constructed. A collection of D flip-flops sharing a common clock input is called a *register*. A register is often drawn as a flip-flop with multi-bit D and Q busses.

In Section 10.2.5 we will see that flip-flops may experience hold-time failures if the system has too much *clock skew*, i.e., if one flip-flop triggers early and another triggers late because of variations in clock arrival times. In industrial designs, a great deal of effort is devoted to timing simulations to catch hold-time problems. When design time is more important (e.g., in class projects), hold-time problems can be avoided altogether by distributing a two-phase nonoverlapping clock. Figure 1.33 shows the flip-flop clocked with two nonoverlapping phases. As long as the phases never overlap, at least one latch will be opaque at any given time and hold-time problems cannot occur.

1.5 CMOS Fabrication and Layout

Now that we can design logic gates and registers from transistors, let us consider how the transistors are built. Designers need to understand the physical implementation of circuits because it has a major impact on performance, power, and cost.

Transistors are fabricated on thin silicon wafers that serve as both a mechanical support and an electrical common point called the *substrate*. We can examine the physical layout of transistors from two perspectives. One is the top view, obtained by looking down on a wafer. The other is the cross-section, obtained by slicing the wafer through the middle of a transistor and looking at it edgewise. We begin by looking at the cross-section of a complete CMOS inverter. We then look at the top view of the same inverter and define a set of masks used to manufacture the different parts of the inverter. The size of the transistors and wires is set by the mask dimensions and is limited by the resolution of the manufacturing process. Continual advancements in this resolution have fueled the exponential growth of the semiconductor industry.

1.5.1 Inverter Cross-Section

Figure 1.34 shows a cross-section and corresponding schematic of an inverter. (See the inside front cover for a color cross-section.) In this diagram, the inverter is built on a p-type substrate. The pMOS transistor requires an n-type body region, so an n-well is diffused into the substrate in its vicinity. As described in Section 1.3, the nMOS transistor

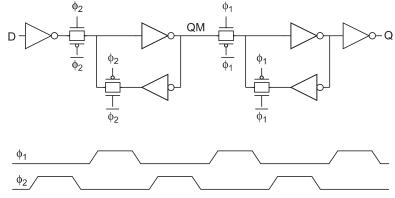


FIGURE 1.33 CMOS flip-flop with two-phase nonoverlapping clocks

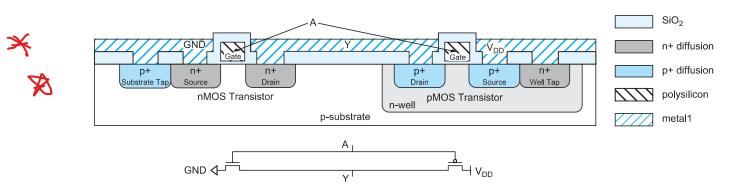


FIGURE 1.34 Inverter cross-section with well and substrate contacts. Color version on inside front cover.

has heavily doped n-type source and drain regions and a polysilicon gate over a thin layer of silicon dioxide (SiO₂, also called *gate oxide*). n+ and p+ diffusion regions indicate heavily doped n-type and p-type silicon. The pMOS transistor is a similar structure with p-type source and drain regions. The polysilicon gates of the two transistors are tied together somewhere off the page and form the input A. The source of the nMOS transistor is connected to a metal ground line and the source of the pMOS transistor is connected to a metal V_{DD} line. The drains of the two transistors are connected with metal to form the output Y. A thick layer of SiO₂ called *field oxide* prevents metal from shorting to other layers except where contacts are explicitly etched.

A junction between metal and a lightly doped semiconductor forms a *Schottky diode* that only carries current in one direction. When the semiconductor is doped more heavily, it forms a good ohmic contact with metal that provides low resistance for bidirectional current flow. The substrate must be tied to a low potential to avoid forward-biasing the p-n junction between the p-type substrate and the n+ nMOS source or drain. Likewise, the n-well must be tied to a high potential. This is done by adding heavily doped substrate and well contacts, or *taps*, to connect GND and V_{DD} to the substrate and n-well, respectively.



