

UNIT-II

Mini-Max Algorithm in Artificial Intelligence

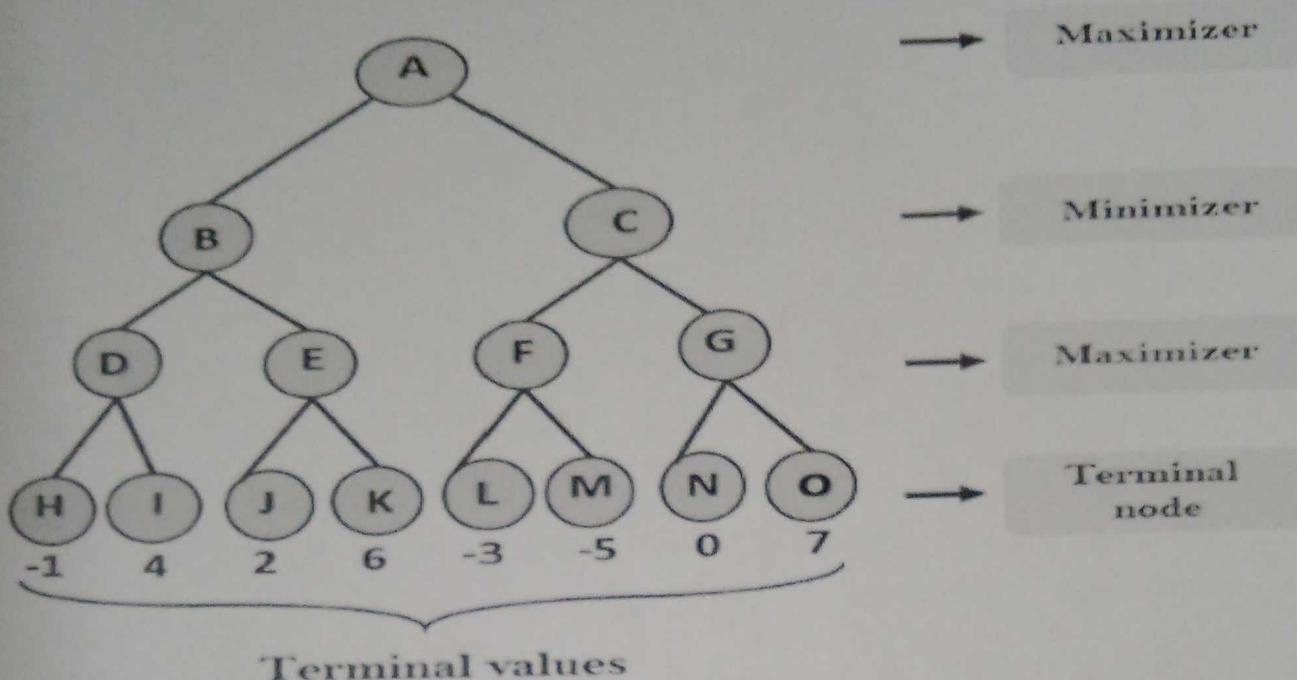
- Mini-max algorithm is a recursive or backtracking algorithm which is used in decision-making and game theory. It provides an optimal move for the player assuming that opponent is also playing optimally.
- Mini-Max algorithm uses recursion to search through the game-tree.
- Min-Max algorithm is mostly used for game playing in AI. Such as Chess, Checkers, tic-tac-toe, go, and various tow-players game. This Algorithm computes the minimax decision for the current state.
- In this algorithm two players play the game, one is called MAX and other is called MIN.
- Both the players fight it as the opponent player gets the minimum benefit while they get the maximum benefit.
- Both Players of the game are opponent of each other, where MAX will select the maximized value and MIN will select the minimized value.
- The minimax algorithm performs a depth-first search algorithm for the exploration of the complete game tree.
- The minimax algorithm proceeds all the way down to the terminal node of the tree, then backtrack the tree as the recursion.

Working of Min-Max Algorithm:

- The working of the minimax algorithm can be easily described using an example. Below we have taken an example of game-tree which is representing the two-player game.
- In this example, there are two players one is called Maximizer and other is called Minimizer.
- Maximizer will try to get the Maximum possible score, and Minimizer will try to get the minimum possible score.
- This algorithm applies DFS, so in this game-tree, we have to go all the way through the leaves to reach the terminal nodes.
- At the terminal node, the terminal values are given so we will compare those value and backtrack the tree until the initial state occurs. Following are the main steps involved in solving the two-player game tree:

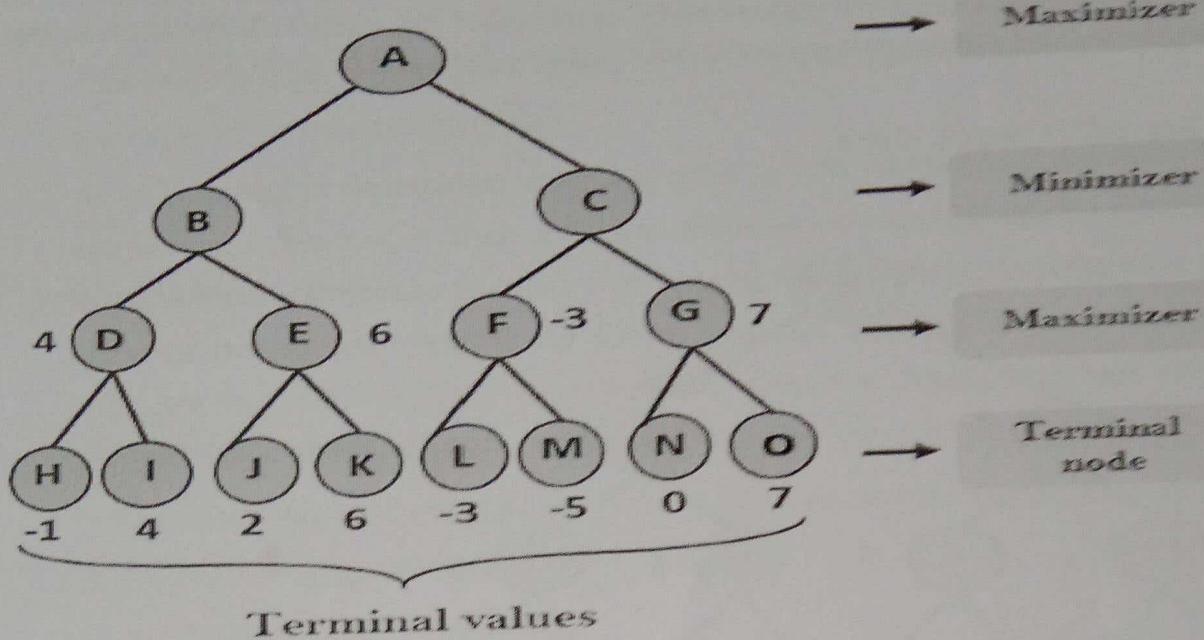
Step-1: In the first step, the algorithm generates the entire game-tree and apply the utility function to get the utility values for the terminal states. In the below tree diagram, let's take A is

the initial state of the tree. Suppose maximizer takes first turn which has worst-case initial value = $-\infty$, and minimizer will take next turn which has worst-case initial value = $+\infty$.



