk
- Large read requests can be made here
- Advantage/Disadvantage of this storage strategy
  - Like RAID 3, but distribute data block-wise (variable block size)
  - small read I/O goes to only one disk
  - bottleneck: all write I/Os go to the one parity disk





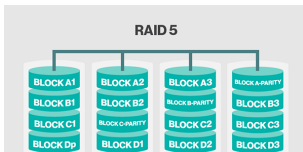
# RAID Level 5

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## Information Storage Medium

- In this level, there is block-interleaved striped parity.
- This level is an improvement over level 4, where parity block are distributed uniformly over all disk
- Several write request can be processed in parallel
- Advantage/Disadvantage of this storage strategy
  - Like RAID 4, but distribute parity data block across all disk load balancing
  - best performance for small and large read as well as large write I/Os
  - variants w.r.t distribution of block





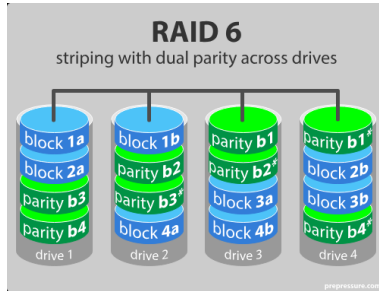
# RAID Level 6

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## Information Storage Medium

- In this level, there is block-interleaved variable striped parity.





# File Structures

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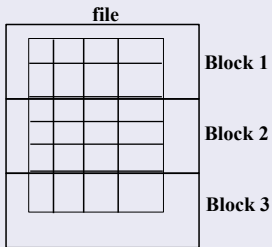
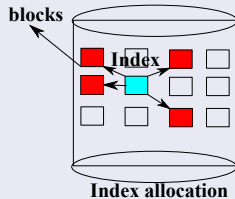
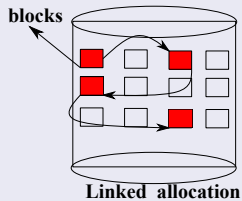
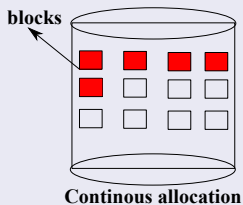
- A file is a collection of records that may reside on several pages
- These records are mapped onto disk blocks.
- We need to consider ways of representing logical data models in terms of files
- Although blocks are of a fixed size determined by the physical properties of the disk and by the operating system
- Types of block allocation
  - Continuous Memory Allocation
  - Linked Memory Allocation



# File Structures

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# File Structures

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## Sorted file

- Can be sorted only according to one attribute (search key)
- Searching fast
- Insertion and deletion will be difficult

## Unsorted file

- Random order, any record can be placed anywhere
- Searching will be slow
- Insertion and deletion will be easy





# File Structures

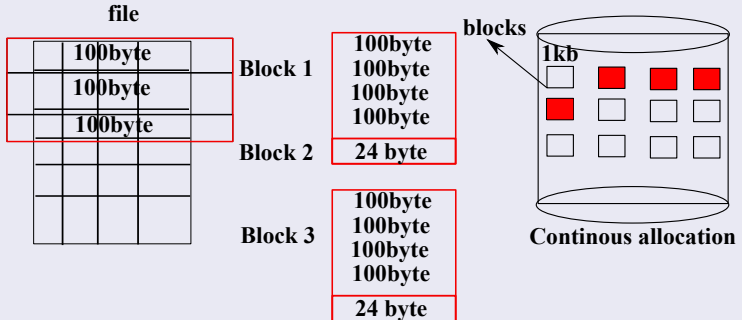
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## Spanned/Unspanned Mapping

**Spanned mapping:** Prevent the memory waste, but increase the search time of the particular record

**Unspanned mapping:** It does not prevent memory waste, but reduce the block search





# Indexing

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**Lets say blocks are sorted**  
**Binary Search**  
**record = 9456**

