

1 DP

1.1 0-1 Knapsack (DP)

```
#include <bits/stdc++.h>
using namespace std;

int main()
{
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

    int N, K;
    cin >> N >> K;

    // weight, value.
    vector<int> W(N+1);
    vector<int> V(N+1);

    for (int i = 1; i <= N; i++)
        cin >> W[i] >> V[i];

    vector<vector<int>> dp(N+1, vector<int>(K+1));

    for (int i = 1; i <= N; i++)
    {
        for (int j = 1; j <= K; j++)
        {
            // the value when the current item is ignored.
            dp[i][j] = dp[i-1][j];

            // the value when the current item is taken.
            if (W[i] <= j)
                dp[i][j] = max(dp[i][j], dp[i-1][j-W[i]] + V[i]);
        }
    }

    cout << dp[N][K] << '\n';
    return 0;
}
```

1.2 0-1 Knapsack (Recursive)

```
#include <bits/stdc++.h>
using namespace std;

int knapsack(int i, int j, vector<int>& W, vector<int>& V,
vector<vector<int>>& dp)
{
    if (i == 0)
```

```
        return 0;

    if (dp[i][j] != -1)
        return dp[i][j];

    int __cache = knapsack(i-1, j, W, V, dp);

    if (W[i] <= j)
        __cache = max(__cache, knapsack(i-1, j-W[i], W, V, dp) + V[i]);

    dp[i][j] = __cache;
    return __cache;
}

int main()
{
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

    int N, K;
    cin >> N >> K;

    // weight, value.
    vector<int> W(N+1);
    vector<int> V(N+1);

    for (int i = 1; i <= N; i++)
        cin >> W[i] >> V[i];

    vector<vector<int>> dp(N+1, vector<int>(K+1, -1));
    cout << knapsack(N, K, W, V, dp) << '\n';
    return 0;
}
```

1.3 Berlekamp-Massey

```
#include <iostream>
#include <vector>
#include <random>
#include <tuple>
using namespace std;
using ll = long long;

const ll mod = 1000000007;

ll ipow(ll x, ll p) {
    ll ret = 1, piv = x;
    while (p) {
        if (p & 1) ret = ret * piv % mod;
```

```

    piv = piv * piv % mod;
    p >>= 1;
}
return ret;
}

vector<ll> berlekamp_massey(vector<ll> x) {
    vector<ll> ls, cur;
    ll lf, ld;
    for (size_t i = 0; i < x.size(); i++) {
        ll t = 0;
        for (size_t j = 0; j < cur.size(); j++) {
            t = (t + 1ll * x[i - j - 1] * cur[j]) % mod;
        }
        if ((t - x[i]) % mod == 0) continue;
        if (cur.empty()) {
            cur.resize(i + 1);
            lf = i;
            ld = (t - x[i]) % mod;
            continue;
        }
        ll k = -(x[i] - t) * ipow(ld, mod - 2) % mod;
        vector<ll> c(i - lf - 1);
        c.push_back(k);

        for (auto& j : ls) c.push_back(-j * k % mod);

        if (c.size() < cur.size()) c.resize(cur.size());

        for (size_t j = 0; j < cur.size(); j++) {
            c[j] = (c[j] + cur[j]) % mod;
        }

        if (i - lf + (int)ls.size() >= (int)cur.size()) {
            tie(ls, lf, ld) = make_tuple(cur, i, (t - x[i]) % mod);
        }

        cur = c;
    }
    for (auto& i : cur) i = (i % mod + mod) % mod;
    return cur;
}

ll get_nth(vector<ll> rec, vector<ll> dp, ll n) {
    ll m = rec.size();
    vector<ll> s(m), t(m);
    s[0] = 1;
    if (m != 1) t[1] = 1;
    else t[0] = rec[0];

```

```

auto mul = [&rec](vector<ll> v, vector<ll> w) {
    int m = v.size();
    vector<ll> t(2 * m);
    for (ll j = 0; j < m; j++) {
        for (ll k = 0; k < m; k++) {
            t[j + k] += 1ll * v[j] * w[k] % mod;
            if (t[j + k] >= mod) t[j + k] -= mod;
        }
    }
    for (ll j = 2 * m - 1; j >= m; j--) {
        for (ll k = 1; k <= m; k++) {
            t[j - k] += 1ll * t[j] * rec[k - 1] % mod;
            if (t[j - k] >= mod) t[j - k] -= mod;
        }
    }
    t.resize(m);
    return t;
};

while (n) {
    if (n & 1) s = mul(s, t);
    t = mul(t, t);
    n >>= 1;
}
ll ret = 0;
for (ll i = 0; i < m; i++) ret += 1ll * s[i] * dp[i] % mod;
return ret % mod;
}

int guess_nth_term(vector<ll> x, size_t n) {
    if (n < x.size()) return x[n];
    vector<ll> v = berlekamp_massey(x);
    if (v.empty()) return 0;
    return get_nth(v, x, n);
}

```

1.4 Li-Chao Tree

```
#include <bits/stdc++.h>
```

```

#define X first
#define Y second
#define all(v) v.begin(),v.end()

```

```
using namespace std;
```

```
typedef long long ll;
```

```
const ll inf = 2e18;
```

```

struct Line{
    ll a, b;
    ll get(ll x){
        return a * x + b;
    }
};

struct Node{
    int l, r; //child
    ll s, e; //range
    Line line;
};

struct Li_Chao{
    vector<Node> tree;

    void init(ll s, ll e){
        tree.push_back({ -1, -1, s, e, { 0, -inf } });
    }

    void update(int node, Line v){
        ll s = tree[node].s, e = tree[node].e;
        ll m = s + e >> 1;

        Line low = tree[node].line, high = v;
        if (low.get(s) > high.get(s)) swap(low, high);

        if (low.get(e) <= high.get(e)){
            tree[node].line = high; return;
        }

        if (low.get(m) < high.get(m)){
            tree[node].line = high;
            if (tree[node].r == -1){
                tree[node].r = tree.size();
                tree.push_back({ -1, -1, m + 1, e, { 0, -inf } });
            }
            update(tree[node].r, low);
        }
        else{
            tree[node].line = low;
            if (tree[node].l == -1){
                tree[node].l = tree.size();
                tree.push_back({ -1, -1, s, m, { 0, -inf } });
            }
            update(tree[node].l, high);
        }
    }
};

