

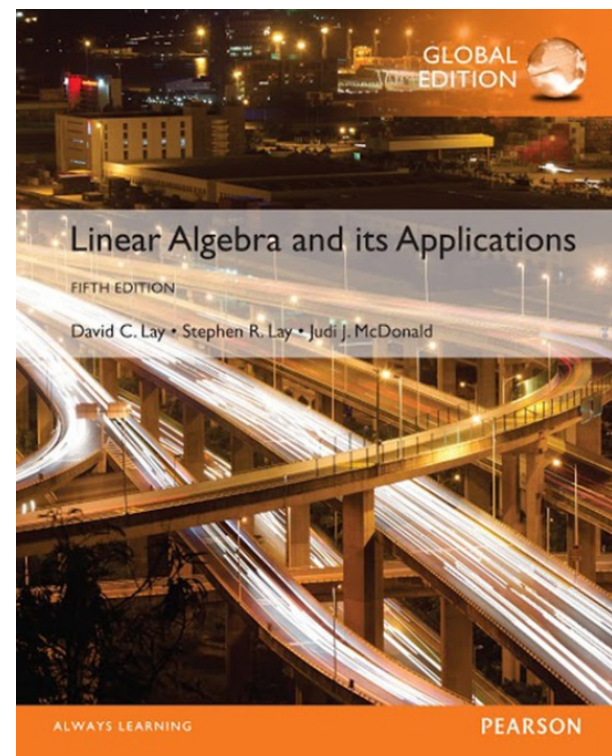
6

Orthogonality and Least Squares

6.3

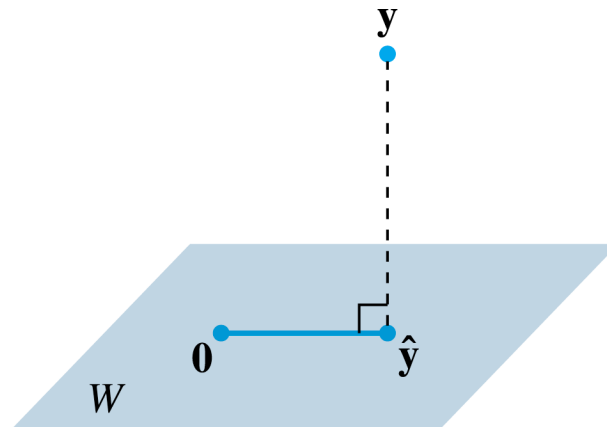
ORTHOGONAL PROJECTIONS

$\hat{y} : \text{تخمین } y$



ORTHOGONAL PROJECTIONS

- The orthogonal projection of a point in \mathbb{R}^2 onto a line through the origin has an important analogue in \mathbb{R}^n .
- Given a vector \mathbf{y} and a subspace W in \mathbb{R}^n , there is a vector $\hat{\mathbf{y}}$ in W such that (1) $\hat{\mathbf{y}}$ is the unique vector in W for which $\mathbf{y} - \hat{\mathbf{y}}$ is orthogonal to W , and (2) $\hat{\mathbf{y}}$ is the unique vector in W closest to \mathbf{y} . See the following figure.



THE ORTHOGONAL DECOMPOSITION THEOREM

- These two properties of \hat{y} provide the key to finding the least-squares solutions of linear systems.
- **Theorem 8:** Let W be a subspace of \mathbb{R}^n . Then each y in \mathbb{R}^n can be written uniquely in the form

$$(1) \quad y = \hat{y} + z$$

where \hat{y} is in W and z is in W^\perp .