**$\log_2 1000 = 10$**   
**Maximum block**

**Lets say block are unsorted**  
**how may block access required**

## Secondary Memory

		10		Block 1
		10		Block 2
		10		Block 3
		10		Block 4
		10		Block 5
		10		Block 1000

**total record = 1000x10**

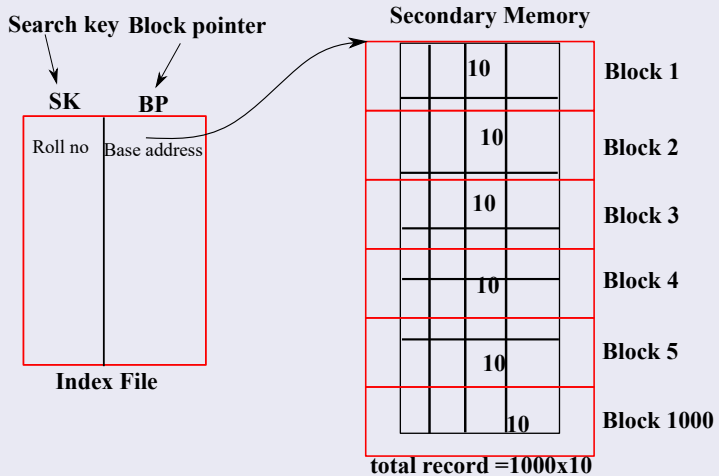


# Indexing

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**Sparse Indexing** :only keep one value per block in index SK (main file sorted)  
**Dense Indexing** :keep all value per block in index SK (main file unsorted )





# Types of Indexing

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- **Primary Indexing**
- **Clustered indexing**
- **Secondary indexing**
- **Multi-level Tree**



# Primary Indexing

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## Primary

- Main file should be sorted
- Primary key is used as the anchor attributes
- Example of sparse indexing
- No of entries in index file = No of block acquired by the main file
- no of access required =  $1\log_2 n + 1$



# Primary Indexing

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## For main file

- Let say we have 30000 records in a file and each record takes 100 bytes of space, and in index file each record will take 15 byte
- The given block size of the secondary memory is 1024 bytes
- Find the blocking factor=?
- If spanned and unspanned mapping is not given in the problem, then always takes unspanned allocation.



# Primary Indexing

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## For main file

- Let say we have 30000 records in a file and each record takes 100 bytes of space, and in index file each record will take 15 byte
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  - **Blocking factor**=  $\frac{\text{Block size}}{\text{record size}}$  no of record per block
- Number of blocks required for main files



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  - **Blocking factor**=  $\frac{\text{No of records in main file}}{\text{blocking factor}}$
- No of block access required





# Primary Indexing

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  - **Blocking factor**=  $\frac{\text{No of records in main file}}{\text{blocking factor}}$
- No of block access required
  - $\log_2 n$



# Primary Indexing

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## For Index file

- Calculate the blocking factor for index file
- Calculate the no of blocks for index files
- No of block access required



# Primary Indexing

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## For Index file

- Calculate the blocking factor for index file
- Calculate the no of blocks for index files
- No of block access required
- $\log_2 n + 1$

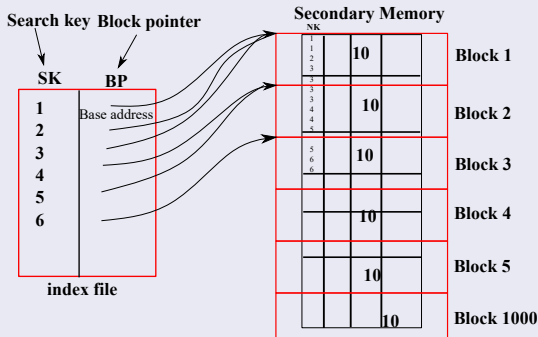


# Cluster Indexing

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- Main file is sorted (on some non-key attributes)
- There will be one entry for each unique value of the non-key attribute
- if number of block acquired by index file is  $n$ , then block access required will be  $\geq \log_2 n + 1$



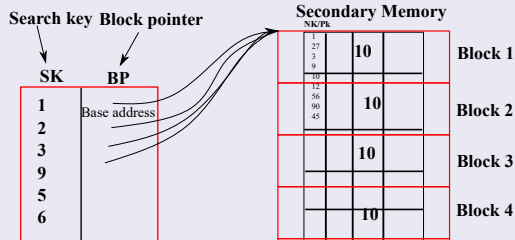


# Secondary Indexing

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- Main file unsorted
- Can be done on key as well as on non-key attributes
- Called secondary because normally one indexing is already done
- Example of dense indexing
- no of entry in index file = no of entry in main file
- no of block access =  $\log_2 n + 1$





# Secondary Indexing

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## For main file

- Let say we have 30000 records in a file and each record takes 100 bytes of space, and in index file each record will take 15 byte
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# Secondary Indexing