```

```

    }
}

ll query(int node, ll x){
    if (node == -1) return -inf;
    ll s = tree[node].s, e = tree[node].e;
    ll m = s + e >> 1;
    if (x <= m) return max(tree[node].line.get(x), query(tree[node].l,
x));
    else return max(tree[node].line.get(x), query(tree[node].r, x));
}

};

int main()
{
    ios::sync_with_stdio(false);
    cin.tie(0); cout.tie(0);

    Li_Chao seg;
    seg.init(-2e12, 2e12);
    int q; cin >> q;
    while(q--){
        int op; cin >> op;
        if(op == 1)
        {
            int a; ll b; cin >> a >> b;
            seg.update(0, {(ll)a, b});
        }
        else
        {
            ll x; cin >> x;
            cout << seg.query(0, x) << '\n';
        }
    }
    return 0;
}

```

//세그먼트 트리+직선의 방정식

//간선 삭제가 없는 컨벡스 헐 트리의 온라인 쿼리

//주어진 코드는 직선의 방정식이 여러개 주어질 때 x좌표 고정시 y좌표의 최댓값

1.5 Longest Increasing Subsequence

```

#include <bits/stdc++.h>
#define ref(i,n) for(int i = 0; i < n; i++)
using namespace std;

int main(){

```

```

int N;    cin >> N;
vector<int> arr(N,0);
vector<int> dp;
for(int i = 0; i<N; i++) cin >> arr[i];
vector<int> index;
for(auto x : arr){ //dp에서 x가처음나오는위치 이분탐색
    auto it = lower_bound(dp.begin(), dp.end(), x);
    index.push_back(it - dp.begin()); //x가부분순열에서
    if(it == dp.end()) { // 위치하는 인덱스(길이-1)
        dp.push_back(x); //만약에dp끝이면pushback.
    } else{ //아니면 바꾸기.
        *it = x;
    }
}
int ct = dp.size(); //LIS길이
cout << ct-- << "\n"; vector<int> result;
for(int i = N-1; i >= 0; i--){
    if(ct == index[i]) {
        result.push_back(arr[i]);
        ct--;
    }
} //인덱스 배열을 뒤에서부터 보면서 수열복원
reverse(result.begin(), result.end());
for(auto x : result) cout << x << " ";
return 0;
}

```

2 Geometry

2.1 CCW Intersection Check, Convex Hull

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef pair<int, int> pi;

static inline int __reduce(ll a)
{
    if (a > 0)
        return 1;

    if (a < 0)
        return -1;

    return 0;
}

// integer square function.
static inline ll __isq(int a)

```

```

{
    return (ll) a*a;
}

// vector subtraction.
static inline pi __pi_sub(const pi& a, const pi& b)
{
    return pi(a.first-b.first, a.second-b.second);
}

// vector cross product.
static inline ll __pi_cross(const pi& a, const pi& b)
{
    return (ll) a.first*b.second - (ll) a.second*b.first;
}

// square distance between two points.
static inline ll __pi_sqdist(const pi& a, const pi& b)
{
    return __isq(a.first-b.first) + __isq(a.second-b.second);
}

// orientation of 3 points: -1 (clockwise), 0 (linear), 1 (counterclockwise)
static inline int __pi_ort(const pi& a, const pi& b, const pi& c)
{
    return __reduce(__pi_cross(__pi_sub(b, a), __pi_sub(c, b)));
}

// convex hull algorithm (graham scan method).
int cvx_hull(vector<pi>& coords, int n)
{
    pi pivot = pi(INT_MAX, INT_MAX);
    int __pivot_idx;

    for (int i = 0; i < n; i++)
    {
        if (coords[i] < pivot)
        {
            pivot = coords[i];
            __pivot_idx = i;
        }
    }

    swap(coords[0], coords[__pivot_idx]);
    sort(coords.begin()+1, coords.end(), [&pivot](const pi& a, const pi& b)
    {
        int ort = __pi_ort(pivot, a, b);

```

```

    if (ort > 0)
        return true;

    if (ort < 0)
        return false;

    return __pi_sqdist(pivot, a) < __pi_sqdist(pivot, b);
});

vector<pi> res;
res.push_back(coords[0]);
res.push_back(coords[1]);

for (int i = 2; i < n; i++)
{
    while (res.size() > 1 && __pi_ort(res.end()[-2], res.end()[-1],
coords[i]) <= 0)
        res.pop_back();

    res.push_back(coords[i]);
}

return res.size();
}

// line segment intersection check.
bool sgmt_check(ppi l1, ppi l2)
{
    pi a = l1.first;
    pi b = l1.second;
    pi c = l2.first;
    pi d = l2.second;

    int ab = __pi_ort(a, b, c) * __pi_ort(a, b, d);
    int cd = __pi_ort(c, d, a) * __pi_ort(c, d, b);

    if (ab == 0 && cd == 0)
    {
        if (a > b) swap(a, b);
        if (c > d) swap(c, d);
        return a <= d && b >= c;
    }

    return ab <= 0 && cd <= 0;
}

```

3 Graph

3.1 Articulation Point, Bridge

```

vector<int> g[s], ans;
int order[s], par[s], low[s], t;

void dfs(int v){
    order[v] = t++;
    low[v] = t;
    int sub = 0; //자식 수
    for(auto i : g[v]){
        if(i == par[v]) continue;

        if(!order[i]){
            par[i] = v;
            sub++;
            dfs(i);
            if(!par[v] && sub > 1) ans.push_back(v); //루트 노드
            else if(par[v] && low[i] >= order[v]) ans.push_back(v);

            low[v] = min(low[v], low[i]);
        }
        else low[v] = min(low[v], order[i]);
    }
}

//단절점
//ans에 있음

vector<int> g[100010];
int order[100010]; //발견 순서
int par[100010]; //부모
int low[100010]; //i를 루트로 하는 서브 트리에서 가장 위로 갈 수 있는 노드
vector<pair<int,int>> ans;
int t;

void dfs(int v){
    order[v] = t++;
    low[v] = t;

    for(auto i : g[v]){ //i : 다음에 갈 노드
        if(i == par[v]) continue; //내 부모 == 나 임면 스킵

        if(order[i] == 0){ //아직 발견이 안되었다면
            par[i] = v; //다음 노드의 부모는 현재 노드
            dfs(i);

            if(low[i] > order[v]) ans.push_back({min(v, i), max(v, i)});
            /*서브 트리에서 위로 더 올라갈 수 없으면 단절점 확정*/

```

```

        low[v] = min(low[v], low[i]);
    }
    else low[v] = min(low[v], order[i]);
}
}
//단절선
//ans에 있음

```

3.2 Bellman Ford