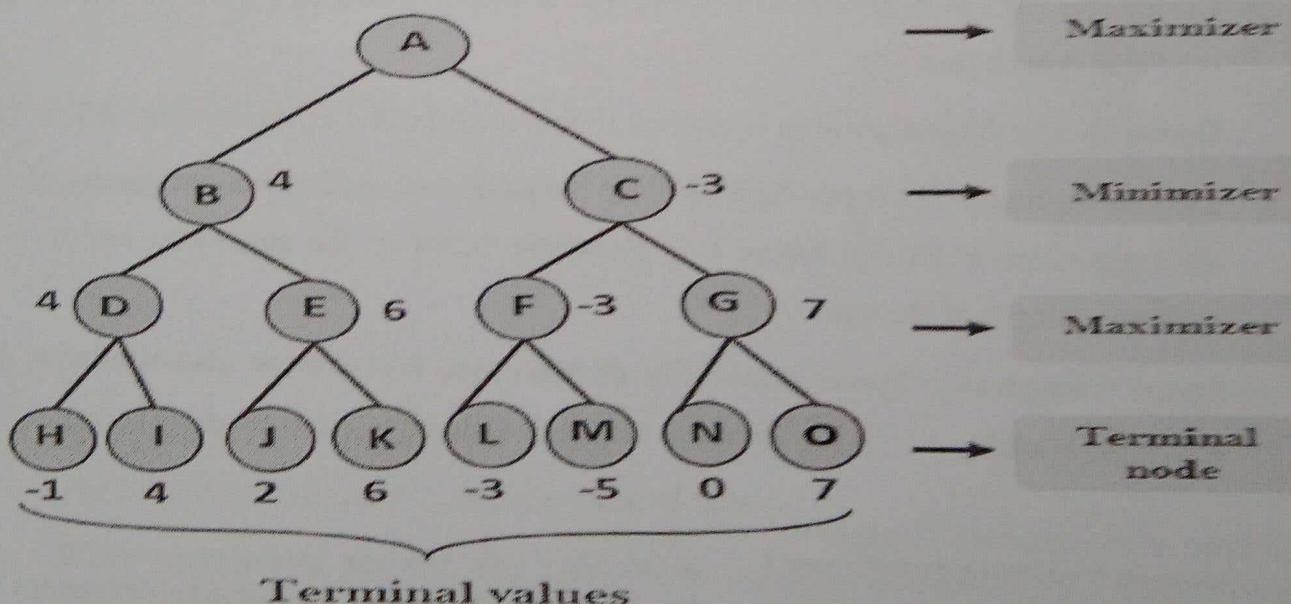
Step 2: Now, first we find the utilities value for the Maximizer, its initial value is $-\infty$, so we will compare each value in terminal state with initial value of Maximizer and determines the higher nodes values. It will find the maximum among the all.

- o For node D $\max(-1, -\infty) \Rightarrow \max(-1, 4) = 4$
- o For Node E $\max(2, -\infty) \Rightarrow \max(2, 6) = 6$
- o For Node F $\max(-3, -\infty) \Rightarrow \max(-3, -5) = -3$
- o For node G $\max(0, -\infty) = \max(0, 7) = 7$



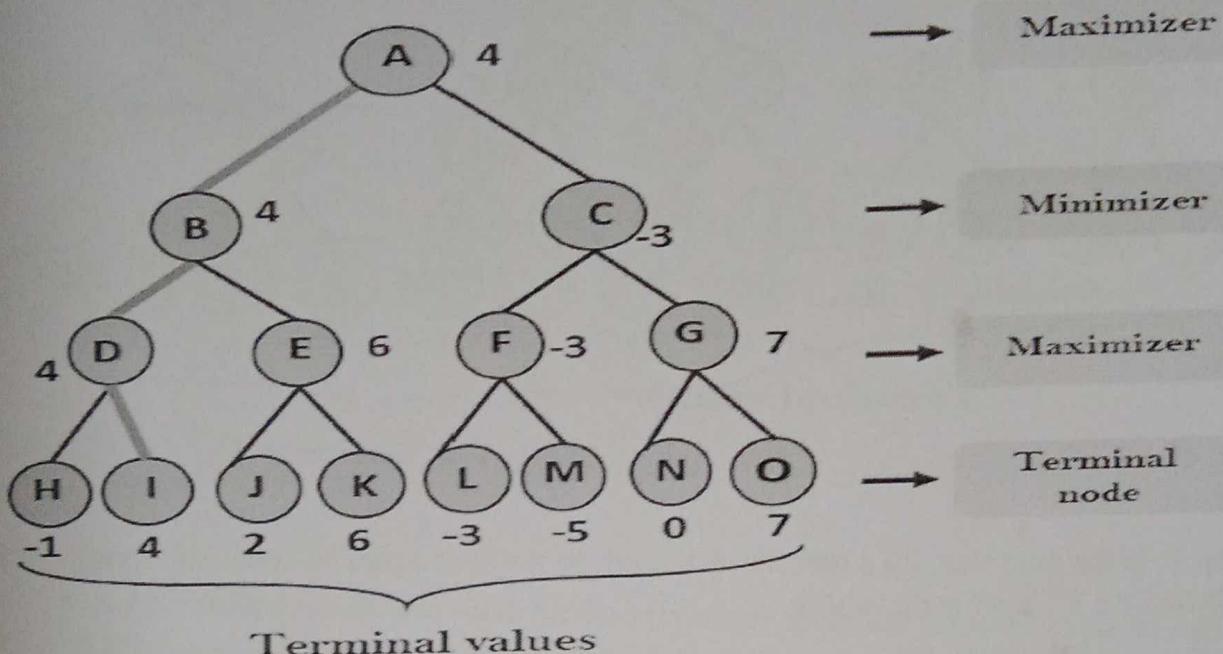
Step 3: In the next step, it's a turn for minimizer, so it will compare all nodes value with $+\infty$, and will find the 3rd layer node values.

