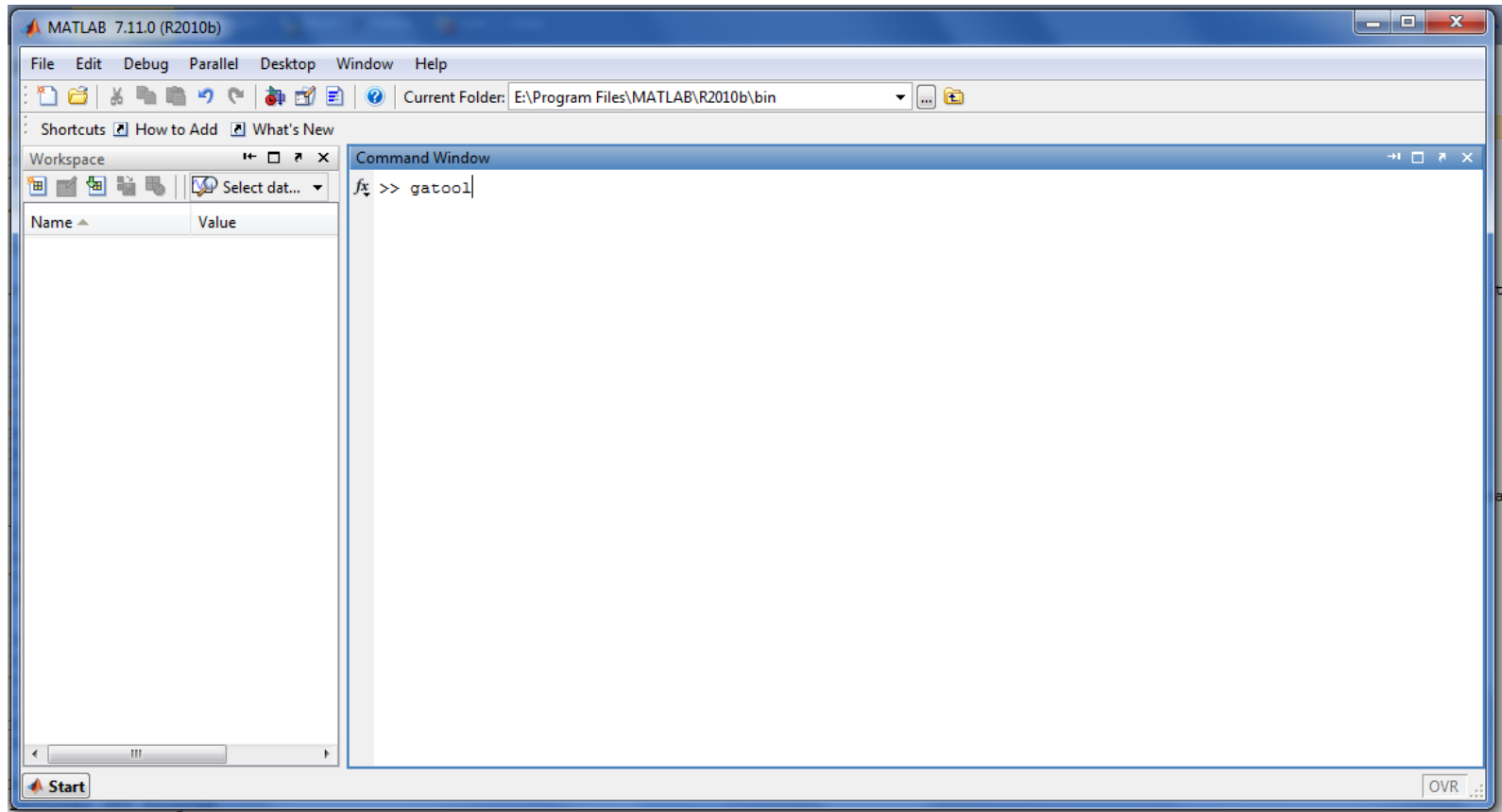


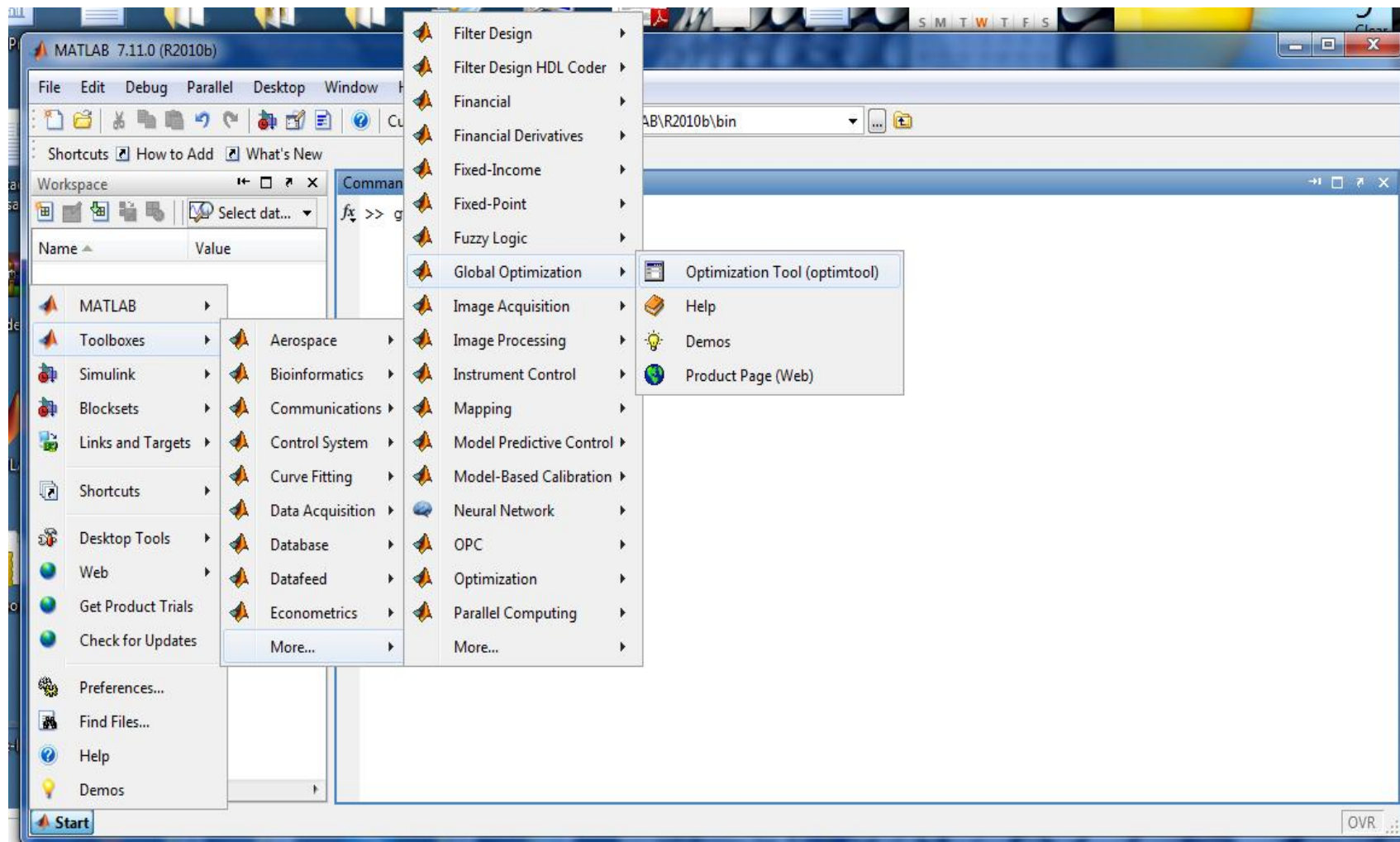
Tutorial on Genetic Algorithm

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- Type in “gatool” in the command window



- OR



Optimization Tool

File Help

Problem Setup and Results

Solver: **ga - Genetic Algorithm**

Problem

Fitness function:

Number of variables:

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Current iteration:

Final point:

Options

Population

Population type:

Population size: ☒ Use default: 20 ☐ Specify:

Creation function:

Initial population: ☒ Use default: [] ☐ Specify:

Initial scores: ☒ Use default: [] ☐ Specify:

Initial range: ☒ Use default: [0;1] ☐ Specify:

Fitness scaling

Scaling function:

Selection

Selection function:

Quick Reference

Genetic Algorithm Solver

This tool corresponds to the ga function.