```

// A C++ program for Bellman-Ford's single source
// shortest path algorithm.
#include <bits/stdc++.h>
using namespace std;

// a structure to represent a weighted edge in graph
struct Edge {
    int src, dest, weight;
};

// a structure to represent a connected, directed and
// weighted graph
struct Graph {
    // V-> Number of vertices, E-> Number of edges
    int V, E;

    // graph is represented as an array of edges.
    struct Edge* edge;
};

// Creates a graph with V vertices and E edges
struct Graph* createGraph(int V, int E)
{
    struct Graph* graph = new Graph;
    graph->V = V;
    graph->E = E;
    graph->edge = new Edge[E];
    return graph;
}

// A utility function used to print the solution
void printArr(int dist[], int n)
{
    printf("Vertex    Distance from Source\n");
    for (int i = 0; i < n; ++i)
        printf("%d \t\t %d\n", i, dist[i]);
}

```

```

// The main function that finds shortest distances from src
// to all other vertices using Bellman-Ford algorithm. The
// function also detects negative weight cycle
void BellmanFord(struct Graph* graph, int src)
{
    int V = graph->V;
    int E = graph->E;
    int dist[V];

    // Step 1: Initialize distances from src to all other
    // vertices as INFINITE
    for (int i = 0; i < V; i++)
        dist[i] = INT_MAX;
    dist[src] = 0;

    // Step 2: Relax all edges |V| - 1 times. A simple
    // shortest path from src to any other vertex can have
    // at-most |V| - 1 edges
    for (int i = 1; i <= V - 1; i++) {
        for (int j = 0; j < E; j++) {
            int u = graph->edge[j].src;
            int v = graph->edge[j].dest;
            int weight = graph->edge[j].weight;
            if (dist[u] != INT_MAX
                && dist[u] + weight < dist[v])
                dist[v] = dist[u] + weight;
        }
    }

    // Step 3: check for negative-weight cycles. The above
    // step guarantees shortest distances if graph doesn't
    // contain negative weight cycle. If we get a shorter
    // path, then there is a cycle.
    for (int i = 0; i < E; i++) {
        int u = graph->edge[i].src;
        int v = graph->edge[i].dest;
        int weight = graph->edge[i].weight;
        if (dist[u] != INT_MAX
            && dist[u] + weight < dist[v]) {
            printf("Graph contains negative weight cycle");
            return; // If negative cycle is detected, simply
                    // return
        }
    }

    printArr(dist, V);
}

```

```

    return;
}

// Driver's code
int main()
{
    /* Let us create the graph given in above example */
    int V = 5; // Number of vertices in graph
    int E = 8; // Number of edges in graph
    struct Graph* graph = createGraph(V, E);

    // add edge 0-1 (or A-B in above figure)
    graph->edge[0].src = 0;
    graph->edge[0].dest = 1;
    graph->edge[0].weight = -1;

    // add edge 0-2 (or A-C in above figure)
    graph->edge[1].src = 0;
    graph->edge[1].dest = 2;
    graph->edge[1].weight = 4;

    // add edge 1-2 (or B-C in above figure)
    graph->edge[2].src = 1;
    graph->edge[2].dest = 2;
    graph->edge[2].weight = 3;

    // add edge 1-3 (or B-D in above figure)
    graph->edge[3].src = 1;
    graph->edge[3].dest = 3;
    graph->edge[3].weight = 2;

    // add edge 1-4 (or B-E in above figure)
    graph->edge[4].src = 1;
    graph->edge[4].dest = 4;
    graph->edge[4].weight = 2;

    // add edge 3-2 (or D-C in above figure)
    graph->edge[5].src = 3;
    graph->edge[5].dest = 2;
    graph->edge[5].weight = 5;

    // add edge 3-1 (or D-B in above figure)
    graph->edge[6].src = 3;
    graph->edge[6].dest = 1;
    graph->edge[6].weight = 1;
}

```

```

// add edge 4-3 (or E-D in above figure)
graph->edge[7].src = 4;
graph->edge[7].dest = 3;
graph->edge[7].weight = -3;

// Function call
BellmanFord(graph, 0);

return 0;
}

```

3.3 Dijkstra

```

vector<pair<int,int>> adj[20005];
int d[20005];
const int INF = INT_MAX;
int main() {
    ios_base::sync_with_stdio(0);
    cin.tie(0);

    int v,e,st; cin >> v >> e >> st;
    fill(d,d+v+1,INF);
    while(e--) {
        int u , v , w;
        cin >> u >> v >> w;
        adj[u].push_back({w,v});
    }

    priority_queue<pair<int,int>,vector<pair<int,int>>,greater<pair<int,int>>>
    pq;
    d[st] = 0;
    pq.push({d[st],st});
    while(!pq.empty()){
        auto cur = pq.top(); pq.pop();
        if(d[cur.second]!= cur.first) continue; //가중치가 같지 않음?
        for(auto nxt : adj[cur.second]) {
            if(d[nxt.second] <= d[cur.second] + nxt.first) continue;
            d[nxt.second] = d[cur.second] + nxt.first;
            pq.push({d[nxt.second],nxt.second});
        }
    }
    for(int i = 1; i <= v; i++) {
        if(d[i] == INF) cout << "INF";
        else cout << d[i];
        cout << '\n';
    }
}

```

3.4 Lowest Common Ancestor

```
const int siz = 1e5+10;
vector<int> ed[siz];
int depth[siz];
int dp[siz][30];
int vis[siz];
int n;

void dfs(int v, int d){
    vis[v] = 1;
    depth[v] = d;
    for(auto i : ed[v]){
        if(!vis[i]){
            dp[i][0] = v;
            dfs(i, d+1);
        }
    }
}

void make_table(){
    for(int j=1; j<30; j++){
        for(int i=1; i<=n; i++){
            dp[i][j] = dp[ dp[i][j-1] ][j-1];
        }
    }
}

int lca(int u, int v){
    if(depth[u] < depth[v]) swap(u, v);
    int diff = depth[u] - depth[v];
    for(int i=0; diff; i++){
        if(diff & 1) u = dp[u][i];
        diff >>= 1;
    }
    if(u == v) return u;

    for(int i=29; i>=0; i--){
        if(dp[u][i] != dp[v][i]) u = dp[u][i], v = dp[v][i];
    }
    return dp[u][0];
}
```

//간선 입력받은 후, dfs(root,0); make_table()로 LCA구축하기

3.5 Union Find, Minimal Spanning Tree

