

Lecture 5

Cameras, Projections, and Clipping

Lecture outline:

1. Pin-hole camera
 2. Family of Projections
 3. Parallel Projection
 4. Perspective Projection
 5. OpenGL Projection Model: 4x4 projection matrix
 6. Clipping and Perspective Division
- 
- Basic Concepts

Camera: Forming an image

- Last lecture: we built a 3D geometric world
- Now, we need some sort of sensor to receive and record a picture.
- Is this all we need?



- Do we get a useful image?

Physical Model 1: Pin-hole Camera

Pinhole Camera

object



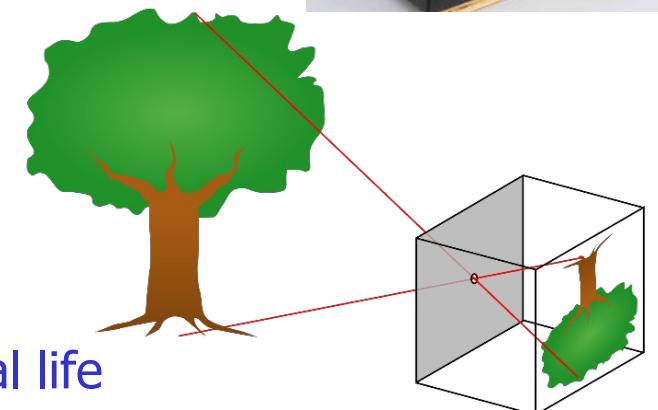
barrier

a hole

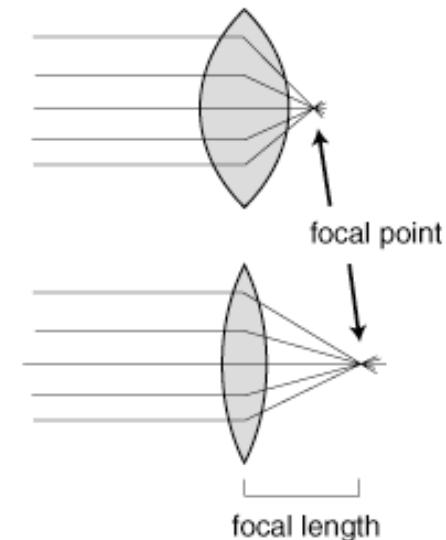
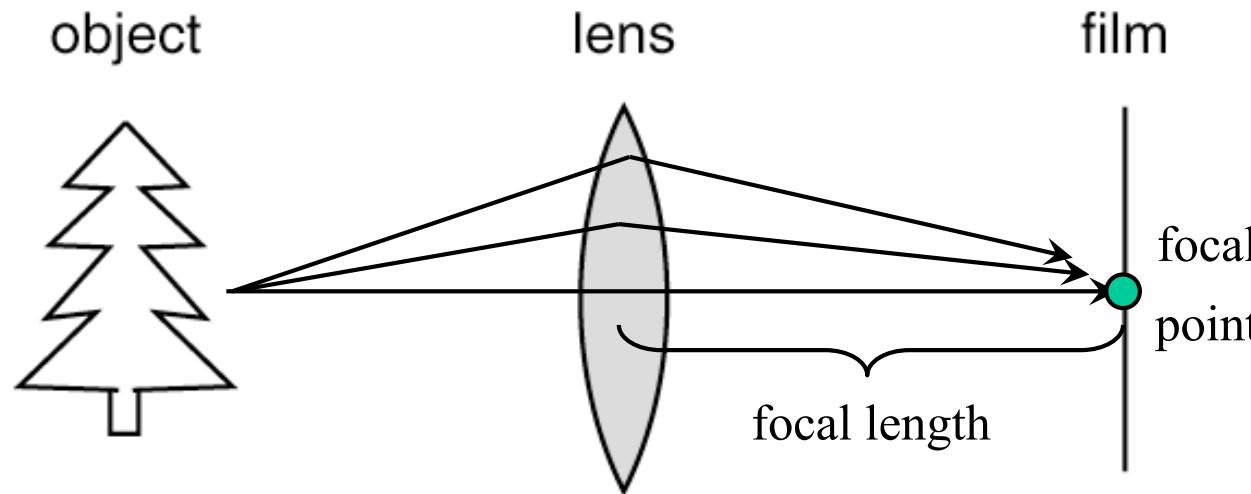
film



- Advantages:
 - easy to simulate
 - everything is in focus
- Disadvantages:
 - needs a bright scene (or long exposure) – in real life
 - everything is in focus (no depth of field) – not realistic (photography)



Physical Model 2: Camera with Lens



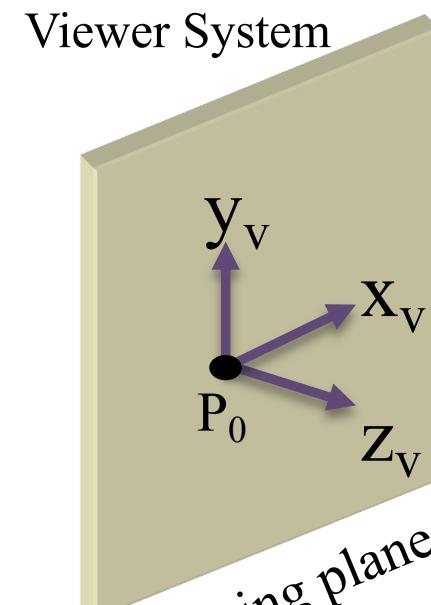
- Advantages:
 - no need to have bright scene - in real life
 - not everything is in focus (more realistic in terms of photography)
- Disadvantages:
 - need more programming to simulate
 - not everything is in focus (can only capture objects within a certain depth range)

Viewing in OpenGL

- ! "#\$%&' \$() *%+, \$- ' . , (/%01/2%02%+, 3/405%106\$30
 - What parameters do you need to define a camera?
 - Viewpoint (Center of Projection)
 - View direction
 - Field of view
 - Film size
 - Projection plane

Viewing

- ! 7,\$- , (8%\$94,3\$2%; %\$5\$6\$ (/2;
 - Objects to be viewed
 - A viewer with a projection surface
 - A projection from the objects to the viewing surface



Viewing plane

Viewing

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- Objects: Whatever you’re taking a picture of: landscape, people, etc.
- Viewer: The camera (with its film as the projection surface)
- Projection: Defined by the lens, maps 3D objects on to the 2D surface

Viewing

- ! <=06' 5\$;%&' \$() *%106\$30
 - Objects: The input geometry
 - Viewer: The OpenGL “camera” (with the view volume as its viewing “surface”)
 - Projection: The OpenGL projection matrix (`GL_PROJECTION`), maps 3D space (world coordinates) into 3D space (eye coordinates)
 - Eventually into normalized device coordinates (NDC)

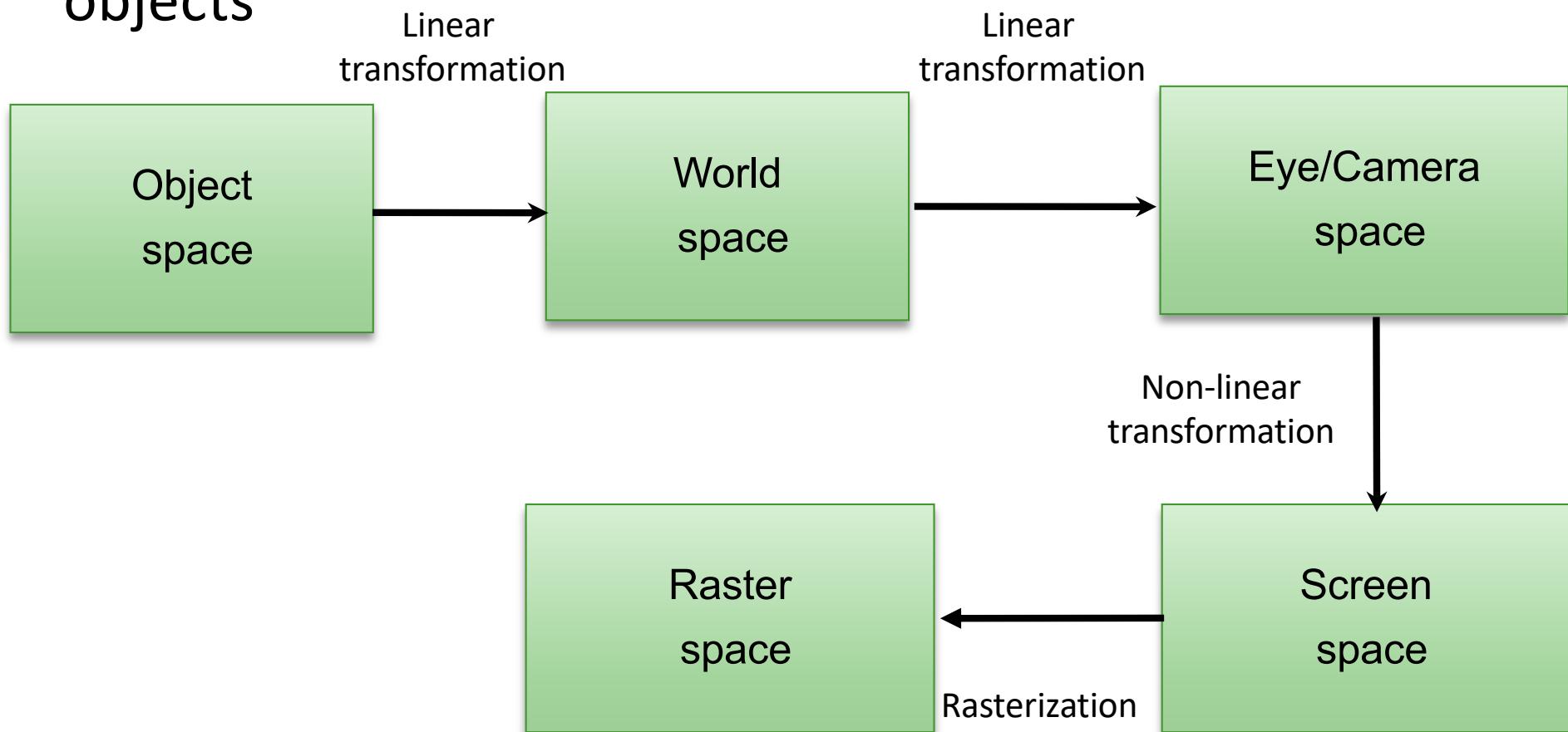
Planar Geometric Projections

- Standard projections are assumed to be onto a single plane
- A projection can be perspective or orthographic
 - In perspective projection, all rays converge at a single point (the center of projection, or COP)
 - In orthographic projection, all rays are parallel



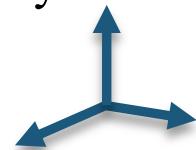
Coordinate Systems

- Coordinate systems used when rendering geometry objects

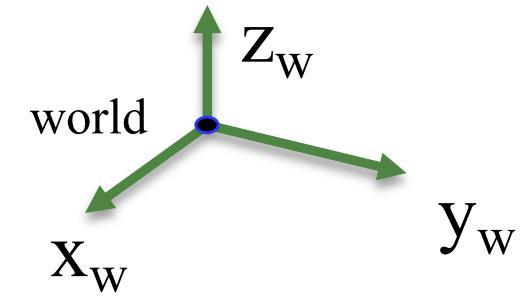


Viewing Coordinate System

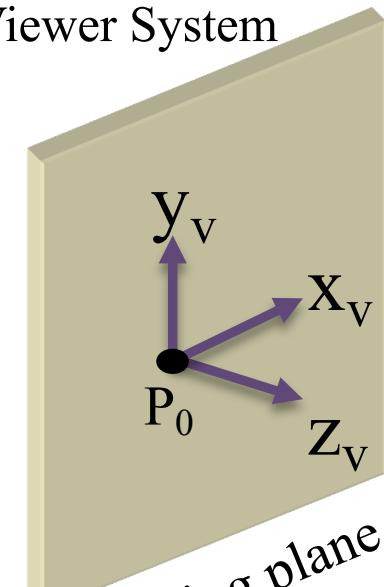
Body System



Front-Wheel System



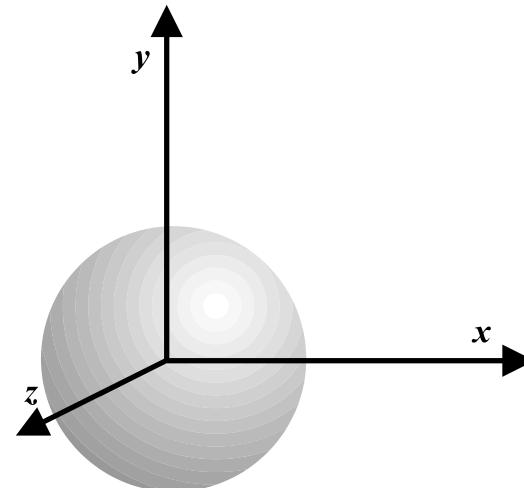
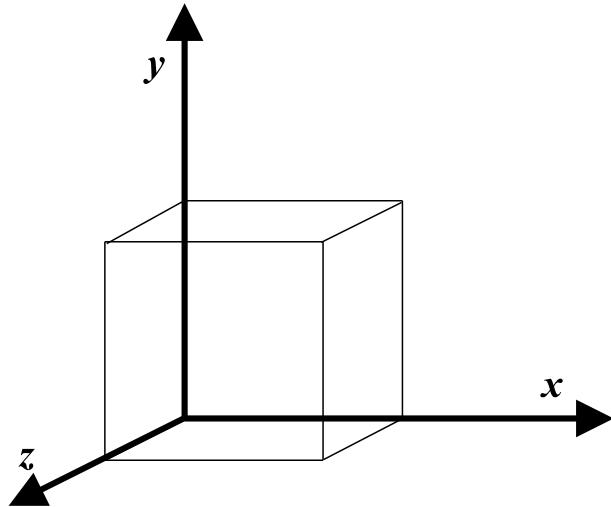
Viewer System



