Eigenvectors and eigenvalues of a square matrix.

Pefin Let A be nxn square matrix

I in IR" is an eigenvector of A if $\vec{x} \neq \vec{0}$ and $\vec{A} = \vec{\lambda} \vec{x}$ for some $\vec{\lambda}$ in \vec{R}

X in IR is an eigenvalue of A if there is a non-tero rector x in 12" such that Ax= >x.

X is an eigenvector corresponding to A

 E_{XI} (i) $\bar{X} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is an eigenvector for $A = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$.

 $A = \begin{bmatrix} 2 & 2 & 3 \\ 2 & 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 4 & 4 \end{bmatrix} = 4 \begin{bmatrix} 1 & 3 \\ 4 & 3 \end{bmatrix} = 4 \begin{bmatrix} 1 & 3 \\ 4 & 3 \end{bmatrix}$

it corresponds to the eigenvalue >=4

 $\bar{x} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is an eigenventur for $A = \begin{bmatrix} 227 \\ -227 \end{bmatrix}$ $A \times = \begin{bmatrix} 2 & 2 & 1 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \underbrace{0 \cdot \times}_{-1} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} =$

(11)

 $\bar{\chi} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ Thus III eigenvector corresponding to eigentable $\lambda = 0$.

Note: eigenvalues con be equal to sero unlike eigenrectors

(Ex2) Is
$$\lambda = 3$$
 an eigenvalue for $A = [1,17]$? (2)

Does the equation A = 3Rephrase: have a non-zero solution?

$$= 2 \times 2 = 0 \quad |x_1| = |0| \quad 2 \times 1 - 4 \times 2 = 0$$

$$x_1 = 0 \quad |x_2| = |0| \quad 2 \times 1 - 4 \times 2 = 0$$

$$x_1 = 0 \quad |x_2| = |0| \quad 2 \times 1 - 4 \times 2 = 0$$

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$$x_2 = 0 \quad |x_2| = 0$$

$$x_3 = 0 \quad |x_3| = 0$$

$$x_4 = 0 \quad |x_4| =$$

Show that $\lambda = 4$ is an eigenvalue for A = [4-3]. Find all the eigenvoitors corresponding to >=4.

corresponding to
$$\lambda = 4$$
.

 $\lambda = 4$ is an eigenvalue \iff $A \times = 4 \times has$
 $\lambda = 4$ is an eigenvalue \iff $\lambda = 4 \times has$
 $\lambda = 4 \times$

$$A - 4I = \begin{bmatrix} 4 & -3 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} 0 & -3 \\ 0 & -3 \end{bmatrix}$$

$$-3 \times 1 = 0$$

$$-3 \times 2 = 0$$

$$\times 2 = 0$$

$$\times 1 = S \quad \text{Sin } \mathbb{R}$$

PORTANT CONCEPTUAL REMARK:

The following assertions are equivalent for A nxm

() A is an eigenxalue of A

(A -
$$\lambda$$
I) $\overline{x} = \overline{0}$

() A is a non-zero solution

() A is a non-zero solution

() A cet (A - λ I) $\overline{x} = \overline{0}$

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Say B (m×n) wakix Reminder When olves B==0 has only the WIVIA/ , 0= x N 102 dim (NN(B))=0 12NK (B) = M <u>(</u> B invertible (=)det (B) +0. (=)B= A-XI Apply purs to x in 12 3x=0 =) x=0 $\frac{1}{3} \cdot (3x) = \frac{1}{3} \cdot 0$ $(\frac{1}{3}, \frac{3}{3}) \times = \frac{1}{3} \cdot 0$ $(\frac{1}{3}, \frac{3}{3}) \times = \frac{1}{3} \cdot 0$ TX IN 12 M - A x = 5 A^{-1} . A = ISay A mxertible X C 5 . B= 1/18/201; (B) def(B) #0

The eigenvalues of a triangular Fact: matrix are the entries on the main diagonal.

diagonal.

$$E \times 4 \qquad A = \begin{bmatrix} -1 & 10 & 5 \\ 0 & 3 & 2 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{has rigenxalnes}$$

$$-1, 3, 1$$

$$E_{\frac{1}{2}} = \begin{bmatrix} -1 & 10 & 3 \\ 0 & 3 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & 10 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} -(-\lambda) & 10 & 5 \\ 0 & 3 - \lambda & 2 \\ 0 & 0 & 1 - \lambda \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} -(-\lambda) & 10 & 5 \\ 0 & 3 - \lambda & 2 \\ 0 & 0 & 1 - \lambda \end{bmatrix}$$

$$A - \lambda I = \begin{cases} 0 & 3 - \lambda \\ k & 0 & 0 \end{cases} (1 - \lambda)$$

$$det(k - \lambda I) = -(\lambda + 1)(3 - \lambda)(1 - \lambda)$$

$$det(k - \lambda I) = 0 \end{cases}$$

$$(k - \lambda I) = 0 \end{cases}$$

 $det (t-\lambda I) = 0$

$$fank(+-\lambda I) = 0$$

$$fank(+-\lambda I) \leq 2$$

$$=) \quad \text{Nullity}(A-\lambda I) \geq 3-2 = 1$$

$$Thus \quad \text{There is } x \neq 0 \quad \text{s.t.} \quad (4-\lambda I)x = 1$$

Tuno prev is \$ \$ 5 s.t. (4-)[/x=0 X in Null (A-XI)

Two previous
$$\overline{X} \neq \overline{0}$$
 s.t. $(A-AL/X \geq 0)$

$$\overline{X} \text{ in } \text{Null}(A-\lambda I)$$

$$\overline{X} \neq \overline{0}.$$

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & 10 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & 10 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & 10 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

 $A - \lambda I = \begin{bmatrix} -1 - \lambda & 10 & 5 \\ 0 & 3 - \lambda & 2 \\ 2 & 0 & 0 & 1 - \lambda \end{bmatrix}$

Find $\frac{1}{2}$ basis of the eigenspace of $A = \begin{bmatrix} 60101 \\ 4360 \\ 2-180 \\ 3-365 \end{bmatrix}$ Ex5 corresponding to X=5 such thit all rectors X in 124 $A \times = J \times (A - SI) \times = \overline{0}$ Find a basis of Rephrase: $A - 5I = \begin{bmatrix} 1010 \\ 4-260 \\ 2-130 \\ 3-36^{3} \end{bmatrix} \text{ PRFF} \begin{bmatrix} 1010 \\ 01-10 \\ 0000 \end{bmatrix}$ NU (A -SI). nullim = 2rank = 2 X1 + X3=0 $x_3 = S$ $x_4 = t$ X2 - X3 = 0 73-(S) $\begin{bmatrix} \chi_1 \\ \chi_3 \\ \chi_4 \end{bmatrix} = S \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ $\Rightarrow 3513$ x4-(t)