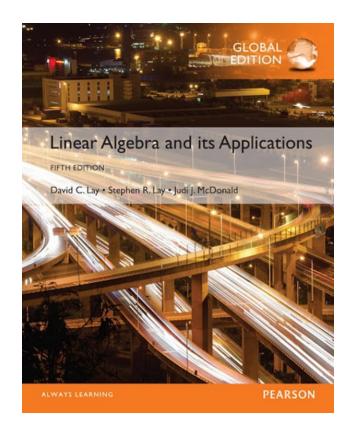
6

# Orthogonality and Least Squares

6.4

# THE GRAM-SCHMIDT PROCESS



- Theorem 11: The Gram-Schmidt Process
- Given a basis  $\{x_1, \ldots, x_p\}$  for a nonzero subspace W of  $\mathbb{R}^n$ , define

$$\begin{aligned} v_1 &= x_1 \\ v_2 &= x_2 - \frac{x_2 \cdot v_1}{v_1 \cdot v_1} v_1 \\ v_3 &= x_3 - \frac{x_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_3 \cdot v_2}{v_2 \cdot v_2} v_2 \\ &\vdots \\ v_p &= xp - \frac{x_p \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_p \cdot v_2}{v_2 \cdot v_2} v_2 - \dots - \frac{x_p \cdot v_{p-1}}{v_{p-1}} v_{p-1} \end{aligned}$$

• Then  $\{v_1, \ldots, v_p\}$  is an orthogonal basis for W. In addition

$$Span\{v_1, ..., v_k\} = Span\{x_1, ..., x_k\} \text{ for } 1 \le k \le p$$
 (1

■ **Proof** For, let  $W_k = \text{Span}\{x_1, \ldots, x_k\}$ . Set  $v_1 = x_1$ , so that  $\text{Span}\{v_1\} = \text{Span}\{x_1\}$ . Suppose, for some k < p, we have constructed  $v_1, \ldots, v_k$  so that  $\{v_1, \ldots, v_k\}$  is an orthogonal basis for  $W_k$ . Define

$$\mathbf{v}_{k+1} = \mathbf{x}_{k+1} - \text{proj}_{\mathbf{W}_{k}} \mathbf{x}_{k+1}$$
 (2)

- By Orthogonal Decomposition Theorem,  $v_{k+1}$  is orthogonal to  $W_k$ . Also,  $v_{k+1} \neq 0$  because  $x_{k+1}$  is not in  $W_k = \text{Span}\{x_1, \ldots, x_k\}$ .
- Hence  $\{v_1, \ldots, v_{k+1}\}$  is an orthogonal set of nonzero vectors in the (k + 1)-dimensional space  $W_{k+1}$ . By the Basis Theorem in Section 4.5, this set is an orthogonal basis for  $W_{k+1}$ . Hence  $W_{k+1} = Span\{v_1, \ldots, v_{k+1}\}$ . When k + 1 = p, the process stops.

**EXAMPLE 2** Let 
$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$
,  $\mathbf{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ , and  $\mathbf{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$ . Then  $\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$  is

clearly linearly independent and thus is a basis for a subspace W of  $\mathbb{R}^4$ . Construct an orthogonal basis for W.

Let 
$$\mathbf{v}_1 = \mathbf{x}_1$$
 and  $W_1 = \operatorname{Span}\{\mathbf{x}_1\} = \operatorname{Span}\{\mathbf{v}_1\}.$ 

$$\mathbf{v}_{2} = \mathbf{x}_{2} - \operatorname{proj}_{W_{1}} \mathbf{x}_{2}$$

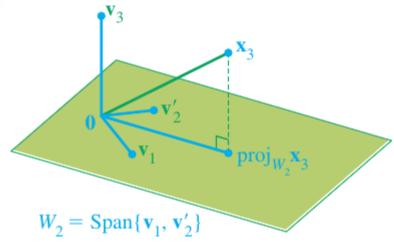
$$= \mathbf{x}_{2} - \frac{\mathbf{x}_{2} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}} \mathbf{v}_{1} \qquad \text{Since } \mathbf{v}_{1} = \mathbf{x}_{1}$$

$$= \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{3}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3/4 \\ 1/4 \\ 1/4 \end{bmatrix}$$

For simplification, we can scale 
$$\mathbf{v}_2$$
  $\mathbf{v}_2' = \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}$  by a factor of 4

$$\operatorname{projection of}_{\mathbf{x}_{3} \text{ onto } \mathbf{v}_{1}} \operatorname{projection of}_{\mathbf{x}_{3} \text{ onto } \mathbf{v}_{2}} \mathbf{v}_{3} = \begin{bmatrix} \mathbf{x}_{3} \cdot \mathbf{v}_{1} \\ \mathbf{v}_{1} \cdot \mathbf{v}_{1} \end{bmatrix} + \begin{bmatrix} \mathbf{x}_{3} \cdot \mathbf{v}_{2}' \\ \mathbf{v}_{2}' \cdot \mathbf{v}_{2}' \end{bmatrix} = \frac{2}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{2}{12} \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2/3 \\ 2/3 \\ 2/3 \end{bmatrix}$$

$$\mathbf{v}_{3} = \mathbf{x}_{3} - \operatorname{proj}_{W_{2}} \mathbf{x}_{3} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 2/3 \\ 2/3 \\ 2/3 \end{bmatrix} = \begin{bmatrix} 0 \\ -2/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$



