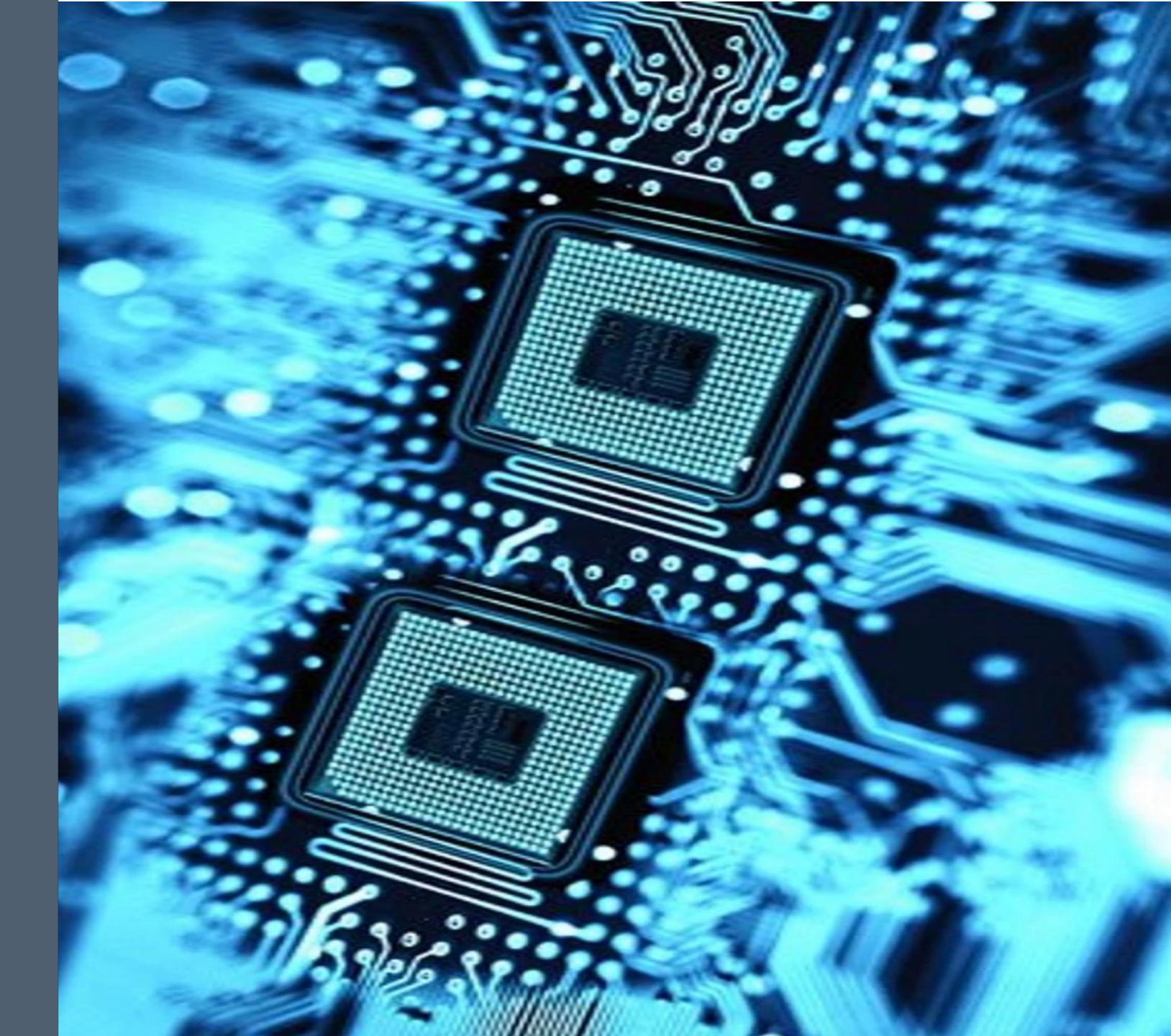
# Computer organization & architecture

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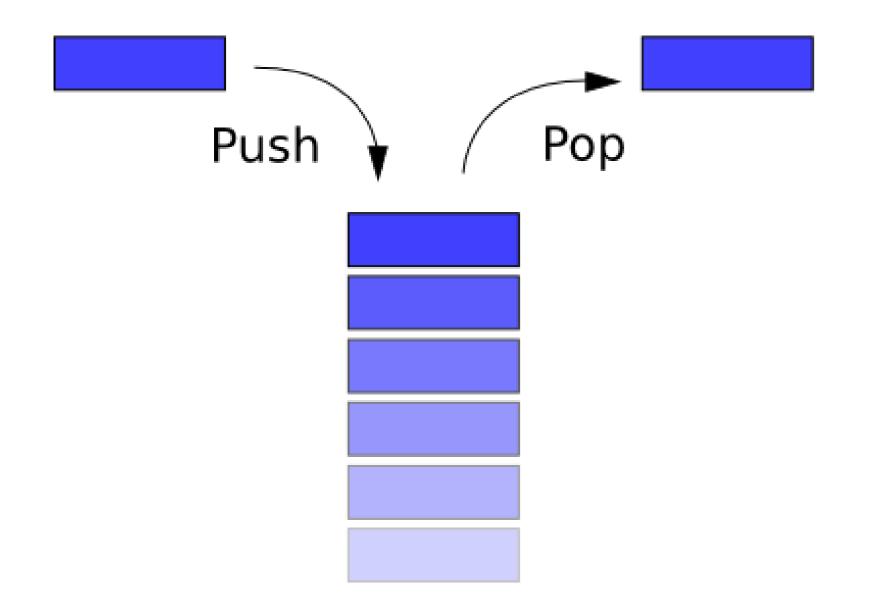
Lab By: Mahmoud Badry

## Interrupts - Procedures

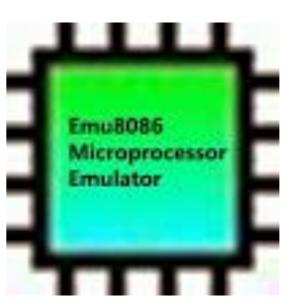
Chapter 5

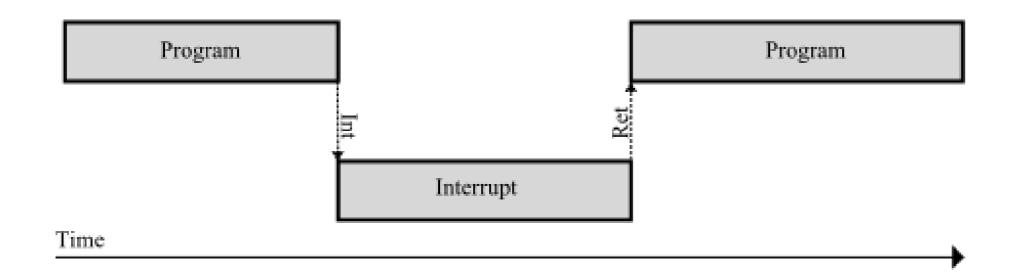


#### What we need to learn more?



- Learn how to do input-output in assembly language.
- learn about the runtime stack, how it is the fundamental mechanism that makes it possible to call and return from functions (we call them procedures).
- Begin logically dividing your programs into procedures.