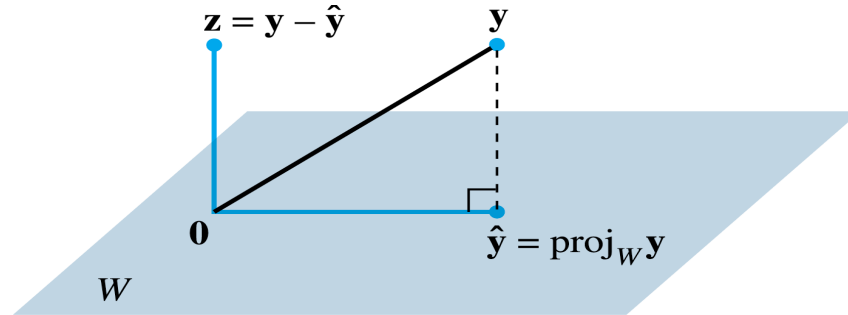
- In fact, if $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is any orthogonal basis of W , then

$$(2) \quad \hat{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \dots + \frac{y \cdot u_p}{u_p \cdot u_p} u_p$$

and $z = y - \hat{y}$.

THE ORTHOGONAL DECOMPOSITION THEOREM

- The vector \hat{y} in (1) is called the **orthogonal projection of y onto W** and often is written as $\text{proj}_W y$. See the following figure:



The orthogonal projection of y
onto W .

- **Proof:** Let $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ be any orthogonal basis for W , and define \hat{y} by (2).
- Then \hat{y} is in W because \hat{y} is a linear combination of the basis $\mathbf{u}_1, \dots, \mathbf{u}_p$.

THE ORTHOGONAL DECOMPOSITION THEOREM

- Let $\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}}$.
- Since \mathbf{u}_1 is orthogonal to $\mathbf{u}_2, \dots, \mathbf{u}_p$, it follows from (2) that

$$\begin{aligned} \mathbf{z} \cdot \mathbf{u}_1 &= (\mathbf{y} - \hat{\mathbf{y}}) \cdot \mathbf{u}_1 = \mathbf{y} \cdot \mathbf{u}_1 - \left(\frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \right) \mathbf{u}_1 \cdot \mathbf{u}_1 - 0 \dots 0 - 0 \\ &= \mathbf{y} \cdot \mathbf{u}_1 - \mathbf{y} \cdot \mathbf{u}_1 = 0 \end{aligned}$$

- Thus \mathbf{z} is orthogonal to \mathbf{u}_1 .
- Similarly, \mathbf{z} is orthogonal to each \mathbf{u}_j in the basis for W .
- Hence \mathbf{z} is orthogonal to every vector in W .
- That is, \mathbf{z} is in W^\perp .

THE ORTHOGONAL DECOMPOSITION THEOREM

- To show that the decomposition in (1) is unique, suppose \mathbf{y} can also be written as $\mathbf{y} = \hat{\mathbf{y}}_1 + \mathbf{z}_1$, with $\hat{\mathbf{y}}_1$ in W and \mathbf{z}_1 in W^\perp .

- Then $\hat{\mathbf{y}} + \mathbf{z} = \hat{\mathbf{y}}_1 + \mathbf{z}_1$ (since both sides equal \mathbf{y}), and so

$$\hat{\mathbf{y}} - \hat{\mathbf{y}}_1 = \mathbf{z}_1 - \mathbf{z}$$

- This equality shows that the vector $\mathbf{v} = \hat{\mathbf{y}} - \hat{\mathbf{y}}_1$ is in W and in W^\perp (because \mathbf{z}_1 and \mathbf{z} are both in W^\perp , and W^\perp is a subspace).
- Hence $\mathbf{v} \cdot \mathbf{v} = 0$, which shows that $\mathbf{v} = \mathbf{0}$.
- This proves that $\hat{\mathbf{y}} = \hat{\mathbf{y}}_1$ and also $\mathbf{z}_1 = \mathbf{z}$.

THE ORTHOGONAL DECOMPOSITION THEOREM

- The uniqueness of the decomposition (1) shows that the orthogonal projection \hat{y} depends only on W and not on the particular basis used in (2).
- **Example 1:** Let $\mathbf{u}_1 = \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$, and $\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.

Observe that $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthogonal basis for $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. Write \mathbf{y} as the sum of a vector in W and a vector orthogonal to W .