#### ORTHONORMAL BASES

Example 3 Example 1 constructed the orthogonal basis

$$v_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}, \ v_2 = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$$

An orthonormal basis is

$$u_{1} = \frac{1}{\|v_{1}\|} v_{1} = \frac{1}{\sqrt{45}} \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \\ 0 \end{bmatrix}$$
$$u_{2} = \frac{1}{\|v_{2}\|} v_{2} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

- Theorem 12: The QR Factorization
- If *A* is an m\*n matrix with linearly independent columns, then *A* can be factored as A = QR, where:
  - Q is an m\*n matrix whose columns form an orthonormal basis for Col A and
  - − *R* is an *n*\**n* upper triangular invertible matrix with positive entries on its diagonal.

**Proof** The columns of A form a basis  $\{\mathbf{x}_1, \ldots, \mathbf{x}_n\}$  for Col A. Construct an orthonormal basis  $\{\mathbf{u}_1, \ldots, \mathbf{u}_n\}$  for W = Col A with property (1) in Theorem 11. This basis may be constructed by e.g., the Gram-Schmidt process.

Let

$$Q = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_n]$$

For k = 1,..., n,  $\mathbf{x}_k$  is in Span $\{\mathbf{x}_1, ..., \mathbf{x}_k\}$  = Span $\{\mathbf{u}_1, ..., \mathbf{u}_k\}$ . So there are constants,  $r_{1k}, ..., r_{kk}$ , such that

$$\mathbf{x}_k = r_{1k}\mathbf{u}_1 + \dots + r_{kk}\mathbf{u}_k + 0 \cdot \mathbf{u}_{k+1} + \dots + 0 \cdot \mathbf{u}_n$$

- We may assume that  $r_{kk} \ge 0$ .
  - If  $r_{kk} < 0$ , multiply both  $r_{kk}$  and  $\mathbf{u}_k$  by -1
- This shows that  $\mathbf{x}_k$  is a linear combination of the columns of Q using as weights the entries in the vector:

$$\mathbf{r}_k = \begin{bmatrix} r_{1k} \\ \vdots \\ r_{kk} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

- That is,  $\mathbf{x}_k = Q \mathbf{r}_k$  for  $k = 1, \ldots, n$ . Let  $R = [\mathbf{r}_1 \ldots \mathbf{r}_n]$ .
- Then

$$A = [\mathbf{x}_1 \dots \mathbf{x}_n] = [Q\mathbf{r}_1 \dots Q\mathbf{r}_n] = QR.$$

- The fact that *R* is invertible follows easily from the fact that the columns of *A* are linearly independent:
  - We form:  $R \mathbf{v} = 0$ , which gives:  $QR \mathbf{v} = 0$ , and  $A\mathbf{v} = 0$ .
  - Since columns of A are linearly independent,  $A\mathbf{v} = 0$  yields  $\mathbf{v} = 0$ .
  - Therefore, from R  $\mathbf{v}$  = 0, we concluded that  $\mathbf{v}$  = 0, which means R is invertible.
- Since R is clearly upper triangular, its nonnegative diagonal entries must be positive.

- **Example 4**Find a QR factorization of  $A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ .
- Solution The columns of A are the vectors  $x_1$ ,  $x_2$ , and  $x_3$  in Example 2. An orthogonal basis for Col A = Span $\{x_1, x_2, x_3\}$  was found in that example:

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 0 \\ -2/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

To simplify the arithmetic that follows, scale  $v_3$  by letting  $v_3 = 3v_3$ . Then normalize the three vectors to obtain  $u_1$ ,  $u_2$ , and  $u_3$ , and use these vectors as the columns of Q:

$$Q = \begin{bmatrix} 1/2 & -3/\sqrt{12} & 0\\ 1/2 & 1/\sqrt{12} & -2/\sqrt{6}\\ 1/2 & 1/\sqrt{12} & 1/\sqrt{6}\\ 1/2 & 1/\sqrt{12} & 1/\sqrt{6} \end{bmatrix}.$$

■ By construction, the first k columns of Q are an orthonormal basis of Span $\{x_1, \ldots, x_k\}$ .

• From the proof of Theorem 12, A = QR for some R. To find R, observe that  $Q^TQ = I$ , because the columns of Q are orthonormal. Hence

$$Q^T A = Q^T (QR) = IR = R$$

and

$$R = \begin{bmatrix} 1/2 & 1/2 & 1/2 & 1/2 \\ -3/\sqrt{12} & 1/\sqrt{12} & 1/\sqrt{12} & 1/\sqrt{12} \\ 0 & -2/\sqrt{6} & 1/\sqrt{6} & 1/\sqrt{6} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 2 & 3/2 & 1 \\ 0 & 3/\sqrt{12} & 2/\sqrt{12} \\ 0 & 0 & 2/\sqrt{6} \end{bmatrix}$$