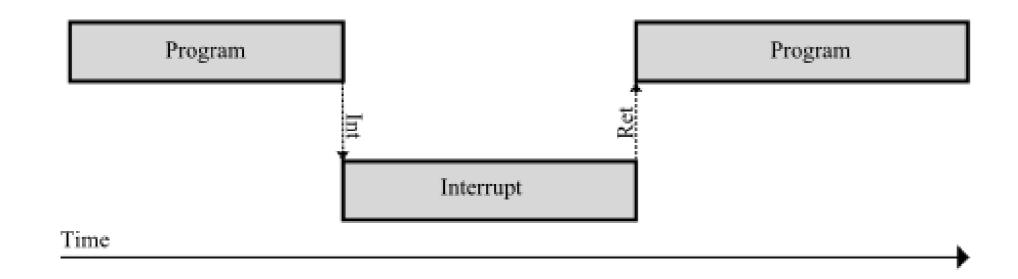




- Interrupts can be seen as a number of functions. These
  functions make the programming much easier, instead of
  writing a code to print a character you can simply call the
  interrupt and it will do everything for you.
- Interrupts are also triggered by different hardware, these are called hardware interrupts. Currently we are interested in software interrupts only. Most of them are used for I/O operations.
- To make a software interrupt there is an INT instruction, it has very simple syntax:

INT Value

Where value can be a number between 0 to 0FFh.



