

# GATE 2023[IN]-36

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## Question:

The impulse response of an LTI system is  $h(t) = \delta(t) + 0.5\delta(t - 4)$ , where  $\delta(t)$  is continuous-time unit impulse signal. If the input signal  $x(t) = \cos\left(\frac{7\pi t}{4}\right)$ , the output is

## Solution:

Variable	Description	value
$\delta(t)$	continuous-time unit impulse signal	1 if $t=0$ ; 0 in other cases
$h(t)$	impulse response	$\delta(t) + 0.5\delta(t - 4)$
$x(t)$	input signal	$x(t) = \cos\left(\frac{7\pi t}{4}\right)$
$y(t)$	output signal	$x(t) * h(t)$

TABLE I

A TABLE WITH INPUT PARAMETERS

from Table I

$$y(t) = x(t) * h(t) \quad (1)$$

$$= \cos\left(\frac{7\pi t}{4}\right) + 0.5\cos\left(\frac{7\pi(t-4)}{4}\right) \quad (2)$$

$$= \cos\left(\frac{7\pi t}{4}\right) + 0.5\cos\left(\frac{7\pi t}{4} - 7\pi\right) \quad (3)$$

$$= 0.5\cos\left(\frac{7\pi t}{4}\right) \quad (4)$$