

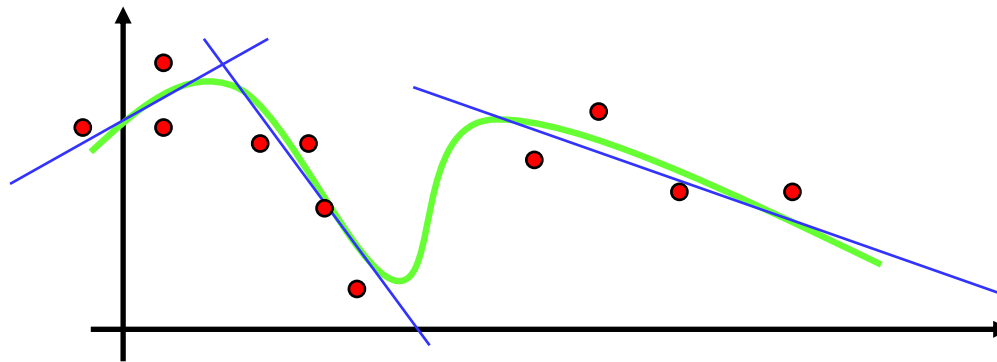
Local Models

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Introduction

- Divide the input space into local regions and learn simple (constant/linear) models in each patch



- Unsupervised: Competitive, online clustering
- Supervised: Radial-basis functions, mixture of experts

K-means Revisit

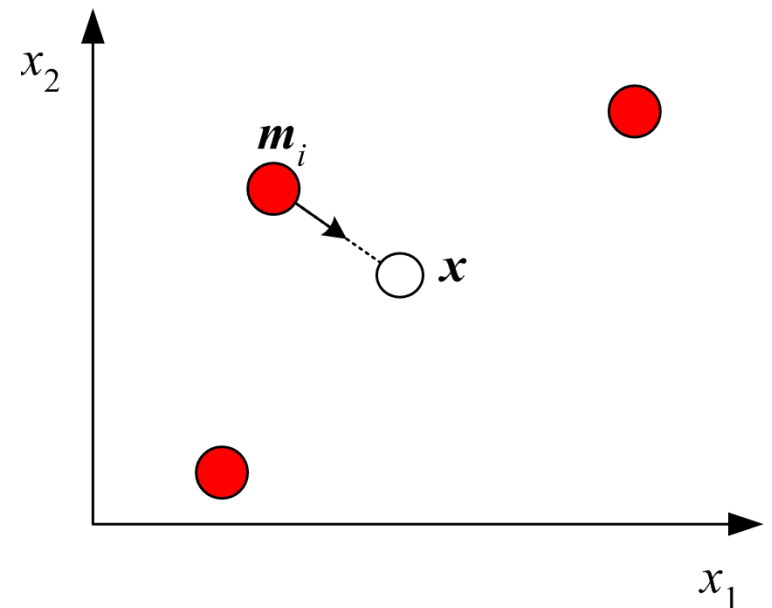
$$E(\{\mathbf{m}_i\}_{i=1}^k | \mathcal{X}) = \sum_t \sum_i b_i^t \|\mathbf{x}^t - \mathbf{m}_i\|^2$$

$$b_i^t = \begin{cases} 1 & \text{if } \|\mathbf{x}^t - \mathbf{m}_i\| = \min_l \|\mathbf{x}^t - \mathbf{m}_l\| \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Batch } k\text{-means: } \mathbf{m}_i = \frac{\sum_t b_i^t \mathbf{x}^t}{\sum_t b_i^t}$$

Online k -means:

$$\Delta m_{ij} = -\eta \frac{\partial E^t}{\partial m_{ij}} = \eta b_i^t (x_j^t - m_{ij})$$



Online K-means

$$E^t = \sum_i b_i^t \|\mathbf{x}^t - \mathbf{m}_i\|^2$$

$$\Delta m_{ij} = -\eta \frac{\partial E^t}{\partial m_{ij}} = \eta b_i^t (x_j^t - m_{ij})$$

Initialize $\mathbf{m}_i, i = 1, \dots, k$, for example, to k random \mathbf{x}^t