- o For node B= $\min(4,6) = 4$
- o For node C= $\min (-3, 7) = -3$



Step 4: Now it's a turn for Maximizer, and it will again choose the maximum of all nodes value and find the maximum value for the root node. In this game tree, there are only 4 layers, hence we reach immediately to the root node, but in real games, there will be more than 4 layers.

- For node A $\max(4, -3) = 4$



Properties of Mini-Max algorithm:

- Complete-** Min-Max algorithm is Complete. It will definitely find a solution (if exist), in the finite search tree.
- Optimal-** Min-Max algorithm is optimal if both opponents are playing optimally.
- Time complexity-** As it performs DFS for the game-tree, so the time complexity of Min-Max algorithm is $O(b^m)$, where b is branching factor of the game-tree, and m is the maximum depth of the tree.
- Space Complexity-** Space complexity of Mini-max algorithm is also similar to DFS which is $O(bm)$.

Limitation of the minimax Algorithm:

The main drawback of the minimax algorithm is that it gets really slow for complex games such as Chess, go, etc. This type of games has a huge branching factor, and the player has lots of choices to decide. This limitation of the minimax algorithm can be improved from **alpha-beta pruning**.

Alpha-Beta Pruning

- Alpha-beta pruning is a modified version of the minimax algorithm. It is an optimization technique for the minimax algorithm.
- As we have seen in the minimax search algorithm that the number of game states it has to examine are exponential in depth of the tree. Since we cannot eliminate the exponent, but we can cut it to half. Hence there is a technique by which without checking each node of the game tree we can compute the correct minimax decision, and this technique is called **pruning**. This involves two threshold parameter Alpha and beta for future expansion, so it is called **alpha-beta pruning**. It is also called as **Alpha-Beta Algorithm**.
- Alpha-beta pruning can be applied at any depth of a tree, and sometimes it not only prune the tree leaves but also entire sub-tree.
- The two-parameter can be defined as:
 - a. **Alpha:** The best (highest-value) choice we have found so far at any point along the path of Maximizer. The initial value of alpha is $-\infty$.
 - b. **Beta:** The best (lowest-value) choice we have found so far at any point along the path of Minimizer. The initial value of beta is $+\infty$.
- The Alpha-beta pruning to a standard minimax algorithm returns the same move as the standard algorithm does, but it removes all the nodes which are not really affecting the final decision but making algorithm slow. Hence by pruning these nodes, it makes the algorithm fast.

Condition for Alpha-beta pruning:

The main condition which required for alpha-beta pruning is:

$$\alpha >= \beta$$

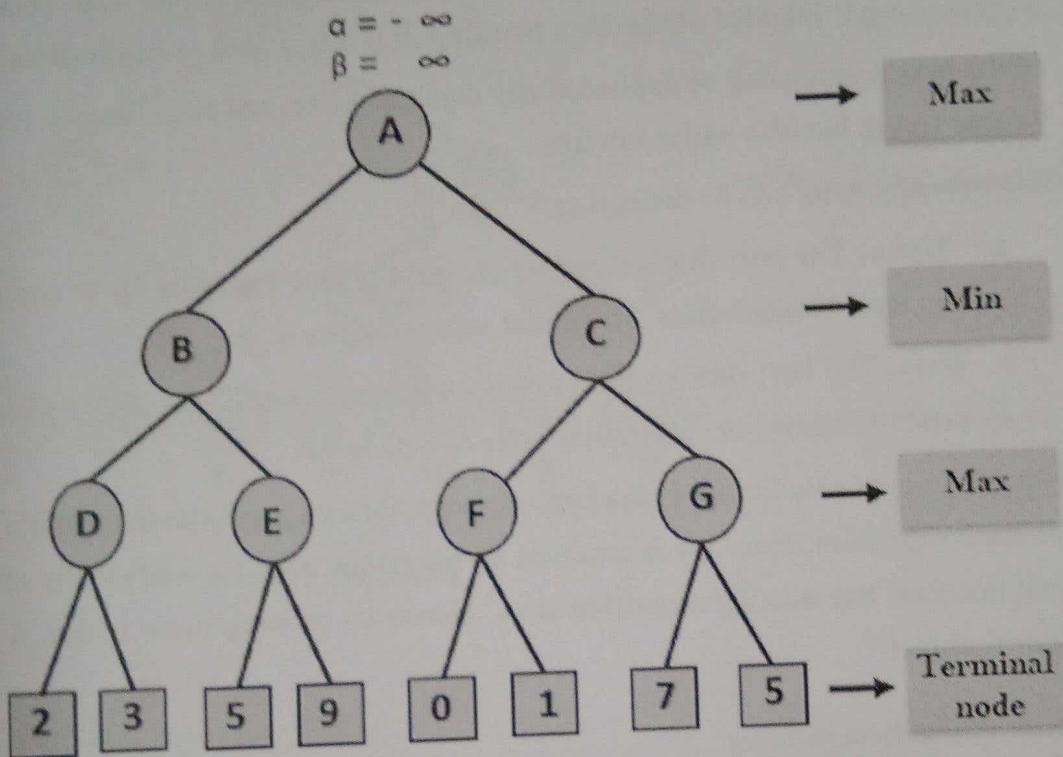
Key points about alpha-beta pruning:

- The Max player will only update the value of alpha.
- The Min player will only update the value of beta.
- While backtracking the tree, the node values will be passed to upper nodes instead of values of alpha and beta.
- We will only pass the alpha, beta values to the child nodes.

Working of Alpha-Beta Pruning:

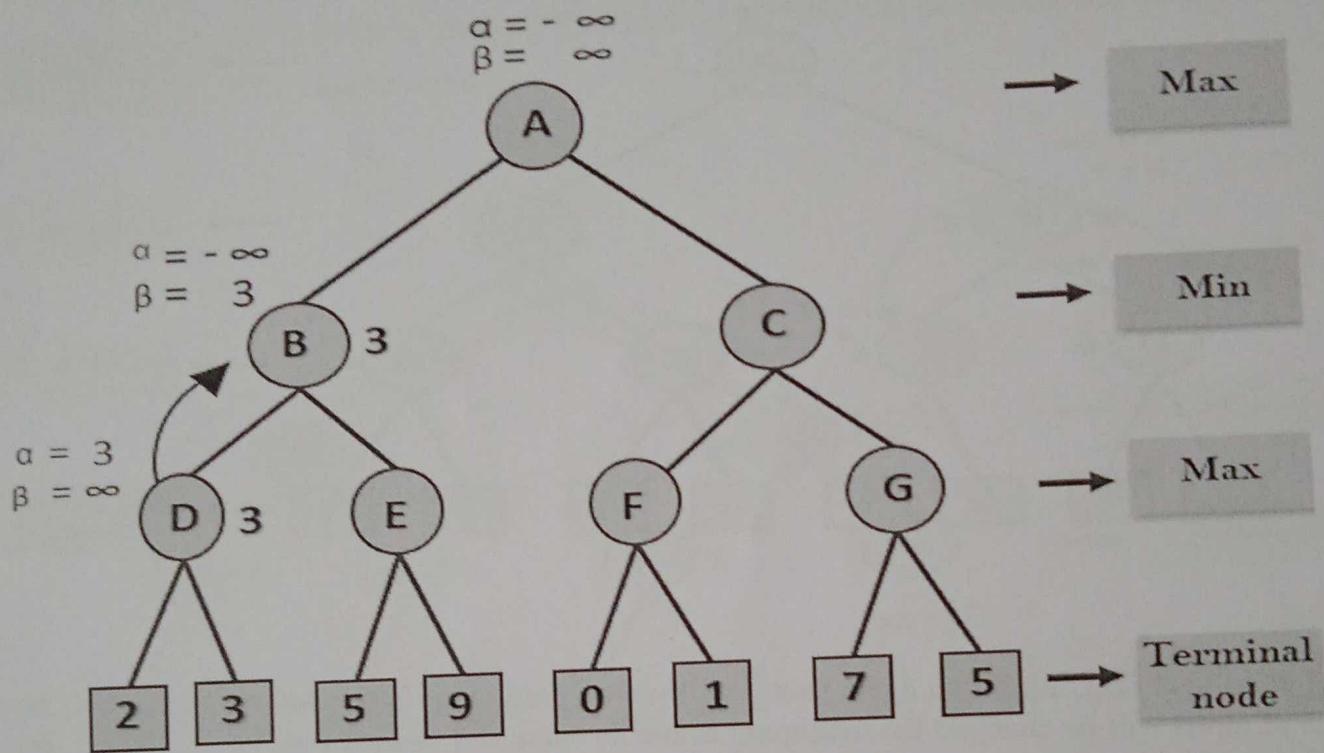
Let's take an example of two-player search tree to understand the working of Alpha-beta pruning

Step 1: At the first step the, Max player will start first move from node A where $\alpha = -\infty$ and $\beta = +\infty$, these value of alpha and beta passed down to node B where again $\alpha = -\infty$ and $\beta = +\infty$, and Node B passes the same value to its child D.



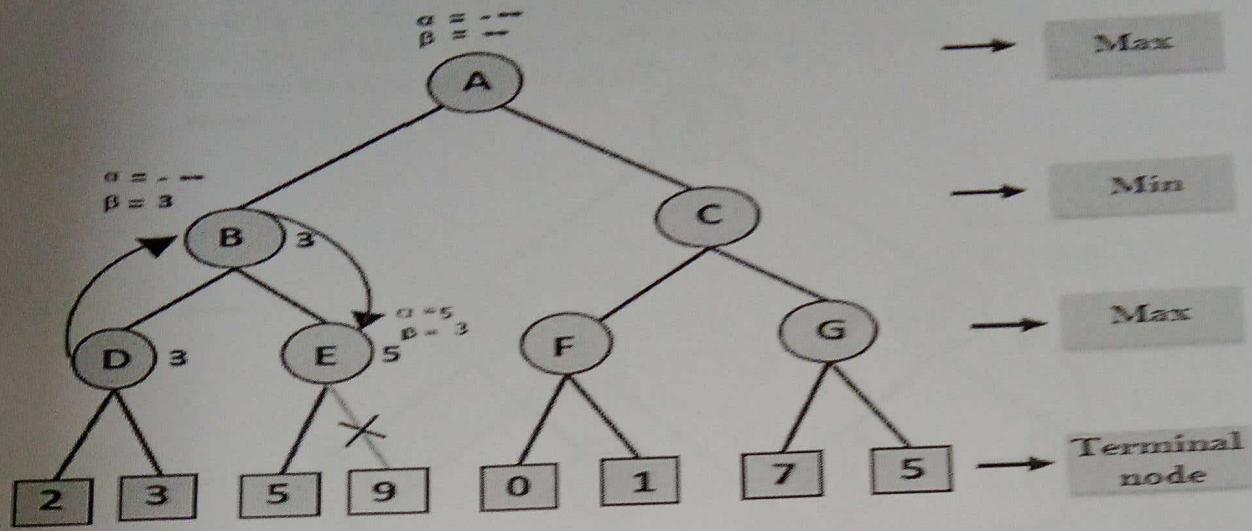
Step 2: At Node D, the value of α will be calculated as its turn for Max. The value of α is compared with firstly 2 and then 3, and the max ($2, 3$) = 3 will be the value of α at node D and node value will also 3.

Step 3: Now algorithm backtrack to node B, where the value of β will change as this is a turn of Min, Now $\beta = +\infty$, will compare with the available subsequent nodes value, i.e. min ($\infty, 3$) = 3, hence at node B now $\alpha = -\infty$, and $\beta = 3$.



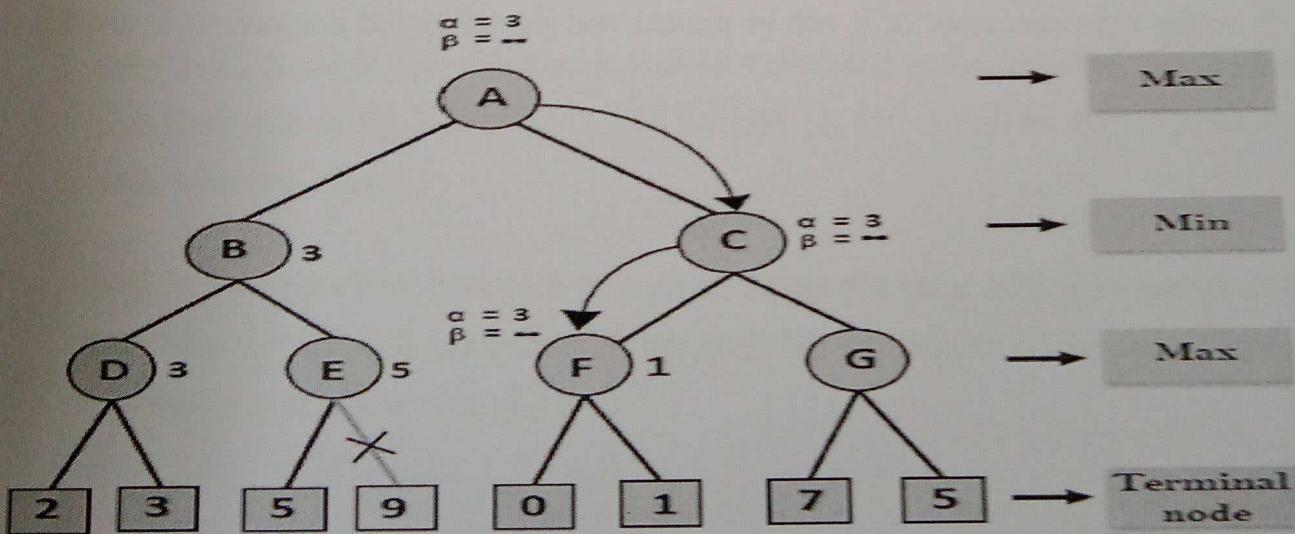
In the next step, algorithm traverse the next successor of Node B which is node E, and the values of $\alpha = -\infty$, and $\beta = 3$ will also be passed.