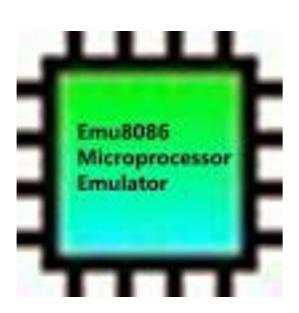
- You may think that there are only 256 functions, but that
  is not correct. Each interrupt may have sub-functions. To
  specify a sub-function AH register should be set before
  calling interrupt.
- An example interrupt:

```
INT 10h / AH = 0Eh
```

Input: AL = character to write

• Simple example on INT 10h/ AH=0Eh

```
mov al, 'a'
mov ah, 0eh
int 10h ; Print a on screen
```



- INT 20h Exits the program.
- INT 21h / AH=2Ah get system date;
  - return: CX = year (1980-2099). DH = month. DL = day. AL = day of week (00h=Sunday)
- All set of interrupts functions can be found on this PDF:
   "8068 interrupts.pdf"

## emu8086.inc

Library of common functions



### Library of common functions - emu8086.inc

To make programming easier there are some common functions that can be included in your program.
 To make your program use functions defined in other file you should use the INCLUDE directive followed by a file name.

INCLUDE emu8086.inc

- Assembler automatically searches for the file in the same folder where the source file is located, and if it cannot find the file there it searches in\_Inc\_folder .
- The emu8086.inc library is created by the emulator developers. It contains Macros and procedures.

- We present some of emu8086.inc macros:
  - PUTC char macro with 1 parameter, prints out an ASCII char at current cursor position.
  - PRINT string macro with 1 parameter, prints out a string.
  - PRINTN string macro with 1 parameter, prints out a string. The same as PRINT but automatically adds "carriage return" at the end of the string.