Repeat

For all $\mathbf{x}^t \in \mathcal{X}$ in random order

$$i \leftarrow \arg \min_j \|\mathbf{x}^t - \mathbf{m}_j\|$$

$$\mathbf{m}_i \leftarrow \mathbf{m}_i + \eta(\mathbf{x}^t - \mathbf{m}_i)$$

Until \mathbf{m}_i converge

Network Interpretation

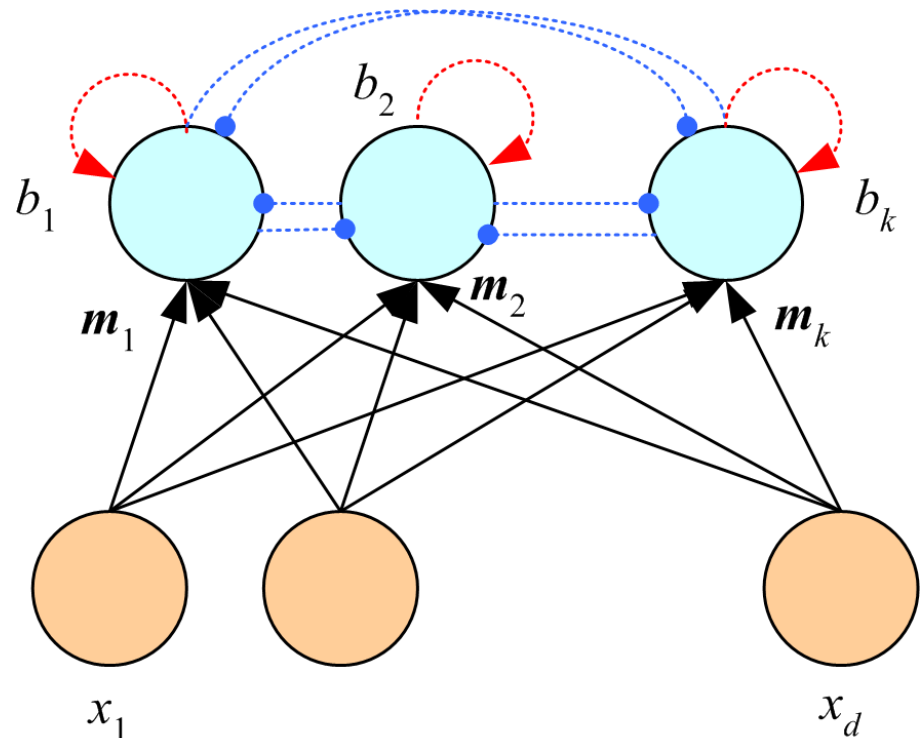
Winner-take-all network

Renormalizing:

$$|\mathbf{m}_i| = 1, \forall i$$

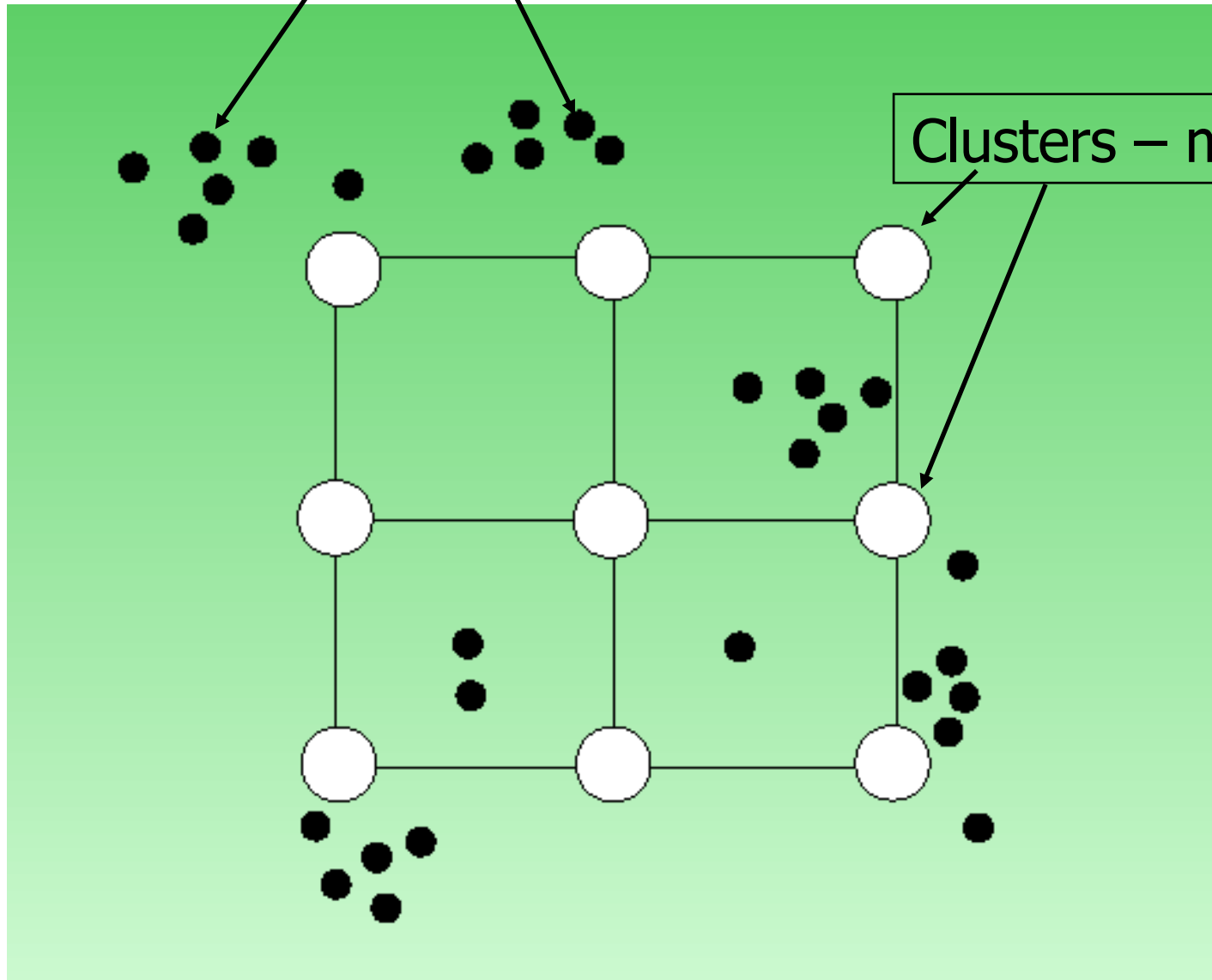
Weight decay term:

$$\Delta m_{ij} = \eta b_i^t (x_j^t - m_{ij}) = \eta b_i^t x_j^t - \eta b_i^t m_{ij}$$



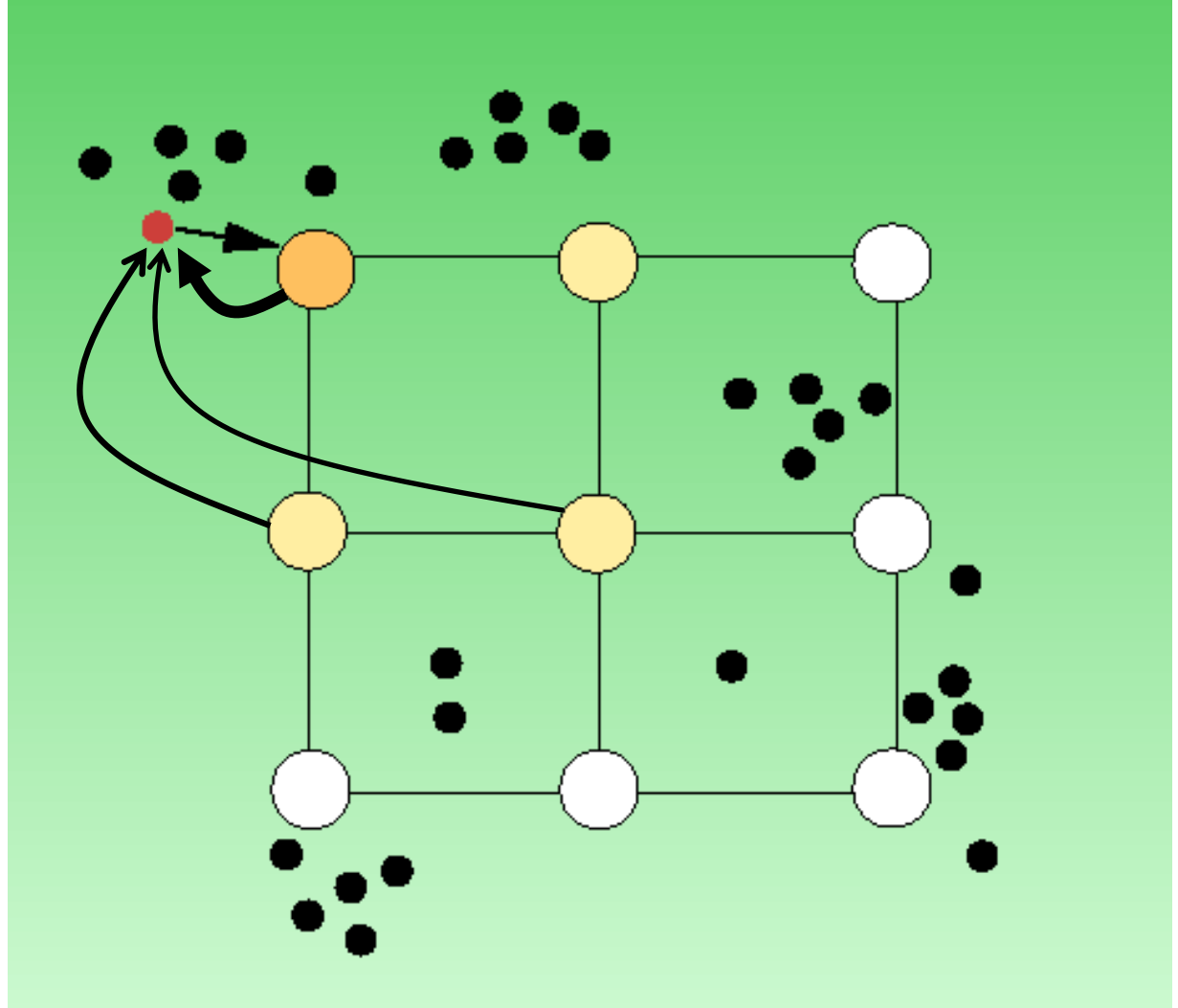
data points

Clusters – map nodes

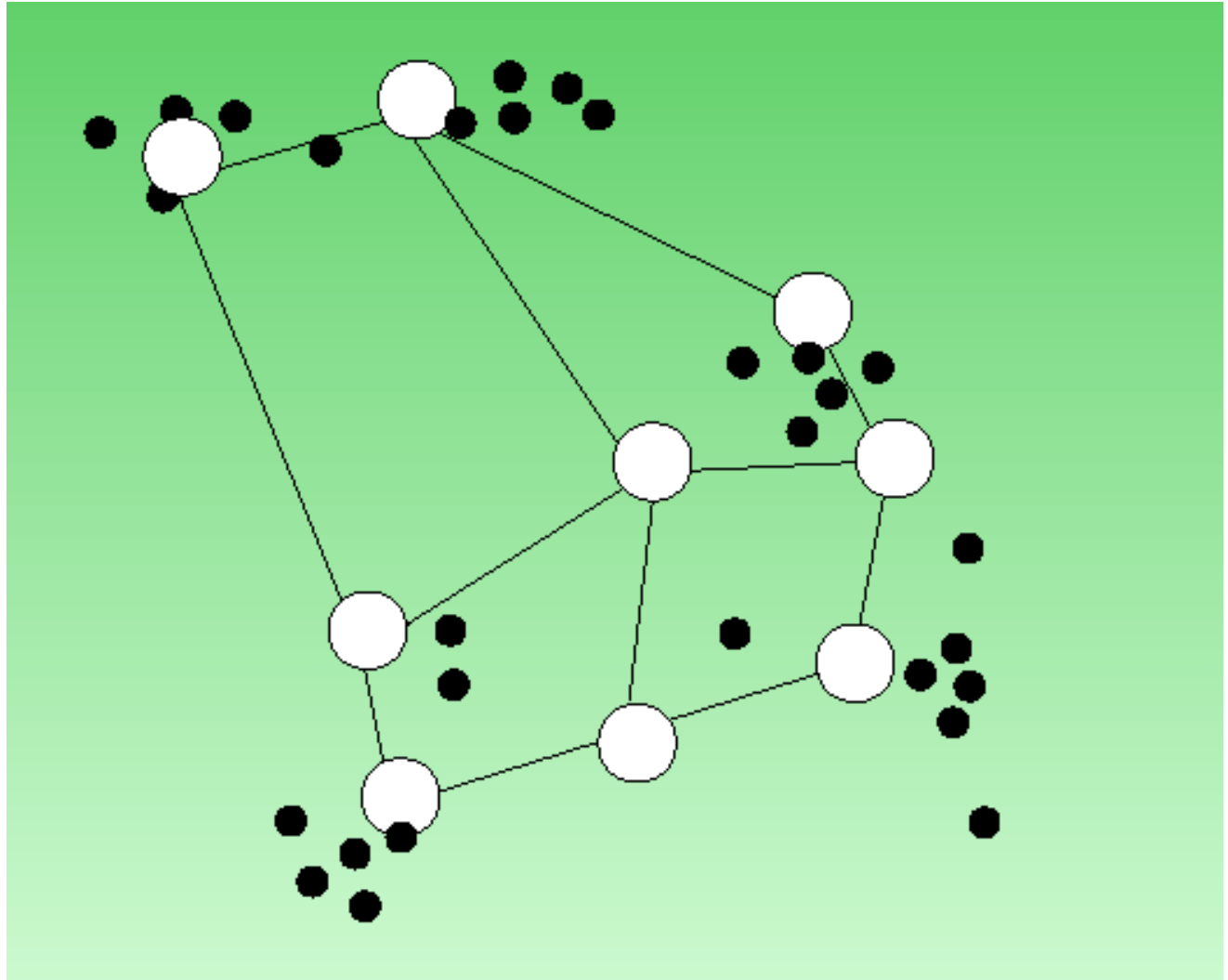


SOM - Scheme

- Randomly choose a data point.
- Find its closest map node
- Move this map node towards the data point
- Move the neighbor map nodes towards this point, but to lesser extent
- Iterate over data points