Viewing plane

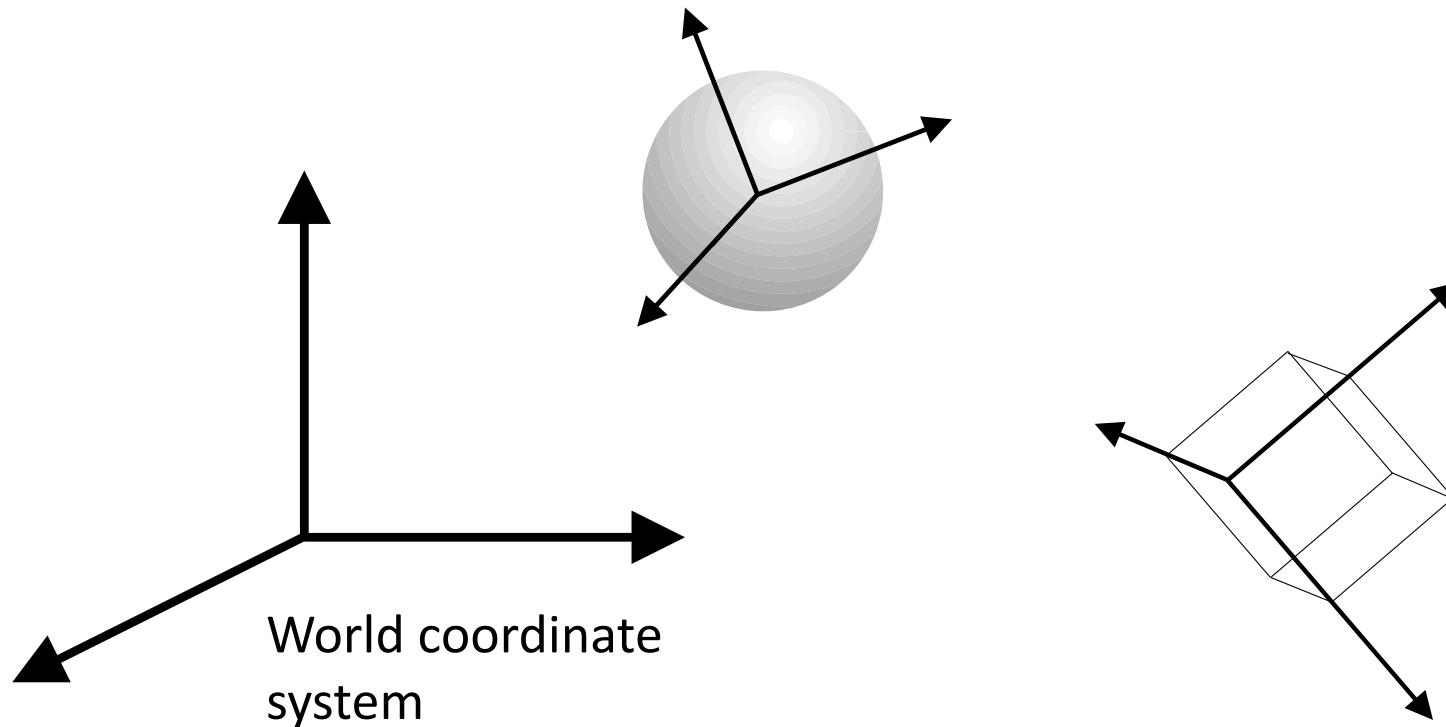
Object Space

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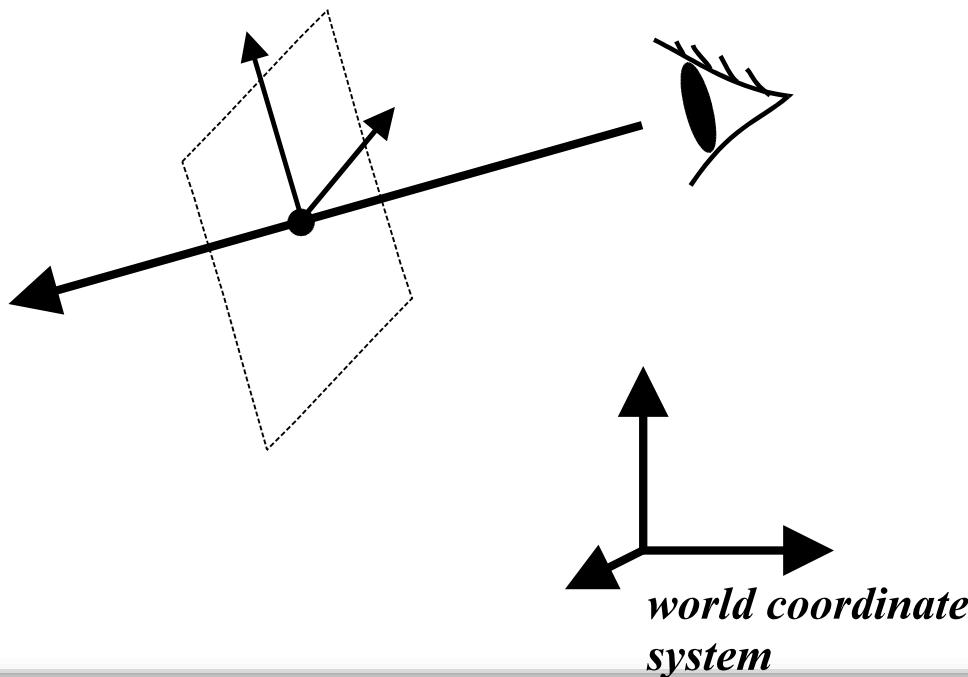
World Space

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2#03\$?%B@%055% BC\$1/2%(%#\$/%. ?\$5\$?%21\$(\$



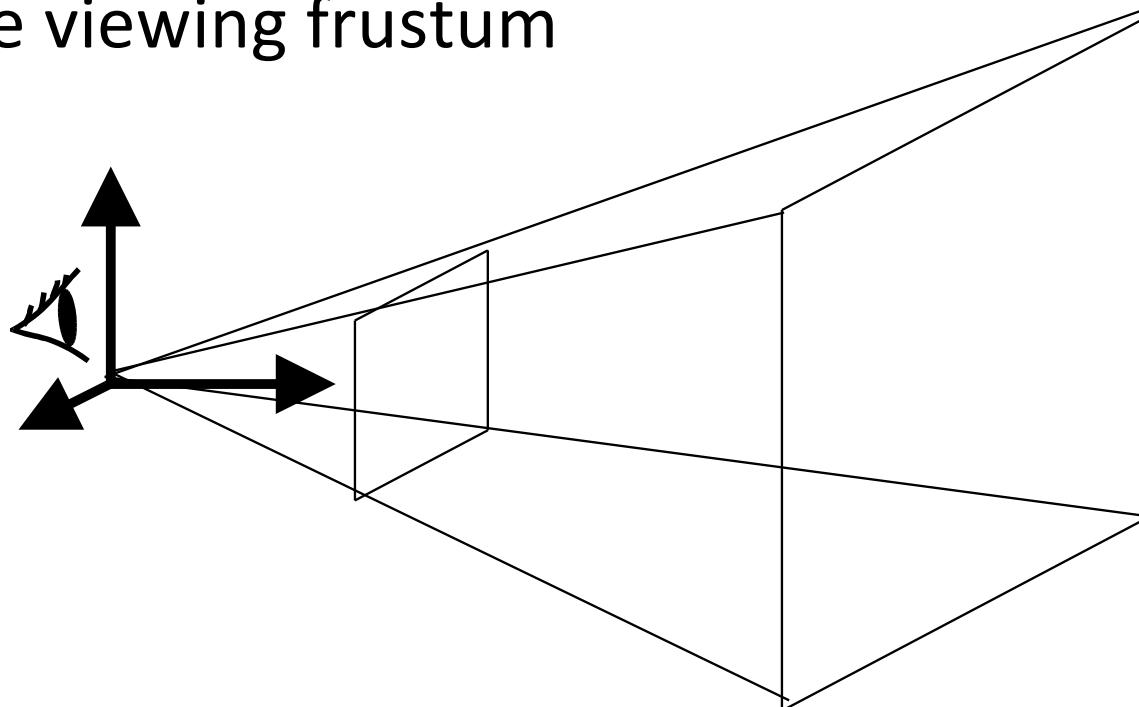
Eye/Camera Space

- The coordinate system with the eye or the center of projection as its origin
- A space in which the viewing volume is established
- Facilitates clipping (removing out-of-view objects)



Screen Space

- Transformation to screen space is a process that describes how light rays reach our eyes
- Screen space is defined to act within a closed volume called the viewing frustum

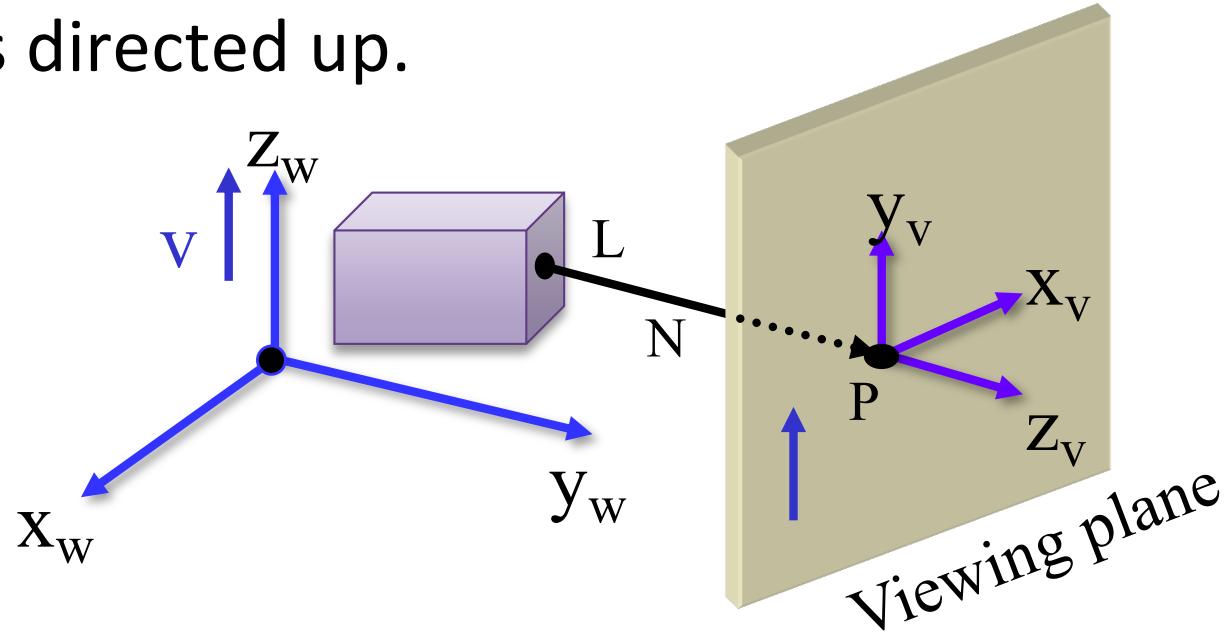


Specifying the Viewing Coordinate System

- ! Viewing Coordinates system : N% BC\$1/2%- ,/#%\$2' \$1/%. %0%+, \$ - \$3D
- ! >%+\$- ,(8% 50(\$ Hprojection plane ' \$3' \$(?,14503%. %L_v 0(?)%05,8(\$?%- ,/#%H=J@_v ID

! 0(% 3?%%. %2\$/%0%, \$-, (8% 50(\$%- \$%#0+\$%. %2' \$1,A@;%

- $P=(P_x, P_y, P_z)$ is a point where a camera is located.
- L - is a point to **look-at**.
- V - is the view up vector, whose projection onto the view-plane is directed up.



Viewing Coordinate System

! P. - %. %A. 36%7,\$- ,(8%1.. 3?,(0/\$%2@2/\$6%

$$Z_v = \frac{P - L}{|P - L|} \quad ; \quad X_v = \frac{V \times Z_v}{|V \times Z_v|} \quad ; \quad Y_v = Z_v \times X_v$$

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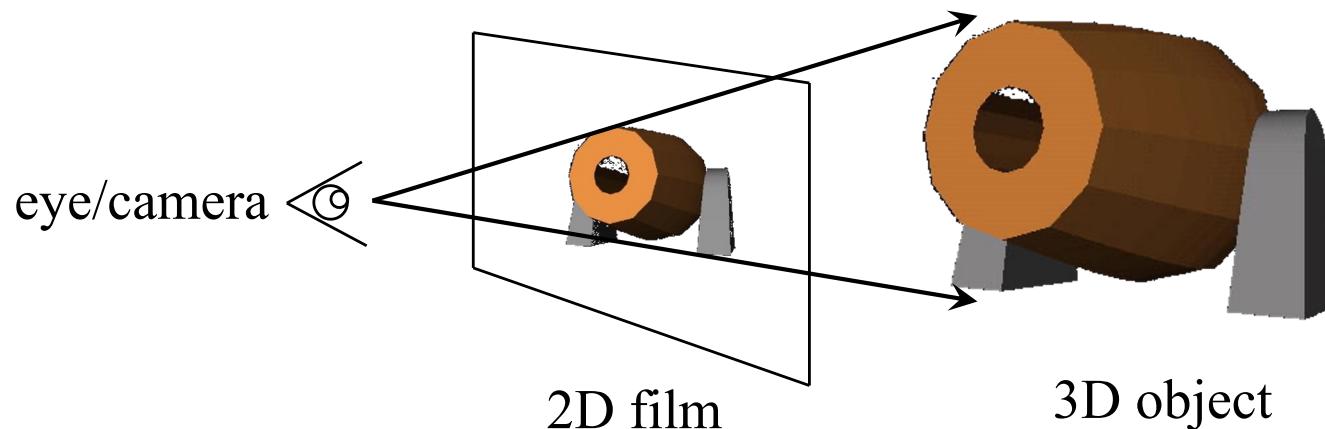
$$M = \begin{bmatrix} x_v^x & x_v^y & x_v^z & 0 \\ y_v^x & y_v^y & y_v^z & 0 \\ z_v^x & z_v^y & z_v^z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -P_x \\ 0 & 1 & 0 & -P_y \\ 0 & 0 & 1 & -P_z \\ 0 & 0 & 0 & 1 \end{bmatrix} = R \cdot T$$

3D Projection

- Even we model the world in 3D, the final display on your monitor is 2D!!!
- Projection refers to the process of projecting the 3D world onto the tiny 2D screen, so that you can visualize on your monitor.
- There are two major types of projections:
 - Perspective projection, simulates your eye
 - Orthogonal projection, preserve length after projection, used in CAD systems.