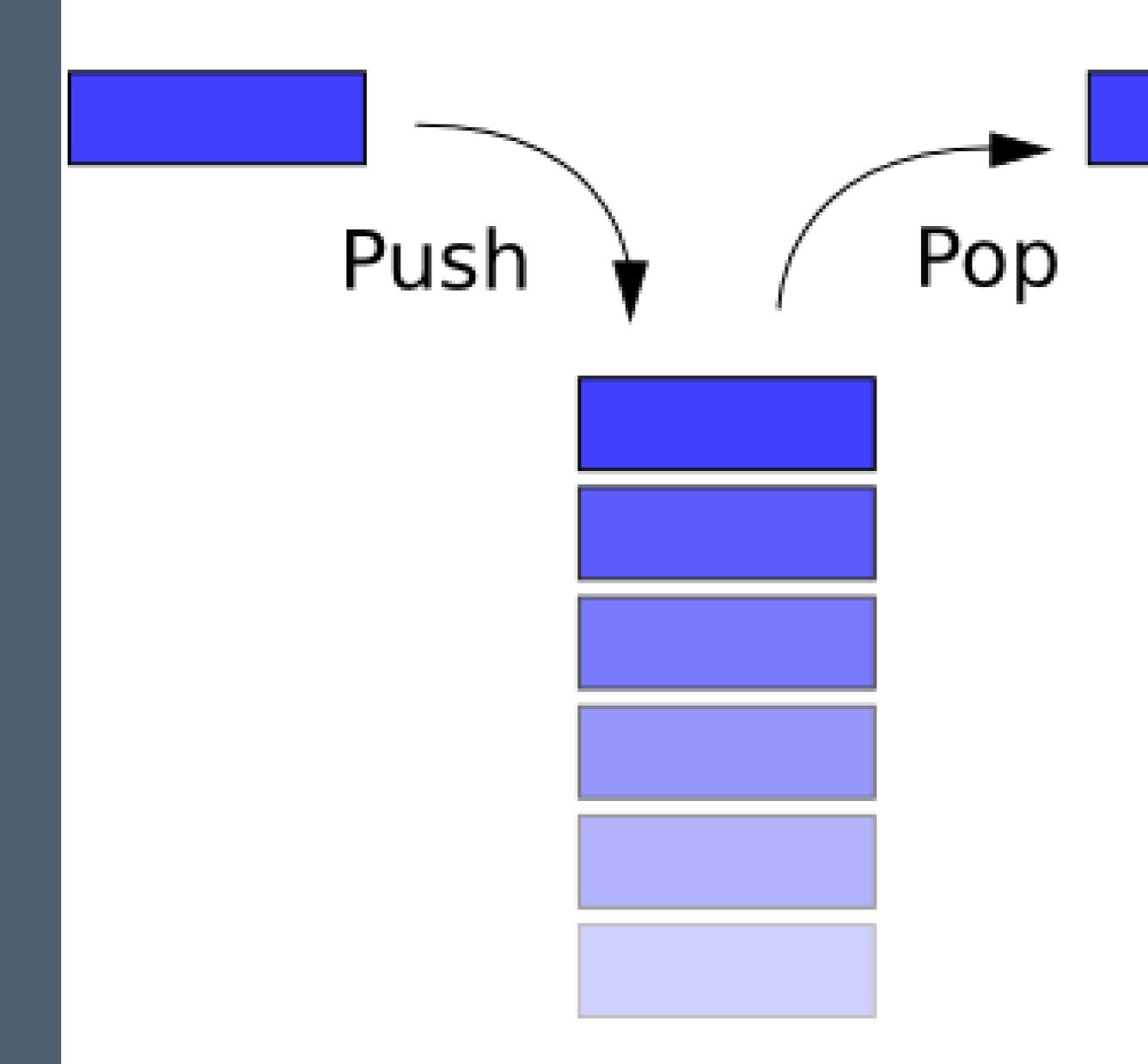
- We present some of emu8086.inc Procedures:
  - PRINT\_STRING procedure to print a null terminated string receives address of string in DS:SI register. To use it declare: <u>DEFINE\_PRINT\_STRING</u> before END directive.
  - <u>GET\_STRING</u> procedure to <u>get</u> a null terminated <u>string</u> from a user, the received string is written to buffer at **DS:DI**, buffer size should be in **DX**. Procedure stops the input when 'Enter' is pressed. To use it <u>declare</u>: <u>DEFINE\_GET\_STRING</u> before <u>END</u> directive.
  - <u>CLEAR\_SCREEN</u> procedure to clear the screen, and set cursor position to top of it. To use it declare: <u>DEFINE\_CLEAR\_SCREEN</u> before <u>END</u> directive.

#### emu8086.inc Procedures

- We present some of emu8086.inc Procedures:
  - <u>SCAN\_NUM</u> procedure that gets the multi-digit SIGNED number from the keyboard, and stores the result in CX register. To use it declare: <u>DEFINE\_SCAN\_NUM</u> before END directive.
  - PRINT\_NUM procedure that prints a signed number in AX register. To use it declare:
     DEFINE\_PRINT\_NUM and DEFINE\_PRINT\_NUM\_UNS before END directive.
  - PRINT\_NUM\_UNS procedure that prints out an unsigned number in AX register. To use it declare: DEFINE\_PRINT\_NUM\_UNS before END directive.
- Now lets review "StringCopy.asm"