Click to expand the section below corresponding to your task.

Problem Setup and Results

- [Problem](#)
- [Constraints](#)
- [Run solver and view results](#)

Options

Specify options for the Genetic Algorithm solver.

- [Population](#)
- [Fitness scaling](#)
- [Selection](#)
- [Reproduction](#)
- [Mutation](#)
- [Crossover](#)
- [Migration](#)
- [Constraint parameters](#)

Example 1 : Ackley Function

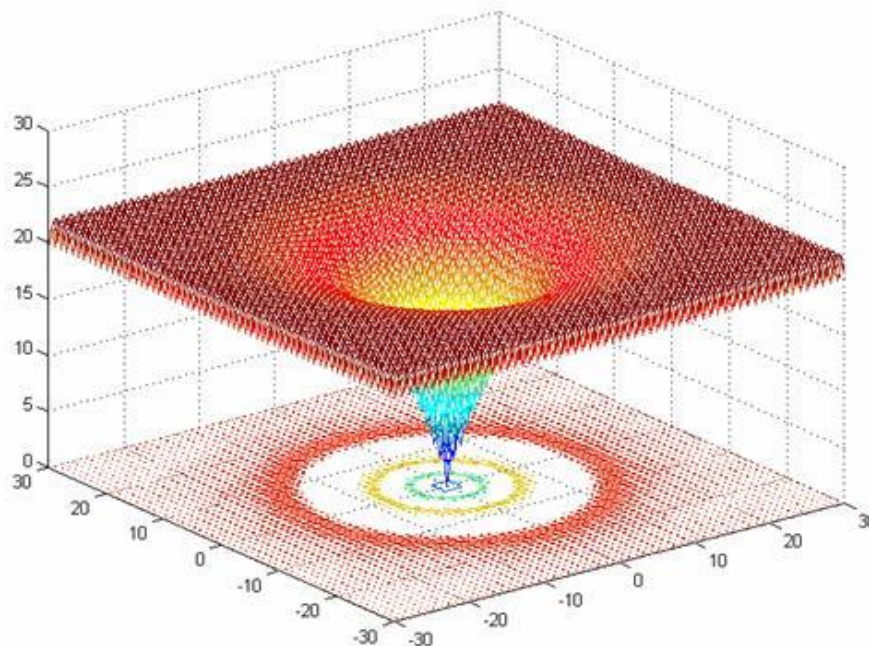
- $$f(x, y) = \frac{1}{20} \left\{ -20 \times e \left[-0.2 \sqrt{\frac{1}{2} (x^2 + y^2)} \right] - e \left[\frac{1}{2} (\cos(cx) + \cos(cy)) \right] + 20 + e + 5.7 \right\}$$
- Number of variables: can be 'n' variables.
- Search domain: $-15 \leq x_i \leq 30, i = 1, 2, \dots, n$.
- Number of local minima: several local minima.
- The global minimum: $\mathbf{x}^* = (0, \dots, 0), f(\mathbf{x}^*) = 0$.

Ackley Function

Function graph: for $n = 2$.

MATLAB CODE :

```
function z = ft_ackley(in)
    a = 20; b = 0.2; c = 2*pi; d = 5.7; f = 0.8;
    n = 2;
    x = in(:,1); y = in(:,2);
    z = (1/f)*( -a*exp(-b*sqrt((1/n)*(x.^2+y.^2))) - exp((1/n)*(cos(c*x) + cos(c*y))) + a + exp(1) + d);
```



Using the gatool

Problem Setup and Results

Solver:

Problem
Fitness function:
Number of variables:

Constraints:
Linear inequalities: A: b:
Linear equalities: Aeq: beq:
Bounds: Lower: Upper:
Nonlinear constraint function:

