

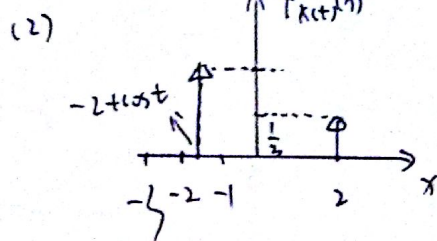
# ECE 581 Hmwk 9.

9-1: (a).

$x_1$	2	$\cos(t_1) - 2$
$x_2$	$\frac{1}{3}$	0
$\cos(t_2) - 2$	0	$\frac{2}{3}$

$$\begin{aligned} \therefore R_X(t_1, t_2) &= 4 \cdot \frac{1}{3} + (\cos t_1 - 2)(\cos t_2 - 2) \cdot \frac{2}{3} \\ &= \frac{4}{3} + \frac{2}{3} \cos t_1 \cos t_2 - \frac{4}{3} (\cos t_1 + \cos t_2) \\ &\quad + \frac{8}{3} = 4 + \frac{2}{3} \cos t_1 \cos t_2 - \frac{4}{3} (\cos t_1 + \cos t_2) \end{aligned}$$

(b) (1)  $f_{X(t)}(x) = \frac{1}{3} \delta(x_2) + \frac{2}{3} \delta(x - \cos t + 2)$

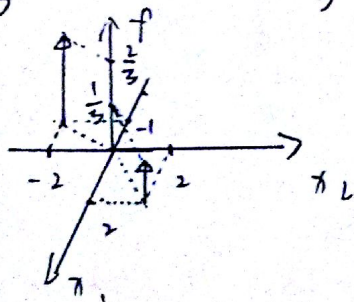


(c) (1)  $f_{X(t_1), X(t_2)}(x_1, x_2)$

$$= \frac{1}{3} \delta(x_1 - 2) \delta(x_2 - 2) + \frac{2}{3} \delta(x_1 - \cos t_1 + 2) \delta(x_2 - \cos t_2 + 2)$$

(2)  $f_{X(t_1), X(t_2)}(x_1, x_2)$

$$= \frac{1}{3} \delta(x_1 - 2) \delta(x_2 - 2) + \frac{2}{3} \delta(x_1 + 1) \delta(x_2 + 2)$$



(d)  $R_X(0, \frac{\pi}{2}) = 4 - \frac{4}{3} = \frac{8}{3}$

$$E[X(t_1)] = \frac{1}{3} \cdot 2 + (-1) \cdot \frac{2}{3} = 0$$

$$\therefore E[X(t_1) X(t_2)] \neq E[X(t_1)] E[X(t_2)]$$

not correlated

9-2: (a)  $E[X(t)] = E[X^2(t)]$   
 $= E^2[X] + \text{variance}$

$$= R_X(0) = E[X(t) X(t)]$$

(b)  $E[X(t)] = 4 + 3 = 7$

9-3: (a)  $E[X(k)]$

$$= \cos(\omega_0 k) E[A]$$

$$= \eta_A \cos(\omega_0 k)$$

(b)  $E[X(k)]^2 + E[X(k)]^2$

$$= \text{variance}$$

$$= \eta_A^2 \cos^2(\omega_0 k) + \cos^2(\omega_0 k) E[A^2]$$

$$= \eta_A^2 \cos^2(\omega_0 k) + (6^2 A + \eta_A^2)$$

$$\cos^2(\omega_0 k)$$

$$= 6^2 A \cos^2(\omega_0 k)$$

$$= 6^2 A \cos^2(\omega_0 k)$$

(c) not wss r.p.

because  $E[X(k)]$

$\neq \text{constant}$