```
#include <bits/stdc++.h>
using namespace std;
```

```
struct itriple
{
    int x, y, z;

    itriple() {}
    itriple(int x, int y, int z): x(x), y(y), z(z) {}
    bool operator<(const itriple& a) const
    {
        if (x < a.x)
            return true;
        else if (x > a.x)
            return false;

        if (y < a.y)
            return true;
        else if (y > a.y)
            return false;

        if (z < a.z)
            return true;

        return false;
    }
};

// find the root of an element in a forest; the paths are recursively
// compressed to improve performance of future calls.
int disjoint_root(vector<int>& forest, int a)
{
    if (forest[a] == a)
        return a;

    forest[a] = disjoint_root(forest, forest[a]);
    return forest[a];
}

// merge the two elements in a forest (size based).
// returns zero if merging is unnecessary (already in the same group);
// otherwise, the elements are merged and 1 is returned.
int disjoint_merge_size(vector<int>& forest, vector<int>& __size, int a, int
b)
{
    int root_a = disjoint_root(forest, a);
    int root_b = disjoint_root(forest, b);

    if (root_a == root_b)
```



```

    return 0;

if (__size[root_a] < __size[root_b])
{
    forest[root_a] = root_b;
    __size[root_b] += __size[root_a];
}
else
{
    forest[root_b] = root_a;
    __size[root_a] += __size[root_b];
}

return 1;
}

// merge the two elements in a forest (rank based).
// returns zero if merging is unnecessary (already in the same group);
// otherwise, the elements are merged and 1 is returned.
int disjoint_merge_rank(vector<int> &forest, vector<int>& __rank, int a, int
b)
{
    int root_a = disjoint_root(forest, a);
    int root_b = disjoint_root(forest, b);

    if (root_a == root_b)
        return 0;

    if (__rank[root_a] < __rank[root_b])
        forest[root_b] = root_a;
    else if (__rank[root_a] > __rank[root_b])
        forest[root_a] = root_b;
    else
    {
        forest[root_b] = root_a;
        __rank[root_a]++;
    }

    return 1;
}

int main()
{
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

    int v, e;

```

```

    cin >> v >> e;

    vector<itriple> edges(e);
    for (int i = 0; i < e; i++)
    {
        int a, b, c;
        cin >> a >> b >> c;
        edges[i] = itriple(c, a, b);
    }
    sort(edges.begin(), edges.end());

    vector<int> forest(v+1);
    vector<int> __size(v+1);
    vector<int> __rank(v+1);
    for (int i = 1; i <= v; i++)
    {
        forest[i] = i;
        __size[i] = 1;
        __rank[i] = 1;
    }

    int ans = 0;
    for (const itriple& edge : edges)
        ans += disjoint_merge_rank(forest, __rank, edge.y, edge.z) * edge.x;
        // ans += disjoint_merge_size(forest, __size, edge.y, edge.z) * edge.x;

    cout << ans << '\n';
    return 0;
}

```

3.6 Strongly Connected Components

```
#include <bits/stdc++.h>
```

```
using namespace std;
```

```
typedef long long ll;
```

```
/*
```

scc 는 사이클의 더 확장된 개념이라고 볼 수 있다. 유허 그래프에서, 모든 정점에 대해서 서로 도달가능한

최대부분 그래프를 의미한다. 방향 비순환 그래프로 그래프를 압축할 수 있음.*/

```
//정점x부터 dfs하면서 scc 찾기.
```

```
int findscc(int x, int &id, int (&P)[], bool (&finished)[],
stack<int> &S, vector<vector<int>> &adj, vector<vector<int>> &scc,
vector<int> &sccID, int &sccCnt) {
```

```
    P[x] = ++id; S.push(x); int parent = P[x];
```

```
    //정점x와 인접한 정점들의 부모노드를 결정. 사이클이 돌면 호출 멈추기.
```

```
    for(auto y : adj[x]) {
```

```
        if(P[y]==0) parent =
```

```
min(parent, findscc(y, id, P, finished, S, adj, scc, sccID, sccCnt));
```

```

    else if(!finished[y]) parent = min(parent,P[y]);
} //같은 scc들을 가장작은 정점의 값으로 같은 소속임을 나타냄.
if(parent == P[x]) {
    vector<int> SCC;
    while(true) {
        int y = S.top();
        S.pop();
        SCC.push_back(y);
        finished[y] = true;
        sccID[y] = sccCnt;
        if(y==x) break;
    }
    sccCnt++;
    scc.push_back(SCC);
}
return parent; //P[x]에 부모 넣어서 scc 까지 확인하기 <- 반례가 나오긴
했는데 약한 데이터에서는 괜찮을수도
} //P[x] == 0인 정점에 대해서만 탐색을 실시

```

```

int main(void)
{
    int n,m;
    cin >> n >> m;
    int id = 0, sccCnt = 0; //sccID 로 그 노드들이 같은 scc인지 확인
    int P[2*n+1] = {0}; //id: 정점번호, 부모체크
    vector<int> sccID(2*n+1);
    bool finished[2*n+1] = {0}; //scc에 속한 정점체크
    vector<vector<int>> adj(2*n+1); //정점x 인접그래프
    stack<int> S; //dfs에 사용하는 스택
    vector<vector<int>> scc; //scc 저장.

    for(int i = 0; i < m; i++) {
        int u,v; cin >> u >> v;
        if(u<0) u = n-u;
        if(v<0) v = n-v;
        if(u<=n) u += n; else u -= n;
        adj[u].push_back(v);
        if(u<=n) u += n; else u -= n;
        if(v<=n) v += n; else v -= n;
        adj[v].push_back(u);
    }
    for(int i = 1; i <= 2*n; i++) {
        if(P[i]==0) findsccl(i,id,P,finished,S,adj,scc,sccID,sccCnt);
    }
    for(int i = 1; i <= n; i++) {
        if(sccID[i] == sccID[n+i]) {
            cout << 0;

```

```

        return 0;
    }
}
cout << 1;

}

```

3.7 Sparse Table

```

const int siz = 100005;
int n;
vector<int> ed[siz];
int sp[20][100005];
int vis[siz];
void dfs(int v){
    vis[v] = 1;
    for(auto i : ed[v]){
        if(!vis[i]){
            sp[0][i]=v;
            dfs(i.X);
        }
    }
}
void make_sparse()
{
    for(int p=1; p<20; p++)
    {
        for(int i=1; i<=n; i++)
        {
            sp[p][i]=sp[p-1][sp[p-1][i]];
        }
    }
}
int f(int v, int k)
{
    for(int i=19; i>=0; i--)
    {
        if(k&(1<<i))
        {
            v=sp[i][v];
        }
    }
    return v;
}

```

3.8 Topology Sort