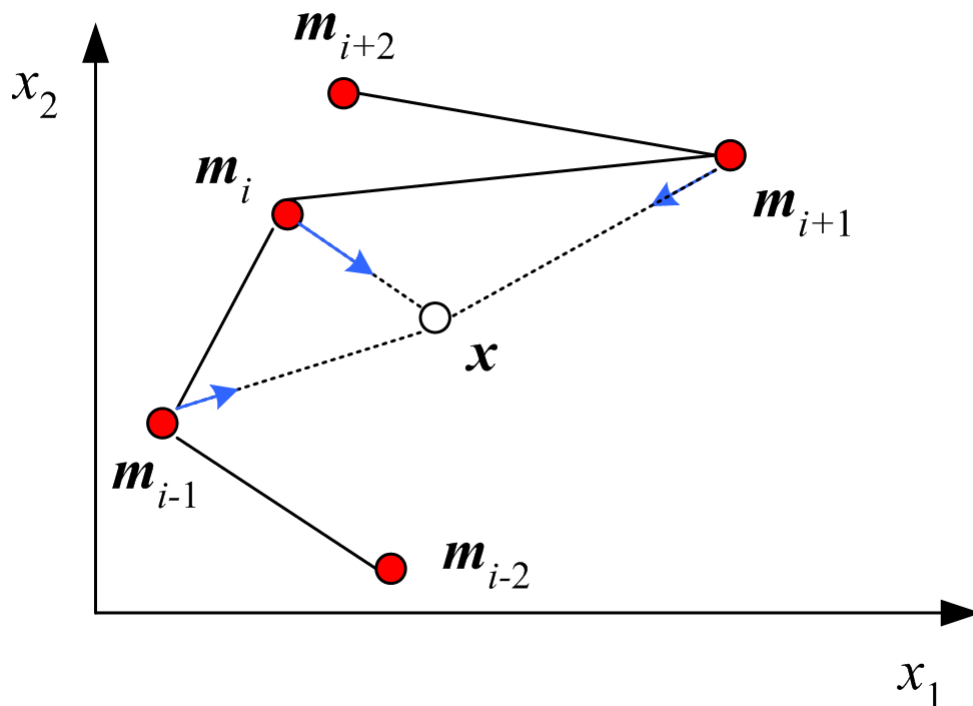


- The extent of node displacements is relaxed with the iteration number
- After thousands of iterations:
 - Assign each data point to the map node (cluster) it is most similar to



Self-Organizing Maps

- Units have a **neighborhood** defined; \mathbf{m}_i is “between” \mathbf{m}_{i-1} and \mathbf{m}_{i+1} , and are all updated together



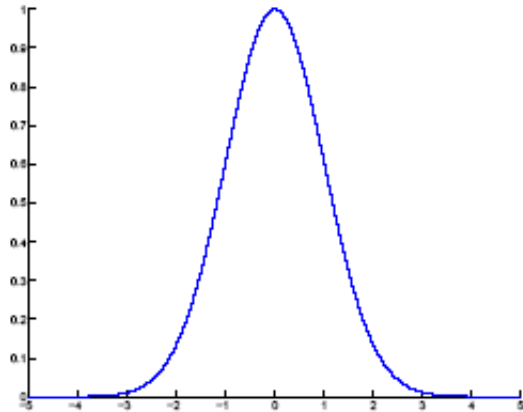
$$\Delta \mathbf{m}_l = \eta e(l, i) (\mathbf{x}^t - \mathbf{m}_l)$$

$$e(l, i) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{(l-i)^2}{2\sigma^2} \right]$$