Run solver and view results
☐ Use random states from previous run

Current iteration:

Optimization running.
Objective function value: 7.2600498236760895
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | |
|-------|-------|
| 1 | 2 |
| 0.028 | -0.01 |

Options

☐ Population
Population type:
Population size: ☒ Use default: 20
☐ Specify:
Creation function:

Initial population: ☒ Use default: []
☐ Specify:

Initial scores: ☒ Use default: []
☐ Specify:

Initial range: ☒ Use default: [0;1]
☐ Specify:

☐ Fitness scaling
Scaling function:

☐ Selection
Selection function:

☐ Reproduction
Elite count: ☒ Use default: 2

Quick Reference

Genetic Algorithm Solver
This tool corresponds to the ga function.

Click to expand the section below corresponding to your task.

Problem Setup and Results
[▶ Problem](#)
[▶ Constraints](#)
[▶ Run solver and view results](#)

Options
Specify options for the Genetic Algorithm solver.
[▶ Population](#)
[▶ Fitness scaling](#)
[▶ Selection](#)
[▶ Reproduction](#)
[▶ Mutation](#)
[▶ Crossover](#)
[▶ Migration](#)
[▶ Constraint parameters](#)
[▶ Hybrid function](#)
[▶ Stopping criteria](#)
[▶ Plot Functions](#)

You can customize your solution by manipulating the “Option Menu”

The screenshot displays the Genetic Algorithm Solver interface, divided into three main sections: Problem Setup and Results, Options, and Quick Reference.

Problem Setup and Results:

- Solver: **ga - Genetic Algorithm**
- Problem:
 - Fitness function: **@ft_ackley** (circled in red)
 - Number of variables: **2**
- Constraints:
 - Linear inequalities: A: b:
 - Linear equalities: Aeq: beq:
 - Bounds: Lower: Upper:
 - Nonlinear constraint function:
- Run solver and view results:
 - ☐ Use random states from previous run
 - Start** (circled in red), **Pause**, **Stop**
 - Current iteration: **51** (circled in red)
 - Clear Results**
- Optimization running:
 - Objective function value: 7.2600498236760895
 - Optimization terminated: average change in the fitness value less than options.TolFun.
- Final point:** (highlighted with a red box)

| | 1 | 2 |
|--|-------|-------|
| | 0.028 | -0.01 |

Options: (indicated by a red arrow)

- Population:**
 - Population type: **Double vector**
 - Population size: ☒ Use default: 20
☐ Specify:
 - Creation function: **Constraint dependent**
- Initial population:** ☒ Use default: []
☐ Specify:
- Initial scores:** ☒ Use default: []
☐ Specify:
- Initial range:** ☒ Use default: [0;1]
☐ Specify:
- Fitness scaling:**
 - Scaling function: **Rank**
- Selection:**
 - Selection function: **Stochastic uniform**
- Reproduction:**
 - Elite count: ☒ Use default: 2

Quick Reference:

- Genetic Algorithm Solver**
This tool corresponds to the ga function.
- Click to expand the section below corresponding to your task.
- Problem Setup and Results**
 - [Problem](#)
 - [Constraints](#)
 - [Run solver and view results](#)
- Options**
Specify options for the Genetic Algorithm solver.
 - [Population](#)
 - [Fitness scaling](#)
 - [Selection](#)
 - [Reproduction](#)
 - [Mutation](#)
 - [Crossover](#)
 - [Migration](#)
 - [Constraint parameters](#)
 - [Hybrid function](#)
 - [Stopping criteria](#)
 - [Plot Functions](#)

For example plotting the fitness function

Problem Setup and Results

Solver: **ga - Genetic Algorithm**

Problem

Fitness function: **@ft_ackley**

Number of variables: **2**

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Start **Pause** **Stop**

Current iteration: **51** **Clear Results**

Optimization running.
Objective function value: 7.132680531213246
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | 1 | 2 |
|--|-------|-------|
| | 0.001 | 0.002 |