```

#include <bits/stdc++.h>
using namespace std;

```

```

void solve(int n, const vector<int>& time, const vector<vector<int>>& adj,
vector<int>& res)
{
    vector<int> start(n+1);
    vector<int> indeg(n+1);
    queue<int> tsort_queue;

    // pre-compute indegree.
    for (int i = 1; i <= n; i++)
    {
        for (int j : adj[i])
            indeg[j]++;
    }

    // search starting positions;
    for (int i = 1; i <= n; i++)
    {
        if (!indeg[i])
            tsort_queue.push(i);
    }

    while (!tsort_queue.empty())
    {
        int cur = tsort_queue.front(); tsort_queue.pop();
        res[cur] = start[cur] + time[cur];

        for (int i : adj[cur])
        {
            indeg[i]--;
            start[i] = max(start[i], res[cur]);

            if (!indeg[i])
                tsort_queue.push(i);
        }
    }
}

int main()
{
    std::ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

    int n;
    cin >> n;

    vector<int> time(n+1);

```

```

vector<vector<int>> adj(n+1);

for (int i = 1; i <= n; i++)
{
    int pre;
    cin >> time[i] >> pre;

    while (pre != -1)
    {
        adj[pre].push_back(i);
        cin >> pre;
    }
}

vector<int> res(n+1);
solve(n, time, adj, res);

for (int i = 1; i <= n; i++)
    cout << res[i] << '\n';

return 0;
}

```

4 IMOS

4.1 IMOS (1-Dimensional), Value Compression

```

#include <bits/stdc++.h>
using namespace std;
typedef pair<int, int> pi;

int main()
{
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

    int N;
    cin >> N;

    // value collection.
    vector<pi> T;
    for (int i = 0; i < N; i++)
    {
        int e, x;
        cin >> e >> x;
        T.push_back(pi(e, 1)); // 1 marks an entry.
        T.push_back(pi(x, 0)); // 0 marks an exit.
    }
    sort(T.begin(), T.end());

```

```

// value compression.
int prev_val;
vector<int> orig(T.size());
orig[0] = T[0].first;
prev_val = T[0].first;
T[0].first = 0;

int comp = 0; // compressed value.
for (int i = 1; i < T.size(); i++)
{
    if (T[i].first != prev_val)
    {
        orig[++comp] = T[i].first;
        prev_val = T[i].first;
    }

    T[i].first = comp;
}

// difference array construction.
vector<int> diff(comp+1);
for (pi& p : T)
{
    if (p.second)
        diff[p.first]++;
    else
        diff[p.first]--;
}

for (int i = 1; i <= comp; i++)
    diff[i] += diff[i-1];

// finally, we find the segment with the largest diff-value.
int ans = diff[0];
int seg_begin = 0;
int seg_end = 1;

for (int i = 1; i <= comp; i++)
{
    if (diff[i] > ans)
    {
        ans = diff[i];
        seg_begin = i;
        seg_end = i+1;
    }
    else if (diff[i] == ans && i == seg_end)

```

```

        seg_end++;
    }

    cout << ans << '\n';
    cout << orig[seg_begin] << ' ' << orig[seg_end] << '\n';
    return 0;
}

```

4.2 IMOS (2-Dimensional), Rectangle, Diamond

```

#include <bits/stdc++.h>
using namespace std;

int rect_img[2502][2502];
int diag_img[2502][2502];
int W, H;

// mark start/terminal points on a rectangular basis.
void mark_rect(int px, int py, int qx, int qy)
{
    rect_img[py][px]++;
    rect_img[py][qx+1]--;
    rect_img[qy+1][px]--;
    rect_img[qy+1][qx+1]++;
}

// mark start/terminal points on a diagonal basis.
void mark_diag(int px, int py, int r)
{
    diag_img[py][px-r]++;

    if (py+r+1 < H)
        diag_img[py+r+1][px+1]--;
    else
        diag_img[py+r][px+2]--;

    if (py-r-1 >= 0)
        diag_img[py-r-1][px+1]--;

    diag_img[py][px+r+2]++;
}

// rectangular imos sweeping.
void sweep_rect()
{
    // sweep from left to right.
    for (int i = 0; i < H; i++)
    {

```

```

    for (int j = 1; j < W; j++)
        rect_img[i][j] += rect_img[i][j-1];
}

// sweep from top to bottom.
for (int i = 1; i < H; i++)
{
    for (int j = 0; j < W; j++)
        rect_img[i][j] += rect_img[i-1][j];
}
}

// diagonal imos sweeping.
void sweep_diag()
{
    // sweep diagonally from bottom-left to top-right.
    for (int i = 1; i < H; i++)
    {
        for (int j = 1; i-j >= 0 && j < W; j++)
            diag_img[i-j][j] += diag_img[i-j+1][j-1];
    }

    for (int i = 1; i < W-1; i++)
    {
        for (int j = 1; j < H && i+j < W; j++)
            diag_img[H-1-j][i+j] += diag_img[H-j][i+j-1];
    }

    // sweep diagonally from top-left to bottom-right.
    for (int i = 0; i < H-1; i++)
    {
        for (int j = 1; i+j < H && j < W; j++)
            diag_img[i+j][j] += diag_img[i+j-1][j-1];
    }

    for (int i = 1; i < W-1; i++)
    {
        for (int j = 1; j < H && i+j < W; j++)
            diag_img[j][i+j] += diag_img[j-1][i+j-1];
    }
}

int main()
{
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);

```

```

int K;
cin >> W >> H >> K;

while (K--)
{
    // type variable.
    int t;
    cin >> t;

    if (t == 1)
    {
        int px, py, qx, qy;
        cin >> px >> py >> qx >> qy;
        mark_rect(px, py, qx, qy);
    }
    else
    {
        int px, py, r;
        cin >> px >> py >> r;
        mark_diag(px, py, r);
        mark_diag(px, py, r-1);
    }
}

sweep_rect();
sweep_diag();

