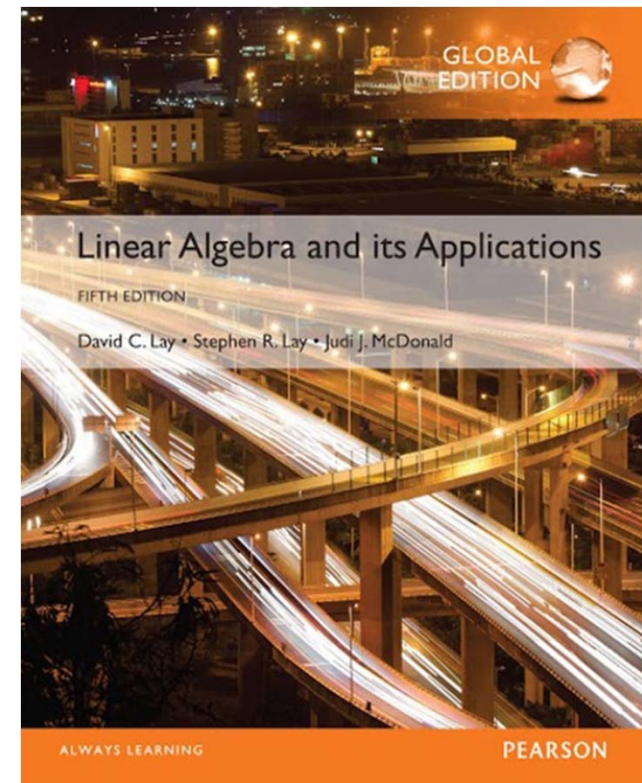


# 7

## Symmetric Matrices and Quadratic Forms

### 7.3

### CONSTRAINED OPTIMIZATION



## 7.3

# CONSTRAINED OPTIMIZATION

Engineers, economists, scientists, and mathematicians often need to find the maximum or minimum value of a quadratic form  $Q(\mathbf{x})$  for  $\mathbf{x}$  in some specified set. Typically, the problem can be arranged so that  $\mathbf{x}$  varies over the set of unit vectors. This *constrained optimization problem* has an interesting and elegant solution.

The requirement that a vector  $\mathbf{x}$  in  $\mathbb{R}^n$  be a unit vector can be stated in several equivalent ways:

$$\|\mathbf{x}\| = 1, \quad \|\mathbf{x}\|^2 = 1, \quad \mathbf{x}^T \mathbf{x} = 1$$

and

$$x_1^2 + x_2^2 + \cdots + x_n^2 = 1 \tag{1}$$

The expanded version (1) of  $\mathbf{x}^T \mathbf{x} = 1$  is commonly used in applications.

When a quadratic form  $Q$  has no cross-product terms, it is easy to find the maximum and minimum of  $Q(\mathbf{x})$  for  $\mathbf{x}^T \mathbf{x} = 1$ .

**EXAMPLE 1** Find the maximum and minimum values of  $Q(\mathbf{x}) = 9x_1^2 + 4x_2^2 + 3x_3^2$  subject to the constraint  $\mathbf{x}^T \mathbf{x} = 1$ .

**SOLUTION** Since  $x_2^2$  and  $x_3^2$  are nonnegative, note that

$$4x_2^2 \leq 9x_2^2 \quad \text{and} \quad 3x_3^2 \leq 9x_3^2$$

and hence

$$\begin{aligned} Q(\mathbf{x}) &= 9x_1^2 + 4x_2^2 + 3x_3^2 \\ &\leq 9x_1^2 + 9x_2^2 + 9x_3^2 \\ &= 9(x_1^2 + x_2^2 + x_3^2) \\ &= 9 \end{aligned}$$

whenever  $x_1^2 + x_2^2 + x_3^2 = 1$ . So the maximum value of  $Q(\mathbf{x})$  cannot exceed 9 when  $\mathbf{x}$  is a unit vector. Furthermore,  $Q(\mathbf{x}) = 9$  when  $\mathbf{x} = (1, 0, 0)$ . Thus 9 is the maximum value of  $Q(\mathbf{x})$  for  $\mathbf{x}^T \mathbf{x} = 1$ .

To find the minimum value of  $Q(\mathbf{x})$ , observe that

$$9x_1^2 \geq 3x_1^2, \quad 4x_2^2 \geq 3x_2^2$$

and hence

$$Q(\mathbf{x}) \geq 3x_1^2 + 3x_2^2 + 3x_3^2 = 3(x_1^2 + x_2^2 + x_3^2) = 3$$

whenever  $x_1^2 + x_2^2 + x_3^2 = 1$ . Also,  $Q(\mathbf{x}) = 3$  when  $x_1 = 0$ ,  $x_2 = 0$ , and  $x_3 = 1$ . So 3 is the minimum value of  $Q(\mathbf{x})$  when  $\mathbf{x}^T \mathbf{x} = 1$ . ■

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- **Theorem 6** Let  $A$  be a symmetric matrix, and define  $m$  and  $M$  as in (2):

$$m = \min\{\mathbf{x}^T A \mathbf{x} : \|\mathbf{x}\|=1\} \quad \text{and} \quad M = \max\{\mathbf{x}^T A \mathbf{x} : \|\mathbf{x}\|=1\} \quad (2)$$

