

STAT 460 HW5

Benjamin Pond and Dylan Borchert

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Homework 5

Exercise 4.8

The data in Tables E4.4 exhibit a linear trend

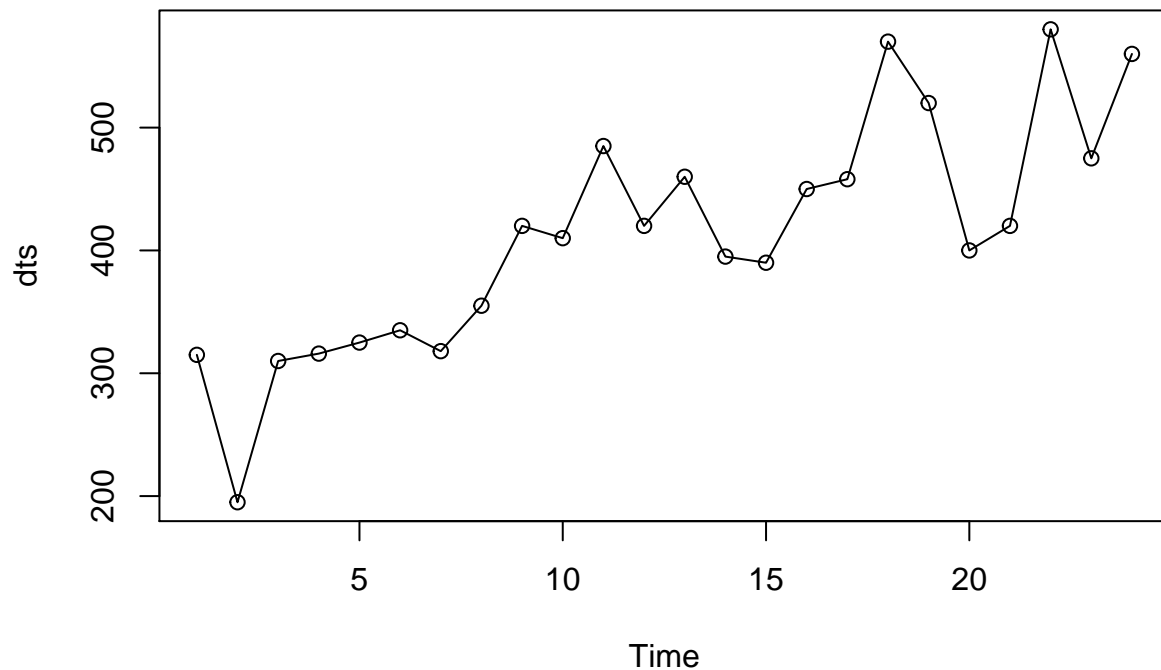
###(a) Verify there is a trend by plotting the data

```
# write data
period <- seq(from=1, to=24, by=1)
yt <- c(315, 195, 310, 316, 325, 335, 318, 355, 420, 410, 485, 420,
        460, 395, 390, 450, 458, 570, 520, 400, 420, 580, 475, 560)

# create data frame
d <- data.frame(period, yt)
# make into time series
dts<-ts(d[,2])

# plot time series
plot(dts, type='o', main='Time Series Plot of data')
```

Time Series Plot of data



The data shows a positive linear trend.