// final output.
for (int i = 0; i < H; i++)
{
    for (int j = 0; j < W; j++)
    {
        int __value = rect_img[i][j] + diag_img[i][j];
        cout << (__value % 2 ? '#' : '.');
    }

    cout << '\n';
}

return 0;
}

```

5 Math

5.1 Extended GCD

```

ll POW(ll a, ll b, ll MMM) {
    ll ret = 1; for (; b >>= 1; a = (a * a) % MMM)
        if (b & 1) ret = (ret * a) % MMM; return ret; }

```

```

11 mod(ll a,ll m) {return (a % m + m) % m;}
11 binary_gcd(ll a,ll b) { //큰 수에 대해서 사용.
    if(a==0||b==0) return a+b;
    int shift = __builtin_ctzll(a|b);
    a >>= __builtin_ctzll(a);
    while(b != 0) {
        b >>= __builtin_ctzll(b);
        if(a>b) swap(a,b); b-=a;
    }
    return a << shift;
}
struct egcdResult {
    ll gcd,x,y;
};
egcdResult egcd(ll a,ll b) {
    if(b==0) {
        return {a,1,0};
    }
    egcdResult res = egcd(b,a%b);
    ll x = res.y;
    ll y = res.x - (a/b) * res.y;
    return {res.gcd,x,y};
} // x인 해와 그 mod
pair<ll,ll> crt(ll a1, ll m1,ll a2, ll m2) {
    ll g = gcd(m1,m2) , m = m1 / g * m2;
    if((a2 - a1) % g) return {-1,-1}; //crt의 해가 존재x
    ll md = m2/g, s = mod((a2-a1)/g,m2/g);
    ll t = mod(egcd(m1/g%md,m2/g).x ,md);
    return {a1 + s * t % md * m1,m};
}

```

```

pair<ll,ll> crtmany(const vector<ll> &a,const vector<ll> &m) {
    ll ra = a[0], rm = m[0];
    for(int i = 1; i < m.size(); i++) {
        auto [aa,mm] = crt(ra,rm,a[i],m[i]);
        if(mm == -1) return {-1,-1}; else tie(ra,rm) = tie(aa,mm);
    }return {ra,rm};
}

```

5.2 Floor Sum

```

11 floorsum(ll a, ll b,ll c,ll n){ //[(ax+b)/c] x=0~n sum.
    if(!a) return (b / c) * (n + 1);
    if(a >= c or b >= c) return ( ( n * (n + 1) ) / 2 ) * (a / c) + (n + 1) *
(b / c) + floorsum(a % c, b % c, c, n);
    long long m = (a * n + b) / c;
    return m * n - floorsum(c, c - b - 1, a, m - 1);
}

```

5.3 Integer Division Algorithm

```

// computes a/b and prints out p digits after the decimal point (rounded).
void printd(int a, int b, int p)
{
    // int sign = a*b < 0;
    a = abs(a);
    b = abs(b);
    vector<int> digits;

    digits.push_back(a/b);
    a %= b;

    for (int i = 0; i <= p; i++)
    {
        a *= 10;
        digits.push_back(a/b);
        a %= b;
    }

    if (digits[p+1] >= 5)
        digits[p]++;

    for (int i = p; i >= 1; i--)
    {
        if (digits[i] == 10)
        {
            digits[i] = 0;
            digits[i-1]++;
        }
        else
            break;
    }

    // if (sign)
    // cout << '-';

    cout << digits[0] << '.';
    for (int i = 1; i <= p; i++)
        cout << digits[i];
    cout << '\n';
}

```

5.4 Linear Sieve

```

// computes a/b and prints out p digits after the decimal point (rounded).
void printd(int a, int b, int p)

```

```

{
    // int sign = a*b < 0;
    a = abs(a);
    b = abs(b);
    vector<int> digits;

    digits.push_back(a/b);
    a %= b;

    for (int i = 0; i <= p; i++)
    {
        a *= 10;
        digits.push_back(a/b);
        a %= b;
    }

    if (digits[p+1] >= 5)
        digits[p]++;

    for (int i = p; i >= 1; i--)
    {
        if (digits[i] == 10)
        {
            digits[i] = 0;
            digits[i-1]++;
        }
        else
            break;
    }

    // if (sign)
    //     cout << '-';

    cout << digits[0] << '.';
    for (int i = 1; i <= p; i++)
        cout << digits[i];
    cout << '\n';
}

```

5.5 Modular Integer Power (Nonnegative)

```

#include <bits/stdc++.h>
typedef long long ll;
//
ll POW(ll a, ll b, ll MMM) { ll ret = 1; for (; b >= 1; a = (a * a) % MMM) if (b & 1) ret = (ret * a) % MMM; return ret; }

```

6 Network Flow

6.1 Bimatch

```

#define MXN 1001
int A[MXN], B[MXN];
vector<int> adj[MXN]; bool visited[MXN];
bool dfs(int a) {
    visited[a]=true;
    for(int b : adj[a]){
        if(B[b]==-1||!visited[B[b]]&&dfs(B[b])) {
            A[a]=b;B[b]=a;return true;
        }
    }
    return false;}
int main() {
    int n,m; cin >> n >> m;
    for(int i=0; i<n;i++){
        int s; cin >> s;
        for(int j=0; j<s;j++){
            int z; cin >> z;
            adj[i].push_back(z-1);
        }
    }//A는 왼쪽,B는오른쪽
    fill(A,A+n,-1); fill(B,B+m,-1);
    int match = 0;
    while(true) {
        bool flow = false;
        fill(visited,visited+n,false);
        for(int i=0;i < n;i++){
            if(A[i]==-1){
                if(dfs(i)){
                    flow=true; match++;
                }
            }
        }
        if(!flow) break;
    }

    cout<<match;
}

```

6.2 Dinic

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;

struct Edge { // u -> v
    int v,cap,ref; //ref 는 역간선 ?
    Edge(int v,int cap,int ref) :v(v),cap(cap),ref(ref) {}
}

