

Objectives of Session3a_Derivatives_and_Integration:

- 1-To understand how to take derivatives and integrals by using library functions of python.
- 2-To implement Numerical Differentiation methods to find values of $f'(x)$ for a given table of x and $f(x)$.
- 3-To implement Numerical Integration methods to find values of definite integrals and their error bound by a specific method.

▼ How to take derivative in python:

```
from sympy import* #Call Library of sympy
x = symbols('x')  #Make x a symbol
f = 2*x**2+5      #Function to take derivative

df = diff(f, x,2)  #diff(f,x,1) is used to take first derivative of f w.r.t x
#df = diff(f, x,n) #diff(f,x,1) is used to take nth derivative of f w.r.t x
print(df)
print(float(df.subs(x,3))) #df.subs(x,1) is used to substitute value of x=1 in above taken derivative

4
4.0

# another procedure for finding derivative
y=sin(x)-x
derivative_y=y.diff(x) #differentiate y w.r.t x
print(derivative_y)

cos(x) - 1
```

How to convert a sympy symbolic expression into numpy function to evaluate it on a point or array.

```
f1=lambdify(x,f) #Now f1 is numpy function
print(f1(1)) #f1 at 1, you can also evaluate f1 at an array.
df1=lambdify(x,df)
print(df1(1))

7
4
```

Task1

- a)Use above two procedures to find the second derivative of $f(x)=x^2 \exp(-x)$.
- b)Convert symbolic expression in part (a) into numpy function.
- c)Evaluate the numpy function (obtained in part b)at a single value and at an array.

▼ Coding of some Numerical differentiation formulae

▼ Code of forward difference formula

Forward Differnce

$$\bullet f'(x_0) = \frac{f(x_0+h)-f(x_0)}{h}$$

Backward Differnce

$$\bullet f'(x_0) = \frac{f(x_0)-f(x_0-h)}{h}$$

code of forward difference formula.

```
import numpy as np
from tabulate import tabulate
```

```
def forward_diff(x, y):

    # Compute the step size h
    h = x[1] - x[0]
    data=[]

    # Compute the forward difference approximation
    fdf = np.zeros_like(y)
    fdf[-1] = (y[-1] - y[-2]) / h # use backward difference at the end point
    for i in range(len(y) - 1):
        fdf[i] = (y[i+1] - y[i]) / h
        data.append([x[i],y[i],fdf[i]])
    data.append([x[-1],y[-1],fdf[-1]])

    print(tabulate(data,headers=['x', 'f(x)', 'df(x)/dx'],tablefmt="github"))

    return

# example to run above code
x=[0.2,0.4,0.6,0.8]
y=[3,3.9,3.98,4.2]
forward_diff(x, y)
```

x	f(x)	df(x)/dx
0.2	3	4.5
0.4	3.9	0.4
0.6	3.98	1.1
0.8	4.2	1.1

Task 2: Write a code for Backward difference approximation (apply forward difference approximation on first point)

▼ Code of three point endpoint and three point midpoint formula

Three-Point Endpoint Formula

$$f'(x_0) = \frac{-3f(x_0) + 4f(x_0 + h) - f(x_0 + 2h)}{2h}$$

Three-Point Midpoint Formula

$$f'(x_0) = \frac{f(x_0+h) - f(x_0-h)}{2h}$$

code for three point endpoint and three point midpoint formulae for finding f'(x) for an array of x and f(x).
import numpy as np

```
def three_point(x, y):

    # Compute the step size h
    data=[]
    h = x[1] - x[0]

    # Compute the forward difference approximation
    tp = np.zeros_like(y)
    tp[0]=(-3*y[0]+4*y[1]-y[2])/(2*h) #three point endpoint (left end) formula
    tp[-1]=(3*y[-1]-4*y[-2]+y[-3])/(2*h) #three point endpoint (right end) formula

    data.append([x[0],y[0],tp[0]])
    for i in range(1,len(y)-1):
        tp[i] = (y[i+1] - y[i-1]) / (2*h)
        data.append([x[i],y[i],tp[i]])
    data.append([x[-1],y[-1],tp[-1]])

    print(tabulate(data,headers=['x', 'f(x)', 'df(x)/dx'],tablefmt="github"))

    return

# example to run above code
x=[0.2,0.4,0.6,0.8]
y=[3,3.9,3.98,4.2]
three_point(x, y)
```