###(b) Using the first 12 observations, develop an appropriate procedure for forecasting.

```
# first smooth function
firstsmooth<-function(y,lambda,start=y[1]){
  ytilde<-y
  ytilde[1]<-lambda*y[1]+(1-lambda)*start
  for (i in 2:length(y)){
    ytilde[i]<-lambda*y[i]+(1-lambda)*ytilde[i-1]
  }
  ytilde
}

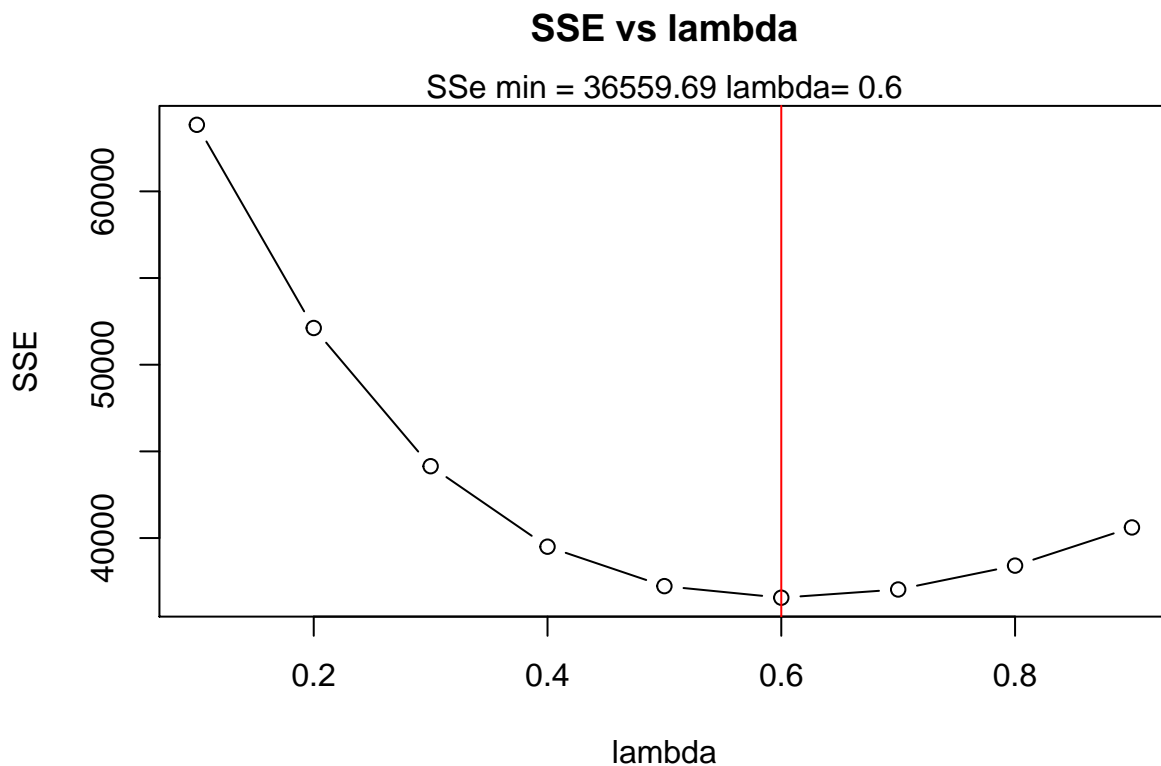
# function calculate values of prediction, prediction error,
# SSE, MAPE, MAD, MSD at different steps in the model
measacc.fs<-function(y,lambda){
  out <- firstsmooth(y,lambda)
  T <- length(y)
  pred <- c(y[1], out[1:(T-1)])
  prederr <- y-pred
  SSE <- sum(prederr^2)
  MAPE <- 100*sum(abs(prederr)/y)/T
  MAD <- sum(abs(prederr))/T
  MSD <- sum(prederr^2)/T
  ret1 <- c(SSE,MAPE,MAD,MSD)
  names(ret1)<-c('SSE', 'MAPE', 'MAD', 'MSD')
```

```

    return(ret1)
}

# apply to data and plot SSE Vs Lambda
lambda.vec <- seq(0.1, 0.9, 0.1)
sse <- function(sc){measacc.fs(d[1:12,2],sc)[1]}
sse.vec <- sapply(lambda.vec, sse)
opt.lambda <- lambda.vec[sse.vec == min(sse.vec)]
plot(lambda.vec, sse.vec, type='b', main='SSE vs lambda',
      xlab='lambda', ylab='SSE')
abline(v=opt.lambda, col='red')
mtext(text=paste('SSE min =', round(min(sse.vec),2), 'lambda=', opt.lambda))