```

```

};

class Dinic {
    int S,T;
    vector<vector<Edge>> edges; //그래프
    vector<int> level, next_v; //레벨그래프, flow계산시 역추적 사용.
public:
    Dinic(int MAX_V, int S,int T) : S(S),T(T) {
        edges.resize(MAX_V);
        level.resize(MAX_V);
        next_v.resize(MAX_V);
    } //역방향 간선 있으면 추가.
    void addEdge(int u,int v,int cap,bool inv) {
        edges[u].emplace_back(v, cap, (int)edges[v].size());
        edges[v].emplace_back(u, inv?cap : 0, (int) edges[u].size()-1);
    } // 이 간선의 역방향 간선이 v의 인접 리스트에서 어떤 위치에 있는지 저장.
    void reset_next_v() {
        fill(next_v.begin(),next_v.end(),0);
    }
    bool bfs() {
        fill(level.begin(),level.end(),-1);
        queue<int> Q;
        level[S] = 0;
        Q.push(S);
        while(!Q.empty()) {
            int u = Q.front(); Q.pop();
            for(auto edge: edges[u]) {
                int v = edge.v, cap = edge.cap;
                if(level[v]==-1 && cap > 0) {
                    level[v] = level[u] + 1;
                    Q.push(v);
                }
            }
        }
        return level[T] != -1; //sink T 에 도달가능여부.
    }
    int dfs(int u,int max_flow) {
        if(u==T) return max_flow; //싱크에 도달
        for(int &i = next_v[u]; i<edges[u].size(); i++) {
            int v = edges[u][i].v, cap = edges[u][i].cap;
            if(level[u]+1 == level[v] && cap > 0) { //level satisfy
                int flow = dfs(v,min(max_flow,cap));
                if(flow>0) {
                    edges[u][i].cap -= flow; //유량갱신
                    edges[v][edges[u][i].ref].cap += flow; //역간선용량증가
                    return flow;
                }
            }
        }
    }
};

```

```

    }
    }
    return 0;
}

};

int main(void)
{
    ios_base::sync_with_stdio(0);
    cin.tie(0);

    Dinic netflow(58,0,25);
    int tt; cin >> tt;
    while(tt--) {
        int cap;
        char a,b; cin >> a >> b >> cap;
        a -= 'A';
        b -= 'A';
        netflow.addEdge(a,b,cap,true);
    }
    int result = 0;
    while(netflow.bfs()) {
        netflow.reset_next_v();
        while(true) {
            int flow = netflow.dfs(0,INT_MAX);
            if(!flow) break;
            result += flow;
        }
    }
    cout << result;
}

```

6.3 Network Flow

```

int c[60][60], f[60][60];
int MaxFlow(int source,int sink) {
    int totalFlow = 0;
    while(true) {
        vector<int> parent(60,-1);
        queue<int> Q; parent[source] = source; Q.push(source);
        while(!Q.empty() && parent[sink] == -1) {
            int here = Q.front(); Q.pop();
            for(int t_here = 0; t_here < 60; t_here++) {
                if(c[here][t_here] - f[here][t_here] > 0 && parent[t_here]
== -1) {
                    Q.push(t_here); parent[t_here] = here; } } }
            if(parent[sink] == -1) break;
            int amount = INT_MAX;
            for(int p = sink; p != source; p = parent[p])

```



```

        amount = min(c[parent[p]][p]-f[parent[p]][p],amount);
    for(int p = sink; p != source; p = parent[p]) {
        f[parent[p]][p] += amount; f[p][parent[p]] -= amount;
    }
    totalFlow += amount; }
return totalFlow; }

int main() {
    int n; cin >> n;
    for(int i = 0; i < n; i++) {
        int cap,fr,to; cin >> fr >> to >> cap;
        c[fr][to] += cap; //간선마다용량추가
    } //시작과끝노드지정
    cout << MaxFlow(0,25);
    return 0;
}

```

7 Segment Tree

7.1 Persistent Segment Tree

```

int c[60][60], f[60][60];
int MaxFlow(int source,int sink) {
    int totalFlow = 0;
    while(true) {
        vector<int> parent(60,-1);
        queue<int> Q; parent[source] = source; Q.push(source);
        while(!Q.empty() && parent[sink] == -1) {
            int here = Q.front(); Q.pop();
            for(int t_here = 0; t_here < 60; t_here++) {
                if(c[here][t_here] - f[here][t_here] > 0 && parent[t_here]
== -1) {
                    Q.push(t_here); parent[t_here] = here; } } }
            if(parent[sink] == -1) break;
            int amount = INT_MAX;
            for(int p = sink; p != source; p = parent[p])
                amount = min(c[parent[p]][p]-f[parent[p]][p],amount);
            for(int p = sink; p != source; p = parent[p]) {
                f[parent[p]][p] += amount; f[p][parent[p]] -= amount;
            }
            totalFlow += amount; }
    return totalFlow; }

int main() {
    int n; cin >> n;
    for(int i = 0; i < n; i++) {
        int cap,fr,to; cin >> fr >> to >> cap;
        c[fr][to] += cap; //간선마다용량추가
    } //시작과끝노드지정
    cout << MaxFlow(0,25);
    return 0;
}

```

```

}

```

7.2 Lazy Segment Tree

```

#include <iostream>
#include <cmath>
#include <vector>
using namespace std;
typedef long long ll;

void init(vector<ll> &a, vector<ll> &tree, int node, int start, int end) {
    if (start == end) {
        tree[node] = a[start];
    } else {
        init(a, tree, node*2, start, (start+end)/2);
        init(a, tree, node*2+1, (start+end)/2+1, end);
        tree[node] = tree[node*2] + tree[node*2+1];
    }
}

void update_lazy(vector<ll> &tree, vector<ll> &lazy, int node, int start,
int end) {
    if (lazy[node] != 0) {
        tree[node] += (end-start+1)*lazy[node];
        if (start != end) {
            lazy[node*2] += lazy[node];
            lazy[node*2+1] += lazy[node];
        }
        lazy[node] = 0;
    }
}

void update_range(vector<ll> &tree, vector<ll> &lazy, int node, int start,
int end, int left, int right, ll diff) {
    update_lazy(tree, lazy, node, start, end);
    if (left > end || right < start) {
        return;
    }
    if (left <= start && end <= right) {
        tree[node] += (end-start+1)*diff;
        if (start != end) {
            lazy[node*2] += diff;
            lazy[node*2+1] += diff;
        }
        return;
    }
    update_range(tree, lazy, node*2, start, (start+end)/2, left, right,
diff);
    update_range(tree, lazy, node*2+1, (start+end)/2+1, end, left, right,
diff);
}