1.5.2 Fabrication Process

For all their complexity, chips are amazingly inexpensive because all the transistors and wires can be printed in much the same way as books. The fabrication sequence consists of a series of steps in which layers of the chip are defined through a process called *photolithography*. Because a whole wafer full of chips is processed in each step, the cost of the chip is proportional to the chip area, rather than the number of transistors. As manufacturing advances allow engineers to build smaller transistors and thus fit more in the same area, each transistor gets cheaper. Smaller transistors are also faster because electrons don't have to travel as far to get from the source to the drain, and they consume less energy because fewer electrons are needed to charge up the gates! This explains the remarkable trend for computers and electronics to become cheaper and more capable with each generation.

The inverter could be defined by a hypothetical set of six masks: n-well, polysilicon, n+ diffusion, p+ diffusion, contacts, and metal (for fabrication reasons discussed in Chapter 3, the actual mask set tends to be more elaborate). Masks specify where the components will be manufactured on the chip. Figure 1.35(a) shows a top view of the six masks. (See also the inside front cover for a color picture.) The cross-section of the inverter from Figure 1.34 was taken along the dashed line. Take some time to convince yourself how the top view and cross-section relate; this is critical to understanding chip layout.

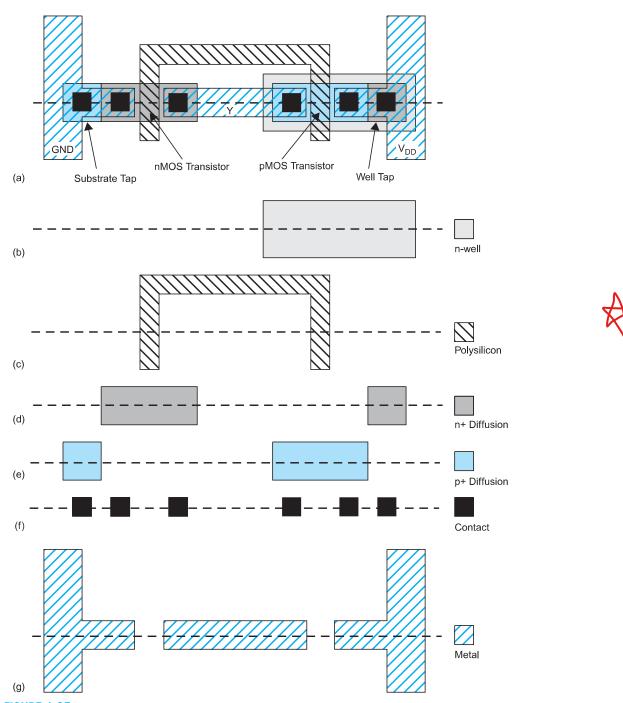


FIGURE 1.35 Inverter mask set. Color version on inside front cover.

Consider a simple fabrication process to illustrate the concept. The process begins with the creation of an n-well on a bare p-type silicon wafer. Figure 1.36 shows cross-sections of the wafer after each processing step involved in forming the n-well; Figure 1.36(a) illustrates the bare substrate before processing. Forming the n-well requires adding enough Group V dopants into the silicon substrate to change the substrate from p-type to n-type in the region of the well. To define what regions receive n-wells, we grow a protective layer of

oxide over the entire wafer, then remove it where we want the wells. We then add the ntype dopants; the dopants are blocked by the oxide, but enter the substrate and form the wells where there is no oxide. The next paragraph describes these steps in detail.