```



The value of lambda that minimizes SSE is $\lambda = 0.6$. So our forecast model is:

$$\hat{y}_{T+1}(T) = \left(2 + \frac{\lambda}{1-\lambda}\right) * \tilde{y}_T^{(1)} - \left(1 + \frac{\lambda}{1-\lambda}\right) * \tilde{y}_T^{(2)} = 3.5 * \tilde{y}_T^{(1)} + 2.5 * \tilde{y}_T^{(2)}$$

The forecast model predicts y using a linear combination of the first smoothed value, $\tilde{y}_T^{(1)}$, and second smoothed value $\tilde{y}_T^{(2)}$ of the prior observation. The weights involve our optimum value of lambda, $\lambda = 0.6$

###(c) Forecast the last 12 observations and calculate the forecast errors. Does the forecasting procedure seem to be working satisfactorily?

```

# initialize vectors and values
l<-0.6

```

```

T<-12
tau<-12
alpha.lev<-0.05
cpi.forecast<-rep(0,tau)
cl<-rep(0,tau)
cpi.smooth1<-rep(0,tau+T)
cpi.smooth2<-rep(0,tau+T)

# forecast
for (i in 1:tau){
  cpi.smooth1[1:(T+i-1)] <-firstsmooth(y=d[1:(T+i-1),2], lambda=1)
  cpi.smooth2[1:(T+i-1)] <-firstsmooth(y=cpi.smooth1[1:(T+i-1)], lambda=1)
  cpi.forecast[i]<-(2+(1/(1-l)))*cpi.smooth1[T+i-1]-
    (1+(1/(1-l)))*cpi.smooth2[T+i-1]
  cpi.hat<-2*cpi.smooth1[1:(T+i-1)]-cpi.smooth2[1:(T+i-1)]
  sig.est<-sqrt(var(d[2:(T+i-1),2]-cpi.hat[1:(T+i-2)]))
  cl[i]<-qnorm(1-alpha.lev/2)*sig.est
}

# calculate forecast errors and display
forecast.error<-d[,2]-cpi.forecast
data.frame(Forecast=cpi.forecast, Forecast_Error<-forecast.error)[13:24,]