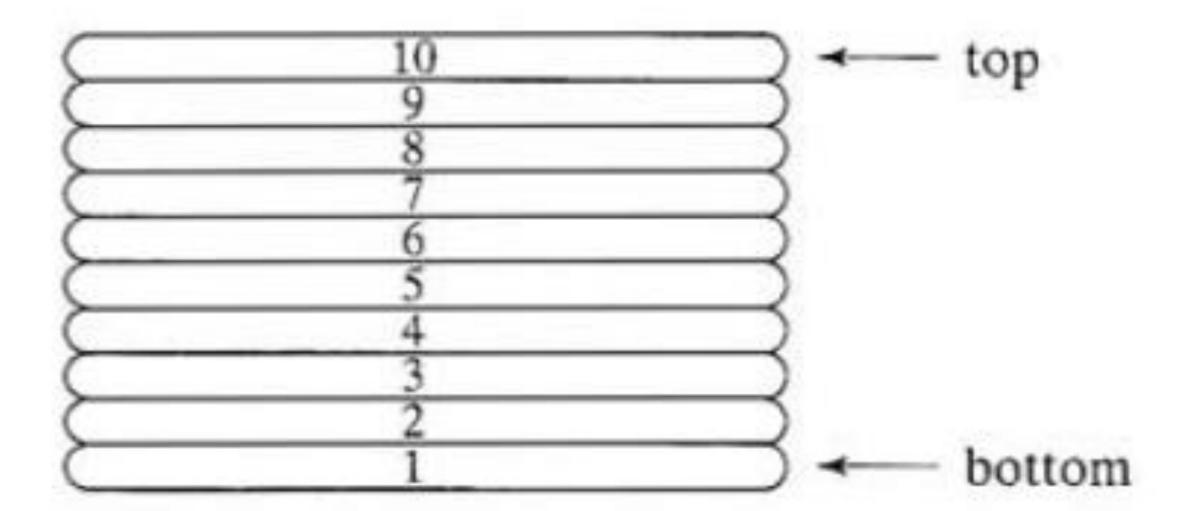
## Stack Operations

Section 4

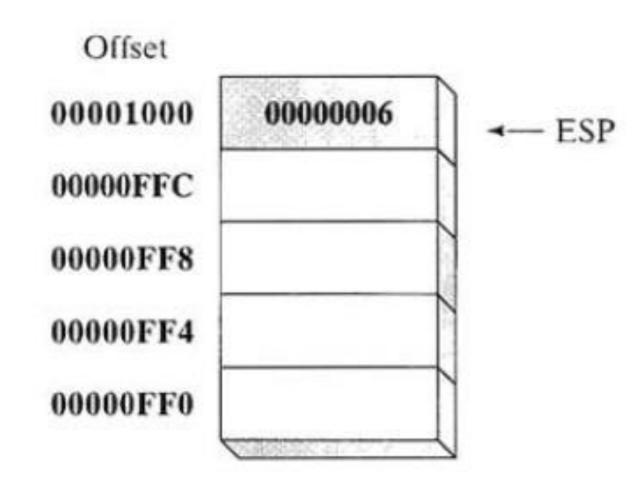


#### Stack

• A **stack** is called a **LIFO** *structure* (**last-in**, **first-out**). because the last value put into the stack is always the first value taken out.

