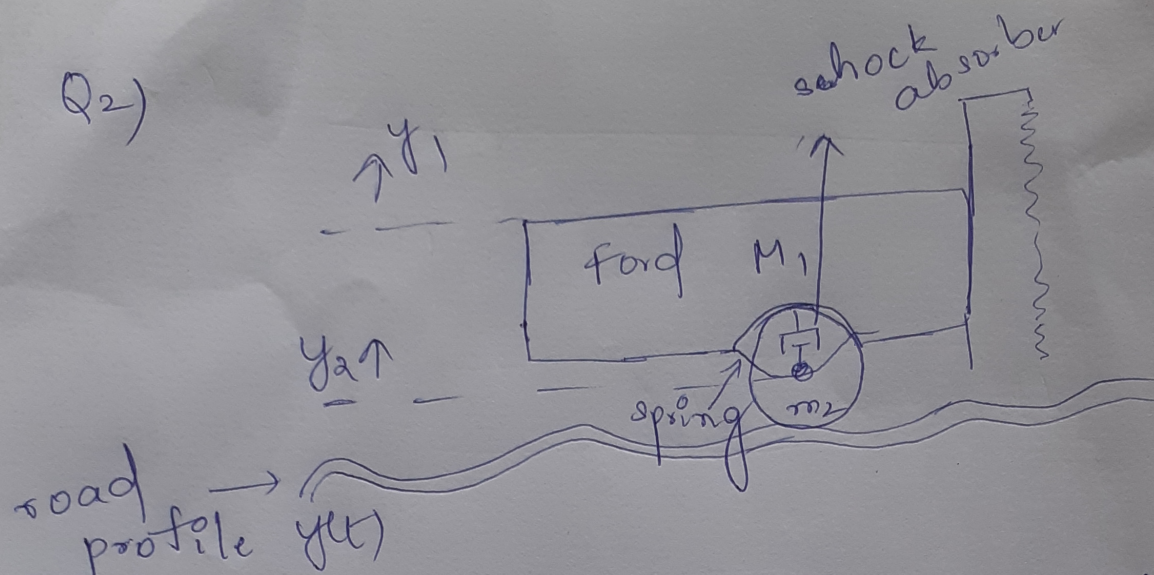
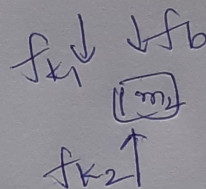
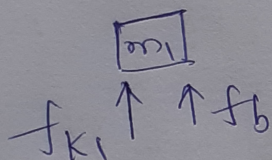


Q2)



Free body for m_1

Free body for m_2



$$-k_1(y_1 - y_2) - b(\dot{y}_1 - \dot{y}_2) = m_1 \ddot{y}_1$$

$$\therefore \ddot{y}_1 = \frac{1}{m_1} (-k_1(y_1 - y_2) - b(\dot{y}_1 - \dot{y}_2))$$

$$+k_1(y_1 - y_2) + b(\dot{y}_1 - \dot{y}_2) - k_2(y_2 - y(t)) = m_2 \ddot{y}_2$$

$$\ddot{y}_2 = \frac{1}{m_2} (k_1(y_1 - y_2) + b(\dot{y}_1 - \dot{y}_2) - k_2(y_2 - y(t))) = 0$$

The values of m_1, m_2, k_1, k_2, b are adjusted.