```

```

##      Forecast Forecast_Error...forecast.error
## 13 439.3167                20.683340
## 14 468.1451               -73.145141
## 15 391.8254               -1.825447
## 16 374.7571               75.242865
## 17 449.5136                8.486363
## 18 471.2498               98.750232
## 19 604.3576              -84.357632
## 20 553.2861             -153.286143
## 21 389.1317               30.868307
## 22 390.7796              189.220428
## 23 593.5626             -118.562586
## 24 495.1253               64.874662

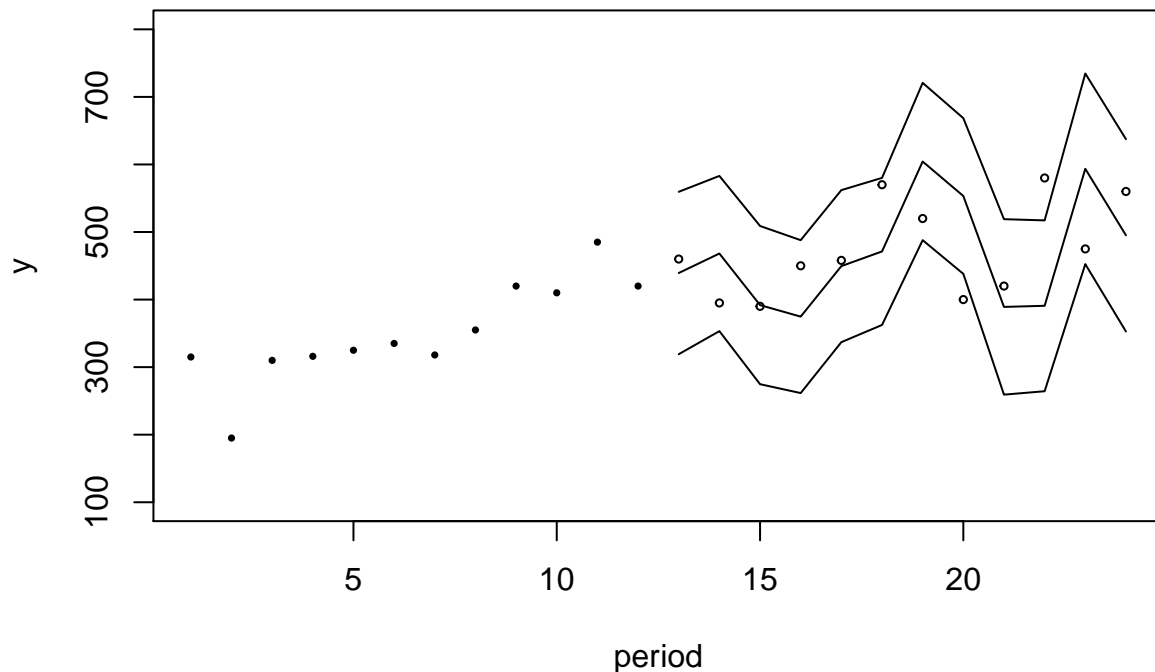
```

```

# plot forecast model with prediction intervals
plot(d[1:T,2], type='p', pch=16, cex=0.5, xlim=c(1,T+tau), ylim=c(100,800),
     ylab='y', xlab='period', main='Freecast Model for last 12 points')
points((T+1):(T+tau), d[(T+1):(T+tau),2], cex=0.5)
lines((T+1):(T+tau), cpi.forecast)
lines((T+1):(T+tau), cpi.forecast+cl)
lines((T+1):(T+tau), cpi.forecast-cl)

```

Freecast Model for last 12 points