- Then  $M$  is the greatest eigenvalue  $\lambda_1$  of  $A$  and  $m$  is the least eigenvalue of  $A$ . The value of  $\mathbf{x}^T A \mathbf{x}$  is  $M$  when  $\mathbf{x}$  is a unit eigenvector  $\mathbf{u}_1$  corresponding to  $M$ . The value of  $\mathbf{x}^T A \mathbf{x}$  is  $m$  when  $\mathbf{x}$  is a unit eigenvector corresponding to  $m$ .
- **Proof** Orthogonally diagonalize  $A$  as  $PDP^{-1}$ . We know that (3)

$$\mathbf{x}^T A \mathbf{x} = \mathbf{y}^T D \mathbf{y} \quad \text{when} \quad \mathbf{x} = P\mathbf{y}$$

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- Also,

$$\|x\| = \|Py\| = \|y\| \text{ for all } y$$

- Because  $P^T P = I$  and  $\|Py\|^2 = (Py)^T(Py) = y^T P^T P y = y^T y = \|y\|^2$ . In particular,  $\|y\| = 1$  if and only if  $\|x\| = 1$ . Thus,  $x^T A x$  and  $y^T D y$  assume the same set of values as  $x$  and  $y$  range over the set of all unit vectors.
- To simplify notation, suppose that  $A$  is a  $3 \times 3$  matrix with eigenvalues  $a \geq b \geq c$ . Arrange the columns of  $P$  so that  $P = [u_1 \ u_2 \ u_3]$  and

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$$D = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$$

- Given any unit vector  $y$  in  $\mathbb{R}^3$  with coordinates  $y_1, y_2, y_3$ , observe that

$$\begin{aligned} ay_1^2 &= ay_1^2 \\ by_2^2 &\leq ay_2^2 \\ cy_3^2 &\leq ay_3^2 \end{aligned}$$

- and obtain these inequalities:

$$\begin{aligned} y^T D y &= ay_1^2 + by_2^2 + cy_3^2 \\ &\leq ay_1^2 + ay_2^2 + ay_3^2 \\ &= a(y_1^2 + y_2^2 + y_3^2) = a\|y\|^2 = a \end{aligned}$$

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- Thus  $M \leq a$ , by definition of  $M$ . However,  $y^T D y = a$  when  $y = e_1 = (1, 0, 0)$ , so in fact  $M = a$ . By (3), the  $x$  that corresponds by  $y = e_1$  is the eigenvector  $u_1$  of  $A$ , because

$$x = P e_1 = [u_1 \quad u_2 \quad u_3] \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = u_1$$

- Thus  $M = a = e_1^T D e_1 = u_1^T A u_1$ , which proves the statement about  $M$ . A similar argument shows that  $m$  is the least eigenvalue,  $c$ , and this value of  $x^T A x$  is attained when  $x = P e_3 = u_3$ .

# CONSTRAINED OPTIMIZATION

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- **Example 3** Let  $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 4 \end{bmatrix}$ . Find the maximum value of the quadratic form  $\mathbf{x}^T A \mathbf{x}$  subject to the constraint  $\mathbf{x}^T \mathbf{x} = 1$ , and find a unit vector at which this maximum value is attained.
- **Solution** By Theorem 6, the desired maximum value is the greatest eigenvalue of  $A$ . The characteristic equation turns out to be

$$0 = -\lambda^3 + 10\lambda^2 - 27\lambda + 18 = -(\lambda - 6)(\lambda - 3)(\lambda - 1)$$



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- The greatest eigenvalue is 6.
- The constrained maximum of  $x^T A x$  is attained when  $x$  is a unit eigenvector for  $\lambda = 6$ . Solve  $(A - 6I)x = 0$  and find an eigenvector  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ . Set  $u_1 = \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$ .

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- **Theorem 7** Let  $A$ ,  $\lambda_1$ , and  $u_1$  be as in Theorem 6. Then the maximum value of  $x^T A x$  subject to the constraints
$$x^T x = 1, x^T u_1 = 0$$
- is the second greatest eigenvalue  $\lambda_2$ , and this maximum is attained when  $x$  is an eigenvector  $u_2$  corresponding to  $\lambda_2$ .
- **Example 4** Find the maximum value of  $9x_1^2 + 4x_2^2 + 3x_3^2$  subject to the constraints  $x^T x = 1$ , and  $x^T u_1 = 0$ , where  $u_1 = (1, 0, 0)$ . Note that  $u_1$  is a unit eigenvector corresponding to the greatest eigenvalue  $\lambda = 9$  of the matrix of the quadratic form.

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- **Solution** If the coordinates of  $x$  are  $x_1, x_2, x_3$ , then the constraint  $x^T u_1 = 0$  means simply that  $x_1 = 0$ . For such a unit vector,  $x_2^2 + x_3^2 = 1$ , and

$$\begin{aligned} 9x_1^2 + 4x_2^2 + 3x_3^2 &= 4x_2^2 + 3x_3^2 \\ &\leq 4x_2^2 + 4x_3^2 \\ &= 4(x_2^2 + x_3^2) \\ &= 4 \end{aligned}$$

- Thus the constrained maximum of the quadratic form does not exceed 4. And this value is attained for  $x = (0, 1, 0)$  which is the eigenvector for the second greatest eigenvalue of the matrix of the quadratic form.

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- **Theorem 8** Let  $A$  be a symmetric  $n \times n$  matrix with an orthogonal diagonalization  $A = PDP^{-1}$ , where the entries on the diagonal of  $D$  are arranged so that  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$  and where columns of  $P$  are corresponding unit eigenvectors  $u_1, \dots, u_n$ . Then for  $k = 2, \dots, n$ , the maximum value of  $x^T A x$  subject to the constraints

$$x^T x = 1, x^T u_1 = 0, \quad \dots, \quad x^T u_{\underline{k-1}} = 0$$

- is the eigenvalue  $\lambda_{\underline{k}}$ , and this maximum is attained at  $x = u_k$ .