

# Ameer Tamoor Khan

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## EDUCATION

### PH.D. IN COMPUTING

THE HONG KONG POLYTECHNIC UNIVERSITY  
Expected June 2022  
Cum. GPA: 3.57/4.00

#### PUBLICATIONS: 10

First Author: 9  
Second Author: 1  
Additional Submissions: 5

Website: [bas.atkhan.info](https://bas.atkhan.info)

### BS IN ELECTRICAL ENGINEERING

Completed June 2017  
Pakistan Institute of Engineering And Applied Sciences, Islamabad.  
Cum. GPA: 3.85 / 4.0

## LINKS

Github:// [AmeerTamoorKhan](#)  
LinkedIn:// [ameer-tamoor-khan](#)  
Twitter:// [@AmeerTamoorKhan](#)

## COURSEWORK

### GRADUATE

Advanced Data Analytics  
Advanced Artificial Intelligence  
Advanced Computer Algorithms  
Advanced Visual Computing

### UNDERGRADUATE

FPGA, Control System,  
Signal Processing, Robotics,  
Circuit Analysis, Microcontroller

## SKILLS

### PROGRAMMING

Professional:  
Python • Numpy • Pandas  
• Keras • Tensorflow

Intermediate:  
Pytorch • Matlab • C  
• C++

Familiar:  
HTML • CSS • JavaScript

## EXPERIENCE

### THE HONG KONG POLYTECHNIC UNIVERSITY RESEARCH ASSISTANT

Duration: 2017-2018

- Vision-based autonomous control of Soft robotic hand to pick-place objects.
- Human Assistive Soft Arm using SMA (Shape Memory Alloy).
- Stewart Platform using Soft Robotic Muscle.
- Implementation of Forward and Inverse Kinematic of Dobot.

### PTCL (TELECOMMUNICATION): INTERN IP NETWORK SERVICES

Duration: 2016

- Improve network operations, enhance network resilience, bandwidth capacity, latency, and packet loss.

### PTCL (TELECOMMUNICATION): INTERN CUSTOMER SERVICES

Duration: 2016

- Improve customer's network experience.

### WRITING CREEK: FREELANCER INTERMEDIATE WRITER

Duration: 2017-2018

Success Rate: 96%

Rating: 4.75/5

## PUBLICATIONS

### FIRST AUTHOR

#### 2021:

- 1) Trajectory Optimization of 5-link Biped Robot Using Beetle Antennae Search (Accepted)
- 2) Obstacle Avoidance and Model-free Tracking Control for Home Automation Using Bio-inspired Approach
- 3) Control framework for cooperative robots in smart home using bio-inspired neural network

#### 2020:

- 4) Human Guided Cooperative Robotic Agents in Smart Home Using Beetle Antennae Search
  - 5) Control framework for trajectory planning of soft manipulator using optimized RRT algorithm
  - 6) Quantum beetle antennae search: a novel technique for the constrained portfolio optimization problem
- For more publications visit **Publications** section at [atkhan.info](https://atkhan.info)

#### 2019:

- 7) Blockchain Technology with Applications to Distributed Control and Cooperative Robotics: A Survey

#### 2018:

- 8) A survey on blockchain technology and its potential applications in distributed control and cooperative robots.
- 9) Model-free optimization using eagle perching optimizer.

### CO-AUTHOR

#### 2019:

- 1) Integrating Open-Source Tools for Embedded Software Teaching: A Case Study. Advances in Engineering Education.