The forecast model seems to work pretty well to predict the last 12 data points in the data set. The 99% confidence interval encompasses most of the points, but there are two that lie outside. The points that are outside of the interval are still very close to the interval region. The model appears to be satisfactory.

Exercise 4.27

Table B.10 contains 7 years of monthly data on the number of airline miles flown in the United Kingdom. This is seasonal data.

###(a) Make a time series plot of the data and verify that it is seasonal.

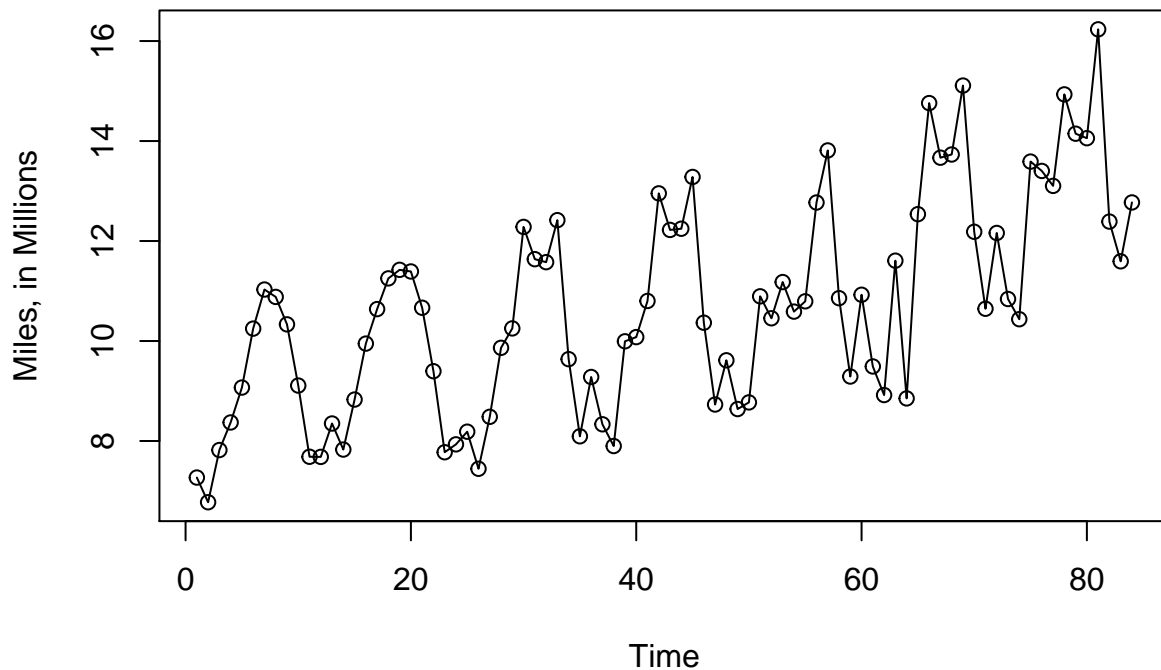
```
# import Data
library(readxl)
```

```
## Warning: package 'readxl' was built under R version 3.5.3
```

```
data <- read_excel("C:/College Stuff/Time series/AppendixB_datafile.xls",
  sheet = "B.10-FLOWN", col_types = c("date",
    "numeric"), skip = 2)
# create timeseries
data_ts<-ts(data[,2])

# plot time series
plot(data_ts, type='o',
  main='Time Series Plot of Data')
```