x	f(x)	df(x)/dx
0.2	3	6.55
0.4	3.9	2.45
0.6	3.98	0.75
0.8	4.2	1.45

Task 3: Make a code for five point endpoint and midpoint formulae where possible in given table.:

▼ How to take integral in python

```
x = symbols('x')    #Make x a symbol
f = 2*x/(x**2-4)     #Function to take integrate

I_actual = float(integrate(f, (x,1,1.6)))    #integrate(f,(x,1,u)) is used to take integral of f from 1 to u
print(I_actual)
```

-0.7339691750802008

▼ Numerical Integration by using Composite Trapezoidal rule

Trapezoid Rule

$$\int_a^b f(x) dx \approx \frac{h}{2} [f(a) + \sum_{i=1}^{n-1} \{f(x_i) + f(b)\}]$$

$$\int_a^b f(x) dx \approx \frac{h}{2} [f(a) + \sum_{i=1}^{n-1} \{f(x_i) + f(b)\}]$$

```
def comp_trapezoidal_rule(f, a, b, n=1):    #n=1 indicates simple trapezoidal rule
    h = (b - a) / n
    x = [a + i*h for i in range(n+1)]
    y = [f(xi) for xi in x]
    s = sum(y[1:-1])
    ans=h/2 * (y[0] + 2*s + y[-1])
    return ans
```

```
#Example for simple and composite Trapezoidal
def f(x):
    return(2*x/(x**2-4))
strap=comp_trapezoidal_rule(f,1,1.6)
print(strap) # gives ans of simple trapezoidal rule
ctrap=comp_trapezoidal_rule(f,1,1.6,4)
print(ctrap) # gives ans of composite trapezoidal rule with n=4
```

-0.8666666666666667
-0.7435983879717899

Computing Actual Error for simple and composite trapezoidal rules

```
print(I_actual-strap)
print(I_actual-ctrap)

0.13269749158646627
0.009629212891589134
```

▼ For calculating SimpleTrapezoidal error bound

Working for Question no 3e Exercise 4.3

```
from sympy import* #Call Library of sympy
def f(x):
    return(2*x/(x**2-4))

def Error_bound_trap(f,l,u):#l is the lower limit and u is the upper limit of integral
```

```

ddf = diff(f, x, 2)    #Evaluating second derivative of f
abs_max_ddf=max(abs(ddf.subs(x,1)),abs(ddf.subs(x,u)))
h=u-1
Error_bound=h**3*abs_max_ddf/12
return(Error_bound,abs_max_ddf)

```

```
Error_bound_trap(f,1,1.6)
```

```
(0.552960000000000, 30.7200000000000)
```

Task 4: Make a code of composite simpson's 1/3rd rule (set n=2 for simple simpson and raise exception when user enters n=odd value) and run on f(x) mentioned in exercise # 4.2, Question #5c and exercise # 4.3, Question 3e

For calculating simple Simpson's 1/3rd rule error bound

```

from sympy import* #Call Library of sympy
x = symbols('x')  #Make x a symbol
f = x**4           #Define your function here in 'x'
def Error_bound_simp(f,l,u):#l is the lower limit and u is the upper limit of integral
    d4f = diff(f, x, 4)    #Evaluating second derivative of f
    abs_max_ddf=max(abs(d4f.subs(x,1)),abs(d4f.subs(x,u)))
    h=(u-1)/2
    Error_bound=h**5*abs_max_ddf/90
    return(Error_bound,abs_max_ddf)

```

Task 5: Find Error bound for Exercise 4.3 Qno 7 part(a) and (b)