Options

Stall time limit: ☐ Specify:
☒ Use default: Inf

Function tolerance: ☒ Use default: 1e-6
☐ Specify:

Nonlinear constraint tolerance: ☒ Use default: 1e-6
☐ Specify:

Plot functions

Plot interval: **1**

☒ **Best fitness** ☐ Best individual ☐ Distance
☐ Expectation ☐ Genealogy ☐ Range
☐ Score diversity ☐ Scores ☐ Selection
☐ Stopping ☐ Max constraint
☐ Custom function:

Output function

☐ History to new window Interval: **1**
☐ Custom function:

Display to command window

Level of display: **off**

User function evaluation

Evaluate fitness and constraint functions: **in serial**

Solver: **ga - Genetic Algorithm**

Problem

Fitness function: **@ft_ackley**

Number of variables: **2**

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Start

Pause

Stop

Current iteration: **51**

Clear Results

Optimization running.
Objective function value: 7.132680531213246
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | |
|-------|-------|
| 1 | 2 |
| 0.001 | 0.002 |

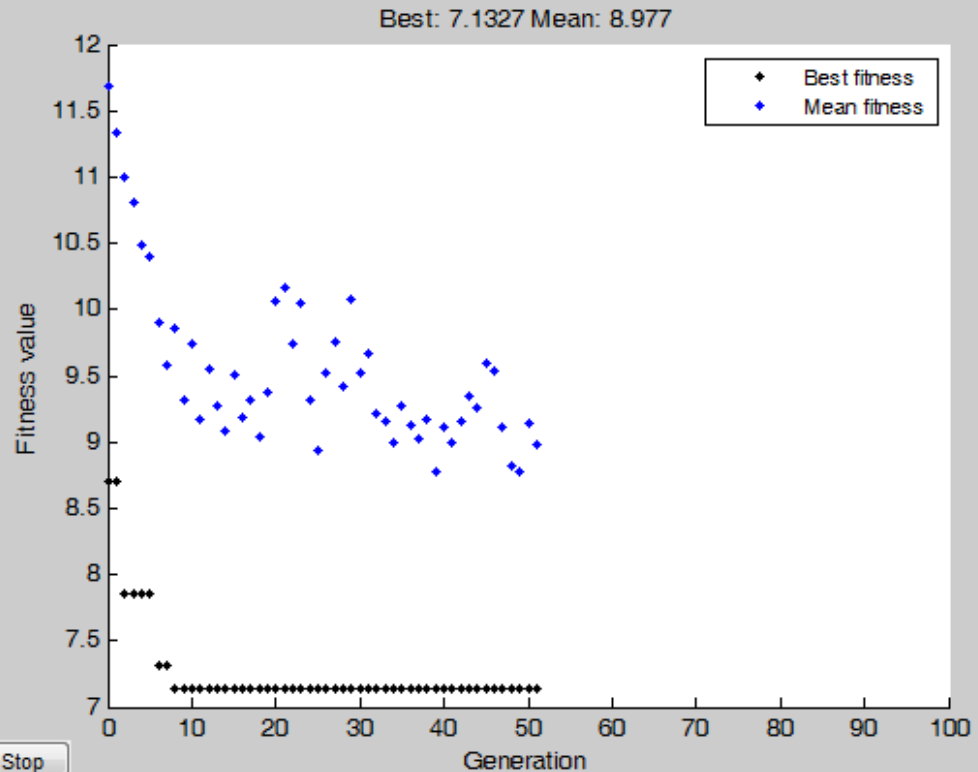
Stall time limit:

☐ Specify:

☒ Use default: Inf

Genetic Algorithm

File Edit View Insert Tools Desktop Window Help



Level of display: **off**

☐ User function evaluation

Evaluate fitness and constraint functions: **in serial**

Genetic Algorithm Solver

This tool corresponds to the Genetic Algorithm Solver in the MATLAB Optimization Toolbox.

