

# AMBARISH G KALIAMURTHI

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## Education

### San Jose State University

May 2026

*Master of Science in Computer Engineering*

- Data Structures
- Machine Learning
- Adv Computer Design
- Software Sys Design
- Internet of Things
- NLP
- Computer Architecture
- AI and Data Engg

## Experience

### San Jose State University Research Foundation

Sep 2024 – Present

*Graduate Research Assistant - 📺 ambarishgk*

*San Jose, CA*

- Developing a vLLM-powered exploration framework for LiDAR + stereo-based AGVs, enabling richer scene understanding, object exploration, and improved autonomous navigation.
- Prototyping an LLM-powered voice teleoperation system using ROS2, integrating Google Speech-to-Text to enable natural language AGV navigation and task commands.
- Designed and deployed a multi-modal sensor fusion pipeline on NVIDIA Orin, integrating LiDAR and stereo cameras for real-time 3D mapping and robust perception in dynamic environments.
- Built a LiDAR-based point pillar object detection pipeline using MMDetection3D with KITTI 360 and Waymo datasets, enhancing detection accuracy and speed.

### Smarthub.ai

May 2021 – Jan 2024

*Software Engineer*

*Bengaluru, India*

- Engineered an asynchronous Python IoT Docker monitoring system with 99% accuracy, reducing false downtime alerts by 87%.
- Developed a Python Cloud SDK and Golang CLI for efficient product deployment and cloud integration.
- Optimized firmware upgrades using AsyncIO and multithreading, cutting upgrade time from 5 hours to 7 minutes (90% improvement).
- Built monitoring/evaluation pipelines supporting 4000+ devices, ensuring scalable system reliability and enabling 35% revenue growth.
- Created an OpenCV Python script for DataMatrix barcode scanning, enabling fast, reliable CV-based data capture.

### Predigle India Pvt Ltd

Sep 2020 – Apr 2021

*Software Developer*

*Chennai, India*

- Developed a full-stack web app with Python (Flask), Angular, and MySQL to rank 10M+ leads with secure role-based authentication for a health tech domain.
- Implemented secure, role-based authentication with tokenization and hashing for a multi-tenant system supporting 10M+ records, applying scalable database and algorithmic design.
- Built a real-time cluster monitoring dashboard to track key metrics, supporting data-driven decision-making.

## Projects

### LeRobot Hackathon – Robotic Oximeter Placement | *Imitation Learning, ACT, VLMs*

- Developed an imitation learning policy for a robotic arm to autonomously place an oximeter on a human figure.
- Leveraged ACT (Action Chunking with Transformers) and Vision-Language Models for policy training.

### Aether: AI-Powered Meeting Summarization | *Python, LLMs*

Nov 2024

- Built an NLP app with GPT models to auto-summarize meetings, extract code, and generate action items.

### IoT Trojan Image Scanner | *Python, CV, Security*

- Developed a Python-based CV tool to detect Trojan-embedded images in IoT devices via anomaly and file integrity analysis. Built a CLI for seamless deployment with LLM based summarization of results.

### ROS2 Wrapper for DualSense Haptic PS5 Joystick | *ROS2, C++, Robotics*

Dec 2024 – Present

- Integrated PS5 DualSense joystick control (motion, touchpad, haptic feedback) into ROS2 robotic systems.
- Implemented haptic feedback functionality for enhanced robotic control.

## Dec 2024

- Mar 2023

## Mar 2023

- ## Technical Skills

**Libraries & Tools:** Linux, Docker, Kubernetes, Git, AWS, GCP, LlamaIndex, LangChain, Google Speech-to-Text, Whisper, Hugging Face Transformers

## Certifications

Scientific Data Processing (Google cloud)

Leadership / Extracurricular

Apr 2025

Jun 2024

May 2024

*Global Leader*