Time Series Plot of Data



The data does appear to be seasonal. It also follows a linear trend. The seasonal oscillations seem to get larger as time goes on, so using multiplicative seasonality is best.

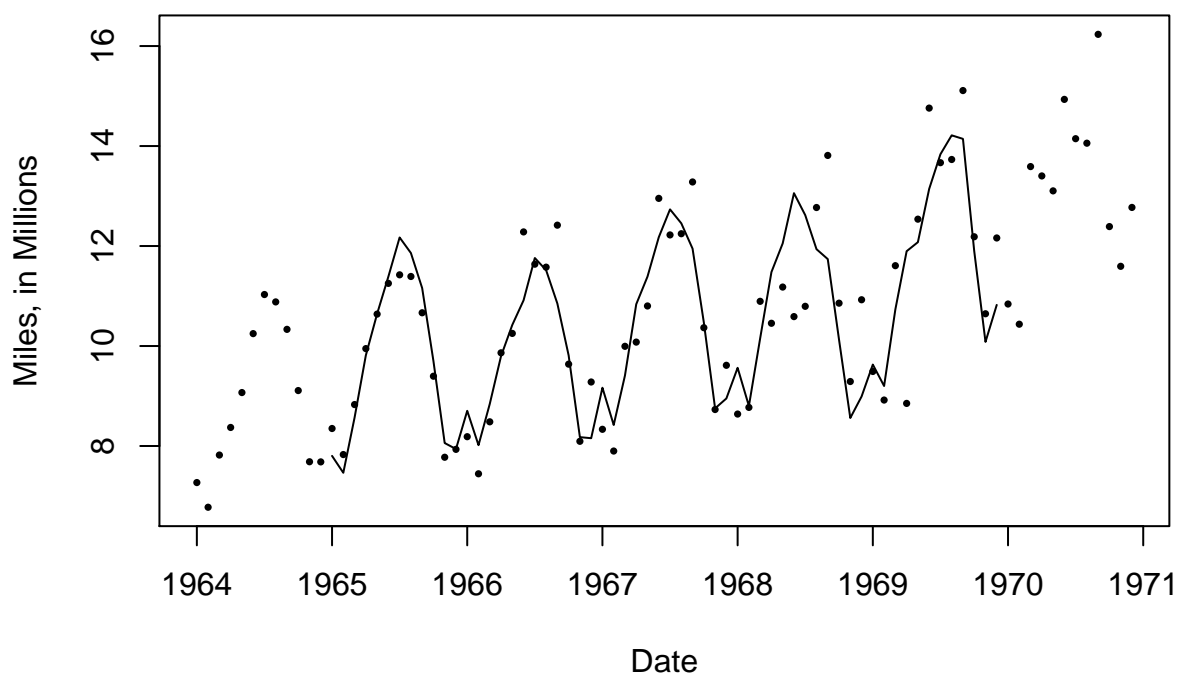
###(b) Use Winter's multiplicative method for the first 6 years to develop a forecasting method for this data. How well does this smoothing procedure work?

```
# create time series for first 6 months
yt <- ts(data[,2], start=c(1964,1), freq=12)
y_first6 <- ts(data[1:72,2], start=c(1964,1), freq=12)

# holt winters model
air.model <- HoltWinters(y_first6,alpha=0.2,beta=0.2, gamma=0.2, seasonal='multiplicative')

# plot data and holt winters fit
plot(yt, type="p", pch=16, cex=0.5, xlab='Date', ylab='Miles, in Millions', main='Holt Winters Plot')
lines(air.model$fitted[,1])
```