- ▶ [Constraint parameters](#)
- ▶ [Hybrid function](#)
- ▶ [Stopping criteria](#)

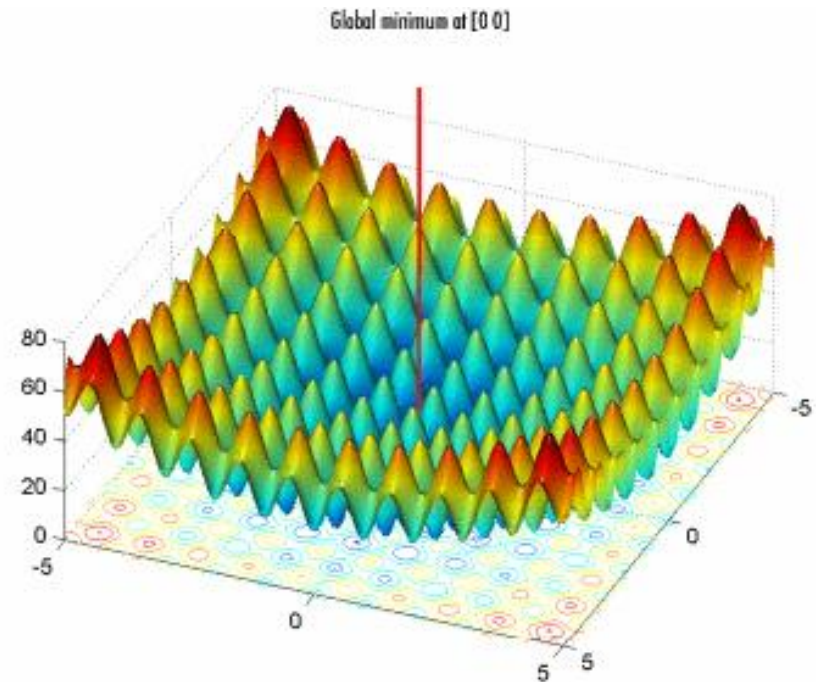
Example 2: Rastrigin's Function

- - $Ras(x) = 20 + x_1^2 + x_2^2 - 10(\cos 2\pi x_1 + \cos 2\pi x_2)$
 - Number of variables: n variables.
 - Search domain: $-5.12 \leq x_i \leq 5.12, i = 1, 2, \dots, n$.
 - Number of local minima: several local minima.
 - The global minima: $x^* = (0, \dots, 0), f(x^*) = 0$.

- **MATLAB Code:**

- `function y = rast(x)`
- `% The default value of n = 2.`
- `n = 2;`
- `s = 0;`
- `for j = 1:n`
- `s = s+(x(j)^2-10*cos(2*pi*x(j)));`
- `end`
- `y = 10*n+s;`

Function graph for n = 2



Problem Setup and Results

Solver:

Problem

Fitness function:

Number of variables:

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Current iteration:

Optimization running.
Objective function value: 0.0036087266888031877
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | |
|-------|---|
| 1 | 2 |
| 0.004 | 0 |