Step 4: At node E, Max will take its turn, and the value of alpha will change. The current value of alpha will be compared with 5, so $\max(-\infty, 5) = 5$, hence at node E $\alpha = 5$ and $\beta = 3$, where $\alpha \geq \beta$, so the right successor of E will be pruned, and algorithm will not traverse it, and the value at node E will be 5.

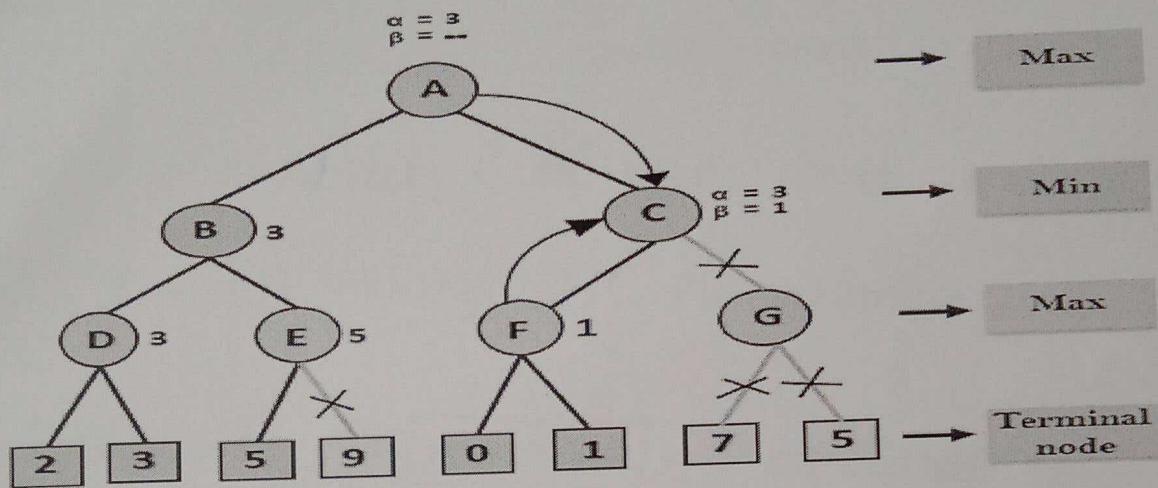


Step 5: At next step, algorithm again backtrack the tree, from node B to node A. At node A, the value of alpha will be changed the maximum available value is 3 as $\max(-\infty, 3) = 3$, and $\beta = +\infty$; these two values now passes to right successor of A which is Node C. At node C, $\alpha = 3$ and $\beta = +\infty$, and the same values will be passed on to node F.

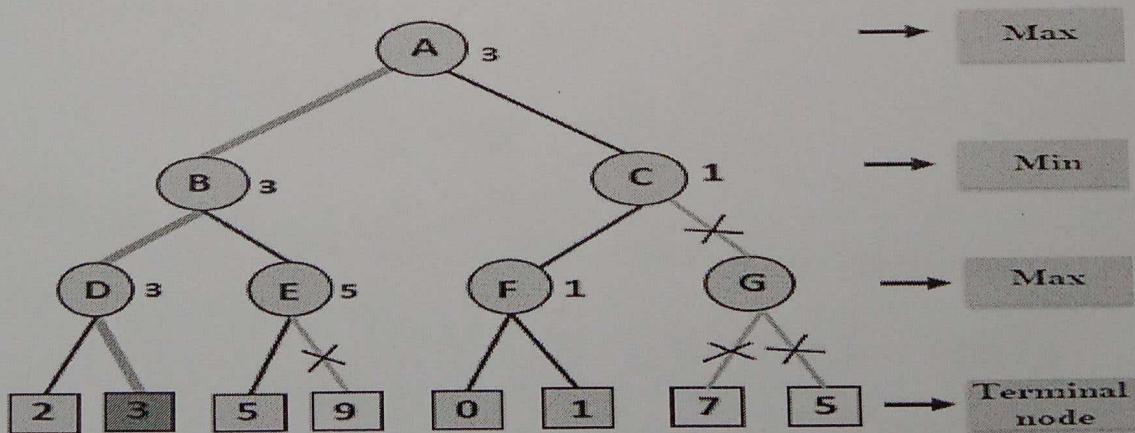
Step 6: At node F, again the value of α will be compared with left child which is 0, and $\max(3, 0) = 3$, and then compared with right child which is 1, and $\max(3, 1) = 3$ still α remains 3, but the node value of F will become 1.



Step 7: Node F returns the node value 1 to node C, at C $\alpha = 3$ and $\beta = +\infty$, here the value of beta will be changed, it will compare with 1 so $\min(\infty, 1) = 1$. Now at C, $\alpha = 3$ and $\beta = 1$, and again it satisfies the condition $\alpha \geq \beta$, so the next child of C which is G will be pruned, and the algorithm will not compute the entire sub-tree G.



Step 8: C now returns the value of 1 to A here the best value for A is $\max(3, 1) = 3$. Following is the final game tree which is showing the nodes which are computed and nodes which have never computed. Hence the optimal value for the maximizer is 3 for this example.



UNIT-II

Basic Knowledge Representation and Reasoning.

- give knowledge to machine, Agent $\xrightarrow{\text{mlc}}$
 $\nwarrow \text{s/w}$
program
- Knowledge \rightarrow facts, skills,
education, experience.
- Intelligent : Ability to use that knowledge
- Reasoning : Processing of knowledge

knowledge \rightarrow machine \rightarrow optimal o/p

- logic
 - ① propositional logic (True / False)
 - ② predicate logic (For all, there exist)
- propositional logic (PL)
 - ⓐ PL is the simplest logic
 - ⓑ A proposition is a declarative statement that is either true or false.
 - * propositional logic cannot predicate it can say either T or F

Basic elements.

