

▼ Euler's Method

▼ Algorithm

Function will take following input: (f, t_initial, t_final, y_initial, h)
 f(t, y) from $y' = f(t, y)$
 t_initial (starting point of domain)
 t_final (ending point of domain)
 y_initial (initial condition)
 h (step size)

1 Initialize the initial value of y and the initial time t.

2 Set the number of steps $n = (t_{\text{final}} - t_{\text{initial}}) / h$.

3 Loop from $i = 1$ to $i = n$:

- a. Calculate the slope of the function at the current time and value of y using the given differential equation.
- b. Calculate the new value of y using the formula: $y(i) = y(i-1) + h * \text{slope}(i-1)$.
- c. Update the value of time $t(i) = t(i-1) + h$.

4 Return the values of time and y at each step.



```
def euler_method(f, t_initial, t_final, y_initial, h):
    """
    Solves the ordinary differential equation  $y' = f(t, y)$  using Euler's method with step size h.
    Returns arrays of time and y values at each step.
    """
    num_steps = int((t_final - t_initial) / h)
    t_values = [t_initial]
    y_values = [y_initial]
    print('\n-----SOLUTION-----')
    print('-----')
    print('#\ttn\tyn')
    print('-----')
    for i in range(num_steps):
        slope = f(t_values[i], y_values[i])
        y_new = y_values[i] + h * slope
        t_new = t_values[i] + h
```

```

        y_values.append(y_new)
        t_values.append(t_new)
        print('%d\t%.2f\t%.4f'% (i+1,t_new,y_new) )
        print('-----')
    return t_values,y_values

```

```

import numpy as np
def f(t,y):
    return np.exp(t)-y

```

```
t_E,y_E=euler_method(f, t_initial=0, t_final=1, y_initial=1,h= 0.1)
```

```

-----SOLUTION-----
-----
#          tn          yn
-----
1          0.10        1.0000
-----
2          0.20        1.0105
-----
3          0.30        1.0316
-----
4          0.40        1.0634
-----
5          0.50        1.1063
-----
6          0.60        1.1605
-----
7          0.70        1.2267
-----
8          0.80        1.3054
-----
9          0.90        1.3974
-----
10         1.00        1.5036
-----

```

▼ RK-4 Method

▼ Algorithm

To solve: $\frac{dy}{dx} = f(x, y)$

$$\begin{aligned}
 x_{i+1} &= x_i + h, \\
 y_{i+1} &= y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)h \\
 k_1 &= f(x_i, y_i), \\
 k_2 &= f(x_i + 0.5h, y_i + 0.5k_1), \\
 k_3 &= f(x_i + 0.5h, y_i + 0.5k_2). \\
 k_4 &= f(x_i + h, y_i + k_3),
 \end{aligned}$$

Function will take following input:(f,t_initial,t_final,y_initial,h)

f(t,y) from y' = f(t,y)

t_initial(starting point of domain)

t_final(ending point of domain)

y_initial(initial condition)

h(step size)

1 Initialize the initial value of y and the initial time t.

2 Set the number of steps $n = (t_{\text{final}} - t_{\text{initial}}) / h$.

3 Loop from $i = 1$ to $i = n$:

a) Calculate

$$k_1 = f(x_0, y_0)$$

$$k_2 = f(x_0 + h/2, y_0 + k_1/2)$$

$$k_3 = f(x_0 + h/2, y_0 + k_2/2)$$

$$k_4 = f(x_0 + h, y_0 + k_3)$$

b) Calculate the new value of y using the formula: $y(i) = y(i-1) + (k_1 + 2k_2 + 2k_3 + k_4)h/6$

c) Update the value of time $t(i) = t(i-1) + h$.

4 Return the values of time and y at each step.

```
def RK4_method(f, t_initial, t_final, y_initial, h):
    """
    Solves the ordinary differential equation y' = f(t, y) using Euler's method with step siz
    Returns arrays of time and y values at each step.
    """
    num_steps = int((t_final - t_initial) / h)
    t_values = [t_initial]
    y_values = [y_initial]
    print('\n-----SOLUTION-----')
```

```

print('-----')
print('#\ttn\tyn')
print('-----')
for i in range(num_steps):
    k1 = f(t_values[i], y_values[i])
    k2 = f(t_values[i]+0.5*h, y_values[i]+0.5*k1)
    k3 = f(t_values[i]+h/2, y_values[i]+k2/2)
    k4 = f(t_values[i]+h, y_values[i]+k3)
    y_new = y_values[i] + (h/6) * (k1+2*k2+2*k3+k4)
    t_new = t_values[i] + h
    y_values.append(y_new)
    t_values.append(t_new)
    print('%d\t%.2f\t%.4f' % (i+1,t_new,y_new) )
    print('-----')
return t_values,y_values

```

```

import numpy as np
def f(t,y):
    return np.exp(t)-y

```

```
t_R,y_R=RK4_method(f, t_initial=0, t_final=1, y_initial=1,h= 0.1)
```

```

-----SOLUTION-----
-----
#          tn          yn
-----
1          0.10        1.0039
-----
2          0.20        1.0145
-----
3          0.30        1.0322
-----
4          0.40        1.0573
-----
5          0.50        1.0903
-----
6          0.60        1.1316
-----
7          0.70        1.1818
-----
8          0.80        1.2416
-----
9          0.90        1.3118
-----
10         1.00        1.3931
-----

