





DLI Accelerated Data Science Teaching Kit

## Lecture 14.6 - Decision Tree





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#### **Decision Tree**

Decision tree builds classification or regression models in the form of a tree structure.

A decision tree allows to predict the value of a target variable by following the decisions in the tree from the root (beginning) down to a leaf node.

A tree consists of branching conditions where the value of a predictor is compared to a trained weight.

• The number of branches and the values of weights are determined in the training process.

Decision trees are prone to overfitting, additional modification, or pruning, may be used to simplify the model.



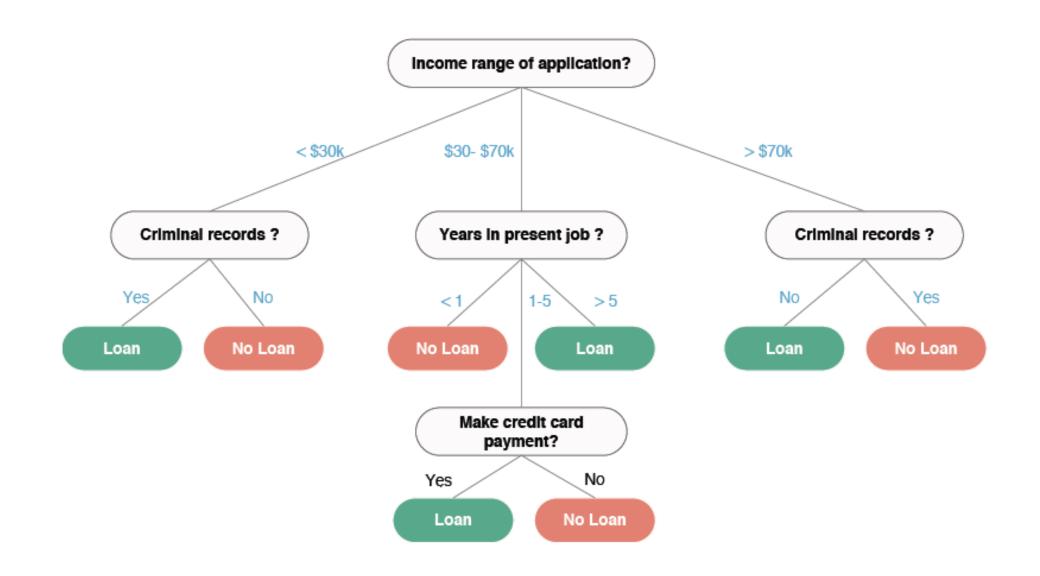




#### **Application**

Decide whether or not to offer someone a loan based on features below

- Income
- Criminal records
- Years in present job
- Payment for credit card





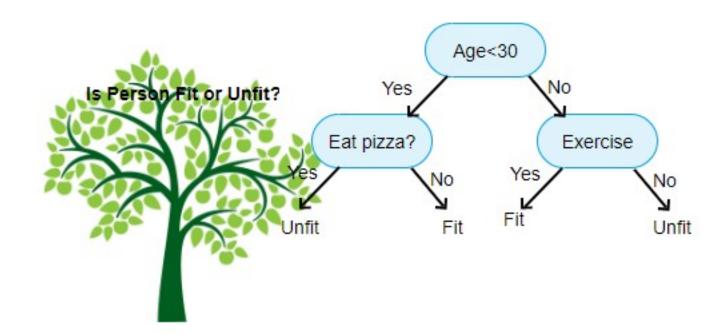




### **Building a Decision Tree**

## Decision Tree generates the output as a tree-like structure

- Built top-down from a root node
- Break down a dataset into smaller and smaller subsets
- An associated decision tree is incrementally developed
- A tree with decision nodes and leaf nodes.
- A decision node has two or more branches.
- Leaf node represents a classification or decision.
- The topmost decision node in a tree which corresponds to the best predictor called root node.



## **Building a Decision Tree (Continued)**

Strategy: top-down recursive divide-and-conquer fashion

Recursively partitions the training set until each partition consists entirely or dominantly of examples from one class.