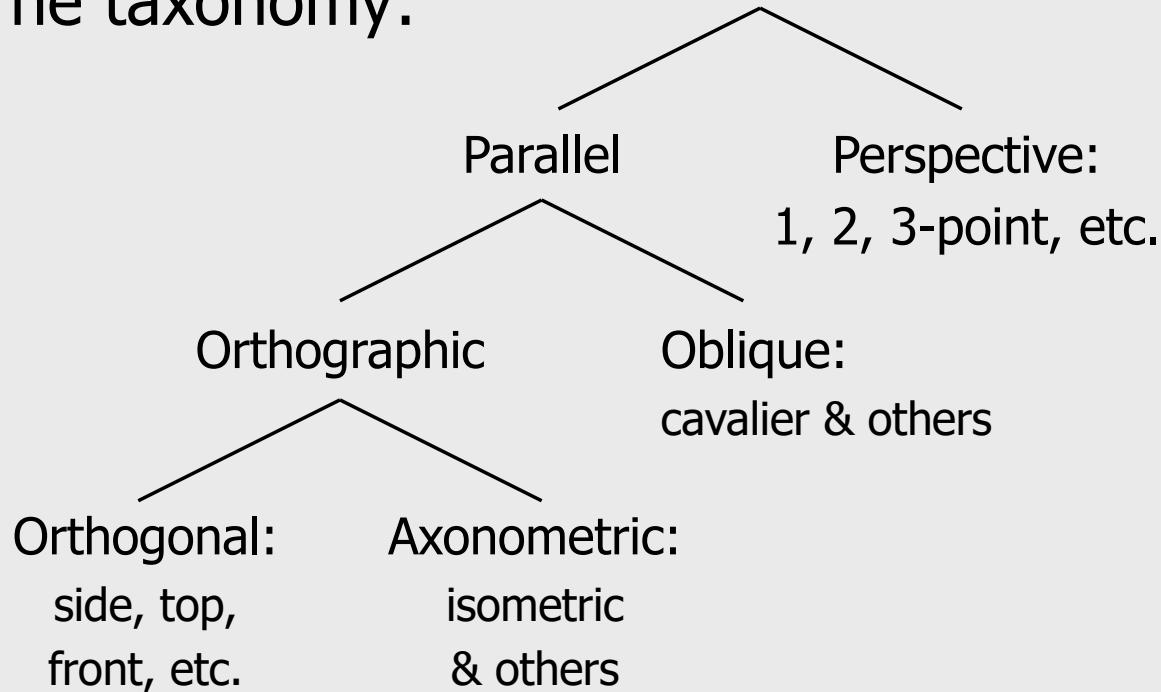
What is a Projection?

- From a higher dimension to a lower dimension
 - E.g. from n -space to m -space such that $m < n$
- So, in 3D computer graphics, usually $n=3$ and $m=2$



Family of Projections

The taxonomy:

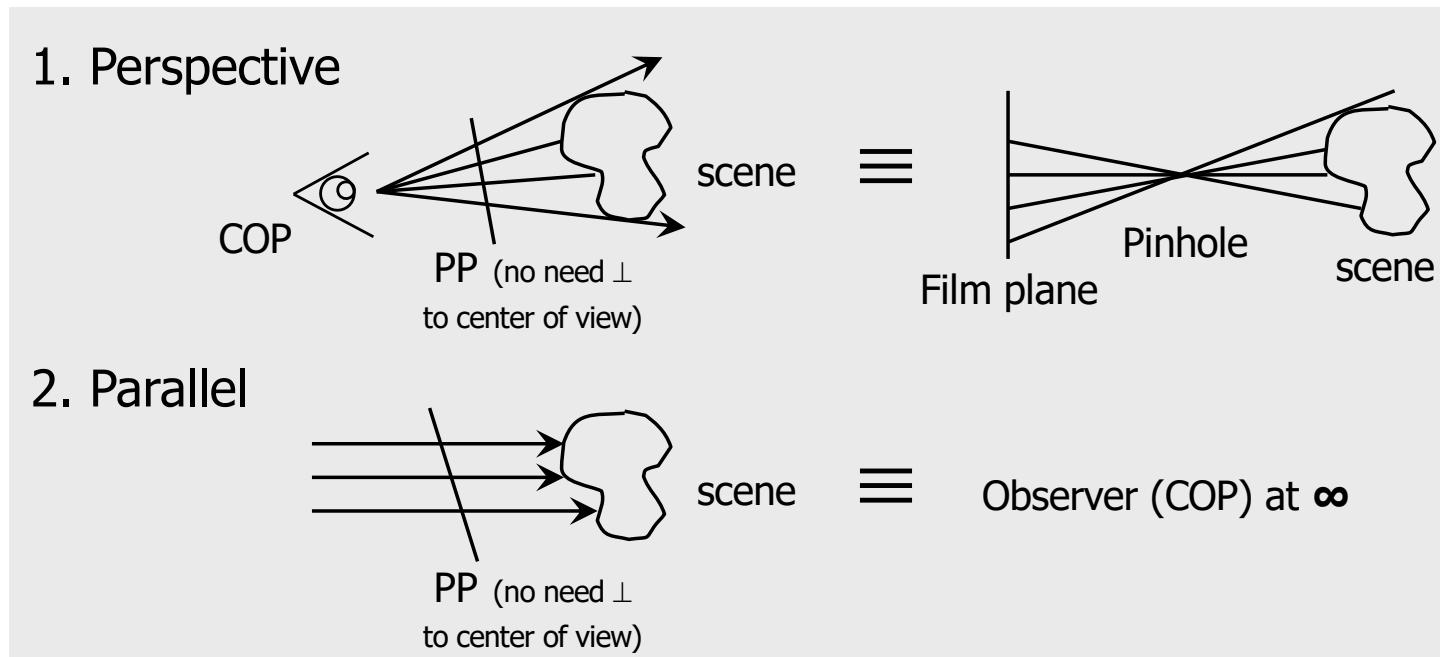


Three basic terms:

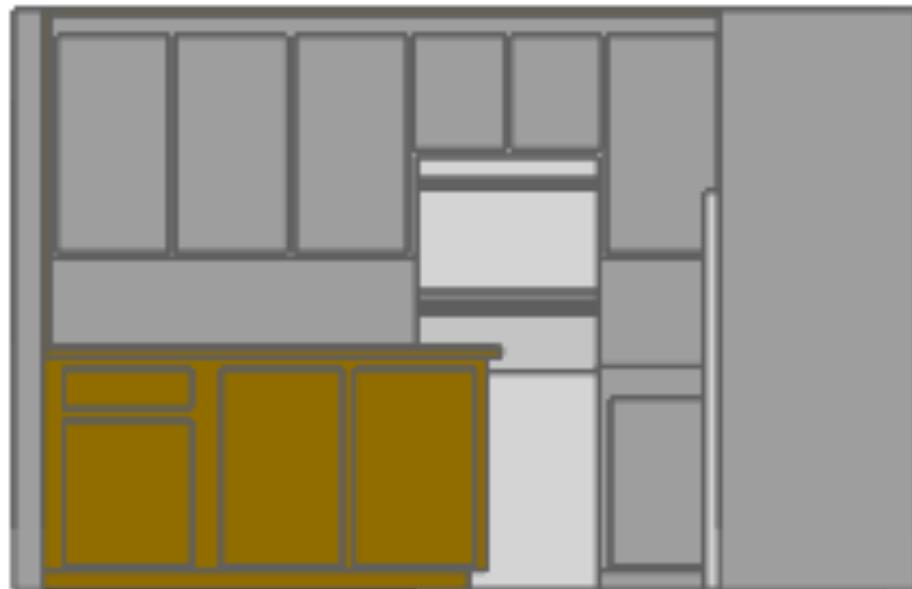
- Center of projector (COP)
- Projection plane (PP)
- Projection line and Direction of Projection (DOP)

Parallel VS Perspective Projections

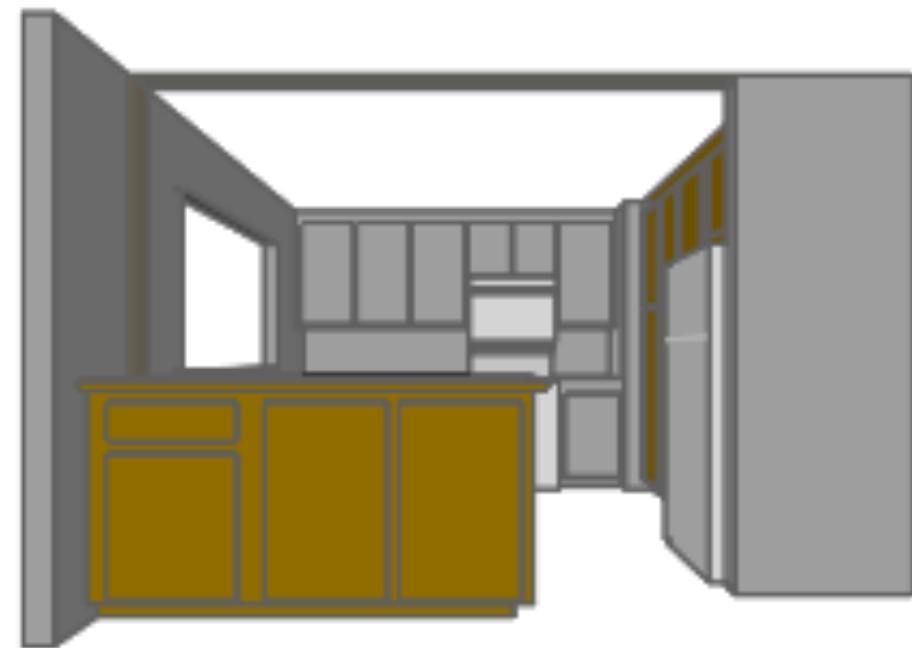
- In 3D, we map points from 3-space to the **projection plane** (PP) along **projection lines** emanating from the **center of projection** (COP):
- The center of projection (COP) is exactly the same as the pinhole in a pinhole camera



Examples



Parallel projection

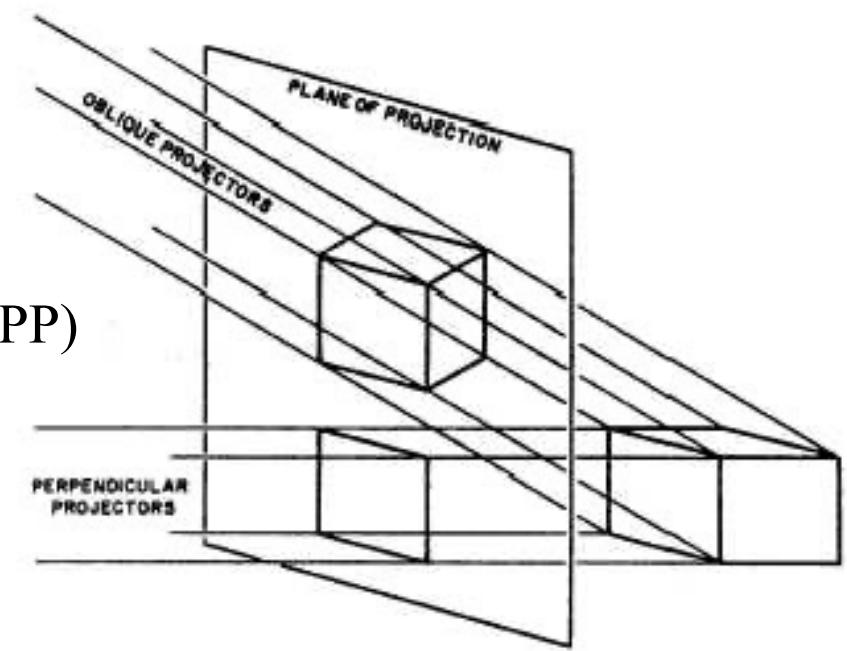
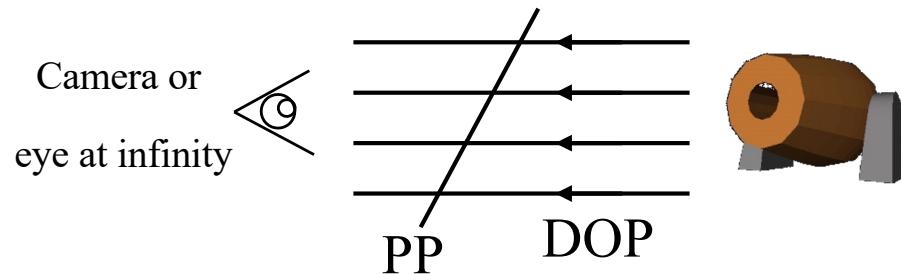


Perspective projection

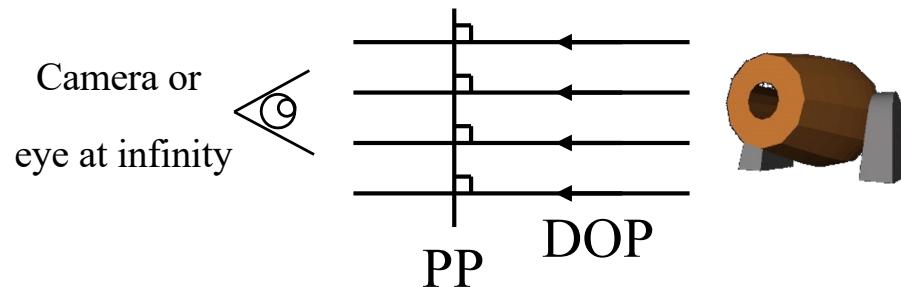
Parallel Projection

In Parallel Projection, we can specify **Direction of Projection (DOP)** because all projection lines are **parallel**.