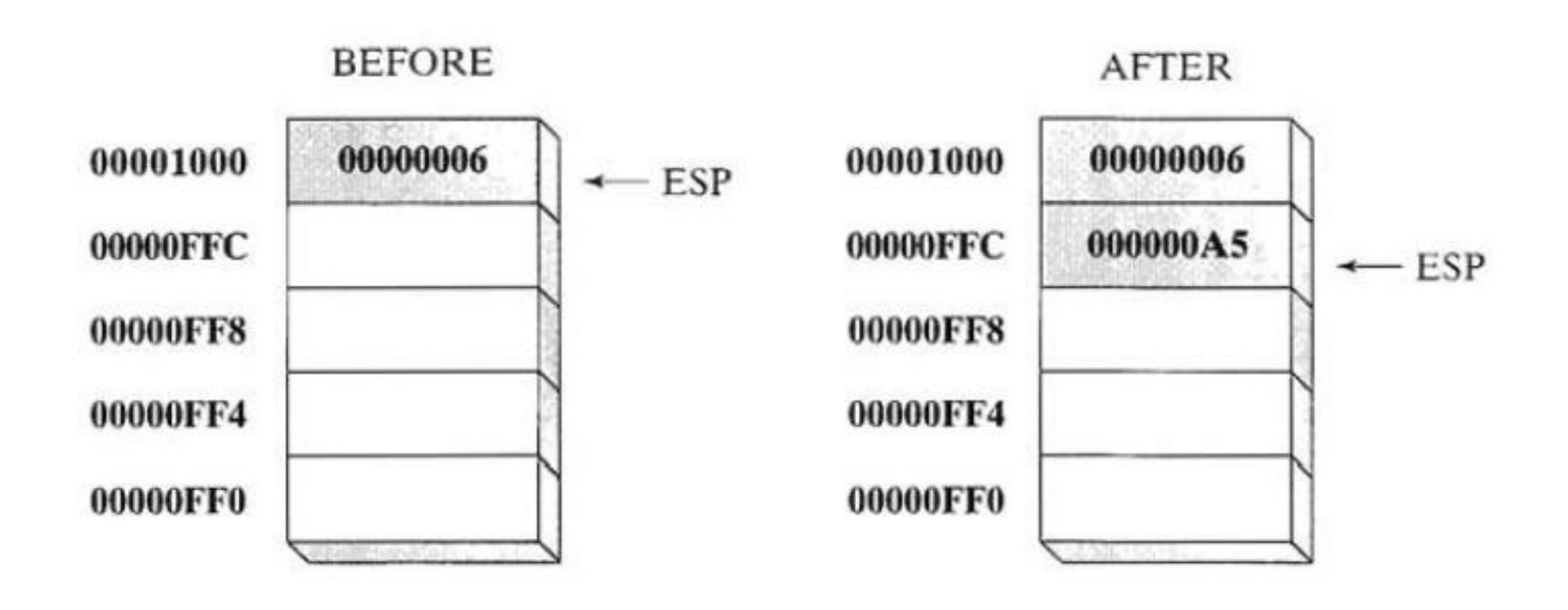


#### **Runtime Stack**

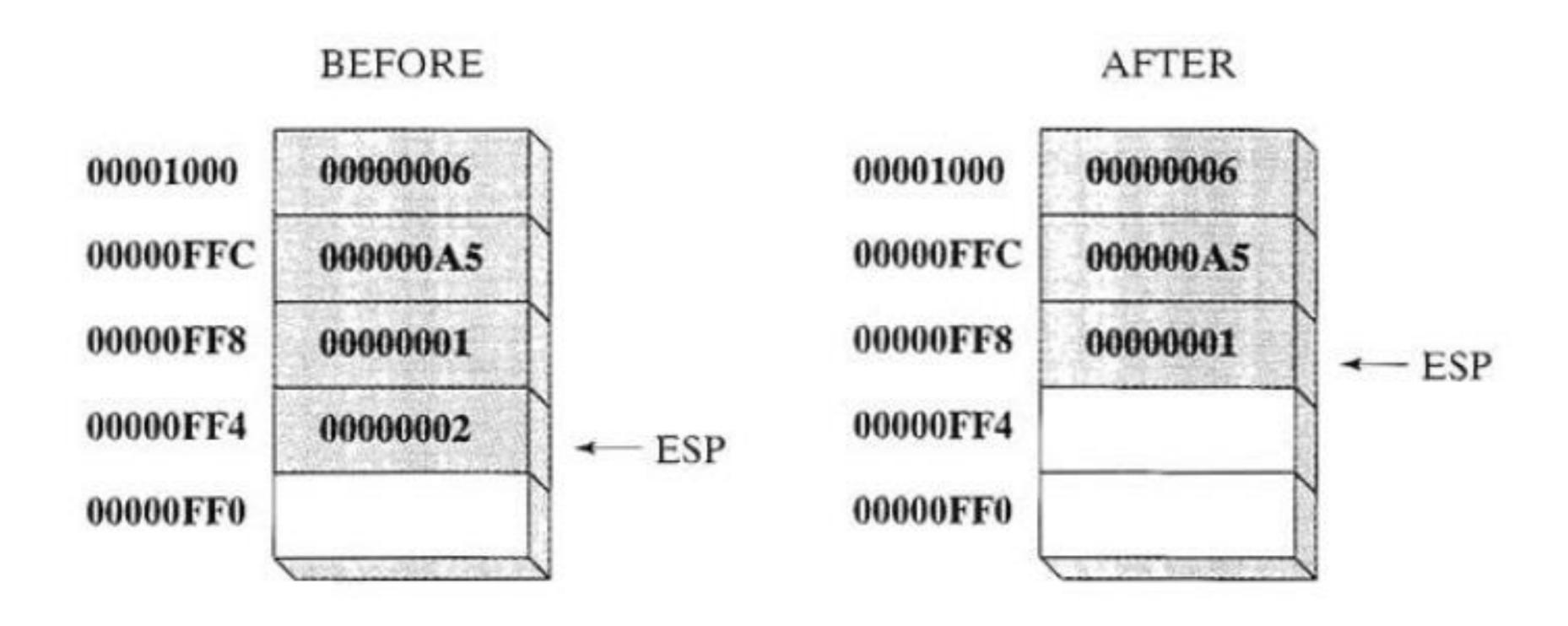


- The runtime stack is a memory array that is managed directly by the CPU, using two registers: SS and SP.
- We rarely manipulate ESP directly; instead, it is indirectly modified by instructions such as CALL, RET, PUSH, and POP.
- The stack pointer register (SP) points to the last integer to be added to, or pushed on The stack.

## **Push Operation**



## Pop Operation



## Stack Applications

- There are several important uses of stacks in programs:
  - A stack makes a convenient temporary save area for registers when they are used for more than one purpose. After they are modified, they can be restored to their original values.
  - When the CALL instruction executes, the CPU saves the current procedure's return address on the stack.
  - When calling a procedure, we often pass input values called arguments. These can be pushed on the stack.
  - Local variables inside a procedure are created on the stack and are discarded when the procedure ends.

#### Stack instructions

• The PUSH instruction first decrements SP and then copies either a source operand into the stack.

```
PUSH r/m16
PUSH imm8/16
```

 The POP instruction first copies the contents of the stack element pointed to by SP into a destination operand and then increments SP.

```
POP r/m16
```

The PUSHF instruction pushes the 16-bit EFLAGS
register on the stack, and POPF pops the stack into
EFLAGS.

```
PUSHF
```

POPF

Example:

- The PUSHA instruction pushes all of the 16-bit general-purpose registers on the stack in the following order: AX, CX, DX, BX, SP, BP, SI, and DI.
   The POPA instruction pops the same registers off the stack in reverse order.
- Best usage are in procedures:

```
myProc PROC
pusha