The wafer is first *oxidized* in a high-temperature (typically 900–1200 °C) furnace that causes Si and O_2 to react and become SiO_2 on the wafer surface (Figure 1.36(b)). The oxide must be *patterned* to define the n-well. An organic photoresist² that softens where

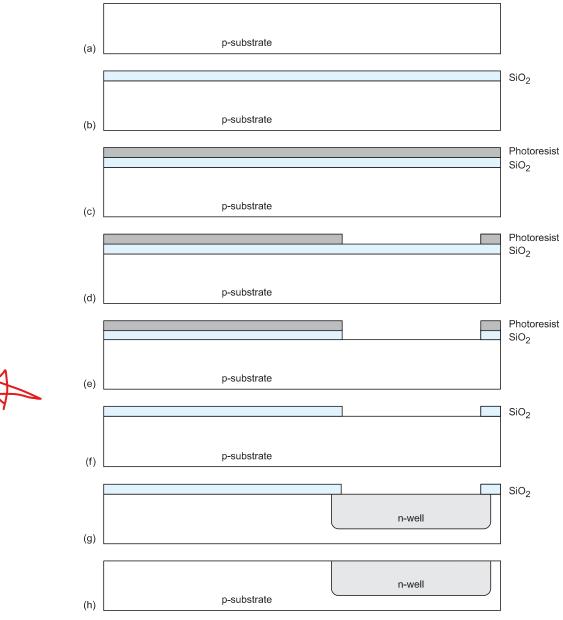


FIGURE 1.36 Cross-sections while manufacturing the n-well

²Engineers have experimented with many organic polymers for photoresists. In 1958, Brumford and Walker reported that Jello™ could be used for masking. They did extensive testing, observing that "various Jellos™ were evaluated with lemon giving the best result."

exposed to light is spun onto the wafer (Figure 1.36(c)). The photoresist is exposed through the n-well mask (Figure 1.35(b)) that allows light to pass through only where the well should be. The softened photoresist is removed to expose the oxide (Figure 1.36(d)). The oxide is etched with hydrofluoric acid (HF) where it is not protected by the photoresist (Figure 1.36(e)), then the remaining photoresist is stripped away using a mixture of acids called *piranha etch* (Figure 1.36(f)). The well is formed where the substrate is not covered with oxide. Two ways to add dopants are diffusion and ion implantation. In the *diffusion* process, the wafer is placed in a furnace with a gas containing the dopants. When heated, dopant atoms diffuse into the substrate. Notice how the well is wider than the hole in the oxide on account of *lateral* diffusion (Figure 1.36(g)). With *ion implantation*, dopant ions are accelerated through an electric field and blasted into the substrate. In either method, the oxide layer prevents dopant atoms from entering the substrate where no well is intended. Finally, the remaining oxide is stripped with HF to leave the bare wafer with wells in the appropriate places.

The transistor gates are formed next. These consist of polycrystalline silicon, generally called *polysilicon*, over a thin layer of oxide. The thin oxide is grown in a furnace. Then the wafer is placed in a reactor with silane gas (SiH₄) and heated again to grow the polysilicon layer through a process called *chemical vapor deposition*. The polysilicon is heavily doped to form a reasonably good conductor. The resulting cross-section is shown in Figure 1.37(a). As before, the wafer is patterned with photoresist and the polysilicon mask (Figure 1.35(c)), leaving the polysilicon gates atop the thin gate oxide (Figure 1.37(b)).

The n+ regions are introduced for the transistor active area and the well contact. As with the well, a protective layer of oxide is formed (Figure 1.37(c)) and patterned with the n-diffusion mask (Figure 1.35(d)) to expose the areas where the dopants are needed (Figure 1.37(d)). Although the n+ regions in Figure 1.37(e) are typically formed with ion implantation, they were historically diffused and thus still are often called *n-diffusion*. Notice that the polysilicon gate over the nMOS transistor blocks the diffusion so the source and drain are separated by a channel under the gate. This is called a *self-aligned* process because the source and drain of the transistor are automatically formed adjacent to the gate without the need to precisely align the masks. Finally, the protective oxide is stripped (Figure 1.37(f)).