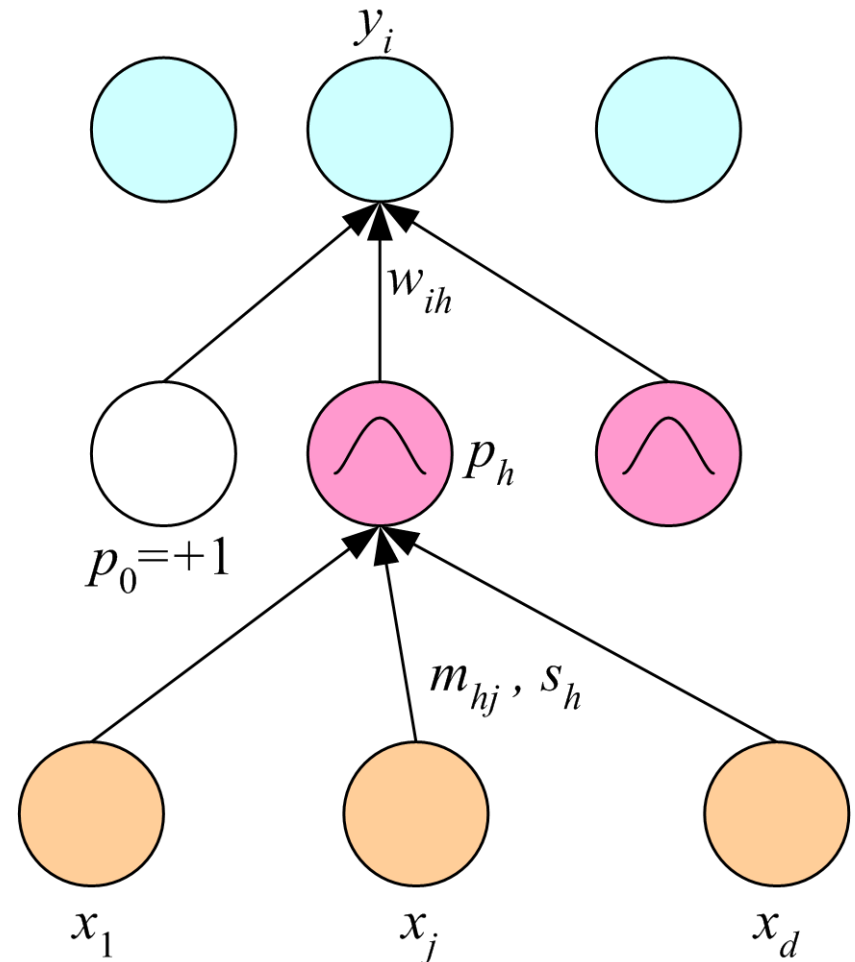
Radial-Basis Functions

■ Locally-tuned units:

$$p_h^t = \exp \left[-\frac{\|\mathbf{x}^t - \mathbf{m}_h\|^2}{2s_h^2} \right]$$

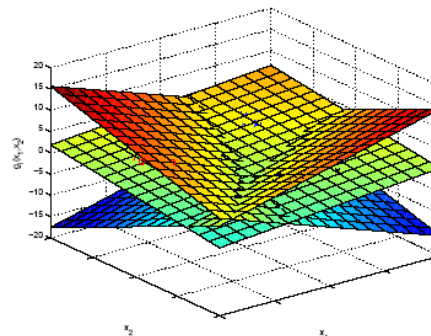
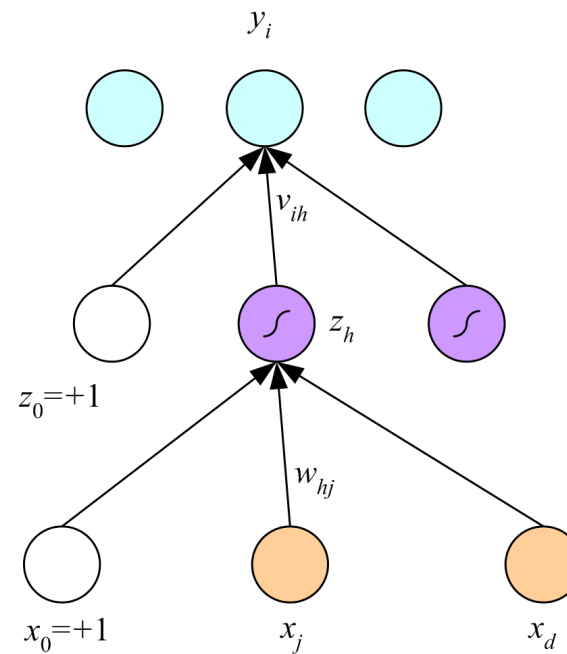
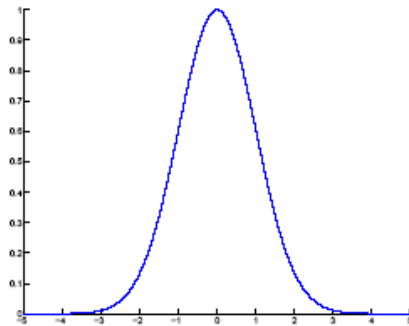
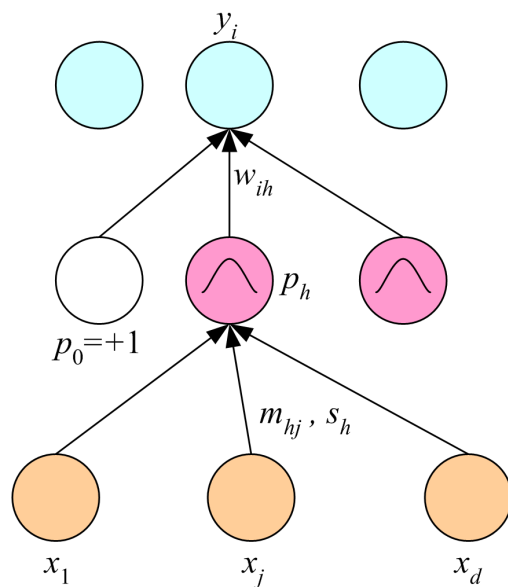