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- Let say we have 30000 records in a file and each record takes 100 bytes of space, and in index file each record will take 15 byte
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- Number of blocks required for main files



# Secondary Indexing

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- Number of blocks required for main files
  - **Blocking factor**=  $\frac{\text{No of records in main file}}{\text{blocking factor}}$
- No of block access required





# Secondary Indexing

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  - **Blocking factor**=  $\frac{\text{No of records in main file}}{\text{blocking factor}}$
- No of block access required
  - **$n$**



# Secondary Indexing

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## For Index file

- Calculate the blocking factor for index file
- Calculate the no of blocks for index files
- No of block access required



# Secondary Indexing

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## For Index file

- Calculate the blocking factor for index file
- Calculate the no of blocks for index files
- No of block access required
- $\log_2 n + 1$

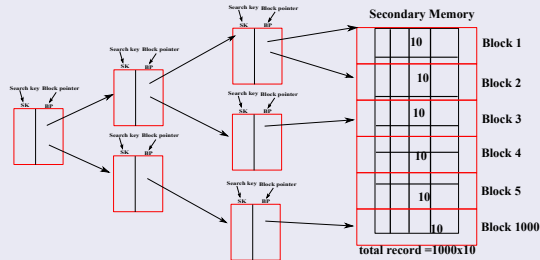


# Multi-Level Indexing

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- In multilevel indexing we divided the big index file into smaller index file (dense indexing case).
- Multilevel indexing permits the faster access of record
- Multilevel indexing concept derived from the m-way search tree



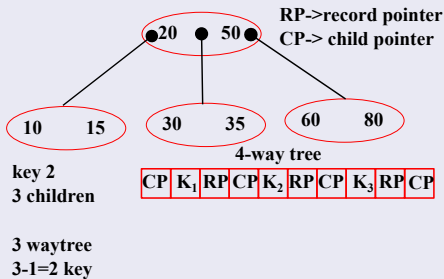
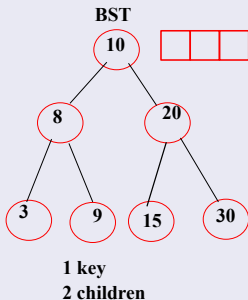


# What is m-way tree

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## BST vs m-way tree





# Multi-Level Indexing

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## m-way search tree

- m-way search tree has no control on reducing the height of the tree
- To resolve the issues of m-way search tree, B-tree is introduced.
- B-tree set some rules for insertion/deletion of keys (it also a kind of m-way search tree with rule)
  - $\lfloor \frac{m}{2} \rfloor$  children
  - Root node can have minimum 2 children
  - All leaf node must be at same level
  - Bottom-up approach



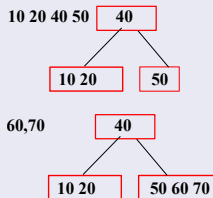
# Multi-Level Indexing Example

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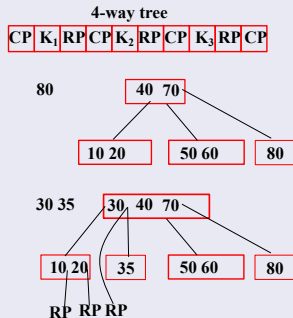
## B-tree

- Lets say  $m=4$ , then  $m-1$  key should be there
- Given keys 10,20,40,50;



B-Tree

In B-tree all nodes will have  
child pointer and  
record pointer





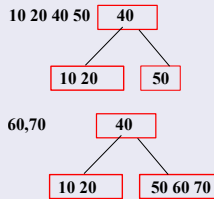
# Multi-Level Indexing Example

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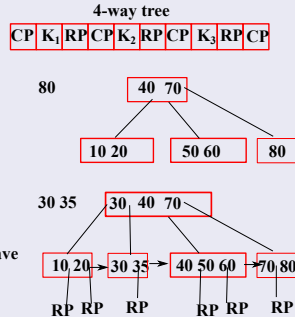
## B+-tree

- In B+-tree all the leaf node will have record pointer
- Every key also present in the leaf node
- And the leaf nodes are connected to another leaf node



B+-Tree

In B+-tree all leaf nodes will have keys and record pointer







# Multi-Level Indexing Example

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## Deletion on B-tree

- Deletion of 2,21,10,3,4

4-way tree