1. Oblique Projection (DOP NOT perpendicular to PP)



2. Orthographic Projection (DOP perpendicular to PP)



Oblique Projection (parallel)

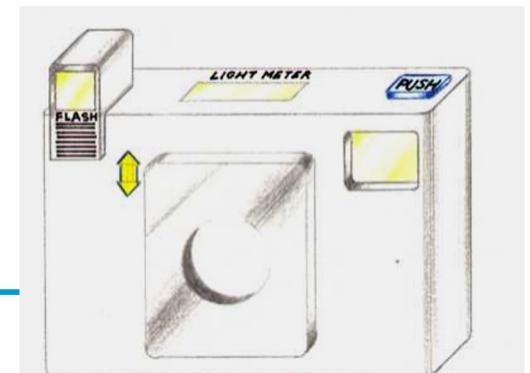
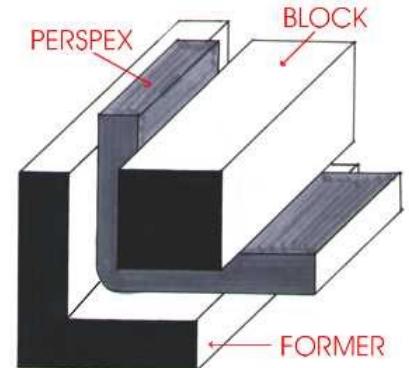
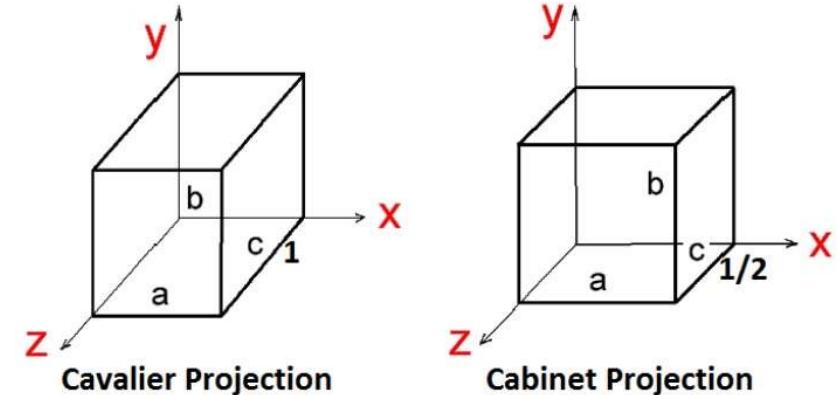
- It is like shearing the geometry along PP
- Two standards of Oblique Projection:

1. Cavalier Projection

- DOP makes 45° angle with PP
- Does not foreshorten lines perpendicular to PP
- So, it preserves lengths

2. Cabinet Projection

- DOP makes 63.4° angle with PP
- Foreshorten lines perpendicular to PP by one-half
- * Also known as “Chinese Perspective”



Orthographic Projection (parallel)

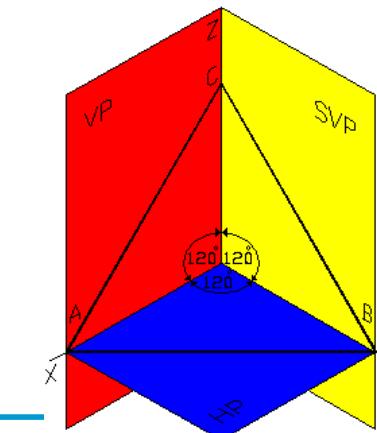
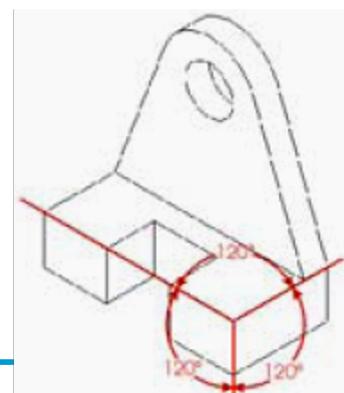
1. Orthogonal Projection

- DOP align with object's X, Y, or Z axes
- implementation: we can simply throw away the X, Y, or Z component (put it as zero) of the eye coordinate
- “side”, “top/plan”, or “front” views

2. Axonometric Projection

- arbitrary DOP, not parallel to world X, Y, nor Z axes
- special case: isometric (exactly 120°)

Example
(isometric):



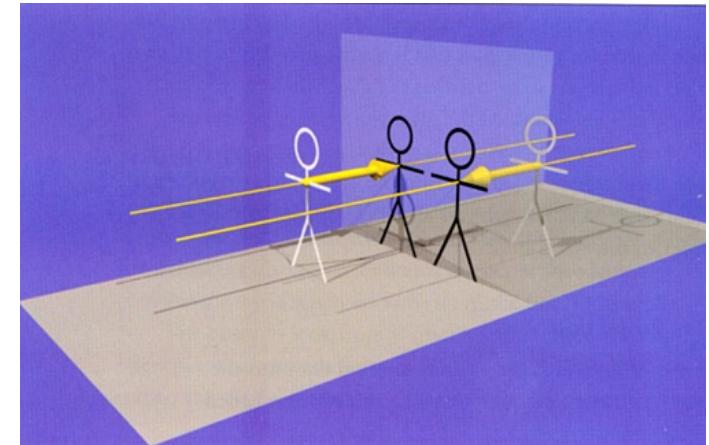
simulation games



Parallel Projection

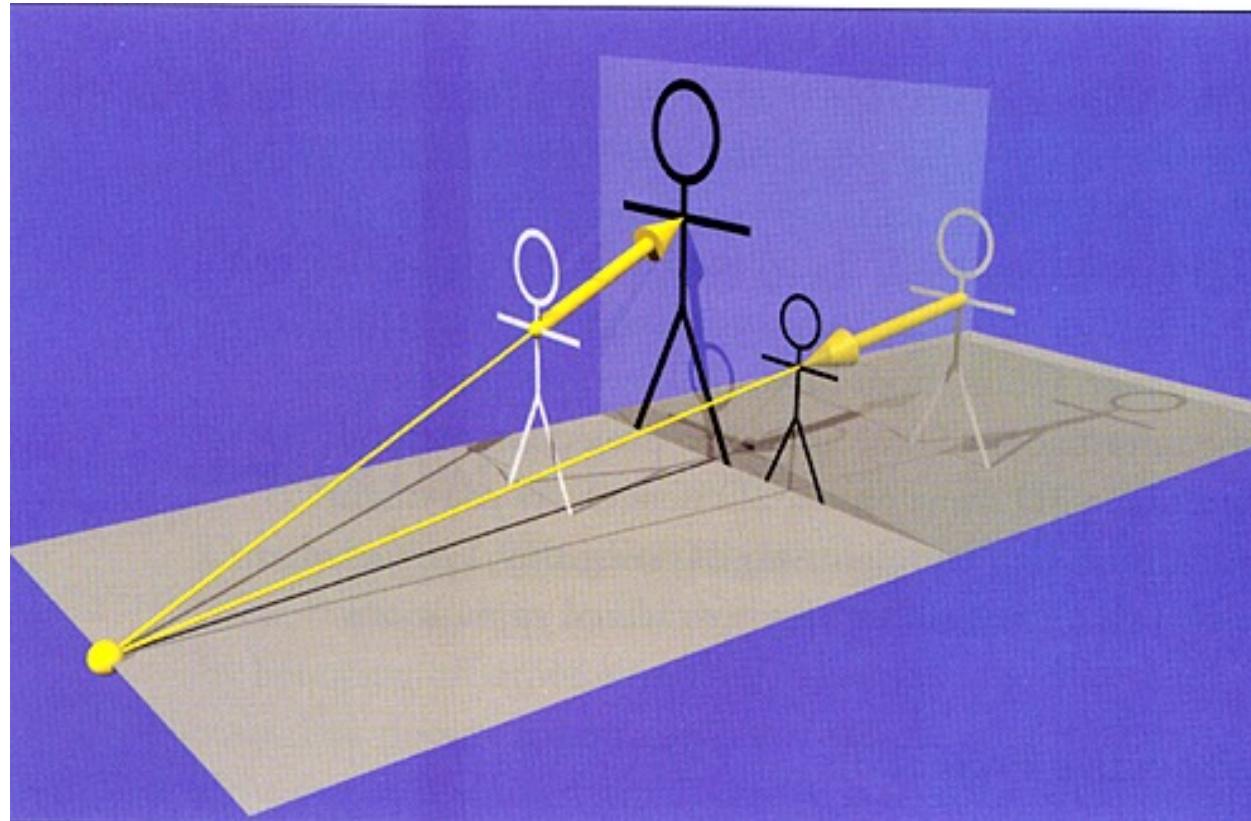
Properties of parallel projection:

- Not realistic looking
- Good for exact measurements
- Are actually a kind of affine transformations
 - Parallel lines remain parallel
 - Angles not (in general) preserved
- Most often used in CAD, architecture drawings, etc., where taking exact measurement is important



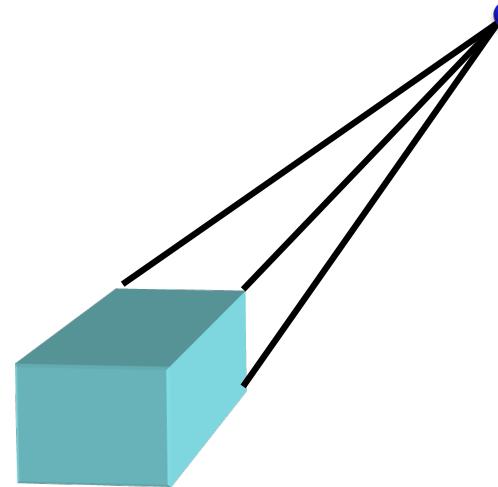
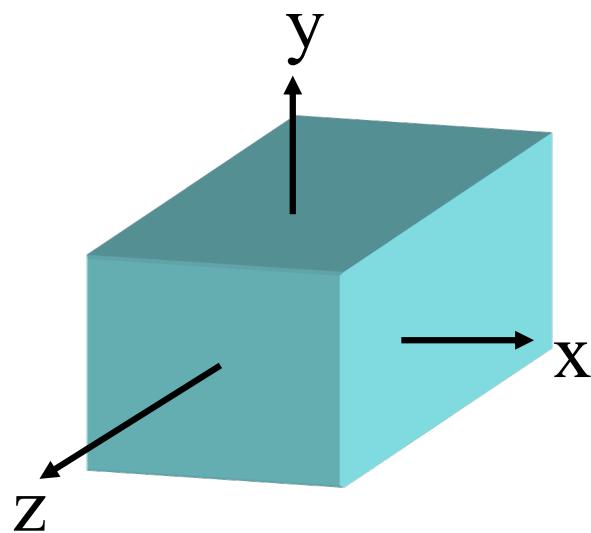
Perspective Projection

- COP is at a finite distance to the PP, so the further away an object is, the smaller it is
- This is how our eyes see the nature

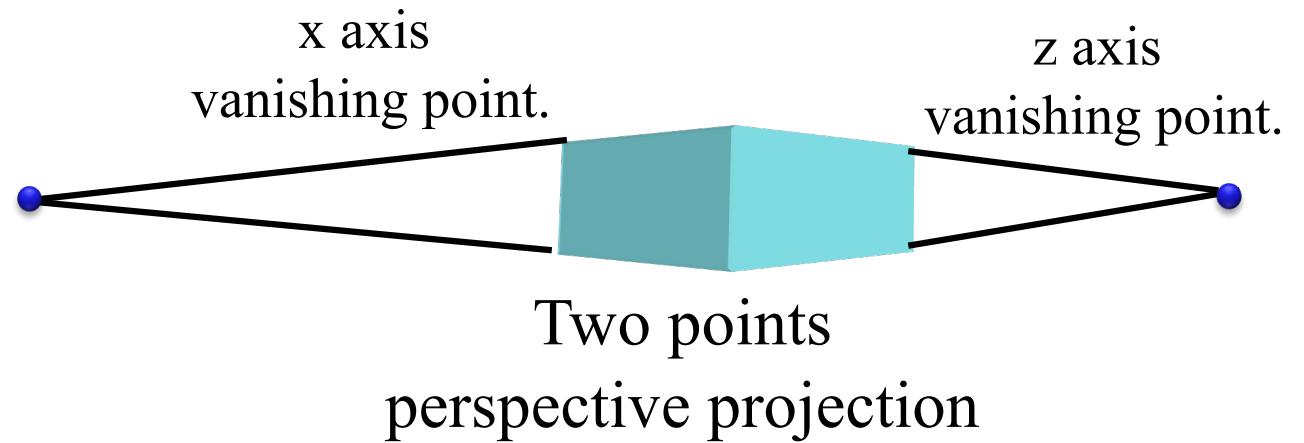


Vanishing Points

- There are infinitely many general vanishing points.
- There can be up to three *principal vanishing points* (axis vanishing points).
- Perspective projections are categorized by the number of principal vanishing points, equal to the number of principal axes intersected by the viewing plane.
- Most commonly used: one-point and two-points perspective.