$$y^t = \sum_{h=1}^H w_h p_h^t + w_0$$

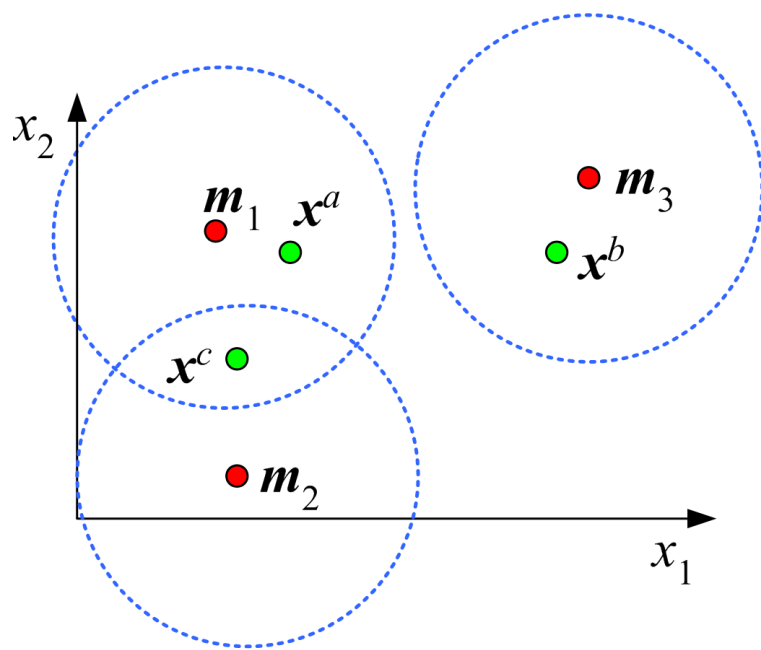


Radial-Basis vs Linear Functions

■ What does the hidden layer do?



Local vs Distributed Representation

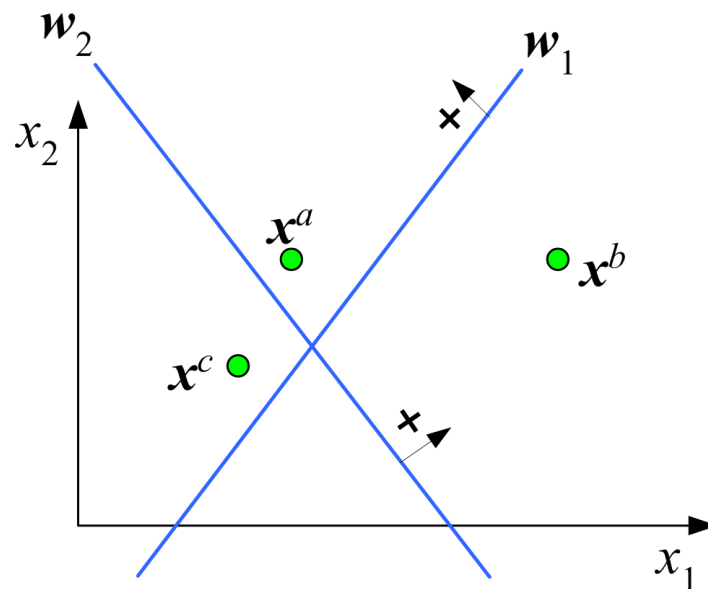


Local representation in the space of (p_1, p_2, p_3)

$x^a : (1.0, 0.0, 0.0)$

$x^b : (0.0, 0.0, 1.0)$

$x^c : (1.0, 1.0, 0.0)$



Distributed representation in the space of (h_1, h_2)