```

```

    tree[node] = tree[node*2] + tree[node*2+1];
}
ll query(vector<ll> &tree, vector<ll> &lazy, int node, int start, int end,
int left, int right) {
    update_lazy(tree, lazy, node, start, end);
    if (left > end || right < start) {
        return 0;
    }
    if (left <= start && end <= right) {
        return tree[node];
    }
    ll lsum = query(tree, lazy, node*2, start, (start+end)/2, left, right);
    ll rsum = query(tree, lazy, node*2+1, (start+end)/2+1, end, left,
right);
    return lsum + rsum;
}
int main() {
    ios_base::sync_with_stdio(false);
    cin.tie(nullptr);
    int n, m, k;
    cin >> n >> m >> k;
    vector<ll> a(n);
    int h = (int)ceil(log2(n));
    int tree_size = (1 << (h+1));
    vector<ll> tree(tree_size);
    vector<ll> lazy(tree_size);
    m += k;
    for (int i=0; i<n; i++) {
        cin >> a[i];
    }
    init(a, tree, 1, 0, n-1);
    while (m--) {
        int what;
        cin >> what;
        if (what == 1) {
            int left, right;
            ll diff;
            cin >> left >> right >> diff;
            update_range(tree, lazy, 1, 0, n-1, left-1, right-1, diff);
        } else if (what == 2) {
            int left, right;
            cin >> left >> right;
            cout << query(tree, lazy, 1, 0, n-1, left-1, right-1) << '\n';
        }
    }
    return 0;
}

```

7.3 Segment Tree

```

int init(int node, int st, int end) {
    // st : init 함수가 관심두는 arr의 시작 인덱스
    // end : init 함수가 관심두는 arr의 끝 인덱스
    // node : segTree의 노드
    // -> node번째 노드가 st ~ end의 합을 저장한다.
    if (st == end) return segTree[node] = arr[st];
    int mid = (st + end) / 2;

    //재귀로 반씩 나눠서 초기화
    return segTree[node] = init(node * 2, st, mid) + init(node * 2 + 1, mid
+ 1, end);
}

void update(int n, int st, int end, int t, int diff) {
    // st : 시작 인덱스
    // end : 끝 인덱스
    // idx : 수정할 원소의 인덱스
    // diff : 수정할 값

    // 범위 안에 있을 경우
    if (st <= t && t <= end) segTree[n] += diff;

    // 범위 밖에 있을 경우
    else return;
    if (st == end) return;
    int mid = (st + end) / 2;
    update(n * 2, st, mid, t, diff);
    update(n * 2 + 1, mid + 1, end, t, diff);
}

//sum함수는 구간합 쿼리이다
int sum(int l, int r, int node, int st, int end) {
    // st : 시작 인덱스
    // end : 끝 인덱스
    // l~r : 구하고자 하는 구간 합의 범위

    // [l, r]이 [st, end]를 완전히 포함하는 경우
    if (l <= st && end <= r) return segTree[node];

    // [l, r]와 [st, end]가 겹치지 않는 경우
    if (r < st || end < l) return 0;

    // 나머지 경우 (일부분 겹칠때)
    int m = (st + end) / 2;
    return sum(l, r, node * 2, st, m) + sum(l, r, node * 2 + 1, m + 1, end);
}

```

```
}
```

8 String

8.1 KMP

```
#include <bits/stdc++.h>
```

```
using namespace std;
typedef long long ll;
typedef pair<ll,ll> pl;
```

```
vector<int> failure(string & s) {
    vector<int> f(s.size());
    int j = 0;
    for(int i = 1; i < s.size(); i++) {
        while(j>0 && s[i] != s[j]) j = f[j-1];
        if(s[i] == s[j]) f[i] = ++j;
    } return f;
}

ll kmp(string s, string p) {
    vector<int> f = failure(p);
    ll cnt = 0;
    int j = 0;
    for(int i = 0; i < s.size(); i++) {
        while(j>0 && s[i] != p[j]) j = f[j-1];
        if(s[i] == p[j]) j++;
        if(j == p.size()) {
            cnt++;
            //w.emplace_back(i-j + 2); 몇번째인덱스인지카운트
        }
    } return cnt;
}
```

8.2 Suffix Array, LCP

```
int n, t;
string s;
int SA[MAX_N], LCP[MAX_N];
int tmp[MAX_N], poz[MAX_N];
```

```
//Algoritam koji generise sufiksni niz i niz najdužeg zajedničkog prefiksa
(LCP) nad datim stringom
//Slozenost:  $O(n \log^2 n)$  za sufiksni niz,  $O(n)$  za LCP niz
```

```
inline bool suff_compare(int i, int j)
{
    if (poz[i] != poz[j]) return (poz[i] < poz[j]);
    i += t;
    j += t;
}
```

```
if (i < n && j < n) return (poz[i] < poz[j]);
else return (i > j);
}

inline void buildSA()
{
    for (int i=0;i<n;i++)
    {
        SA[i] = i;
        poz[i] = s[i];
    }
    for (t = 1 ; t < 2*n+1; t *= 2)
    {
        sort(SA, SA + n, suff_compare);
        for (int i=0;i<n-1;i++)
        {
            tmp[i+1] = tmp[i];
            if (suff_compare(SA[i],SA[i+1])) tmp[i+1]++;
        }
        for (int i=0;i<n;i++)
        {
            poz[SA[i]] = tmp[i];
        }
        if (tmp[n-1] == n-1) break;
    }
}

inline void buildLCP()
{
    int k = 0;
    for (int i=0;i<n;i++)
    {
        if (poz[i] != n-1)
        {
            int j = SA[poz[i]+1];
            while (s[i+k] == s[j+k]) k++;
            LCP[poz[i]] = k;
            if (k > 0) k--;
        }
    }
}

int main()
{
    n = 6;
    s = "banana";
}
```

```

buildSA();
buildLCP();

for (int i=0;i<n;i++) printf("%d ",SA[i]);
printf("\n");
for (int i=0;i<n;i++) printf("%d ",LCP[i]);
printf("\n");

return 0;
}

```

9 Misc

9.1 Custom Comparator, Custom Hashing

```

#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef unsigned long long ull;
typedef unsigned int uint;

struct pos
{
    int x, y;
    pos(): x(0), y(0) {}
    pos(int x, int y): x(x), y(y) {}

    // this comparator is analogous to std::less.
    bool operator<(const pos& another) const
    {
        if (x < another.x)
            return true;

        if (x > another.x)
            return false;

        if (y < another.y)
            return true;

        return false;
    }

    bool operator==(const pos& another) const
    {
        return x == another.x && y == another.y;
    }
};

hash<ull> ull_hash;

```

```

struct pos_hash
{
    size_t operator()(const pos& p) const
    {
        return ull_hash(((ull) p.y << 32) | (uint) p.x);
    }
};

int main()
{
    set<pos> test1;
    unordered_set<pos, pos_hash> test2;

    pos p1(10, 20);
    pos p2(30, 30);

    test1.insert(p1);
    test2.insert(p2);
}

```