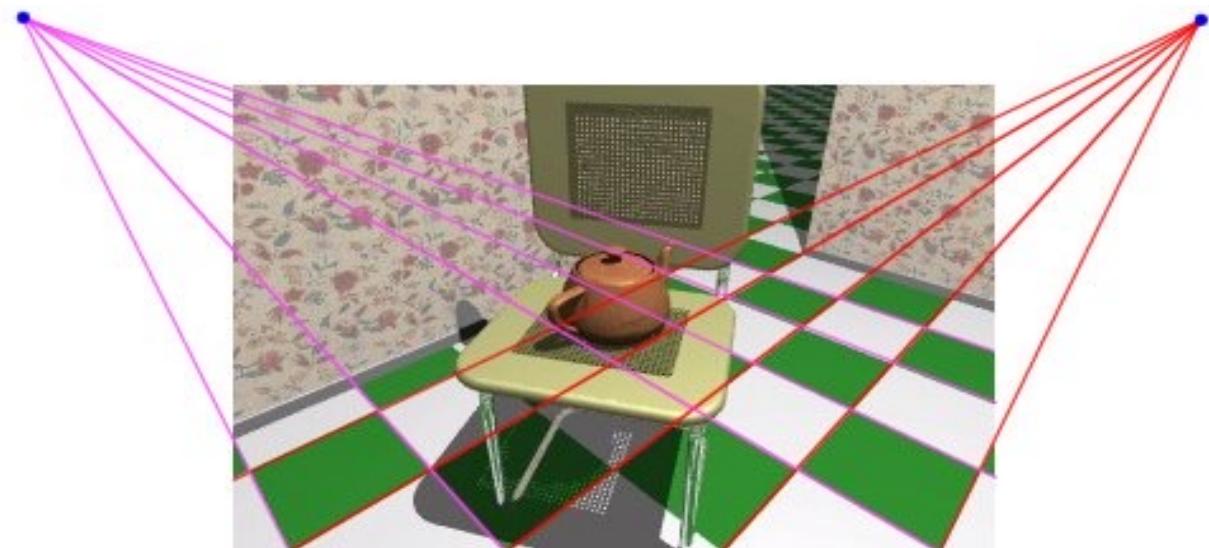
One point (z axis)
perspective projection



Two points
perspective projection

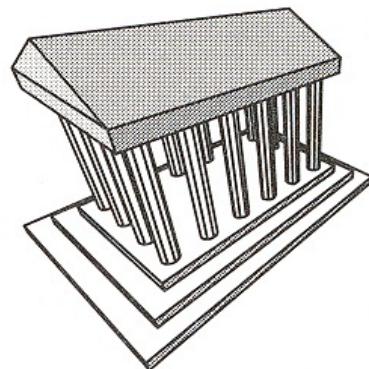
Perspective Transformation

- Parallel lines appear to converge to single point

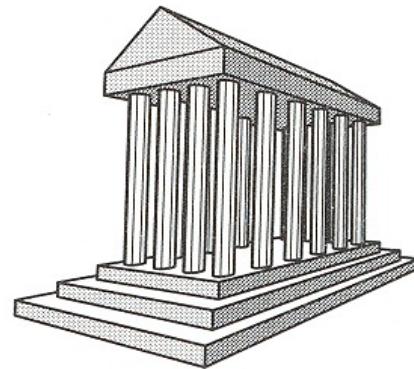


Perspective Projection

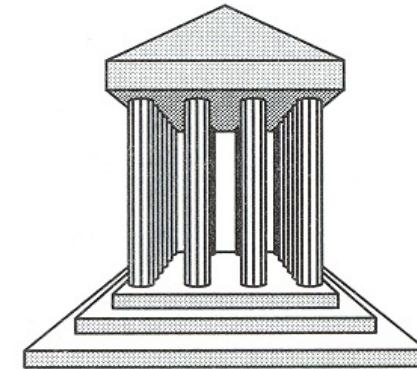
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3-Point
Perspective



2-Point
Perspective

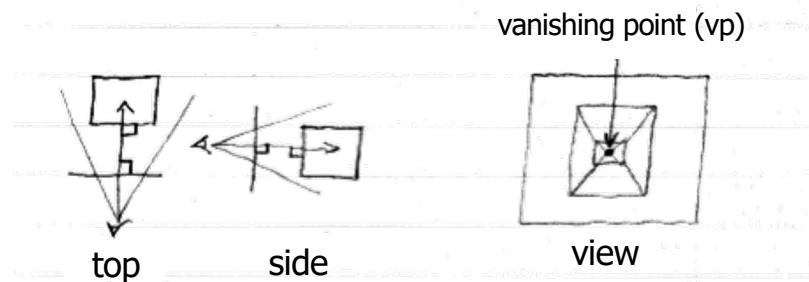


1-Point
Perspective

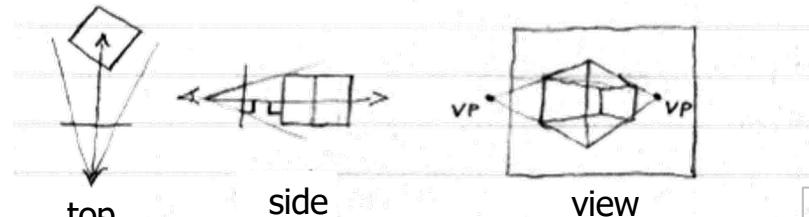
Perspective Projection

- **Vanishing points** – points at which parallel lines meet on PP

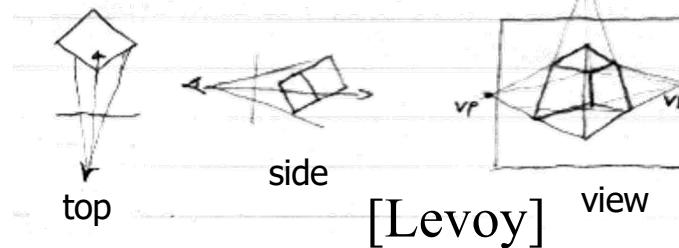
1-point:



2-point:

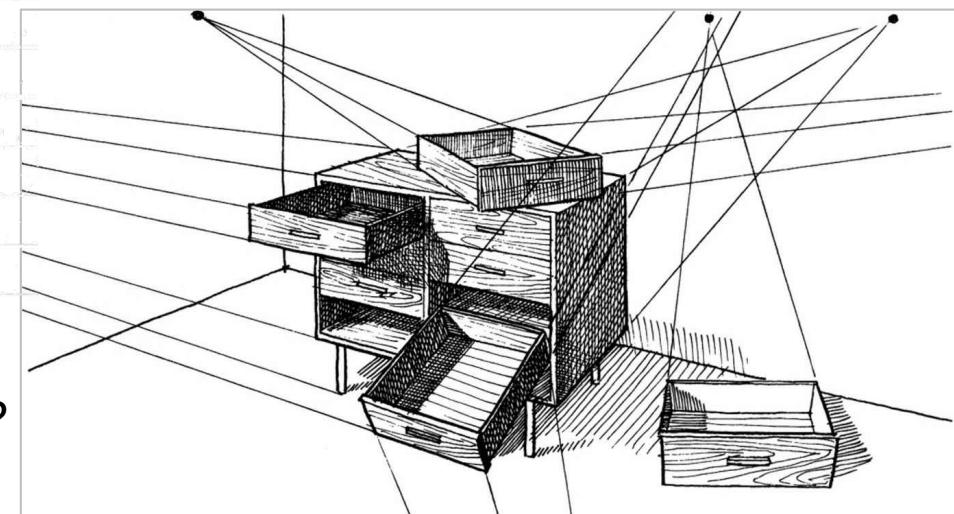


3-point:



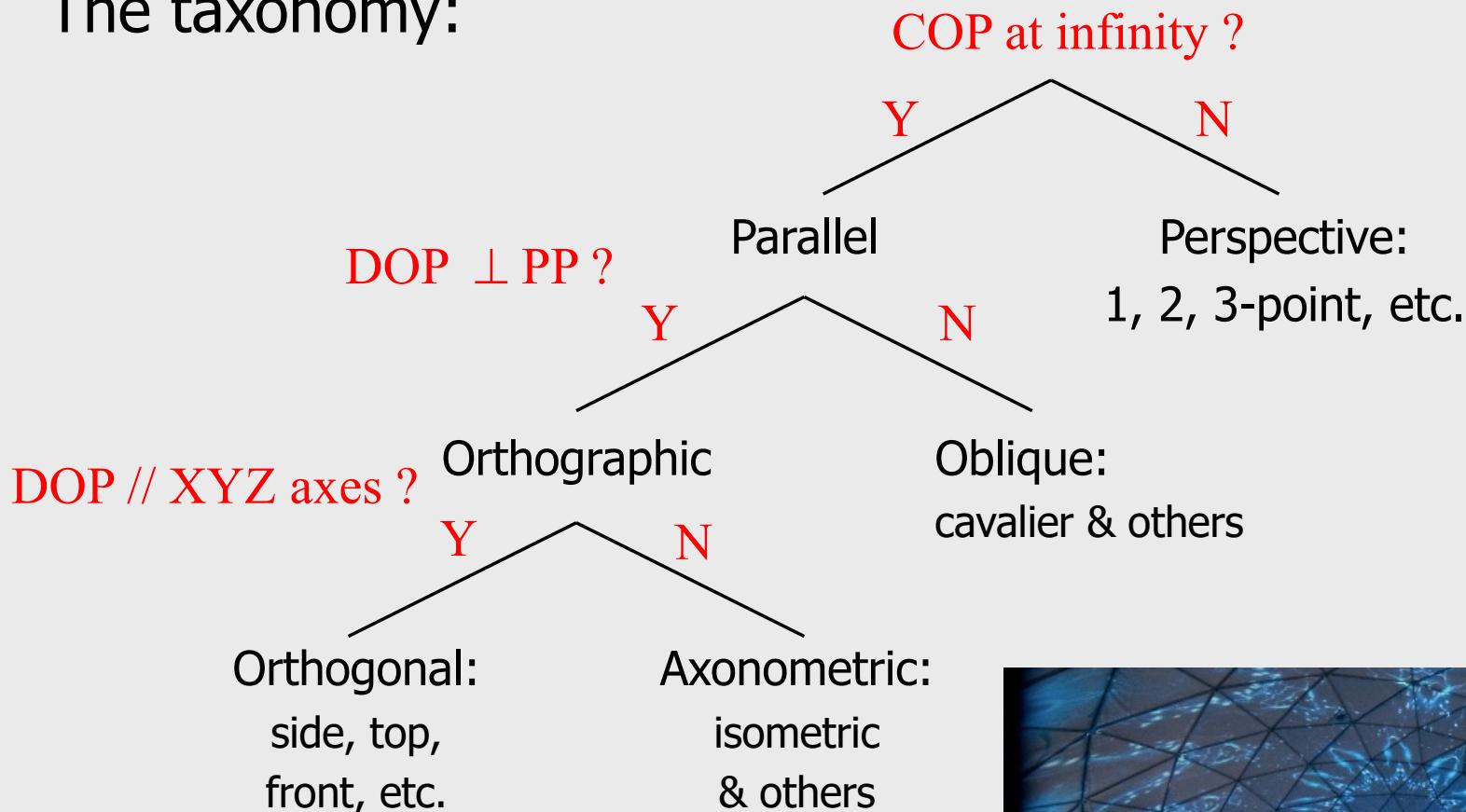
Q. How many vanishing points can a picture contain?

A. One per direction of line in the scene



Summary: Projections

The taxonomy:



Note: all these are **planar** projections

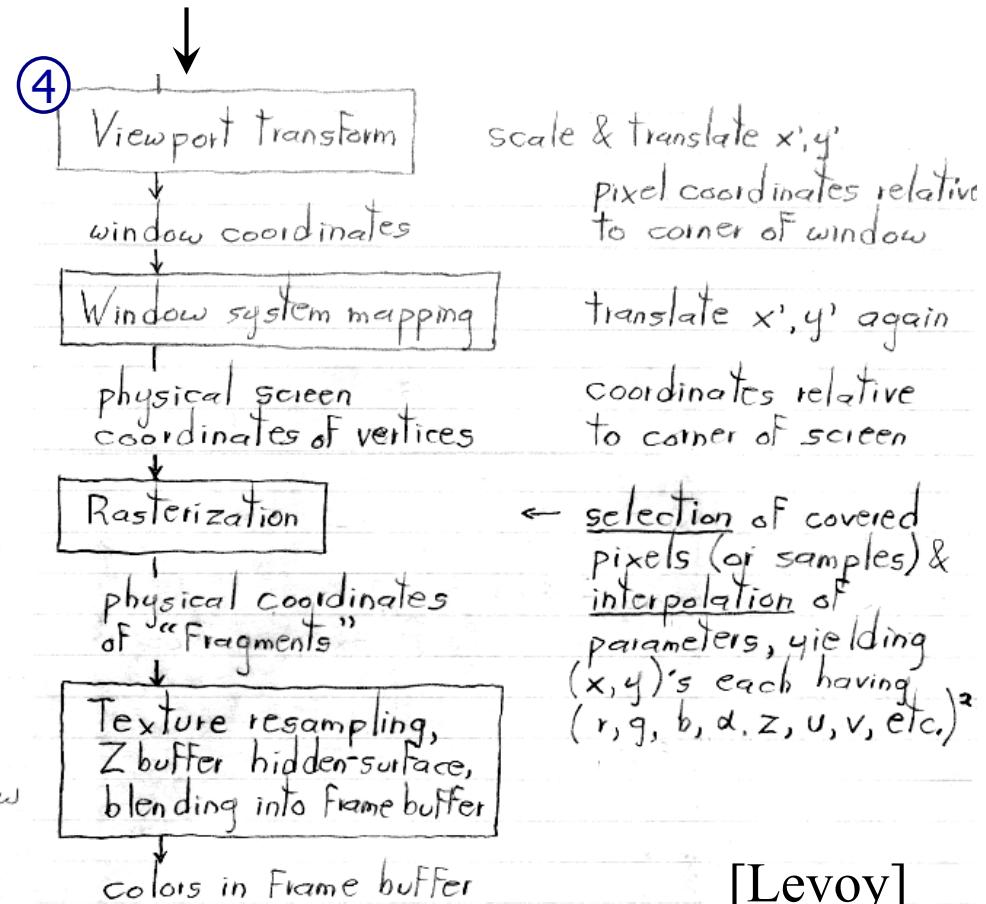
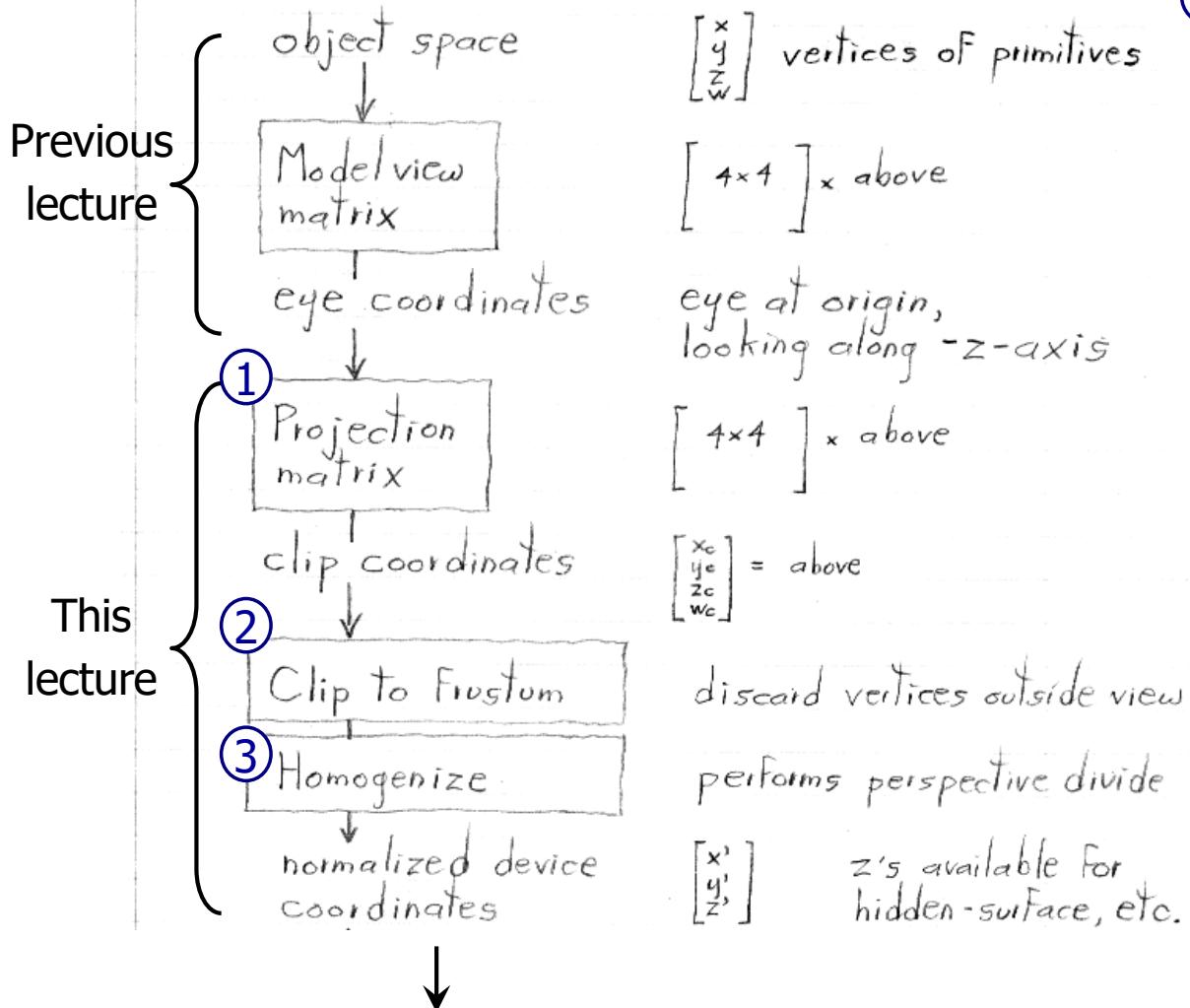
(other projections: planetarium, etc.)



Projections in OpenGL

OpenGL implementation of viewing

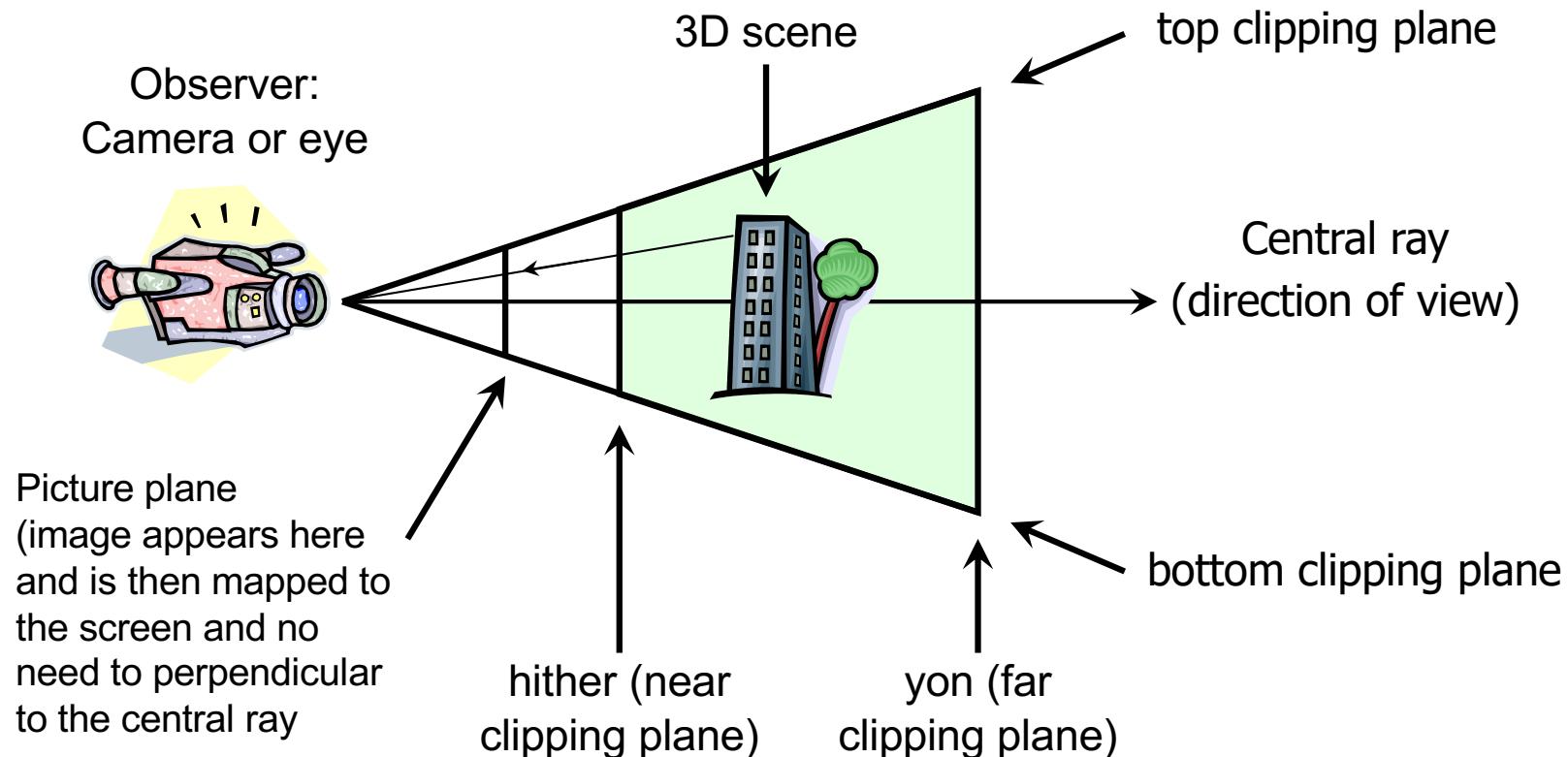
Coordinate systems:



View Frustum: the “Visible Volume”

Specifying projection:

The Viewing Frustum

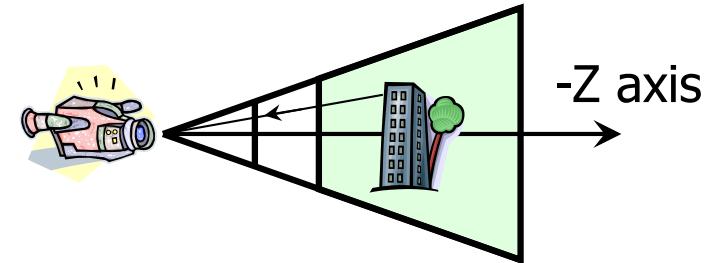


Projection in OpenGL

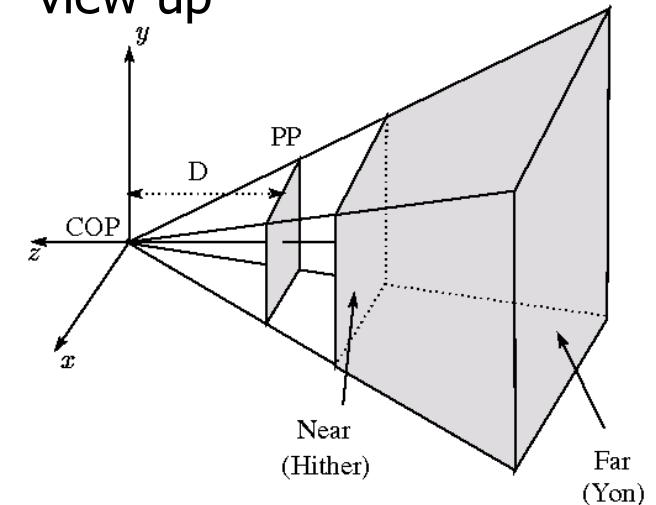
OpenGL Projection Settings:

1. Eye/Camera position: **Origin**
2. Viewing direction: **Negative Z-axis**
3. View-up direction: **Positive Y-axis**
4. Viewing region (viewing frustum):
 between **near** and **far** clipping planes
 between **bottom** and **top** clipping planes
 between **left** and **right** clipping planes
5. Visible depth range: **Hither-yon distance (far – near)**

(all in eye space)



view-up



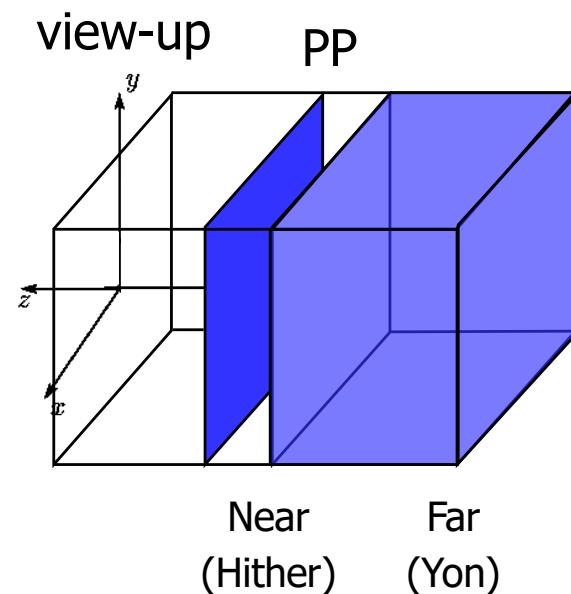
#1: Orthographic Projection in OpenGL

`glOrtho(l,r,b,t,n,f)` or `gluOrtho2D(l,r,b,t)`

- Left/right/bottom/top/near/far
 - gluOrtho2D: near = 0 and far = 1

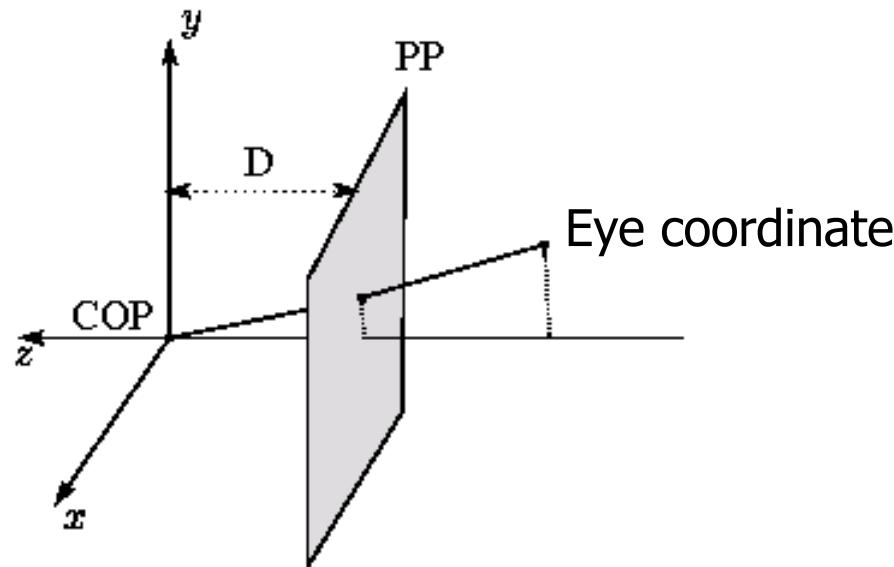
$$\begin{bmatrix} x_c \\ y_c \\ z_c \\ w_c \end{bmatrix} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & -\frac{2}{f-n} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Clip coordinate Projection Matrix (Orthographic) Eye coordinate
(after Modelview transformation)

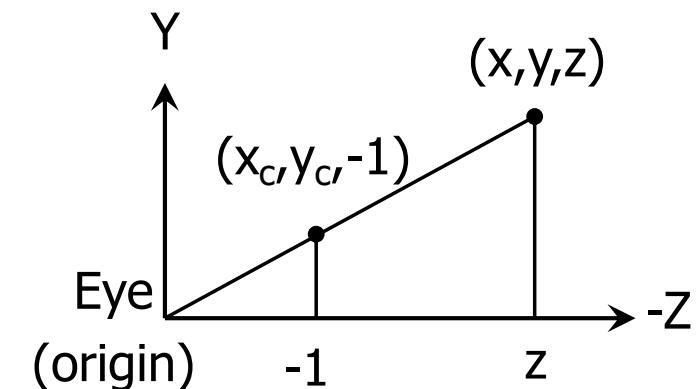


#2: Perspective Concept in OpenGL

Consider the projection of a point onto the projection plane:



By similar triangles, we can compute how much the x and y coordinates are scaled:



By similar triangles: $x_c = -\frac{x}{z}$ and $y_c = -\frac{y}{z}$

$$\begin{bmatrix} x_c \\ y_c \\ z_c \\ w_c \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ * & * & * & * \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

#2: Perspective Concept in OpenGL

How about z_c ?