Word	Symbol	example
not (negation)	\neg	$\neg A$
AND (conjunction)	\wedge	$A \wedge B$
OR (disjunction)	\vee	$A \vee B$
Implies (If then)	\rightarrow	$A \rightarrow B$
Iff (If and only if)	\leftrightarrow	$A \leftrightarrow B$

eg Today is Monday

take $P =$ Today is monday

$PL = \neg P$ (Today is not monday)

2. you should eat or watch mobile
at a time
q

$PL = P \vee R$

3. Please like my ^P video and subscribe
my channel
q

$PL = P \wedge q$

4. If there is rain then the roads
are wet
q

$P \rightarrow q$

I will go to mall iff I have to do shopping

$$PL = P \leftrightarrow q$$

eg

A \rightarrow It is hot

B \rightarrow It is humid

C \rightarrow It is raining

condition.

If it is humid then it is hot

$$PL : B \rightarrow A$$

If it is hot and humid then

It is not raining

$$A \wedge B \rightarrow \neg C$$

eg

Ram cannot play tennis

$$PL : \neg P$$

Ram can play tennis and badminton

$$PL : P \wedge Q$$

Ram can play tennis or badminton

$$PL : P \vee Q$$

Ram can play tennis if and only if he can play badminton

$$P \leftrightarrow Q$$

Predicate logic. also called First order logic (FOL)

Limitations of PL

- we can not represent relations like ALL, some with PL.
- PL has limited expressive power.
- In PL we cannot describe statements in terms of the properties or logical representations.
- In PL we can only represent the facts which are either true or false.

e.g. It is raining

But PL is not sufficiently expressive to represent the following stmts

Some humans are intelligent

All mangoes are sweet

Syntax

Function(term₁, term₂... term_n)

predicate(term₁, " ")

eg

i. Sam is tall

↓ ↓
Subject Predicate FOL: tall(Sam)
Object

2. Ram is a Student

O

P

Student (Ram)

3. Shyam is a teacher

O

P

teacher (Shyam)

4. John likes cricket

O

P

O

likes (John, cricket)

5. Ram takes either maths or Bio

O

P

O

O

takes (Ram, maths) \vee Takes (Ram, Bio)

b. Ram takes Bio if and only if Ram doesn't take maths

Takes (Ram, Bio) \leftrightarrow \neg take (Ram, math)

Elements of FOL

Constant : 1, 2, A, John, eat

Variable : x, y, z, a, b, e

Predicates : greater (5, 3)

Function : mother of (John),
colour of (Basket)

Connectives : $\wedge \vee \neg \rightarrow \leftrightarrow$

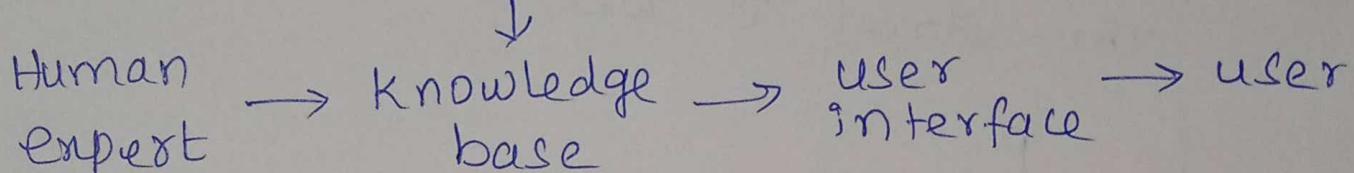
Quantifier : \forall, \exists

Forward chaining and Backward chaining

Inference Engine

- Rule based expert system
- Applies rules
- Add new knowledge to knowledge Base
- Resolve Rule conflicts.

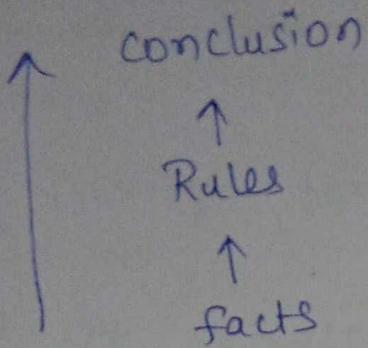
Inference engine (rules)



- It applies logical rules to the knowledge base to infer new information from known facts

Forward chaining

- Forward chaining starts with the available data and uses inference rules to extract more data until a goal is reached.
- What will happen next?
- It is a bottom up approach.
- Forward chaining is data driven because the reasoning starts from a set of data

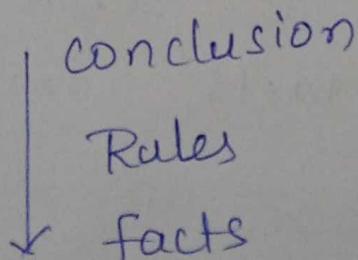


e.g. It is raining
 If it is raining then street is wet
 The street is wet

$$\begin{array}{c} p \\ p \rightarrow q \\ q \end{array}$$

Backward Chaining

- Backward chaining proceeds backward rules that match the goal
- why did this happen?
- IE is top down approach
- Backward chaining is goal driven
- eg. diagnose bacterial infection