Holt Winters Plot



The multiplicative seasonal model is:

$$y_t = L_t S_t + \epsilon_t$$

###(c) Make one-step-ahead forecasts of the last 12 months. Determine the forecast errors. How well did your procedure work in forecasting the new data?

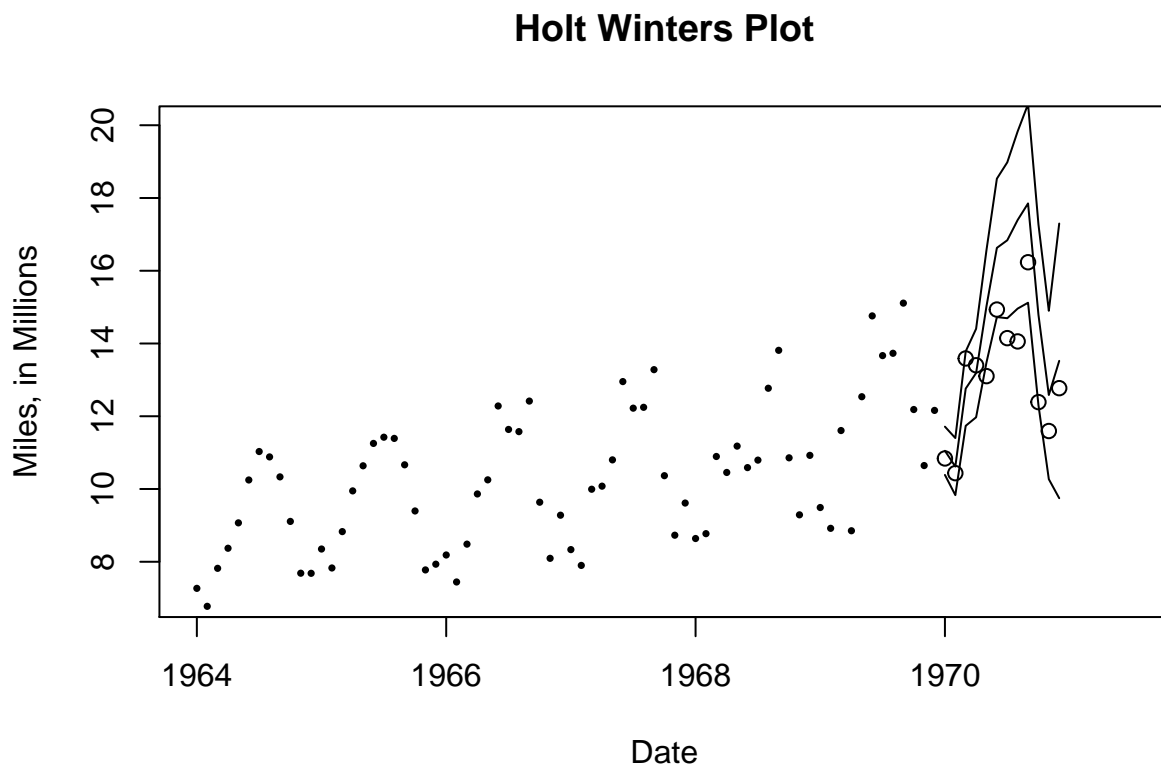
```
# Forecast errors
y2 <- data[73:84,]
y2.ts <- ts(y2[,2], start=c(1970,1), freq=12)
y2.forecast <- predict(air.model, n.ahead=12, prediction.interval=TRUE)
Forecast_Error <- as.numeric(y2.ts)-as.numeric(y2.forecast[,1])

# display
data.frame(observation=1:12, Forecast_Error=Forecast_Error)
```

```
##      observation Forecast_Error
## 1             1      -0.2108528
## 2             2      -0.1799367
## 3             3       0.8288952
## 4             4       0.2142654
## 5             5      -1.9256487
## 6             6      -1.6959719
## 7             7      -2.6903735
## 8             8      -3.3378761
## 9             9      -1.6168380
## 10            10      -2.4004458
```

```
## 11          11      -0.9902873
## 12          12      -0.7506524
```

```
# plot the forecast
plot(y_first6, type="p", pch=16, cex=0.5, xlim=c(1964, 1971.5), ylim=c(7,20),
     xlab='Date', ylab='Miles, in Millions', main='Holt Winters Plot')
points(y2.ts)
lines(y2.forecast[,1])
lines(y2.forecast[,2])
lines(y2.forecast[,3])
```