THE ORTHOGONAL DECOMPOSITION THEOREM

- **Solution:** The orthogonal projection of \mathbf{y} onto W is

$$\begin{aligned}\hat{\mathbf{y}} &= \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 \\ &= \frac{9}{30} \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix} + \frac{3}{6} \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} = \frac{9}{30} \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix} + \frac{15}{30} \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix}\end{aligned}$$

- Also

$$\mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix} = \begin{bmatrix} 7/5 \\ 0 \\ 14/5 \end{bmatrix}$$

THE ORTHOGONAL DECOMPOSITION THEOREM

- Theorem 8 ensures that $y - \hat{y}$ is in W^\perp .
- To check the calculations, verify that $y - \hat{y}$ is orthogonal to both \mathbf{u}_1 and \mathbf{u}_2 and hence to all of W .
- The desired decomposition of \mathbf{y} is

$$\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix} + \begin{bmatrix} 7/5 \\ 0 \\ 14/5 \end{bmatrix}$$

PROPERTIES OF ORTHOGONAL PROJECTIONS

- If $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthogonal basis for W and if \mathbf{y} happens to be in W , then the formula for $\text{proj}_W \mathbf{y}$ is exactly the same as the representation of \mathbf{y} given in Theorem 5 in Section 6.2.
- In this case, $\text{proj}_W \mathbf{y} = \mathbf{y}$.
- If \mathbf{y} is in $W = \text{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$, then $\text{proj}_W \mathbf{y} = \mathbf{y}$.

THE BEST APPROXIMATION THEOREM

- **Theorem 9:** Let W be a subspace of \mathbb{R}^n , let \mathbf{y} be any vector in \mathbb{R}^n , and let $\hat{\mathbf{y}}$ be the orthogonal projection of \mathbf{y} onto W . Then $\hat{\mathbf{y}}$ is the closest point in W to \mathbf{y} , in the sense that

$$(3) \quad \|\mathbf{y} - \hat{\mathbf{y}}\| < \|\mathbf{y} - \mathbf{v}\|$$

for all \mathbf{v} in W distinct from $\hat{\mathbf{y}}$.

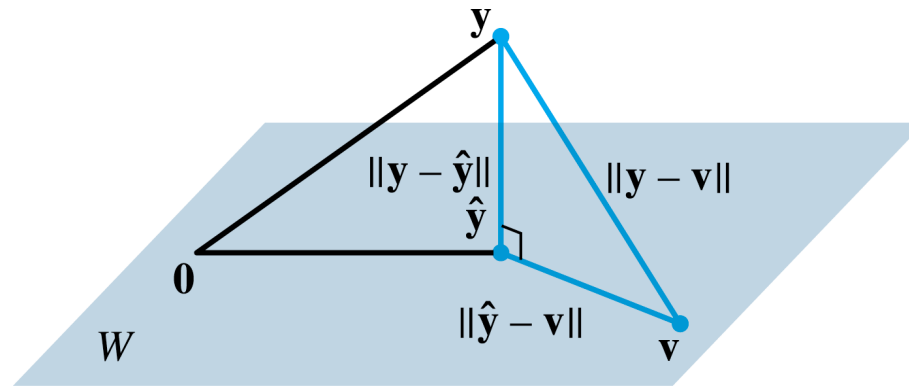
- The vector $\hat{\mathbf{y}}$ in Theorem 9 is called **the best approximation to \mathbf{y} by elements of W .**
- The distance from \mathbf{y} to \mathbf{v} , given by **$\|\mathbf{y} - \mathbf{v}\|$** , can be regarded as the “error” of using \mathbf{v} in place of \mathbf{y} .
- Theorem 9 says that this error is minimized when $\mathbf{v} = \hat{\mathbf{y}}$.

THE BEST APPROXIMATION THEOREM

- Inequality (3) leads to a new proof that $\hat{\mathbf{y}}$ does not depend on the particular orthogonal basis used to compute it.
- If a different orthogonal basis for W were used to construct an orthogonal projection of \mathbf{y} , then this projection would also be the closest point in W to \mathbf{y} , namely, $\hat{\mathbf{y}}$.