e.g. The street is wet
 If it is raining then street is wet
 It is raining

$$\begin{array}{c} q \\ p \rightarrow q \\ p \end{array}$$

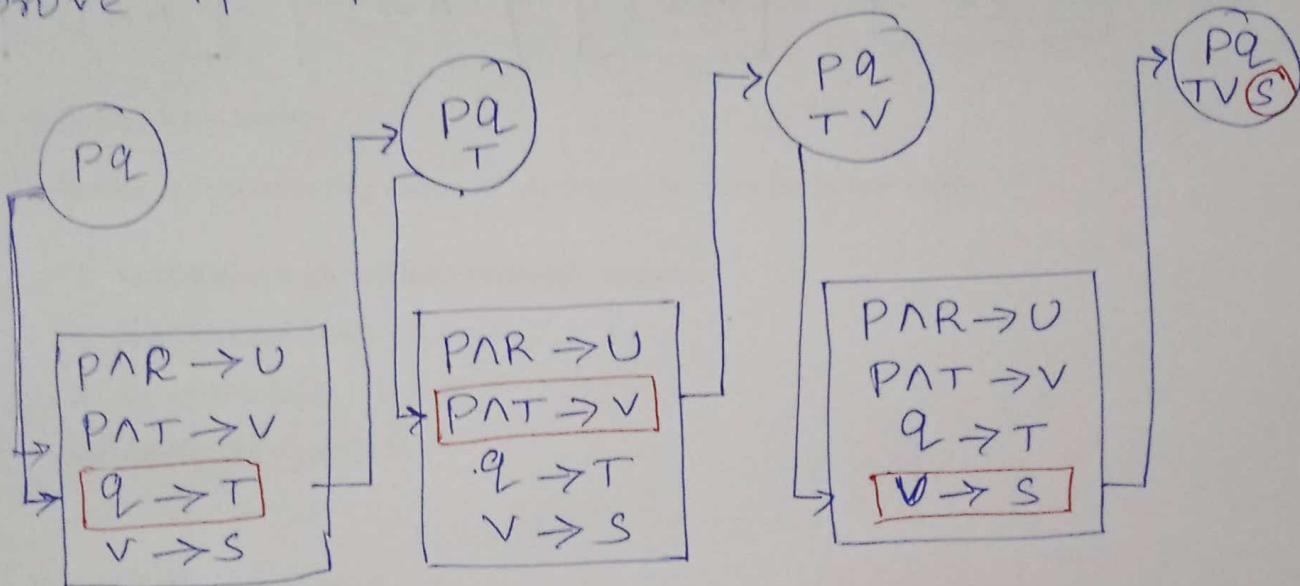
eg2

Database : PQ

Rules

1. If P and R then U $P \wedge R \rightarrow U$
- If P and T then V $P \wedge T \rightarrow V$
- If Q then T $Q \rightarrow T$
- If V then S $V \rightarrow S$

prove if P and Q true then $P \wedge Q \rightarrow S$



eg2

goal state : Z

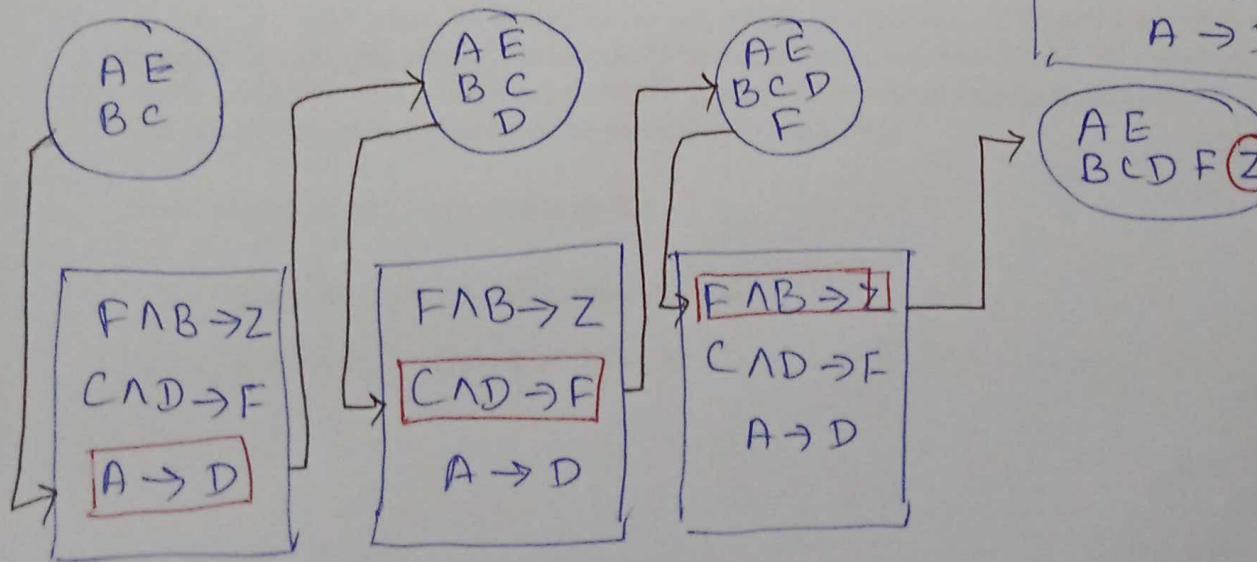
terminal condition

facts $\rightarrow A E B C$

Rules

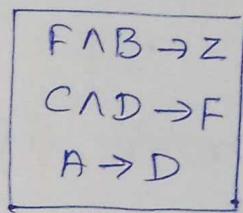
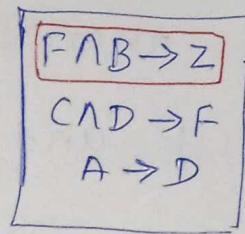
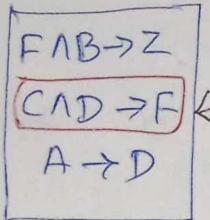
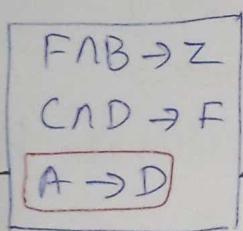
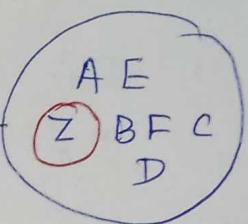
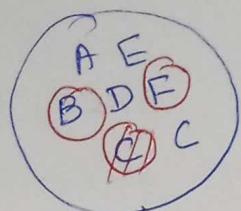
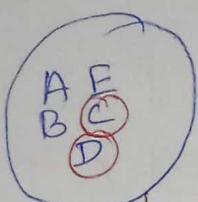
stop if Z is derived

$F \wedge B \rightarrow Z$
$C \wedge D \rightarrow F$
$A \rightarrow D$



Backward chaining

eg



Probabilistic reasoning in Artificial intelligence

Uncertainty:

Till now, we have learned knowledge representation using first-order logic and propositional logic with certainty, which means we were sure about the predicates. With this knowledge representation, we might write $A \rightarrow B$, which means if A is true then B is true, but consider a situation where we are not sure about whether A is true or not then we cannot express this statement, this situation is called uncertainty.

So to represent uncertain knowledge, where we are not sure about the predicates, we need uncertain reasoning or probabilistic reasoning.)

Causes of uncertainty:

Following are some leading causes of uncertainty to occur in the real world.

1. Information occurred from unreliable sources.
2. Experimental Errors
3. Equipment fault
4. Temperature variation
5. Climate change.

Probabilistic reasoning:

Probabilistic reasoning is a way of knowledge representation where we apply the concept of probability to indicate the uncertainty in knowledge. In probabilistic reasoning, we combine probability theory with logic to handle the uncertainty.)

We use probability in probabilistic reasoning because it provides a way to handle the uncertainty that is the result of someone's laziness and ignorance.

