Python 3.5, Libraries: Numpy, Pandas, Matplotlib, Documentation: HTML, Bootstrap 4

Problem 1

- Supervised Learning: In supervised learning we work with isbeied dost that acts as a teacher and adds supervision to the system. Generally in the context of supervised learning we are trying to predict the label for
- Semi-Supervised Learning: This paradigm deals with the amalgam of supervised and unsupervised learning. Generally there will be a small amount of labeled data with a large amount of unlabeled data
- Unsupervise Learning: Index to on incoming inside important accordance and a real or you may be planted in a set of the planted in the plante
- Online Learning: A class of learning algorithms that learn the model on a continuous flow of data

Problem a

In code to detect the possible conditing of the system, one simple way is to compare the training area with the nate error. If the training area (loss promising but the set once is high these we can assume that the model has conflict the code to the promising but the set of one profession in the set of the set of the profession in the set of th

Problem 3

RMSE is the Root of MSE which by self in the Mean Squared Error. MSE is analogous to the variance or the error of our estimator (machine learning mode) and RMSE is analogous to the standard deviation of the error.

By error (i) we mean the residual error or the difference of the prediction with the real predicted value. Each error is then squared so that negative and positive errors don't cancel each other out and mean (M) is just an investment of the prediction with the real predicted value. Each error is then squared so that negative and positive errors don't cancel each other out and mean (M) is just an investment of the prediction with the real predicted value.

average over all of them.

In order to consider the outliers we should consider one simple thing: The MSE criterion squares the error and RMSE normalized this square by rooting it. Therefore the higher the error, the higher distance

Problem 4

The basic dash behind Gradient Descent with momentum is to compute an exponentially weighted average of your gradients, and then use that gradient to update your weights instead. This will almost always work better than the straightforward gradient descent algorithm without momentum. However we should be creefed in choosing the value of momentum because in large or reality small values of momentum there is a chance that we miss the local minimum.

Problem 5

6, in it expresses the bias or the intercept in our model and it represents the mean of the response variable (deprendent variable) when the explanatory variables (proportion variables) are zero. Normally we don't regularies the intercept. Why? Remember that regularization is used in order to avoid overfitting by reducing the magnitude of the coefficients and the value of intercept does not contribute to overfitting and therefore is not desirable to put presslay on its magnitude.

Problem 6

It will decrease the chances of overfitting. Due to having more data we can decrease our general error and our data represent the real world more and more as they increase, therefore having a good fit (or even an

Problem 7

- 1. Using General Simple Models: This way the model is not to complex to over
- 2. Use more data: As described in the previous problem
- Use Cross Wildation: Having a set of data to validate the results on would help avoiding overfitting and choosing a better in
 Use Regularization: Shrinking the coefficients will automatically lead to less overfitting.