```

▼ Library Function to solve ODE(IVP)

```

import numpy as np
from scipy.integrate import solve_ivp
def f(t,y):
    return np.exp(t)-y
sol = solve_ivp(f, [0, 1], [1], t_eval=np.array(np.linspace(0.1,1,10)))
t_l=sol.t
y_l=sol.y.flatten()
print('\n----Library_SOLUTION-----')
print('-----')
print('#\tn\tyn')
print('-----')

for i in range(len(t_l)):
    print('%d\t%.2f\t%.4f'% (i+1,t_l[i],y_l[i]) )
    print('-----')

```

```

----Library_SOLUTION-----
-----
#      tn      yn
-----
1      0.10     1.0050
-----
2      0.20     1.0200
-----
3      0.30     1.0451
-----
4      0.40     1.0807
-----
5      0.50     1.1272
-----
6      0.60     1.1851
-----
7      0.70     1.2549
-----
8      0.80     1.3374
-----
9      0.90     1.4332
-----
10     1.00     1.5433
-----

```

▼ Plotting

```

import matplotlib.pyplot as plt
import numpy as np
plt.figure(figsize=(7,5))

```

```

plt.plot(t_l, y_l, label="Numerical solution:\nLibrary_function_sol", dashes=(3,2), color="re

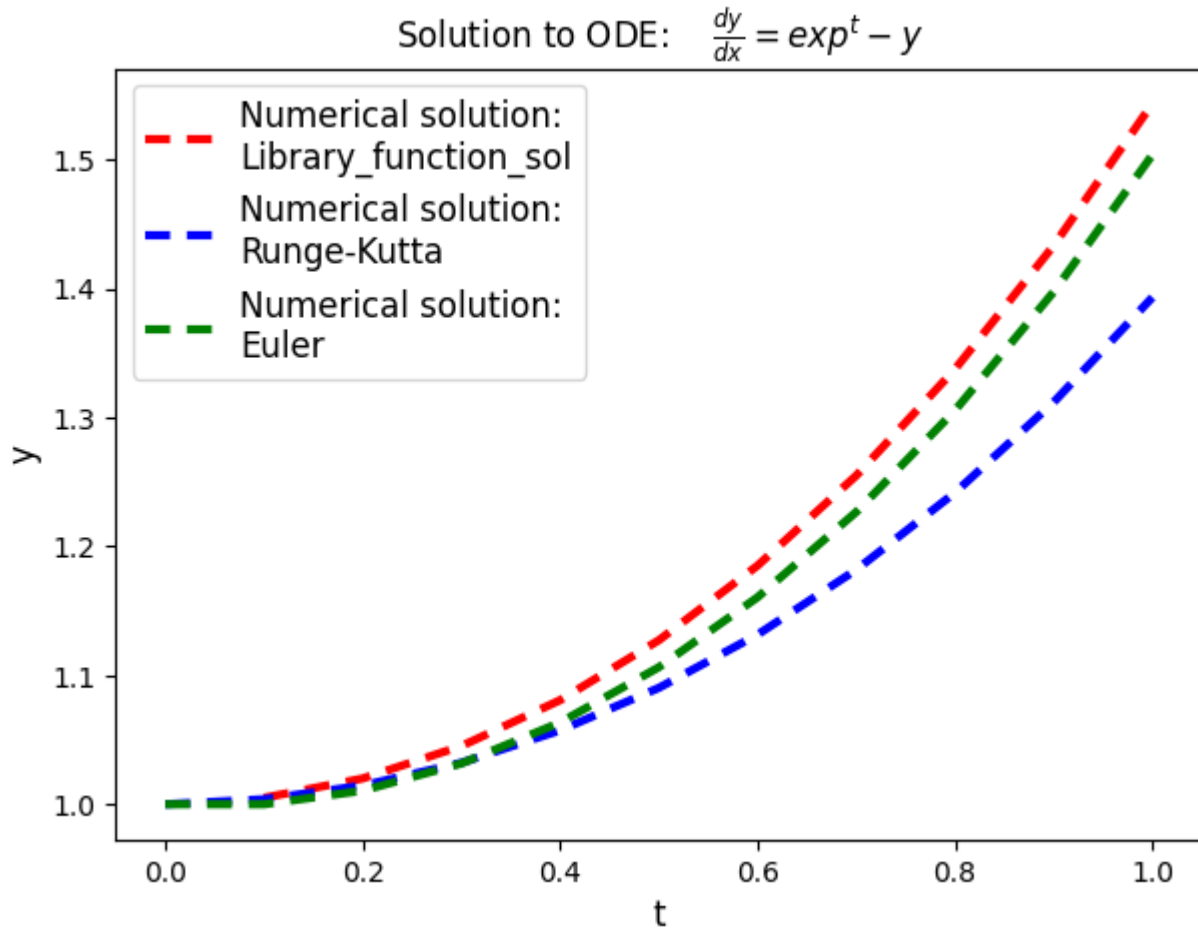
```

```

plt.plot(t_R, y_R, label="Numerical solution:\nRunge-Kutta", dashes=(3,2), color="blue",lw=3)
plt.plot(t_E, y_E, label="Numerical solution:\nEuler", dashes=(3,2), color="green",lw=3)

plt.legend(loc="best", fontsize=12)
plt.title(r"Solution to ODE: $\frac{dy}{dx}=exp^t - y$")
plt.xlabel("t", fontsize=12)
plt.ylabel("y", fontsize=12)
plt.show()

```



Lab Task

- 1- Write the program for Heun's Method.
- 2- Write the code to make a table to compare error of Heun's, Euler's, RK4 by using analytical solution.
- 3- Repeat task 2 for three different DEs.