;Make Procedure operations
popa
ENDP
```

## Defining and Using Procedures

Section 5



## Defining a Procedure

We can define a procedure as a named block of statements that ends in a return statement. A
procedure is declared using the PROC and ENDP directives. It must be assigned a name (a valid
identifier).

```
main PROC

.

main ENDP
```

• ret statement makes the procedure returns to the place it was called from.

## Documenting Procedures

- A good habit to cultivate is that of adding **clear** and **readable documentation** to your programs. The following are a few **suggestions** for information that you can put at the **beginning** of each **procedure**:
  - A description of all tasks accomplished by the procedure.
  - A list of input parameters and their usage.
  - A description of any values returned by the procedure.
  - A list of any special requirements, called preconditions, that must be satisfied before the procedure is called.

## Call and Return Example

• main PROC
 00000020 call MySub
 00000025 mov ax , bx
...
 00000040 MySub PROC
 mov eax, edx
 ret
 MySub ENDP

- When processor executes call MySub, it pushes 00000025 into stack, and make IP value 00000040.
- After ret statement is executed in MySub, the processor pops the stack so IP value will
   00000025 to go to this address.

#### Local Labels and Global Labels

- By default, a code label (followed by a single colon) has local scope, making it visible only to statements inside its enclosing procedure. This prevents you from jumping or looping to a label outside the current procedure.
- If you want to transfer control to label outside procedure, the label must be global. To make a global label use two colons.
- Example:

GlobalLabel::

Now lets review "array sum.asm" and "reverse string.asm"

## **THANKS**