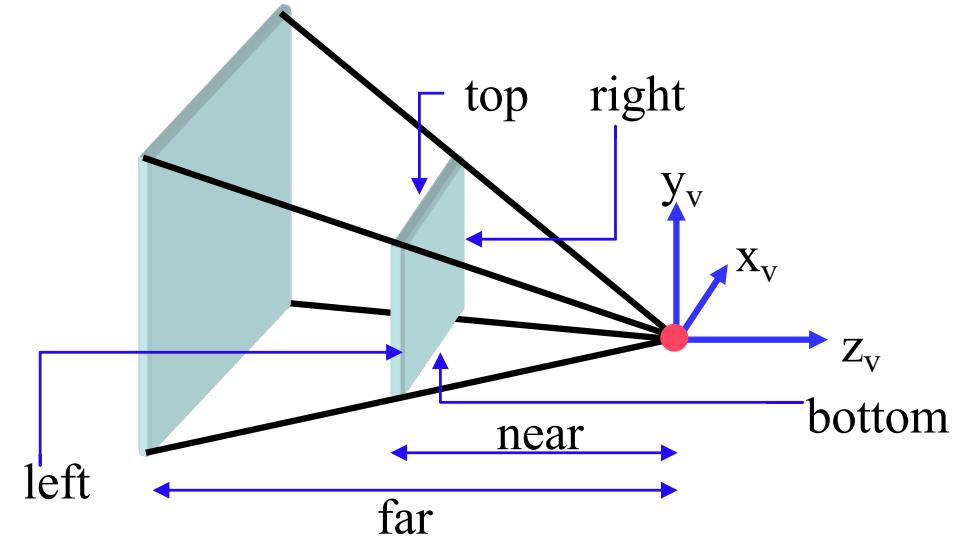
- We need it for hidden-surface removal
- The smaller z_c is, the closer the clip coordinate is from the eye
(note: Z is flipped after this matrix multiplication)

We use $glFrustum(l,r,b,t,n,f)$.

$$\begin{bmatrix} x_c \\ y_c \\ z_c \\ w_c \end{bmatrix} = \begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & -\frac{f+n}{f-n} & -\frac{2fn}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Clip coordinate Projection Matrix Eye coord.
(Perspective) (after)

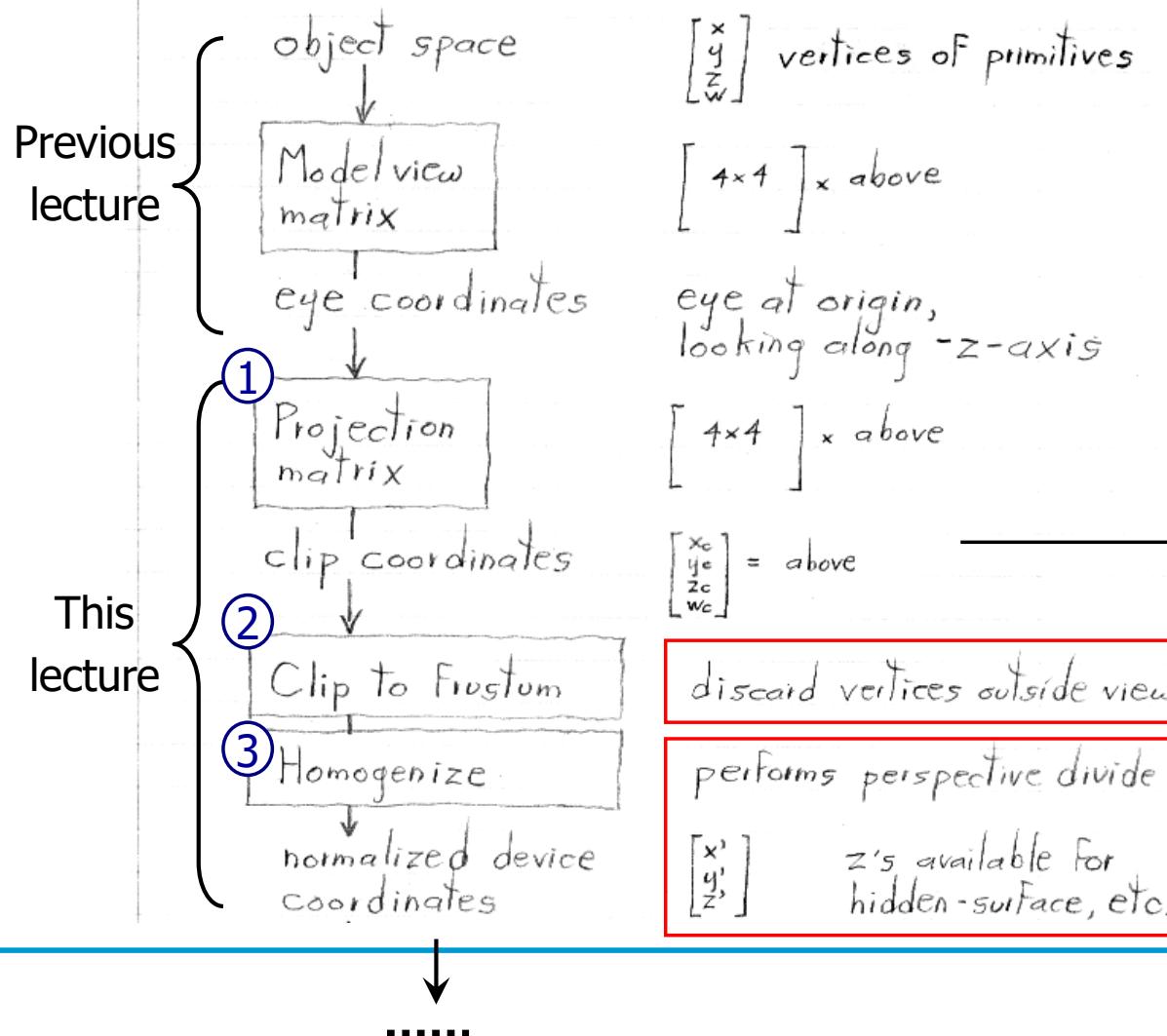
Modelview)



Clipping and Perspective Division

OpenGL implementation of viewing

Coordinate systems:



So, after multiplying the eye coord. with the Projection matrix, we obtain the **clip coord.** (for clipping and Perspective division)

Clipping and Perspective Division

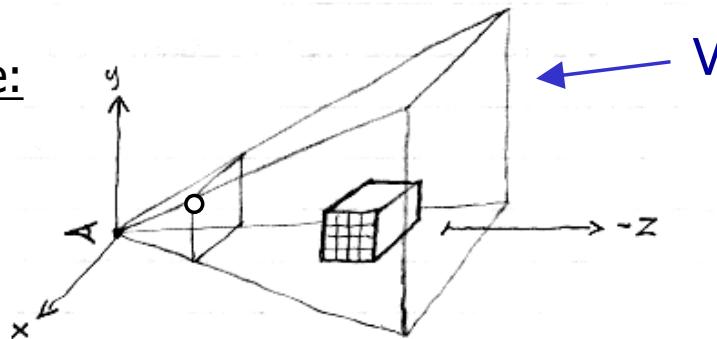
Perspective Division
(or homogenization):

$$x' = \frac{x_c}{w_c} \quad y' = \frac{y_c}{w_c} \quad z' = \frac{z_c}{w_c}$$

Normalized device
coordinates (NDC)

"Perspective" interpreted as a distortion of 3-space, i.e., view frustum

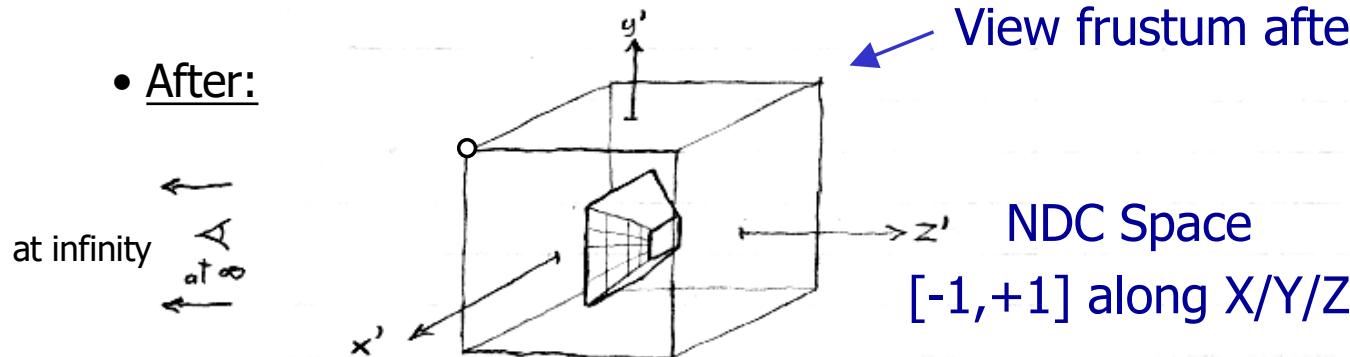
- Before:



View frustum

Eye space

- After:



View frustum after transformation

NDC Space

[−1,+1] along X/Y/Z

View frustum
becomes a cube

[Levoy]

Note: compression of grid lines in x', y' and z'

Clipping and Perspective Division

Clipping before VS after homogenization:

- After:

IF $\left\{ \begin{array}{l} -1 \leq x' \leq 1 \text{ and} \\ -1 \leq y' \leq 1 \text{ and} \\ -1 \leq z' \leq 1 \end{array} \right\}$ then in else out

- Before:

IF $w_c > 0$ then

if $\left\{ \begin{array}{l} -w_c \leq x_c \leq w_c \\ -w_c \leq y_c \leq w_c \\ -w_c \leq z_c \leq w_c \end{array} \right\}$ then in else out

(multiplying through by w_c)

else

if $\left\{ \begin{array}{l} -w_c \geq x_c \geq w_c \\ -w_c \geq y_c \geq w_c \\ -w_c \geq z_c \geq w_c \end{array} \right\}$ then in else out

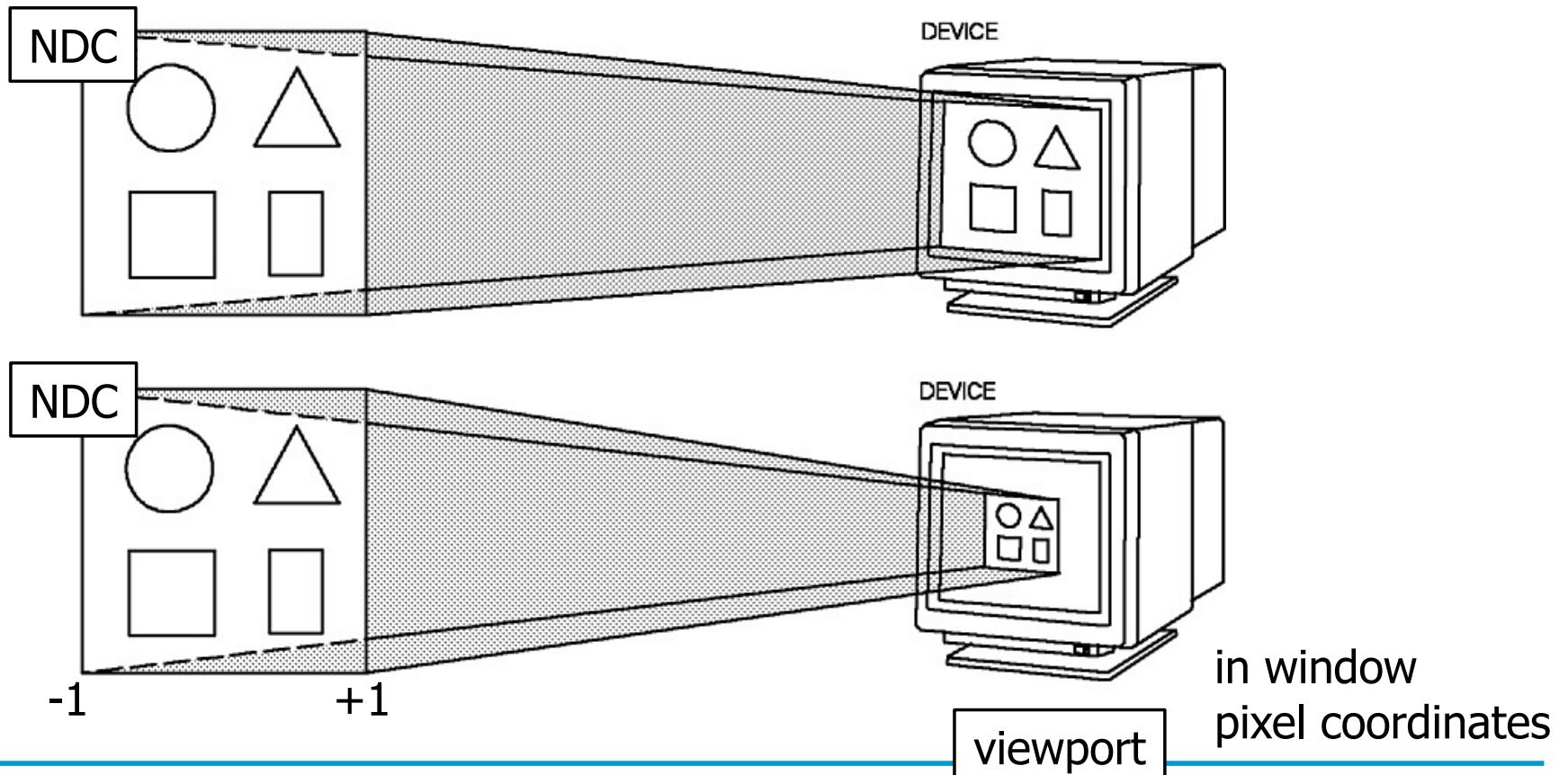
[Levoy]