- 1. First: select attribute for root node
  - Create a branch for each possible attribute value
- 2. Then: split the data set into subsets
  - One for each branch extending from the node
- 3. Finally: repeat recursively for each branch

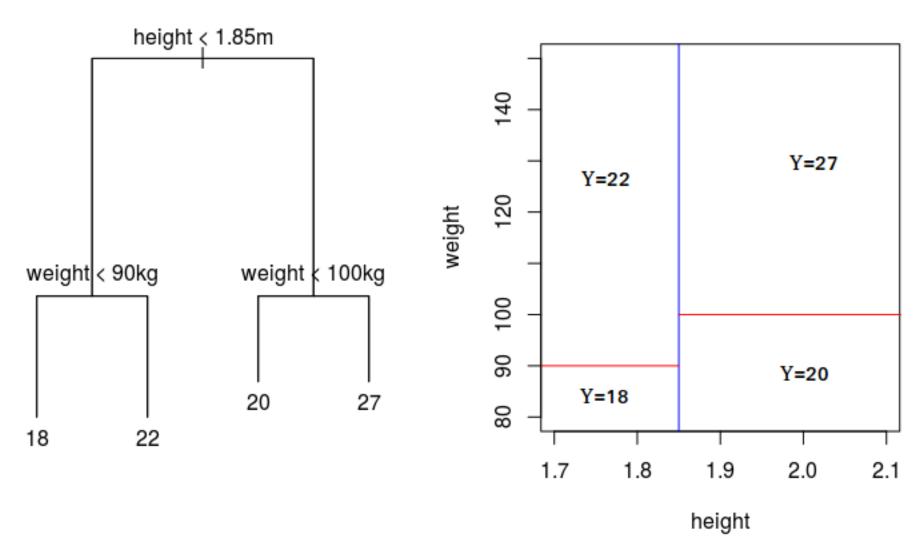
Each non-leaf node of the tree contains a split point that is a test on one or more attributes and determines how the data is partitioned.

The tree is built by recursively partitioning the data.



### **Splitting Data**

A decision tree subdivides a feature space into regions of roughly uniform values



Source: https://medium.com/swlh/decision-tree-classification-de64fc4d5aac

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### **Selecting Feature**

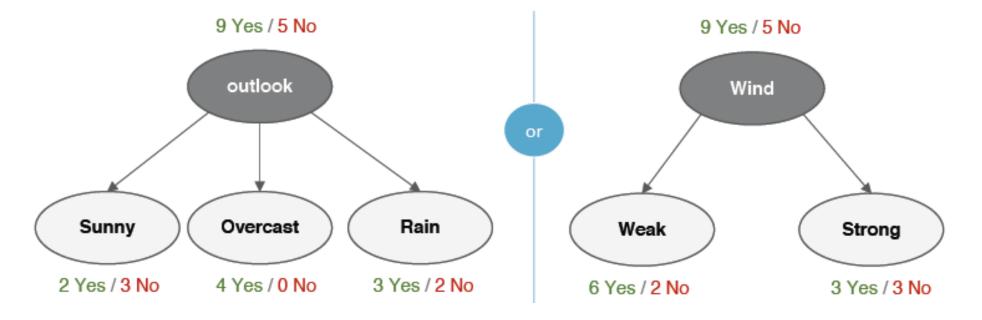
Growing a tree involves deciding on which features to choose and what conditions to use for splitting, along with knowing when to stop.

In this procedure all the features are considered, and different split points are tried and tested using a

cost function.

The split with the best cost (or lowest cost) is selected.

Compare the different ways to split data in a node



Day	Outlook	Humidity	Wind	Play
D1	Sunny	High	Weak	No
D2	Sunny	High	Strong	No
D3	Overcast	High	Weak	Yes
D4	Rain	High	Weak	Yes
D5	Rain	Normal	Weak	Yes
D6	Rain	Normal	Strong	No
D7	Overcast	Normal	Strong	Yes
D8	Sunny	High	Weak	No
D9	Sunny	Normal	Weak	Yes
D10	Rain	Normal	Weak	Yes
D11	Sunny	Normal	Strong	Yes
D12	Overcast	High	Strong	Yes
D13	Overcast	Normal	Weak	Yes
D14	Rain	High	Strong	No

Generally, entropy is a measure of disorder or uncertainty

Entropy is a concept used in Physics, mathematics, computer science (information theory) and other fields of science.

Generally, information entropy is the average amount of information conveyed by an event.

The measure of information entropy associated with each possible data value is the negative logarithm of the probability mass function for the value.

$$Entropy = -\sum_{i=1}^{n} p_i log p_i$$







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$$Entropy = -\sum_{i=1}^{n} p_i log p_i$$

where  $p_i$  is the probability of getting the  $i^{th}$  value when randomly selecting one from the set.

In other words, there are n classes, and  $p_i$  is the probability an object from the  $i^{th}$  class appearing.







Information gain increases with the average purity of the subsets.

Strategy: choose attribute that gives greatest information gain.

A reduction of entropy is often called an information gain.

Uses entropy to calculate the homogeneity of a sample.