$x^a : (1.0, 1.0)$

$x^b : (0.0, 1.0)$

$x^c : (1.0, 0.0)$

Regression

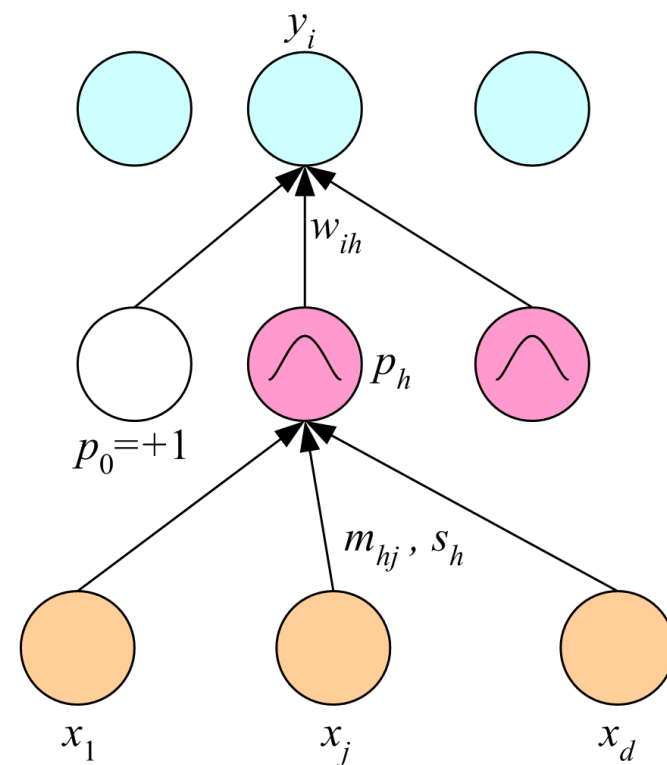
$$E\left(\left\{\mathbf{m}_h, s_h, w_{ih}\right\}_{i,h} \mid \mathcal{X}\right) = \frac{1}{2} \sum_t \sum_i \left(r_i^t - y_i^t\right)^2$$

$$y_i^t = \sum_{h=1}^H w_{ih} p_h^t + w_{i0}$$

$$\Delta w_{ih} = \eta \sum_t \left(r_i^t - y_i^t\right) p_h^t$$

$$\Delta m_{hj} = \eta \sum_t \left[\sum_i \left(r_i^t - y_i^t\right) w_{ih} \right] p_h^t \frac{\left(x_j^t - m_{hj}\right)}{s_h^2}$$

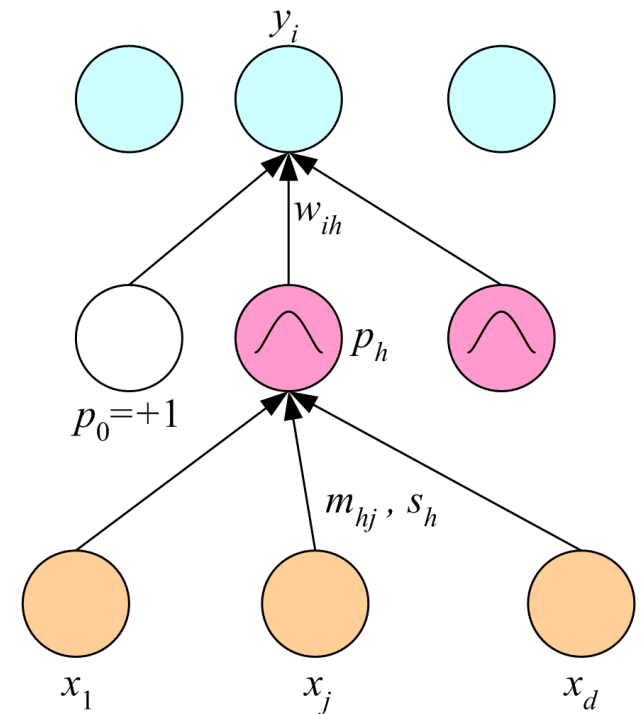
$$\Delta s_h = \eta \sum_t \left[\sum_i \left(r_i^t - y_i^t\right) w_{ih} \right] p_h^t \frac{\left\|\mathbf{x}^t - \mathbf{m}_h\right\|^2}{s_h^3}$$



Classification

$$E\left(\left\{\mathbf{m}_h, s_h, w_{ih}\right\}_{i,h} \mid \mathcal{X}\right) = -\sum_t \sum_i r_i^t \log y_i^t$$

$$y_i^t = \frac{\exp\left[\sum_h w_{ih} p_h^t + w_{i0}\right]}{\sum_k \exp\left[\sum_h w_{kh} p_h^t + w_{k0}\right]}$$



The updates are the same as the regression problem.