THE BEST APPROXIMATION THEOREM

- **Proof:** Take \mathbf{v} in W distinct from $\hat{\mathbf{y}}$. See the following figure:



The orthogonal projection of \mathbf{y} onto W is the closest point in W to \mathbf{y} .

- Then $\hat{\mathbf{y}} - \mathbf{v}$ is in W .
- By the Orthogonal Decomposition Theorem, $\mathbf{y} - \hat{\mathbf{y}}$ is orthogonal to W .
- In particular, $\mathbf{y} - \hat{\mathbf{y}}$ is orthogonal to $\hat{\mathbf{y}} - \mathbf{v}$ (which is in W).

THE BEST APPROXIMATION THEOREM

- Since

$$y - v = (y - \hat{y}) + (\hat{y} - v)$$

the Pythagorean Theorem gives

$$\|y - v\|^2 = \|y - \hat{y}\|^2 + \|\hat{y} - v\|^2$$

- (See the colored right triangle in the figure on the previous slide. The length of each side is labeled.)
- Now $\|\hat{y} - v\|^2 > 0$ because $\hat{y} - v \neq 0$, and so inequality (3) follows immediately.

PROPERTIES OF ORTHOGONAL PROJECTIONS

- **Example 4:** The distance from a point \mathbf{y} in \mathbb{R}^n to a subspace W is defined as the distance from \mathbf{y} to the nearest point in W . Find the distance from \mathbf{y} to $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$, where

$$\mathbf{y} = \begin{bmatrix} -1 \\ -5 \\ 10 \end{bmatrix}, \mathbf{u}_1 = \begin{bmatrix} 5 \\ -2 \\ 1 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

- **Solution:** By the Best Approximation Theorem, the distance from \mathbf{y} to W is $\|\mathbf{y} - \hat{\mathbf{y}}\|$, where $\hat{\mathbf{y}} = \text{proj}_W \mathbf{y}$.

PROPERTIES OF ORTHOGONAL PROJECTIONS

- Since $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthogonal basis for W ,

$$\hat{\mathbf{y}} = \frac{15}{30}\mathbf{u}_1 + \frac{-21}{6}\mathbf{u}_2 = \frac{1}{2}\begin{bmatrix} 5 \\ -2 \\ 1 \end{bmatrix} - \frac{7}{2}\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -8 \\ 4 \end{bmatrix}$$

$$\mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} -1 \\ -5 \\ 10 \end{bmatrix} - \begin{bmatrix} -1 \\ -8 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 6 \end{bmatrix}$$

$$\|\mathbf{y} - \hat{\mathbf{y}}\|^2 = 3^2 + 6^2 = 45$$

- The distance from \mathbf{y} to W is $\sqrt{45} = 3\sqrt{5}$.

PROPERTIES OF ORTHOGONAL PROJECTIONS

■ Theorem 10:

If $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthonormal basis for a subspace W of \mathbb{R}^n , then

$$\text{proj}_W \mathbf{y} = (\mathbf{y} \cdot \mathbf{u}_1)\mathbf{u}_1 + (\mathbf{y} \cdot \mathbf{u}_2)\mathbf{u}_2 + \cdots + (\mathbf{y} \cdot \mathbf{u}_p)\mathbf{u}_p \quad (4)$$

If $U = [\mathbf{u}_1 \quad \mathbf{u}_2 \quad \cdots \quad \mathbf{u}_p]$, then

$$\text{proj}_W \mathbf{y} = UU^T \mathbf{y} \quad \text{for all } \mathbf{y} \text{ in } \mathbb{R}^n \quad (5)$$

Proof:

- Formula (4) follows immediately from (2) in Theorem 8.

PROPERTIES OF ORTHOGONAL PROJECTIONS

- Also, (4) shows that $\text{proj}_W \mathbf{y}$ is a linear combination of the columns of U using the weights.
- The weights can be written as $u_1^T \mathbf{y}, u_2^T \mathbf{y}, \dots, u_p^T \mathbf{y}$
 - showing that they are the entries in $U^T \mathbf{y}$ and justifying (5).