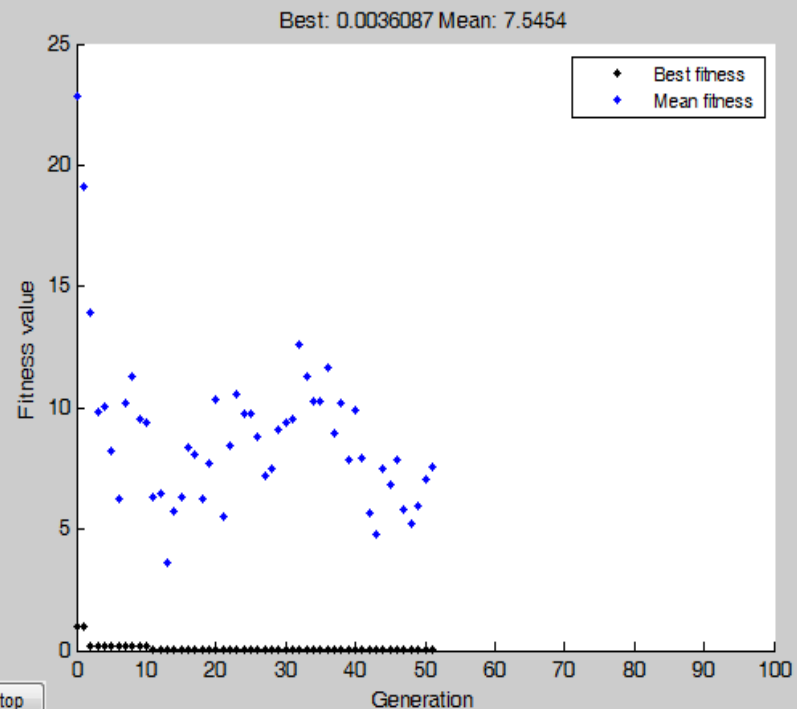
Options

☐ Specify:

Stall time limit: ☒ Use default: Inf

Genetic Algorithm

File Edit View Insert Tools Desktop Window Help



Level of display:

☒ User function evaluation

Evaluate fitness and constraint functions:

Quick Reference

Genetic Algorithm Solver

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► [Constraint parameter:](#)

► [Hybrid function](#)

► [Stopping criteria](#)

Example 3: Sum Squares Function

-

$$f(x) = \sum_{i=1}^n x_i^2$$

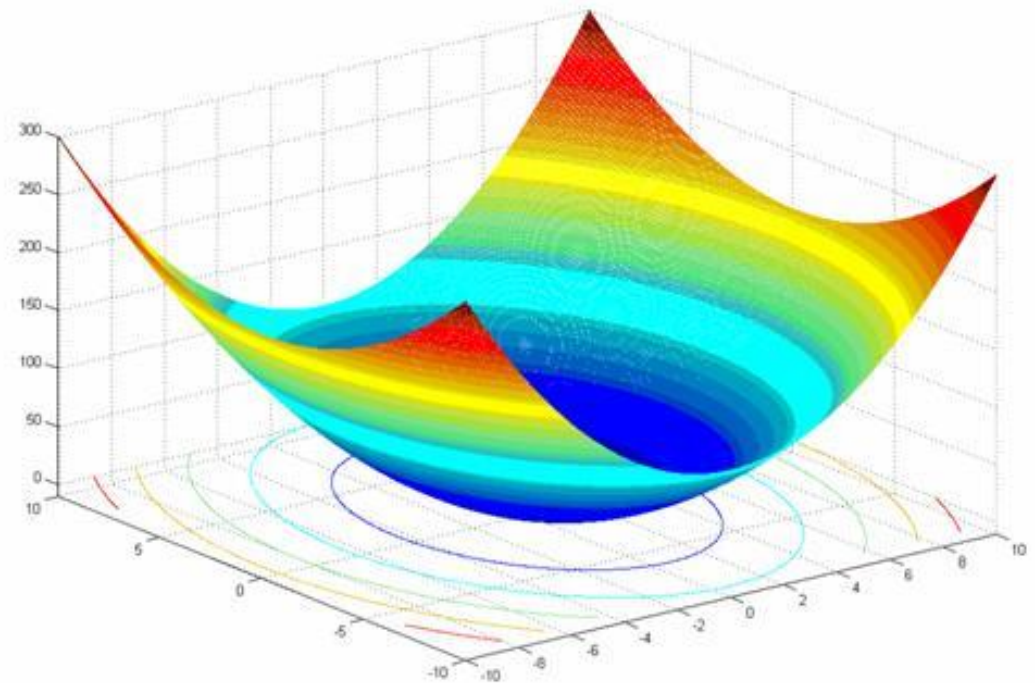
- Number of variables = 'n' variables
- Number of local minima: no local minimum except the global one.
- The global minima: $x^* = (0, \dots, 0)$, $f(x^*) = 0$.