The process is repeated for the p-diffusion mask (Figure 1.35(e)) to give the structure of Figure 1.38(a). Oxide is used for masking in the same way, and thus is not shown. The field oxide is grown to insulate the wafer from metal and patterned with the contact mask (Figure 1.35(f)) to leave contact cuts where metal should attach to diffusion or polysilicon (Figure 1.38(b)). Finally, aluminum is sputtered over the entire wafer, filling the contact cuts as well. Sputtering involves blasting aluminum into a vapor that evenly coats the wafer. The metal is patterned with the metal mask (Figure 1.35(g)) and plasma etched to remove metal everywhere except where wires should remain (Figure 1.38(c)). This completes the simple fabrication process.

Modern fabrication sequences are more elaborate because they must create complex doping profiles around the channel of the transistor and print features that are smaller than the wavelength of the light being used in lithography. However, masks for these elaborations can be automatically generated from the simple set of masks we have just examined. Modern processes also have 5–10+ layers of metal, so the metal and contact steps must be repeated for each layer. Chip manufacturing has become a commodity, and many different foundries will build designs from a basic set of masks.



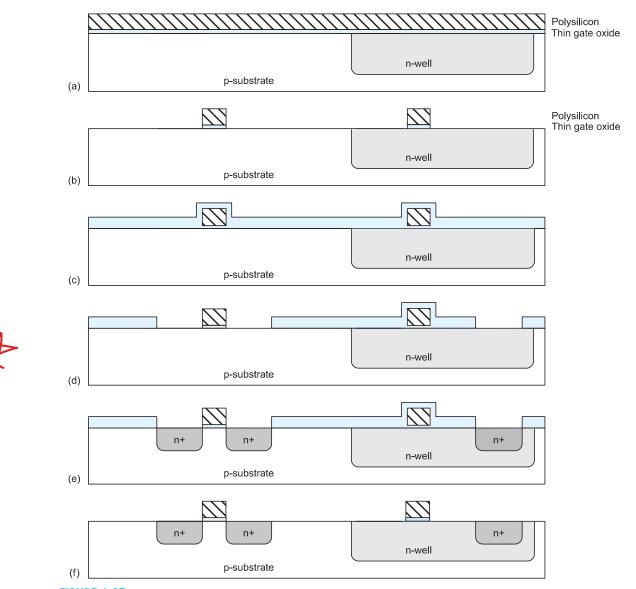


FIGURE 1.37 Cross-sections while manufacturing polysilicon and n-diffusion

1.5.3 Layout Design Rules

Layout design rules describe how small features can be and how closely they can be reliably packed in a particular manufacturing process. Industrial design rules are usually specified in microns. This makes migrating from one process to a more advanced process or a different foundry's process difficult because not all rules scale in the same way.

Universities sometimes simplify design by using scalable design rules that are conservative enough to apply to many manufacturing processes. Mead and Conway [Mead80] popularized scalable design rules based on a single parameter, λ , that characterizes the resolution of the process. λ is generally half of the minimum drawn transistor channel length. This length is the distance between the source and drain of a transistor and is set by the minimum width of a polysilicon wire. For example, a 180 nm process has a minimum polysilicon width (and hence transistor length) of 0.18 μ m and uses design rules with

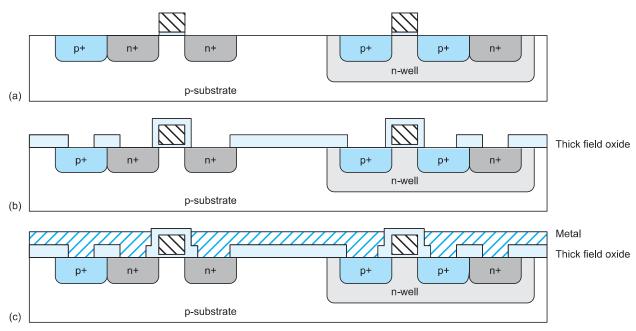


FIGURE 1.38 Cross-sections while manufacturing p-diffusion, contacts, and metal

 $\lambda = 0.09~\mu m.^3$ Lambda-based rules are necessarily conservative because they round up dimensions to an integer multiple of λ . However, they make scaling layout trivial; the same layout can be moved to a new process simply by specifying a new value of λ . This chapter will present design rules in terms of λ . The potential density advantage of micron rules is sacrificed for simplicity and easy scalability of lambda rules. Designers often describe a process by its *feature size*. Feature size refers to minimum transistor length, so λ is half the feature size.