The forecast model seems to be predicting higher values than what the values actually are. We can see this with the negative forecast errors. Most of the data points lie within the confidence interval for the forecasted values. Although there are some points where the trend within the season changes from increasing to decreasing that lie outside of the confidence interval. The confidence interval is also very wide at the peak. The model works fairly well, but it overpredicts at the peak, it might be worth trying another forecast model.

Example 4.6

Compare Trigg-Leader smoother with exponential smoother. Make a plot, and show the first 10 calculations for the Trigg-Leach smoother.

```
# import data
library(readxl)
dji.data <- read_excel("C:/College Stuff/Time series/DowJones.xlsx")
```



```

# TL Smoother function
tllsmooth <- function(y, gamma, y.tilde.start=y[1], lambda.start=1){
  T <-length(y)
  Qt <-vector()
  Dt<-vector()
  y.tilde<-vector()
  lambda<-vector()
  err <- vector()

  lambda[1]=lambda.start
  y.tilde[1]=y.tilde.start
  Qt[1]<-0
  Dt[1]<-0
  err[1]<-0

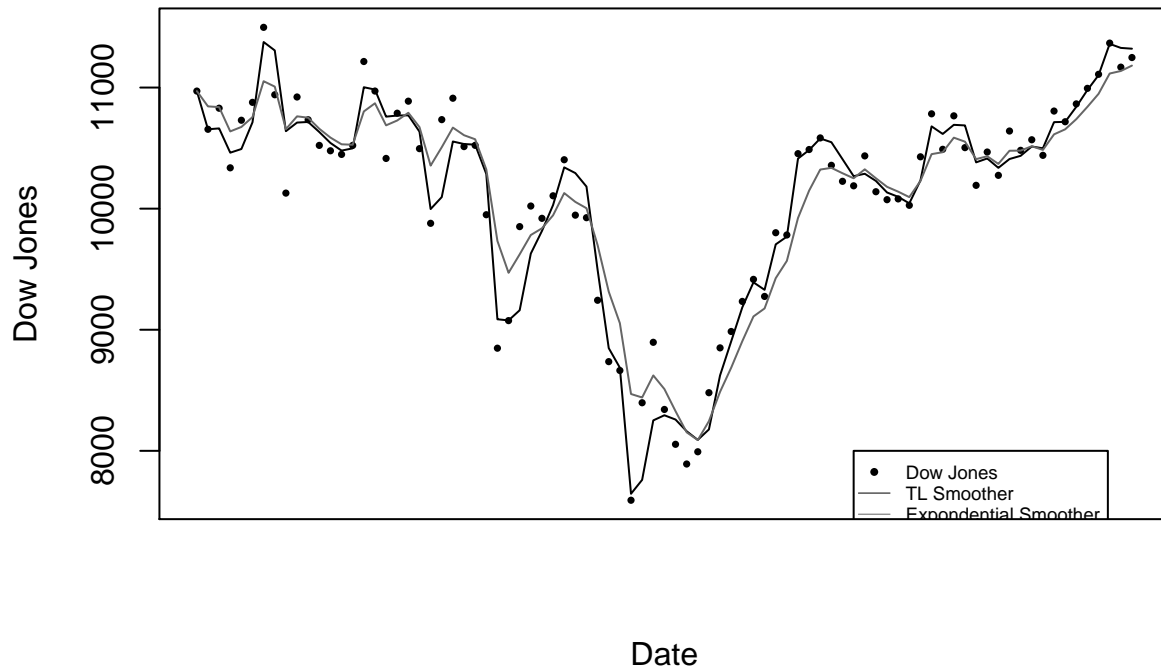
  for (i in 2:T){
    err[i]<-y[i]-y.tilde[i-1]
    Qt[i]<-gamma*err[i]+(1-gamma)*Qt[i-1]
    Dt[i]<-gamma*abs(err[i])+(1-gamma)*Dt[i-1]
    lambda[i]<-abs(Qt[i]/Dt[i])
    y.tilde[i]=lambda[i]*y[i] + (1-lambda[i])*y.tilde[i-1]
  }
  return(cbind(y.tilde,lambda,err,Qt,Dt))
}

# Apply TL smoother
out.tl.dji <-tllsmooth(dji.data$'Dow Jones',0.4)

# Apply Eponential Smoother
dji.smooth1<-firstsmooth(y=dji.data$'Dow Jones', lambda=0.4)

# plot
plot(dji.data$'Dow Jones', type='p', pch=16, cex=0.5, xlab='Date', ylab='Dow Jones', xaxt='n')
lines(out.tl.dji[,1])
lines(dji.smooth1, col="grey40")
legend(60, 8000, c('Dow Jones', 'TL Smoother', 'Exponential Smoother'),
      pch=c(16,NA,NA), lwd=c(NA, .5, .5), cex=0.55, col=c('black', 'black', 'grey40'))

```



```
# output tables for TL smoother model
data.frame(date = dji.data$Date, Dow_Jones=dji.data$'Dow Jones', Lambda=out.tl.dji[,2],
           Error=out.tl.dji[,3], Qt=out.tl.dji[,4], Dt=out.tl.dji[,5])[1:10,]
```

##	date	Dow_Jones	Lambda	Error	Qt	Dt
## 1	1999-06-01	10970.8	1.00000000	0.0000	0.00000	0.0000
## 2	1999-07-01	10655.2	1.00000000	-315.6000	-126.24000	126.2400
## 3	1999-08-01	10829.3	0.04198536	174.1000	-6.10400	145.3840
## 4	1999-09-01	10337.0	0.61566314	-325.5097	-133.86626	217.4343
## 5	1999-10-01	10729.9	0.11279687	267.7946	26.79810	237.5784
## 6	1999-11-01	10877.8	0.57381146	385.4882	170.27416	296.7423
## 7	1999-12-01	11497.1	0.84560785	783.5907	415.60076	491.4817
## 8	2000-01-01	10940.5	0.16010797	-435.6198	75.11256	469.1369
## 9	2000-02-01	10128.3	0.56616891	-1178.0736	-426.16189	752.7116
## 10	2000-03-01	10921.9	0.25271480	282.5151	-142.69111	564.6330

The TL smoother model seems to better fit the model better. The exponential smoother model does not seem to adapt quickly to large changes in the data, where the TL smoother model can. The TL smoother can fit the large peaks and valleys better. The tables shows 10 rows of the values used to construct the TL smoother model.