Constructing a decision tree is all about finding attribute that returns the highest information gain (i.e., the most homogeneous branches)

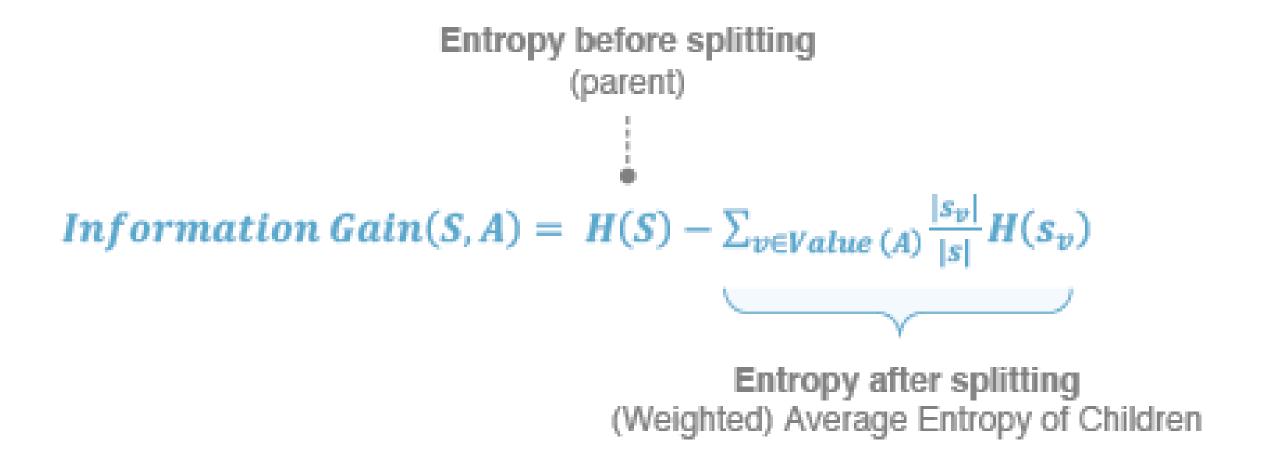
- A decision tree is built to up-down from a root node and involves partitioning the data into subsets that contain instances with similar values (homogenous).
- The information gain is based on the decrease in entropy after a dataset is split on an attribute...







The goal is to decrease in entropy (uncertainty) after splitting.



#### Where

v: possible value of A S: set of example  $\{x\}$  $s_v$ : subset where  $x_A = v$ 



### **Example**

#### Data

Example	crust	shape	filling	Class
	size		size	
<i>e</i> 1	big	circle	small	pos
<i>e</i> 2	small	circle	small	pos
<i>e</i> 3	big	square	small	neg
e4	big	triangle	small	neg
<i>e</i> 5	big	square	big	pos
e6	small	square	small	neg
<i>e</i> 7	small	square	big	pos
e8	big	circle	big	pos

Here is the entropy of the training set where only class labels are known.

$$H(T) = -p_{pos} \log_2 p_{pos} - p_{neg} \log_2 p_{neg}$$
  
=  $-(5/8) \log(5/8) - (3/8) \log(3/8) = 0.954$ 

Next step is to calculate the entropies of the subsets defined by the values of the attribute shape.

$$H(\text{shape=square}) = -(2/4) \cdot \log(2/4) - (2/4) \cdot \log(2/4) = 1$$
  
 $H(\text{shape=circle}) = -(3/3) \cdot \log(3/3) - (0/3) \cdot \log(0/3) = 0$   
 $H(\text{shape=triangle}) = -(0/1) \cdot \log(0/1) - (1/1) \cdot \log(1/1) = 0$ 

$$H(T, \text{shape}) = (4/8) \cdot 1 + (3/8) \cdot 0 + (1/8) \cdot 0 = 0.5$$



#### Example

#### Data

Example	crust	shape	filling	Class
	size		size	
<i>e</i> 1	big	circle	small	pos
<i>e</i> 2	small	circle	small	pos
<i>e</i> 3	big	square	small	neg
<i>e</i> 4	big	triangle	small	neg
<i>e</i> 5	big	square	big	pos
e6	small	square	small	neg
<i>e</i> 7	small	square	big	pos
e8	big	circle	big	pos

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H(T, \text{crust} - \text{size}) = 0.951
H(T, \text{filling} - \text{size}) = 0.607
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$$I(T, \text{shape}) = H(T) - H(T, \text{shape}) = 0.954 - 0.5 = 0.454$$
  
 $I(T, \text{crust-size}) = H(T) - H(T, \text{crust-size}) = 0.954 - 0.951 = 0.003$   
 $I(T, \text{filling-size}) = H(T) - H(T, \text{filling-size}) = 0.954 - 0.607 = 0.347$ 











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# Thank You