Unfortunately, below 180 nm, design rules have become so complex and process-specific that scalable design rules are difficult to apply. However, the intuition gained from a simple set of scalable rules is still a valuable foundation for understanding the more complex rules. Chapter 3 will examine some of these process-specific rules in more detail.

The MOSIS service [Piña02] is a low-cost prototyping service that collects designs from academic, commercial, and government customers and aggregates them onto one mask set to share overhead costs and generate production volumes sufficient to interest fabrication companies. MOSIS has developed a set of scalable lambda-based design rules that covers a wide range of manufacturing processes. The rules describe the minimum width to avoid breaks in a line, minimum spacing to avoid shorts between lines, and minimum overlap to ensure that two layers completely overlap.

A conservative but easy-to-use set of design rules for layouts with two metal layers in an n-well process is as follows:

- Metal and diffusion have minimum width and spacing of 4 λ.
- Contacts are 2 $\lambda \times 2 \lambda$ and must be surrounded by 1 λ on the layers above and below.
- Polysilicon uses a width of 2 λ .





³Some 180 nm lambda-based rules actually set $\lambda = 0.10 \,\mu\text{m}$, then shrink the gate by 20 nm while generating masks. This keeps 180 nm gate lengths but makes all other features slightly larger.

- Polysilicon overlaps diffusion by 2 λ where a transistor is desired and has a spacing of 1 λ away where no transistor is desired.
- Polysilicon and contacts have a spacing of 3 λ from other polysilicon or contacts.
- N-well surrounds pMOS transistors by 6 λ and avoids nMOS transistors by 6 λ .

Figure 1.39 shows the basic MOSIS design rules for a process with two metal layers. Section 3.3 elaborates on these rules and compares them with industrial design rules.

In a three-level metal process, the width of the third layer is typically 6 λ and the spacing 4 λ . In general, processes with more layers often provide thicker and wider top-level metal that has a lower resistance.

Transistor dimensions are often specified by their Width/Length (W/L) ratio. For example, the nMOS transistor in Figure 1.39 formed where polysilicon crosses n-diffusion has a W/L of 4/2. In a 0.6 μ m process, this corresponds to an actual width of 1.2 μ m and a length of 0.6 μ m. Such a minimum-width contacted transistor is often called a unit transistor. PMOS transistors are often wider than nMOS transistors because holes move more slowly than electrons so the transistor has to be wider to deliver the same current. Figure 1.40(a) shows a unit inverter layout with a unit nMOS transistor and a double-sized pMOS transistor. Figure 1.40(b) shows a schematic for the inverter annotated with Width/Length for each transistor. In digital systems, transistors are typically chosen to have the minimum possible length because short-channel transistors are faster, smaller, and consume less power. Figure 1.40(c) shows a shorthand we will often use, specifying multiples of unit width and assuming minimum length.

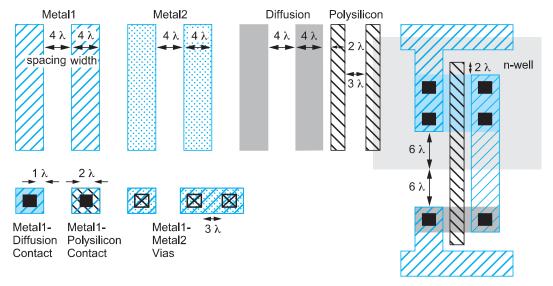




FIGURE 1.39 Simplified λ -based design rules

⁴Such small transistors in modern processes often behave slightly differently than their wider counterparts. Moreover, the transistor will not operate if either contact is damaged. Industrial designers often use a transistor wide enough for two contacts (9 λ) as the unit transistor to avoid these problems.