Q. Why clip beforehand?

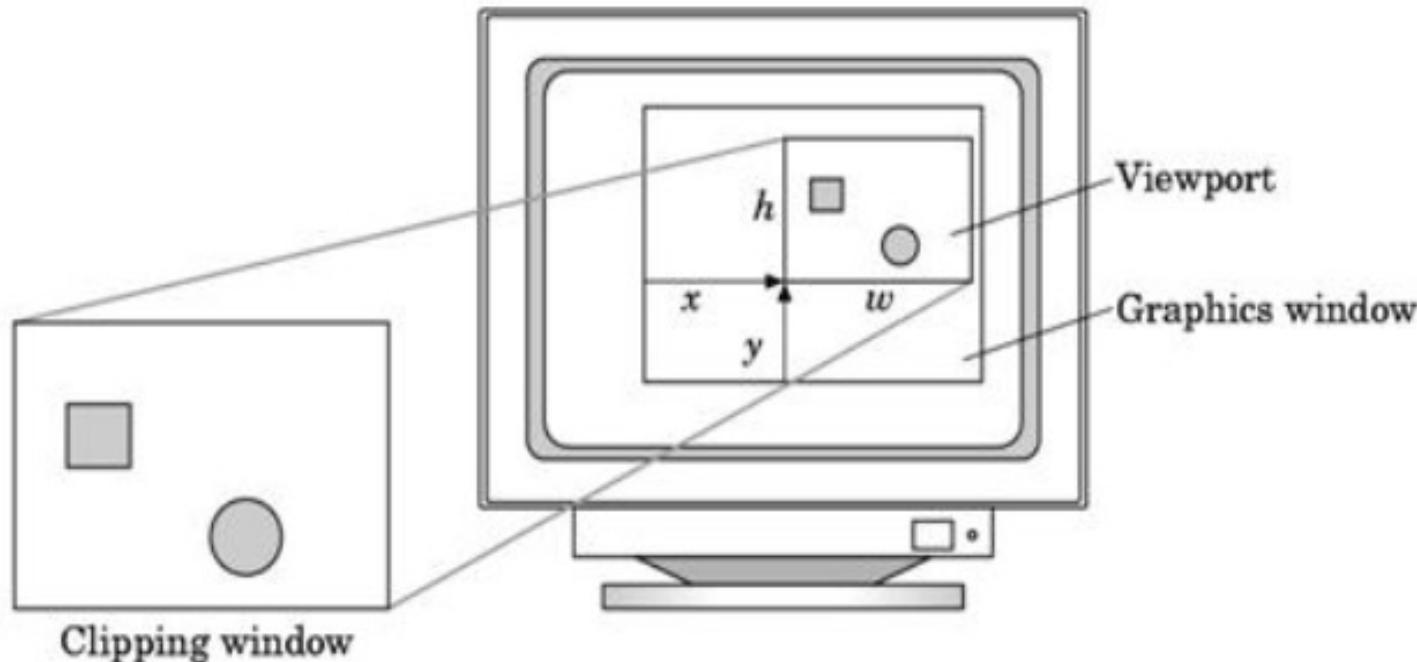
A. Avoids unnecessary divisions

Viewport Transformation

`glViewport()` command is used to define the rectangle of the rendering area where the final image is mapped



Viewport Transformation

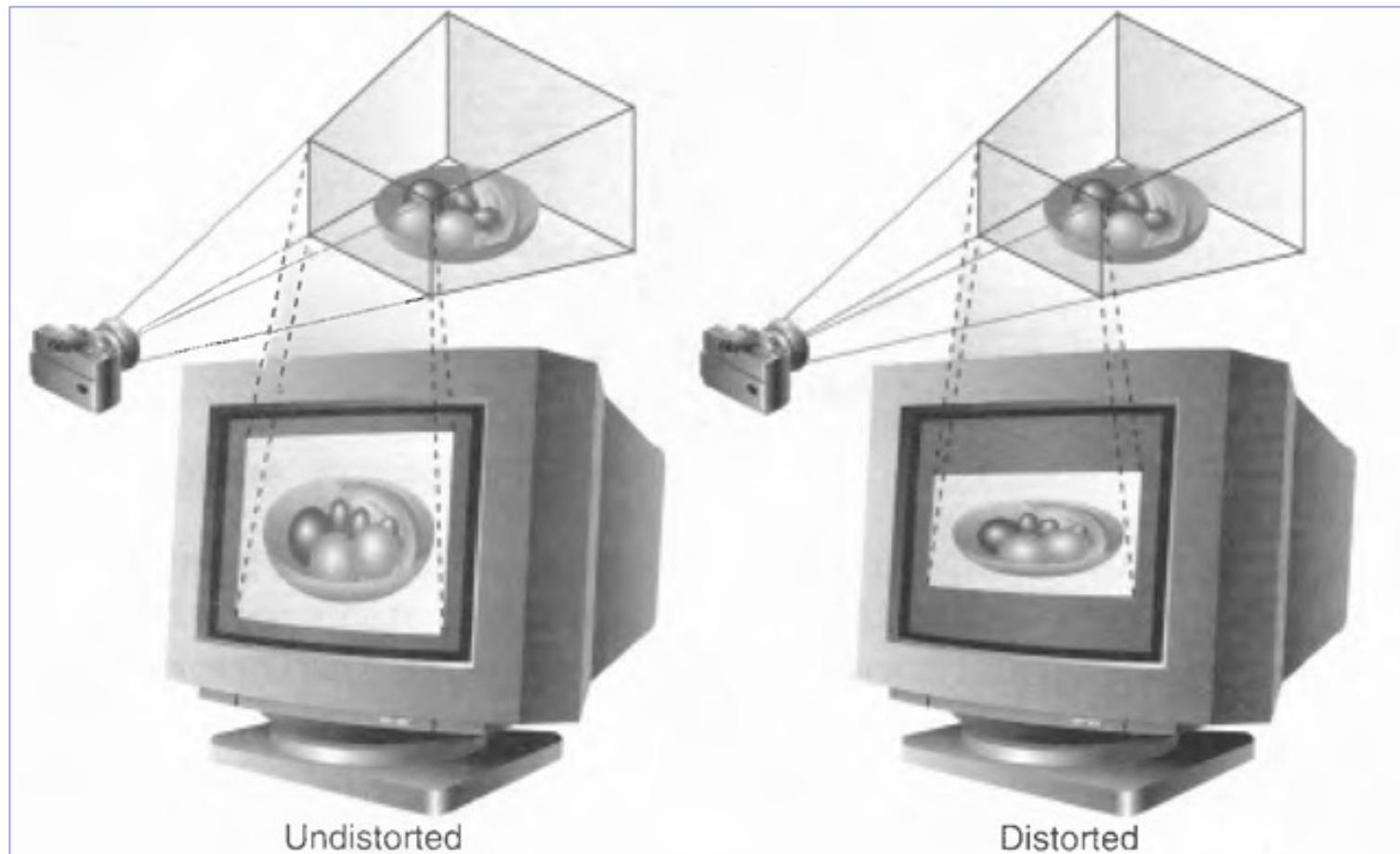


`glViewport (x, y, width, height)`

- x, y – specify the lower left corner of the viewport rectangle in pixels. The default is $(0,0)$
- $width, height$ – specify the width and height of the viewport. When a scene is first attached to a window, width and height are set to the dimensions of that window.

Viewport Transformation

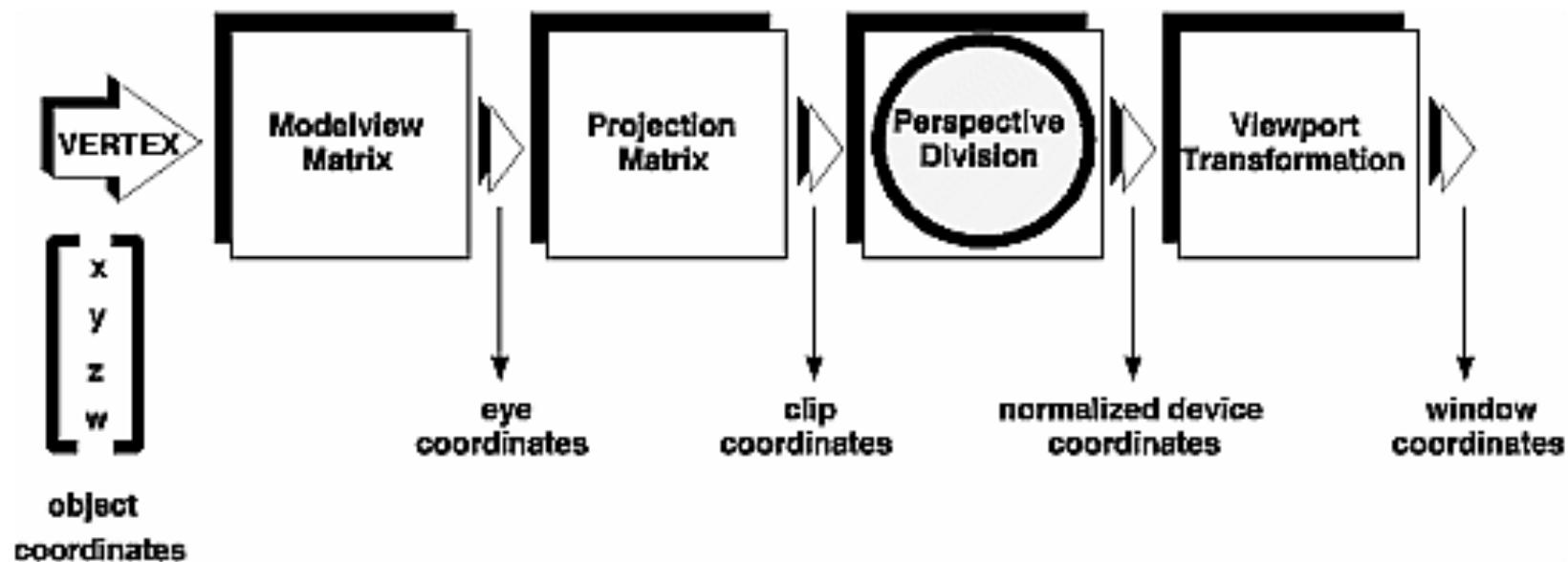
Pay attention to the aspect ratio!!! Why?



Conclusion

- Family of Projections (parallel and perspective, oblique and orthographic, etc.)
- Projection Models in OGL (Orthographic and Perspective)
- Projection Mechanism in OGL:
 1. Eye coordinate to Clip coordinate (Projection Matrix)
 2. Clipping against w_c (inside/outside view frustum)
 3. Perspective Division (homogenization):
Clip coordinate to NDC
 4. Viewport transformation: to window coordinates

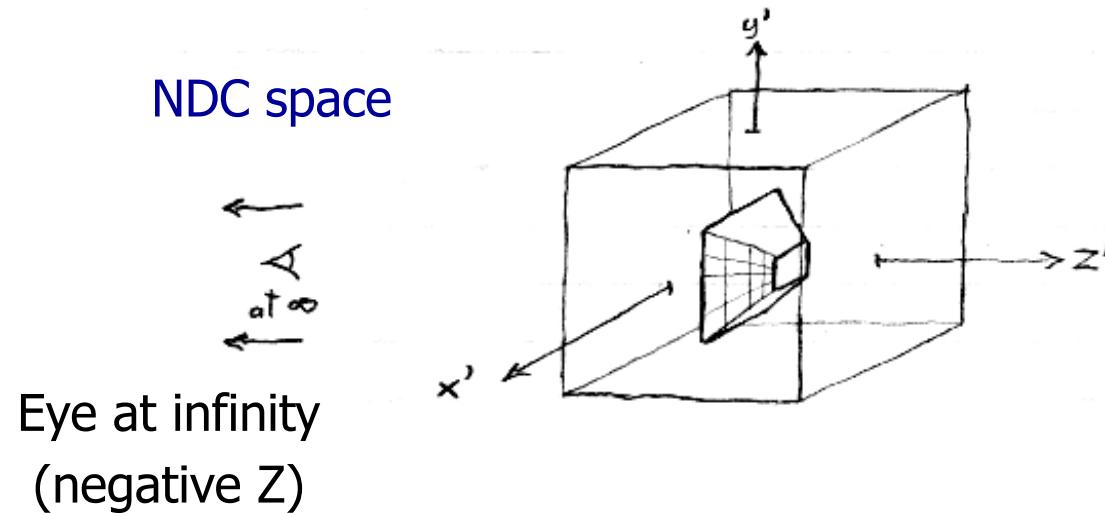
Conclusion



More about NDC

Note:

- xyz of NDC is $[-1,+1]$ (inside view frustum)
- Z of NDC is important for hidden surface removal while X&Y of NDC (next: viewport transform) is for scan conversion
to be continue..... let's look at this in the next lecture.....



More: Useful references (optional)

- About the internal matrix layout in OGL
http://sjbaker.org/steve/omniv/matrices_can_be_your_friends.html
- More about viewing in OGL
<http://www.opengl.org/resources/faq/technical/viewing.htm#view0030>
- A Good article: Projection abuse
http://sjbaker.org/steve/omniv/projection_abuse.html