## REVIEWER:

- 1) IEEE Conf. on Decision and Control
- 2) IEEE Transactions on Circuits and Systems II- Express Brief
- 3) Elsevier: Measurement
- 4) Elsevier: Neurocomputing
- 5) Springer: Neural Processing Letters
- 6) Journal of Sensors

## EDITORIAL BOARD:

- 1) International Journal of Robotics and Control Systems

## UNDER SUBMISSION ARTICLES

- 1) Enhanced Beetle Antennae Search with Zeroing Neural Network For Online Solution of Constrained Optimization  
**Status:** Neurocomputing, Major Revision
- 2) Zeroing Neural Network with Beetle Antennae Search: A Novel Tracking Controller For Surgical Manipulator Under RCM Constraint  
**Status:** IEEE RA-L, Under Review
- 3) Optimally Configured GRU-RNN Using Hyperband For The Long-Term Forecasting Of Solar PV Plant  
**Status:** IEEE TRANSACTIONS ON SUSTAINABLE ENERGY, Under Review
- 4) Using Quadratic Interpolated Beetle Antennae Search For Higher Dimensional Portfolio Selection Under Cardinality Constraints  
**Status:** Applied Mathematics and Computation, Under Review
- 5) Non-linear Activated Beetle Antennae Search: A Novel Technique for Non-Convex Tax-Aware  
**Status:** Expert Systems With Applications, Under Review

## PROJECTS

### PH.D. RESEARCH PROJECT

- 1) **Beetle Antennae Search (BAS):** BAS is a nature inspired heuristic algorithm. It mimics the food searching nature of the beetle to find the optimal solution of the optimization problem. My Ph.D. mostly circles around Beetle Antennae Search (BAS) algorithm and its application in real-world problems, e.g., human assistive bots, surgical bots, cooperative bots, stock market forecasting, etc. I have employed BAS in path-planning of robots, [Click Here](#)

### DATA SCIENCE PROJECTS

- 1) **Twitter Bot:** Scrap tweets, clean them, retrieve relevant data, place them in a data-frame, and save them. [Click Here](#)
- 2) **Pinterest:** It is known as an Image hub, where quality images are available on almost everything in abundance. So to avoid the tireless effort of saving images one by one, the "Pinterest Bot" will crawl and collect images for us along with captions and will save them on our PC. [Click Here](#)
- 3) **Quora Bot:** It is another fun Scraping project to grab the most appropriate, more suitable answer for the asked question. [Click Here](#)

### MACHINE LEARNING PROJECTS

- 1) **Fake News Detector:** It is a research project to classify the FAKE news and REAL news. Deep learning model is trained over 40,000 news taken from a benchmark dataset. The dataset composed of political news mostly, so may not be compatible with news from other walks of life. The model has the accuracy of over 90% with validation and test dataset. [Click Here](#)
- 2) **Diagnoser:** It is a Mini-Machine Learning project to diagnose the disease based on the symptoms. The tested diseases along with the symptoms are on the right text file. [Click Here](#)
- 3) **Sentimeter:** It is designed to analyze the semantic of a sentence to conclude whether it has a positive sentiment or negative. The model includes LSTM (Long Short Term Memory). [Click Here](#)
- 4) **Trump-o-meter:** It is a fun project designed to understand the dynamics of Trump's wording in his tweets. The project is trained using LSTM-RNN and the model is trained on 40,000 tweets [Click Here](#)

## MACHINE LEARNING GAMING PROJECTS

1) **Dino Chrome:** It is a replication of famous Chrome Dino game, which we play without internet connectivity. [Click Here](#)

2) **Pong Game:** Trained the agent through supervised learning to play a pong game. The goal is simple, not letting the ball pass the paddle. After providing a bunch of training data, the system learns to play the game on its own. [Click Here](#)

3) **Self Driving Car Game:** Using reinforcement learning a car is trained to avoid the obstacles. NEAT (Neuro Evolution of Augmenting Topologies) algorithm is used to train the agent. [Click Here](#)

4) **Q-Learning Bridge Cross:** The agent is trained to reach the goal position. The agent is required to cross the broken bridges by putting block to pave the path. Q-Learning is used to train the agent. [Click Here](#)

5) **Q-Learning Maze Runner-:** The agent explores the environment on its own without any prior data and based on the action it takes and the reward it gets on each action, the agent tries to maximize that reward. Q-Learning is used to train the agent. [Click Here](#)

**For more projects visit:** [Github Repository](#) [Website](#)

## ENTREPRENEURSHIP

2019: Secured \$50,000 in PolyU Micro Fund Scheme.

2018: Participated in PolyU Micro Fund Scheme.