1.5.4 Gate Layouts

A good deal of ingenuity can be exercised and a vast amount of time wasted exploring layout topologies to minimize the size of a gate or other *cell* such as an adder or memory element. For many applications, a straightforward layout is good enough and can be automatically generated or rapidly built by hand. This section presents a simple layout style based on a "line of diffusion" rule that is commonly used for standard cells in automated layout systems. This style consists of four horizontal strips: metal ground at the bottom of the cell, n-diffusion, p-diffusion, and metal power at the top. The power and ground lines are often called *supply rails*. Polysilicon lines run vertically to form transistor gates. Metal wires within the cell connect the transistors appropriately.

Figure 1.41(a) shows such a layout for an inverter. The input A can be connected from the top, bottom, or left in polysilicon. The output Y is available at the right side of the

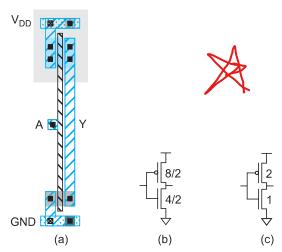


FIGURE 1.40 Inverter with dimensions labeled

cell in metal. Recall that the p-substrate and n-well must be tied to ground and power, respectively. Figure 1.41(b) shows the same inverter with well and substrate taps placed under the power and ground rails, respectively. Figure 1.42 shows a 3-input NAND gate. Notice how the nMOS transistors are connected in series while the pMOS transistors are connected in parallel. Power and ground extend 2 λ on each side so if two gates were abutted the contents would be separated by 4 λ , satisfying design rules. The height of the cell is 36 λ , or 40 λ if the 4 λ space between the cell and another wire above it is counted. All these examples use transistors of width 4 λ . Choice of transistor width is addressed further in Chapters 4–5 and cell layout styles are discussed in Section 14.7.

These cells were designed such that the gate connections are made from the top or bottom in polysilicon. In contemporary standard cells, polysilicon is generally not used as a routing layer so the cell must allow metal to metal and metal to polysilicon contacts

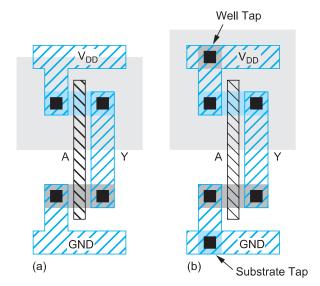


FIGURE 1.41 Inverter cell layout

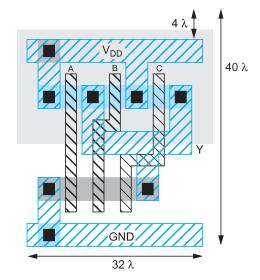


FIGURE 1.42 3-input NAND standard cell gate layouts





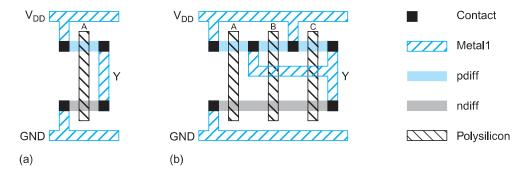
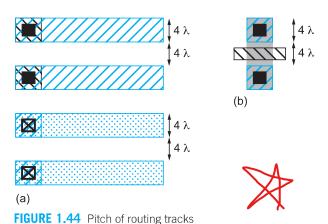


FIGURE 1.43 Stick diagrams of inverter and 3-input NAND gate. Color version on inside front cover.

to each gate. While this increases the size of the cell, it allows free access to all terminals on metal routing layers.