In the real world, there are lots of scenarios, where the certainty of something is not confirmed, such as "It will rain today," "behavior of someone for some situations," "A match between two teams or two players." These are probable sentences for which we can assume that it will happen but not sure about it, so here we use probabilistic reasoning.

Need of probabilistic reasoning in AI:

- o When there are unpredictable outcomes.
- o When specifications or possibilities of predicates becomes too large to handle.

- o When an unknown error occurs during an experiment.

In probabilistic reasoning, there are two ways to solve problems with uncertain knowledge:

Bayes' rule

Bayesian Statistics

As probabilistic reasoning uses probability and related terms, so before understanding probabilistic reasoning, let's understand some common terms:

Probability: Probability can be defined as a chance that an uncertain event will occur. It is the numerical measure of the likelihood that an event will occur. (The value of probability always remains between 0 and 1 that represent ideal uncertainties.)

$0 \leq P(A) \leq 1$, where $P(A)$ is the probability of an event A.

$P(A) = 0$, indicates total uncertainty in an event A.

$P(A) = 1$, indicates total certainty in an event A.

We can find the probability of an uncertain event by using the below formula.

$$\text{Probability of occurrence} = \frac{\text{Number of desired outcomes}}{\text{Total number of outcomes}}$$

- o $P(\neg A)$ = probability of a not happening event.
- o $P(\neg A) + P(A) = 1$.

Event: Each possible outcome of a variable is called an event.

Sample space: The collection of all possible events is called sample space.

Random variables: Random variables are used to represent the events and objects in the real world.

Prior probability: The prior probability of an event is probability computed before observing new information.

Posterior Probability: The probability that is calculated after all evidence or information has taken into account. It is a combination of prior probability and new information.

Conditional probability:

Conditional probability is a probability of occurring an event when another event has already happened.

Let's suppose, we want to calculate the event A when event B has already occurred, "the probability of A under the conditions of B", it can be written as:

$$P(A|B) = \frac{P(A \wedge B)}{P(B)}$$

Where $P(A \wedge B)$ = Joint probability of A and B

$P(B)$ = Marginal probability of B.

If the probability of A is given and we need to find the probability of B, then it will be given as:

$$P(B|A) = \frac{P(A \wedge B)}{P(A)}$$

It can be explained by using the below Venn diagram, where B is occurred event, so sample space will be reduced to set B, and now we can only calculate event A when event B is already occurred by dividing the probability of $P(A \wedge B)$ by $P(B)$.

Example:

In a class, there are 70% of the students who like English and 40% of the students who likes English and mathematics, and then what is the percent of students those who like English also like mathematics?

Solution:

Let, A is an event that a student likes Mathematics

B is an event that a student likes English.

$$P(A|B) = \frac{P(A \wedge B)}{P(B)} = \frac{0.4}{0.7} = 57\%$$

Hence, 57% are the students who like English also like Mathematics.

Bayes' theorem in Artificial intelligence

Bayes' theorem:

Bayes' theorem is also known as **Bayes' rule**, **Bayes' law**, or **Bayesian reasoning**, which determines the probability of an event with uncertain knowledge.

In probability theory, it relates the conditional probability and marginal probabilities of two random events.

Bayes' theorem was named after the British mathematician **Thomas Bayes**. The **Bayesian inference** is an application of Bayes' theorem, which is fundamental to Bayesian statistics.

It is a way to calculate the value of $P(B|A)$ with the knowledge of $P(A|B)$.

Bayes' theorem allows updating the probability prediction of an event by observing new information of the real world.

Example: If cancer corresponds to one's age then by using Bayes' theorem, we can determine the probability of cancer more accurately with the help of age.

Bayes' theorem can be derived using product rule and conditional probability of event A with known event B:

As from product rule we can write:

$$P(A \wedge B) = P(A|B) P(B) \text{ or}$$

Similarly, the probability of event B with known event A:

$$P(A \wedge B) = P(B|A) P(A)$$

Equating right hand side of both the equations, we will get:

$$P(A|B) = \frac{P(B|A) P(A)}{P(B)} \quad \dots(a)$$

The above equation (a) is called as **Bayes' rule** or **Bayes' theorem**. This equation is basic of most modern AI systems for **probabilistic inference**.

It shows the simple relationship between joint and conditional probabilities. Here,

$P(A|B)$ is known as **posterior**, which we need to calculate, and it will be read as Probability of hypothesis A when we have occurred an evidence B.

$P(B|A)$ is called the likelihood, in which we consider that hypothesis is true, then we calculate the probability of evidence.

$P(A)$ is called the **prior probability**, probability of hypothesis before considering the evidence

$P(B)$ is called **marginal probability**, pure probability of an evidence.

In the equation (a), in general, we can write $P(B) = P(A)*P(B|A_i)$, hence the Bayes' rule can be written as:

$$P(A_i | B) = \frac{P(A_i) * P(B|A_i)}{\sum_{i=1}^k P(A_i) * P(B|A_i)}$$

Where $A_1, A_2, A_3, \dots, A_n$ is a set of mutually exclusive and exhaustive events.

Applying Bayes' rule:

Bayes' rule allows us to compute the single term $P(B|A)$ in terms of $P(A|B)$, $P(B)$, and $P(A)$. This is very useful in cases where we have a good probability of these three terms and want to determine the fourth one. Suppose we want to perceive the effect of some unknown cause, and want to compute that cause, then the Bayes' rule becomes:

$$P(\text{cause} | \text{effect}) = \frac{P(\text{effect} | \text{cause}) P(\text{cause})}{P(\text{effect})}$$

Example-1:

Question: what is the probability that a patient has disease meningitis with a stiff neck?

Given Data:

A doctor is aware that disease meningitis causes a patient to have a stiff neck, and it occurs 80% of the time. He is also aware of some more facts, which are given as follows:

- The Known probability that a patient has meningitis disease is 1/30,000.
- The Known probability that a patient has a stiff neck is 2%.

Let a be the proposition that patient has stiff neck and b be the proposition that patient has meningitis. , so we can calculate the following as:

$$P(a|b) = 0.8$$

$$P(b) = 1/30000$$

$$P(a) = .02$$

$$P(b|a) = \frac{P(a|b)P(b)}{P(a)} = \frac{0.8 * (\frac{1}{30000})}{0.02} = 0.001333333.$$

Hence, we can assume that 1 patient out of 750 patients has meningitis disease with a stiff neck.

Application of Bayes' theorem in Artificial intelligence:

Following are some applications of Bayes' theorem:

- It is used to calculate the next step of the robot when the already executed step is given.
- Bayes' theorem is helpful in weather forecasting.
- It can solve the Monty Hall problem.