- Matlab Code:

```
function y = sum2(x)
% The default value of n = 15.
n = 15;
s = 0;
for j = 1:n
    s=s+j*x(j)^2;
end

y = s;
```

Function Graph for n =15



Best Fitness:

Problem Setup and Results

Solver: ga - Genetic Algorithm

Problem

Fitness function: @sum2

Number of variables: 15

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Start

Pause

Stop

Current iteration: 55

Clear Results

Optimization running.
Objective function value: 2.4754498713922684
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | | | | | | | | | | | | | | |
|-------|-------|-------|-------|------|-------|-------|-------|-------|-------|------|-------|------|-------|------|
| ... | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| 0.... | -0... | 0.... | 0.... | -... | 0.... | 0.... | 0.... | 0.... | 0.... | -... | 0.... | -... | 0.... | -... |

Options

☐ Specify:

Stall time limit: ☒ Use default: Inf

☐ Specify:

Function tolerance: ☒ Use default: 1e-6

☐ Specify:

Nonlinear constraint tolerance: ☒ Use default: 1e-6

☐ Specify:

Plot functions

Plot interval: 1

☒ Best fitness ☐ Best individual ☐ Distance

☐ Expectation ☐ Genealogy ☐ Range

☐ Score diversity ☐ Scores ☐ Selection

☐ Stopping ☐ Max constraint

☐ Custom function:

Output function

☐ History to new window Interval: 1

☐ Custom function:

Display to command window

Level of display: off

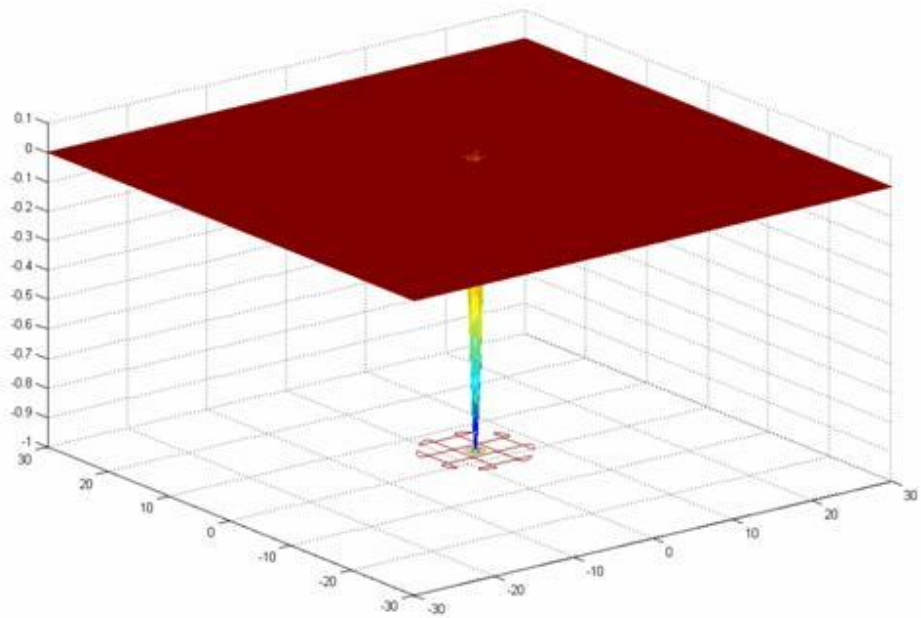
User function evaluation

Evaluate fitness and constraint functions: in serial

Example 4: Easom Function:

-
- $f(x) = -\cos x_1 \cos x_2 \exp(-(x_1 - \pi)^2 - (x_2 - \pi)^2)$
- Number of variables: $n = 2$.
- Number of local minima: several local minima.
- The global minima: $x^* = (\pi, \pi), f(x^*) = -1$.

- **Matlab Code:**
- `function y = easom(x)`
- `% Easom function`
- `%The number of variables n = 2.`
- `y = -cos(x(1))*cos(x(2))*exp(-(x(1)-pi)^2-(x(2)-pi)^2);`



Best Fitness

Solver:

Problem

Fitness function:

Number of variables:

Constraints:

Linear inequalities: A: b:

Linear equalities: Aeq: beq:

Bounds: Lower: Upper:

Nonlinear constraint function:

Run solver and view results

☐ Use random states from previous run

Current iteration:

Optimization running.
Objective function value: -0.9991866665365163
Optimization terminated: average change in the fitness value less than options.TolFun.

Final point:

| | |
|-------|-------|
| 1 | 2 |
| 3.138 | 3.119 |