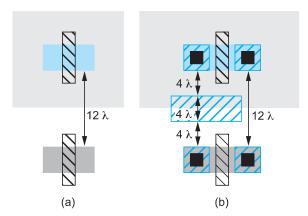


FIGURE 1.45 Spacing between nMOS and pMOS transistors

1.5.5 Stick Diagrams

Because layout is time-consuming, designers need fast ways to plan cells and estimate area before committing to a full layout. *Stick diagrams* are easy to draw because they do not need to be drawn to scale. Figure 1.43 and the inside front cover show stick diagrams for an inverter and a 3-input NAND gate. While this book uses stipple patterns, layout designers use dry-erase markers or colored pencils.

With practice, it is easy to estimate the area of a layout from the corresponding stick diagram even though the diagram is not to scale. Although schematics focus on transistors, layout area is usually determined by the metal wires. Transistors are merely widgets that fit under the wires. We define a routing track as enough space to place a wire and the required spacing to the next wire. If our wires have a width of 4 λ and a spacing of 4 λ to the next wire, the track *pitch* is 8 λ , as shown in Figure 1.44(a). This pitch also leaves room for a transistor to be placed between the wires (Figure 1.44(b)). Therefore, it is reasonable to estimate the height and width of a cell by counting the number of metal tracks and multiplying by 8 λ . A slight complication is the required spacing of 12 λ between nMOS and pMOS transistors set by the well, as shown in Figure 1.45(a). This space can be occupied by an additional track of wire, shown in Figure 1.45(b). Therefore, an extra track must be allocated between nMOS and pMOS transistors regardless of whether wire is actually used in that track. Figure 1.46 shows how to count tracks to estimate the size of a 3-input NAND. There are four vertical wire tracks, multiplied by 8 λ per track to give a cell width of 32 λ . There are five horizontal tracks, giving a cell height of 40 λ . Even though the horizontal tracks are not drawn to scale, they are still easy to count. Figure 1.42

shows that the actual NAND gate layout matches the dimensions predicted by the stick diagram. If transistors are wider than 4 λ , the extra width must be factored into the area estimate. Of course, these estimates are oversimplifications of the complete design rules and a trial layout should be performed for truly critical cells.

Example 1.3

Sketch a stick diagram for a CMOS gate computing $Y = (A + B + C) \cdot \overline{D}$ (see Figure 1.18) and estimate the cell width and height.

SOLUTION: Figure 1.47 shows a stick diagram. Counting horizontal and vertical pitches gives an estimated cell size of 40 by 48 λ .

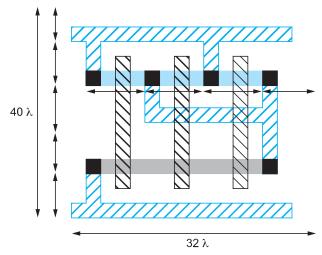


FIGURE 1.46 3-input NAND gate area estimation

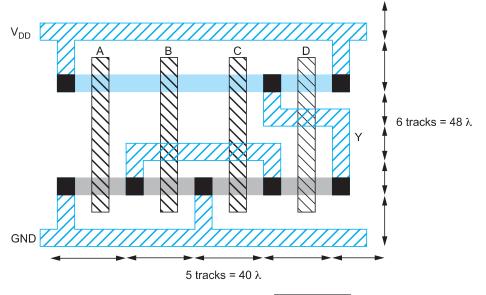


FIGURE 1.47 CMOS compound gate for function $Y = \overline{(A + B + C) \cdot D}$

1.6 Design Partitioning

By this point, you know that MOS transistors behave as voltage-controlled switches. You know how to build logic gates out of transistors. And you know how transistors are fabricated and how to draw a layout that specifies how transistors should be placed and connected together. You know enough to start building your own simple chips.

The greatest challenge in modern VLSI design is not in designing the individual transistors but rather in managing system complexity. Modern *System-On-Chip* (SOC) designs combine memories, processors, high-speed I/O interfaces, and dedicated application-specific logic on a single chip. They use hundreds of millions or billions of transistors and cost tens of millions of dollars (or more) to design. The implementation